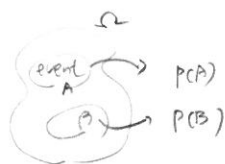


1. Probability models and axioms

• Elements of Probabilistic models

- sample space Ω
- probability law



• Probability Axioms

- nonnegativity
- additivity: $P(A_1 \cup A_2 \cup \dots) = P(A_1) + P(A_2) + \dots$ \leftarrow disjoint
- normalization: $P(\Omega) = 1$

• Discrete Probability law

• Discrete uniform probability law

2. Conditioning and Bayes' rule

• $P(A|B) = \frac{P(A \cap B)}{P(B)}$, new universe B. $P(B) > 0$

• Multiplication rule

$$P(\bigcap_{i=1}^n A_i) = P(A_1) P(A_2|A_1) \dots P(A_n | \bigcap_{i=1}^{n-1} A_i)$$

• Total Probability theorem

$$P(B) = P(A_1 \cap B) + \dots + P(A_n \cap B)$$

$$= P(A_1) P(B|A_1) + \dots + P(A_n) P(B|A_n)$$

$$* A_1 \cup A_2 \cup \dots \cup A_n = \Omega$$

• Inference and Bayes' rule

$$P(A_i|B) = \frac{P(A_i \cap B)}{P(B)} = \frac{P(A_i) P(B|A_i)}{\sum_j P(A_j) P(B|A_j)}$$

3. Independence

• Independence

$$P(A \cap B) = P(A) P(B), \quad P(A|B) = P(A)$$

$$P(\bigcap_{i \in S} A_i) = \prod_{i \in S} P(A_i) \quad S = \{1, 2, \dots, n\}$$

* Pairwise \neq independence

4. Counting

• Counting Principle (tree method)

• $n!$, $\binom{n}{k} = \frac{n!}{k!(n-k)!}$, $\frac{n!}{n_1! n_2! \dots n_r!}$ — Partition

5. Discrete random variables, probability mass functions expectation

• Random variables

- outcome $\xrightarrow{X} \text{value}$, $\omega \in \Omega$, s.t. $X(\omega) = x$

• Probability mass function

• Binomial pmf, geometric, Poisson pmf

• Expectation: center of gravity

• Variance: how far X from mean

6. Discrete random variable examples, joint PMFs

• Joint PMFs

- $P_{X,Y}(x,y) = P(X=x, Y=y)$

- $P_X(x) = \sum_y P_{X,Y}(x,y)$

- $E[g(X,Y)] = \sum_x \sum_y g(x,y) P_{X,Y}(x,y)$

• Conditional PMFs and expectation

$$P_{X|A}(x) = P(X=x|A)$$

$$E[X|A] = \sum_x x P_{X|A}(x)$$

• Total expectation theorem

$$E[X] = P(A_1) E[X|A_1] + \dots + P(A_n) E[X|A_n]$$

$$(A_1 \cup A_2 \cup \dots \cup A_n = \Omega)$$

disjoint event A_1, \dots, A_n

7. Multiple discrete random variables: expectation, conditioning, independence

• Independent random variables

$$P_{X|A}(x) = P_X(x)$$

$$P_{X,Y}(x,y) = P_X(x) P_Y(y) \quad \text{for all } x, y$$

$$P_{X,Y,Z}(x,y,z) = P_X(x) P_{Y|X}(y|x) P_{Z|X,Y}(z|x,y)$$

or $\xrightarrow{\text{indep}} P_X(x) P_Y(y) P_Z(z)$

for all x, y, z

8. Continuous random variables

• Continuous r.v.'s and pdf's

$$P(a \leq X \leq b) = \int_a^b f_X(x) dx$$

$$P(X \leq x \leq x + \delta) = \int_x^{x+\delta} f_X(s) ds \approx f_X(x) \cdot \delta$$

• mean and variances

• CDF $F_X(x) = P(X \leq x) = \int_{-\infty}^x f_X(t) dt$

• mixed distribution

• Gaussian (normal) pdf

$$f_X(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \sim N(\mu, \sigma^2)$$

• normality is preserved by linear transformation

$$Y = aX + b$$

↳ normal

9. Multiple continuous random variables

• Joint PDF $f_{X,Y}(x,y) : P(X \in S) = \iint_S f_{X,Y}(x,y) dx dy$

• Interpretation: volume

$$P(x \leq X \leq x+\delta, y \leq Y \leq y+\delta) \approx f_{X,Y}(x,y) \cdot \delta^2$$

• Expectations

$$E[g(X,Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) f_{X,Y}(x,y) dx dy$$

• from joint to the marginal

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dy$$

• Conditioning

$$f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}, \quad f_Y(y) > 0$$

$$\uparrow P(x \leq X \leq x+\delta | Y \approx y) \approx f_{X|Y}(x|y) \cdot \delta$$

For given y , conditional PDF is a normalized section of the joint PDF

• If independent, $f_{X,Y} = f_X f_Y$

$$f_{X|Y}(x|y) = f_X(x)$$

10. Continuous Bayes rule, derived distributions

• Bayes rule

$$f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)} = \frac{f_X(x) f_{Y|X}(y|x)}{\int_x f_X(x) f_{Y|X}(y|x) dx}$$

• Derived distribution

$$\text{ex) } g(X,Y) = Y/X, \quad X+Y, \quad aX+b$$

• Two-step procedure: $aX+b, Y=g(X)$

• get CDF of Y

• Differentiate to get $f_Y(y) = \frac{dF_Y}{dy}(y)$ compute directly or graphically.

↳ $Y=aX+b$ case

$$f_Y(y) = \frac{1}{|a|} f_X\left(\frac{y-b}{a}\right)$$

11. Derived distributions, convolution, covariance and correlation

• A general formula $Y=g(X)$

g is strictly monotonic

$$\delta f_X(x) = \delta f_Y(y) \left| \frac{dg}{dx}(x) \right| \delta x$$

$$f_X(x) = f_Y(y) \left| \frac{dg}{dx}(x) \right|$$

• Case 1. $X+Y=Z, f_Z(z)$

↳ convolution formula (or graphically)

$$f_Z(z) = \int_{-\infty}^{\infty} f_X(x) f_Y(z-x) dx$$

$$P_Z(z) = \sum_x P_X(x) P_Y(z-x)$$

• Case 2. $Z=Y/X$

↳ finding CDF, diff g

↳ graphically...

• Two independent normal r.v.'s: sum $X+Y=Z$ normal?

• Covariance

$$\text{cov}(X,Y) = E[(X-E[X])(Y-E[Y])]$$

$$= E[XY] - E[X]E[Y]$$

$$\text{var}\left(\sum_{i=1}^n X_i\right) = \sum_{i=1}^n \text{var}(X_i) + \sum_{i,j=1+i}^n \text{cov}(X_i, X_j)$$

• correlation coefficient

$$\rho = E\left[\frac{(X-E[X])}{\sigma_X} \cdot \frac{(Y-E[Y])}{\sigma_Y}\right] = \frac{\text{cov}(X,Y)}{\sigma_X \sigma_Y}$$

• $-1 \leq \rho \leq 1$, $\rho \uparrow \rightarrow$ strong relation linearly related

12. Iterated expectations, sum of random number of r.v.'s

• Conditional expectations

$$E[X|Y=y] = \sum_x x P_{X|Y}(x|y) \quad \text{r.v. of } Y$$

$$E[E[X|Y]] = E[X] \quad \text{total expectation theorem}$$

• $\text{var}(X|Y)$ and its expectation

$$\text{var}(X|Y) : \text{r.v. of } Y = \text{var}(X|Y=y)$$

$$\text{var}(X) = E[\text{var}(X|Y)] + \text{var}(E[X|Y])$$

avg var within sections var between sections

• Sum of random number of independent r.v.'s: X_i, N

$$E[Y] = E[E[Y|N]] = E[N]E[X] \quad (Y=X_1+\dots+X_N)$$

$$\text{var}(Y) = E[N]\text{var}(X) + (E[X])^2 \text{var}(N)$$

13. Bernoulli Process

- binomial with params p and n : k , fixed n

$$P_S(k) = \binom{n}{k} p^k (1-p)^{n-k} \quad k=0, \dots, n$$

$$E[S] = np, \quad \text{var}(S) = np(1-p)$$

- Geometric with parameter $p = \alpha$, ($k=1$)

$$P_T(t) = (1-p)^{t-1} p \quad t=1, 2, \dots$$

$$E[T] = \frac{1}{p}, \quad \text{var}(T) = \frac{1-p}{p^2}$$

- Independence properties of the Bernoulli Process

- Properties of the k th Arrival time

$$T_k = T_1 + \dots + T_k, \quad P_{T_k}(t) = \binom{t-1}{k-1} p^k (1-p)^{t-k}$$

Pascal proof of order k $E[T_k] = \frac{k}{p}$ $\text{var}(T_k) = \frac{k(1-p)}{p^2}$ $t=k, k+1, \dots$

- Splitting and merging of Bernoulli Processes

- Poisson approximation to the Binomial

Poisson r.v. Z with param λ (Poisson approximation)

$$P_Z(k) = e^{-\lambda} \frac{\lambda^k}{k!} \quad (k=0, 1, \dots)$$

$$P_S(k) = \frac{n!}{(n-k)!k!} p^k (1-p)^{n-k} \rightarrow P_Z(k) \text{ as } n \rightarrow \infty \text{ and } p = \lambda/n$$

14. Poisson Process

- Definition of the Poisson process
(arrival process with rate λ)

(time-homogeneity) : $P(k, r)$

(Independence)

(Small interval probabilities) : $P(k, \tau)$

$$P(0, \tau) = 1 - \lambda \tau$$

$$P(1, \tau) = \lambda \tau$$

$$P(k, \tau) = 0$$

- r.v. with Poisson process

$$P_{N_\tau}(k) = P(k, \tau) = e^{-\lambda \tau} \frac{(\lambda \tau)^k}{k!}, \quad k=0, 1, \dots$$

$$E[N_\tau] = \lambda \tau, \quad \text{var}(N_\tau) = \lambda \tau$$

$$f_T(t) = \lambda e^{-\lambda t}, \quad (t \geq 0) \quad E[T] = \frac{1}{\lambda}, \quad \text{var}(T) = \frac{1}{\lambda^2}$$

- Independence Properties of the Poisson process

- Properties of the k th arrival time

$$T_k = T_1 + \dots + T_k$$

$$E[T_k] = k \cdot \frac{1}{\lambda}, \quad \text{var}(T_k) = k \cdot \frac{1}{\lambda^2}$$

$$f_{T_k}(t) = \frac{(\lambda t)^{k-1} e^{-\lambda t}}{(k-1)!} \cdot \lambda = \frac{\lambda^k t^{k-1} e^{-\lambda t}}{(k-1)!}$$

Erlang pdf of order k

- Splitting and merging of Poisson process

- The random incidence paradox



16. Markov Process

- Specification

- States $S = \{1, \dots, m\}$ (Set of states S)

- transition probability P_{ij} , ($P_{ij} \geq 0$) (from state i to j)

- Independent from the past

$$P(X_{n+1} = j \mid X_n = i, X_{n-1}, \dots, X_0) = P(X_{n+1} = j \mid X_n = i) = P_{ij}$$

- n -step transition probability (recursion)

$$r_{ij}(n) = \sum_{k=1}^m r_{ik}(n-1) P_{kj}, \quad \text{for } n \geq 1, \text{ all } i, j$$

- Decomposition : recurrent and transient (classes) (states)

- Periodicity : states can be grouped in $d \geq 1$, s.t. lead to S_{k+1} (All transitions from one group lead to the next group)

- Steady-state convergence theorem

- recurrent, aperiodic $\rightarrow \pi_j$

$$\pi_j = \lim_{n \rightarrow \infty} r_{ij}(n), \quad \text{for all } i$$

$$\pi_j = \sum_{k=1}^m \pi_k P_{kj} \quad (j=1, \dots, m)$$

$$1 = \sum_{k=1}^m \pi_k$$

- Steady-state Probabilities as Expected State Frequencies

π_j : (Long run) frequency of being in j

$\pi_k P_{kj}$: frequency of transitions $k \rightarrow j$

$\sum_k \pi_k P_{kj}$: frequency of transitions into j

Birth-death Processes

$$\pi_{i+1} = \pi_i \frac{p_i}{q_i} = \pi_i \rho$$

$$\pi_i = \pi_0 \rho^i, \quad (i=0, \dots, m)$$

$$\pi_0 = 1 - \rho, \quad E[X_n] = \frac{\rho}{1 - \rho} \quad (\text{steady-state})$$



- Absorption probability Equations (to state s)

$$a_i = \sum_{j=1}^m P_{ij} a_j, \quad a_s = 1$$

(for all other i)

- Expected time to Absorption (to state s)

$$u_i = 1 + \sum_{j=1}^m P_{ij} u_j$$

- Mean first passage and recurrence times

- passage i to s : $t_i = 1 + \sum_j P_{ij} t_j$ ($i \neq s$)

$t_s = 0$

- recurrence s : $t_s^* = 1 + \sum_j P_{sj} t_j$

14. Limit theorems

- Markov Inequality: Nonnegative values X ,

$$P(X \geq a) \leq \frac{E[X]}{a}, \text{ for all } a > 0.$$
- Chebyshev Inequality

$$P(|X - \mu| \geq c) \leq \frac{\sigma^2}{c^2} \text{ for all } c > 0$$
- Weak Law of large numbers
 X_1, X_2, \dots iid rv with mean μ .

$$P(|\bar{X}_n - \mu| \geq \epsilon) = P\left(\left|\frac{X_1 + \dots + X_n}{n} - \mu\right| \geq \epsilon\right) \rightarrow 0$$

as $n \rightarrow \infty$

- Convergence in probability
 - Convergence of a deterministic sequence
 a_n converges to a , $\lim_{n \rightarrow \infty} a_n = a$
 if for every $\epsilon > 0$, there exists n_0 s.t
 $|a_n - a| < \epsilon$, for all $n \geq n_0$
 - Convergence in probability

$$\lim_{n \rightarrow \infty} P(|Y_n - a| \geq \epsilon) = 0 \text{ for every } \epsilon > 0$$

Sequence Y_n converges to a in probability

- Central Limit Theorem
 $X_1, \dots, X_n \rightarrow$ iid rv common μ, σ

$$Z_n = \frac{X_1 + \dots + X_n - n\mu}{\sigma\sqrt{n}}$$

$$\lim_{n \rightarrow \infty} P(Z_n \leq z) = \Phi(z) \text{ for every } z$$
- De Moivre-Laplace approximation to the Binomial

$$P(k \leq S_n \leq l) \approx \Phi\left(\frac{l + \frac{1}{2} - np}{\sqrt{np(1-p)}}\right) - \Phi\left(\frac{k - \frac{1}{2} - np}{\sqrt{np(1-p)}}\right)$$

21. Bayesian Inference

- Terms: Bayesian statistics (parameter estimation, hypothesis testing)
- MAP rule, LUS estimation, Linear LUS estimation
- Summary: Prior fo of unknown r.v θ
 model $P_{X|\theta}$ (or $f_{X|\theta}$) of the observation
 vector X .
 After observing X , form posterior distribution of θ . (using Bayes' rule)
 (estimator output of Bayesian inference)
- MAP rule: $\text{Argmax}_{\theta} f_{\theta|X}(\theta|X) = \hat{\theta}$
- LUS: $\hat{\theta} = E[\theta|X=x]$: conditional expectation

$$\left(\hat{\theta} = \text{argmax}_{\theta} \frac{f_{X|\theta}(x|\theta) \cdot f_{\theta}}{f_X(x)} \right)$$

- LUS estimation
 - without information

$$E[(\theta - E[\theta])^2] \leq E[(\theta - \hat{\theta})^2] \text{ for all } \hat{\theta}$$
 - Given any value x ,

$$E[(\theta - E[\theta|X=x])^2 | X=x] \leq E[(\theta - \hat{\theta})^2 | X=x]$$

$$E[(\theta - E[\theta|X])^2] \leq E[(\theta - g(X))^2]$$
- Properties of the estimation error
 - estimator $\hat{\theta} = E[\theta|X]$, error $\tilde{\theta} = \hat{\theta} - \theta$
 - $\text{cov}(\hat{\theta}, \tilde{\theta}) = 0$, $\text{var}(\theta) = \text{var}(\hat{\theta}) + \text{var}(\tilde{\theta})$

- Linear LUS
 estimator form $\hat{\theta} = aX + b$, Minimize $E[(\theta - aX - b)^2]$

$$\hat{\theta}_L = E[\theta] + \frac{\text{cov}(X, \theta)}{\text{var}(X)} (X - E[X])$$

$$\rho = \frac{\text{cov}(\theta, X)}{\sigma_{\theta} \sigma_X}, \text{ var}(\hat{\theta} - \theta) = (1 - \rho^2) \sigma_{\theta}^2$$

$\rightarrow \rho \uparrow$ uncertainty \downarrow

- * cleanest linear LUS
 example: (- set derivatives to zero to find a, \dots, b)

23. Classical Inference

- Terms: classical statistics (parameter estimation, hypothesis testing, significance testing)
- ML estimation (mean estimation, variance)
- Desirable properties of estimator
 - unbiased, consistent, small mean squared error
 $E[\hat{\theta}_n] = \theta$, $\hat{\theta}_n \rightarrow \theta$, $E[(\hat{\theta} - \theta)^2] = \text{var}(\hat{\theta}) + \text{bias}^2$

- ML estimation (tradeoff)
 - : Pick θ that makes data most likely

$$\hat{\theta}_{ML} = \text{argmax}_{\theta} P_X(x; \theta)$$

likelihood function of X parameterized by θ
- Estimate mean, variance

$$\downarrow$$

 sample mean

$$\bar{X}_n = \frac{1}{n}(X_1 + \dots + X_n) = \hat{\theta}$$
 - Bernoulli \rightarrow upperbound $\frac{1}{2}(\sigma)$ ad hoc $\sqrt{\hat{\theta}(1-\hat{\theta})}$
 - generic

$$\hat{\sigma}_n^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \hat{\theta})^2$$

\uparrow
 $\hat{\sigma}_n = \frac{1}{n} \sum_{i=1}^n X_i = \bar{X}_n$
- Confidence Interval
 : single answer may not be informative... Estimating sample mean, compute CIs using CLT

$$P(\hat{\theta} - \frac{\epsilon \sigma}{\sqrt{n}} \leq \theta \leq \hat{\theta} + \frac{\epsilon \sigma}{\sqrt{n}}) \approx 1 - \alpha$$