Dynamic Programming for Beat Tracking

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MUMT 621, Winter 2021

Feburary 23, 2021

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2021-02-23

Dynamic programming





Dynamic programming applies to optimization problems in which a set of choices must be made in order to arrive at an optimal solution – we seek to find a solution that maximizes or minimizes some function.

Greedy algorithms make the best local choice – efficient but doesn't guarantee a globally optimal solution. Exhaustive search algorithms try all combinations of choices, at a **prohibitive cost in time complexity**.

As choices are made, subproblems of the same form arise, often more than once. Dynamic programming's key technique is to store solutions to each subproblem while searching all possibilities.

- 1. Thomas H. Cormen et al. 2001. Introduction to Algorithms. 2nd. 28, 323, 339. The MIT Press. ISBN: 0262032937.
- 2. Steven S. Skiena. 2008. The Algorithm Design Manual. 31-40, 273-278. London: Springer. ISBN: 9781848000704 1848000707 9781848000698 1848000693. https://doi. org/10.1007/978-1-84800-070-4.

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-Dynamic programming

Dynamic programming

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1. Thomas H. Cormen et al. 2001. Introduction to Alexithms. 2nd. 28, 323, 339. 1 2. Steven S. Skiera. 2008. The Algorithm Design Manual. 31-40. 273-278. Londo Springer, print: 9781848000704 1848000707 9781848000998 1848000693, https://doi.

Time complexity and Big-Oh notation

Algorithms in computer science are often described by their time complexity in a hypothetical computer where simple operations take 1 time step. Big-Oh provides the upper bound of algorithm running time in relation to number of input elements.

```
function linearSearch(animalToFind, arrayOfAnimals) -> bool
    for every animal in arrayOfAnimals
        if animal == animalToFind
            return true
   return false
```

```
animals = string[5]
  "cat"
           "dog"
                     "rat"
                                 "pig"
                                           "fish"
animals = string[500]
   "cat"
                                           "fish"
```

Linear search is O(n) – directly proportional to input size

3. Skiena 2008.

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Time complexity and Big-Oh notation

Algorithms in computer science are often described by their time omplexity in a hypothetical computer where simple operations take : time step. Big-Oh provides the upper bound of algorithm running time in unction linearSearch(animalToFind, arrayOfAnimals) -> for every animal in arrayOfAnimals if animal -- animalToFind return false nor reor ner ner mer Linear search is O(n) – directly proportional to input size

Time complexity and Big-Oh notation

- Suppose an algorithm written in C is two times faster than the same algorithm written in Java - doesn't tell us much about the algorithm at all
- Ignores specific implementation details such as: programming languages, CPU models, types of storage – the goal is to understand and study algorithms in a language- and machine-independent manner. Details are less important than the worst-case time complexity

Common values for Big-Oh

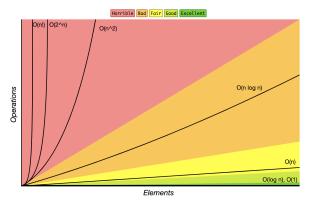


Figure: Big-Oh complexity chart⁴

Analogous concept: space complexity

4. Huyen Pham. What Is Big O Notation? https://dzone.com/articles/what-is-bigo-notation.

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Common values for Big-Oh

2021-02-23 -Common values for Big-Oh

Recursion

Many algorithms are recursive in structure – to solve a problem, they call themselves recursively to deal with closely related subproblems⁵

Typical paradigm is **divide-and-conquer**:

- **Divide** the problem into a number of subproblems
- **2** Conquer the subproblems by solving them recursively if the subproblem is "small enough," just solve it in a straightforward manner
- **Ombine** the solutions to the subproblems into a solution for the original problem

5. Cormen et al. 2001.

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Recursion

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Recursion

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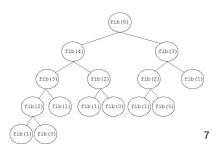
5. Cormen et al. 2001.

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Recursive definition:

- $f_n = f_{n-1} + f_{n-2}$ for n > 2

What happens when we call fib(5)



- 6. Cormen et al. 2001.
- 7. Mark Fienup. Divide-and-Conquer. https://www.cs.uni.edu/~fienup/cs188s05/lectures/lec
6 $\,$ 1-27-05.htm

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Recursion example – Fibonacci sequence



Fibonacci sequence with dynamic programming

Trade off space for time by storing the computed subproblems:

```
int[10000] cache; // global storage array
function init_fib() {
    cache[0] = 0;
    cache[1] = 1;
    for i = 2; i < 10000; i++ {
        cache[i] = -1;
function fib(n int) -> int {
    if cache[n] == -1 {
        cache[n] = fib(n-1) + fib(n-2):
    return cache[n]:
```

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Fibonacci sequence with dynamic programming

```
cache[0] = 0;
cache[1] = 1:
for i = 2; i < 10000; i++ {
   cache[n] = fib(n-1) + fib(n-2)
return cache[n];
```

ibonacci sequence with dynamic programming

- No optimizing here simply caching a recursive function gets you, most of the way to the benefits of dynamic programming
- Labmate Nestor got an improvement of 34% by caching partial results in a Python piece of music code doing something with chord keys and voicings and mus21

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Beat tracking as an optimization problem

Beat tracking as an optimization problem⁸:

$$C(\{t_i\}) = \sum_{i=1}^{N} O(t_i) + \alpha \sum_{i=2}^{N} F(t_i - t_{i-1}, \tau_p)$$

- Compute an onset strength envelope O(t) for the whole signal
- Compute a target tempo by applying autocorrelation (including some human tempo preference) to find periodicity in the onsets
- Optimize the score $C(t_i)$ of a beat at time t_i based on two terms:
 - $O(t_i)$ onset strength should be strong at tentative beat location t_i
 - $P(t_i t_{i-1}, \tau_p)$ or $F(\Delta t, \tau_p)$ there should be consistency between the inter-beat interval Δt and the beat spacing τ_n from target tempo

 α is the weighting term to balance the importance of the 2 terms. This results in an exponential search over all time t_i^9

9. Daniel Ellis. 2013. "Lecture 10: Beat Tracking." ELEN E4896 Music Signal Processing (April). https://www.ee.columbia.edu/~dpwe/e4896/lectures/E4896-L10.pdf.

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-Beat tracking as an optimization problem

Beat tracking as an optimization problem Beat tracking as an optimization problem⁸:

 $C(\{t_i\}) = \sum_{i=1}^{N} O(t_i) + \alpha \sum_{i=2}^{N} F(t_i - t_{i-1}, \tau_p)$

 Compute an onset strength envelope O(t) for the whole signa · Compute a target tempo by applying autocorrelation (including som human tempo preference) to find periodicity in the onsets

Optimize the score C(t:) of a beat at time t: based on two terms: $F(t_i - t_{i-1}, \tau_i)$ or $F(\Delta t, \tau_g)$ – there should be consistency between inter-beat interval Δt and the beat spacing τ_a from target tempo

This results in an exponential search over all time tight 8. Daniel Ellis. 2007. "Beat Tracking by Dynamic Programming." Journal of New Musi Research 36 (March): 51-60. https://doi.org/10.1090/09298210701653344. http:// 9. Daniel Ellis. 2013. "Lecture 10: Beat Tracking." ELEN E4896 Music Signal Proce

- in the paper he says 120bpm is a natural choice for listeners
- Exhaustive search algorithms try all combinations of choices, at a prohibitive cost in time complexity

^{8.} Daniel Ellis. 2007. "Beat Tracking by Dynamic Programming." Journal of New Music Research 36 (March): 51-60. https://doi.org/10.1080/09298210701653344. http:// www.music.mcgill.ca/~ich/classes/mumt621_09/presentations/wingate/27406228. pdf.

Onset strength envelope and tempo estimation

Onsets mark the start of a musical note or acoustic event 10

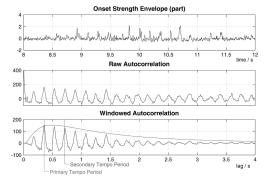


Figure: Top: onset strength envelope. Middle: raw autocorrelation. Bottom: autocorrelation with perceptual weighting window. 11

11. Ellis 2007.

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Onset strength envelope and tempo estimation

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Onset strength envelope and tempo estimation

- Human tempo perception is known to have a bias towards 120
 BPM. We apply a perceptual weighting window to the raw autocorrelation to downweight periodicity peaks far from this bias
- This plot contains all the information you need for a beat tracker!
 but remember the optimization goals

^{10.} Juan Bello et al. 2005. "A Tutorial on Onset Detection in Music Signals." *Speech and Audio Processing, IEEE Transactions on* 13 (October): 1035–1047. https://doi.org/10.1109/TSA.2005.851998. https://citeseerx.ist.psu.edu/viewdoc/download?doi=10.1.332.989&rep=rep1&type=pdf.

Beat tracking with dynamic programming

Recall: beat tracking as an optimization problem¹²:

$$C(\{t_i\}) = \sum_{i=1}^{N} O(t_i) + \alpha \sum_{i=2}^{N} F(t_i - t_{i-1}, \tau_p)$$

Recursive definition from best possible score $C^*(t)$ at time t:

$$C^*(t) = O(t) + \max_{\tau = 0...t} \{ \alpha F(t - \tau, \tau_p) + C^*(\tau) \}$$

Record preceding beat time that gave best score:

$$P^*(t) = \operatorname{argmax}_{\tau=0...t} \{ \alpha F(t-\tau, \tau_p) + C^*(\tau) \}$$

The best score C^* for time t is the local onset strength, plus the best score to the preceding beat time τ that maximizes the sum of that best score and the transition cost from that time

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Beat tracking with dynamic programming

Beat tracking with dynamic programming Recall: beat tracking as an optimization problem¹²:

racking as an optimization problem :
$$C(\lbrace t_{l} \rbrace) = \sum_{i=1}^{N} O(t_{i}) + \alpha \sum_{i=2}^{N} F(t_{i} - t_{i-1}, \tau_{p})$$

cursive definition from best possible score $C^*(t)$ at time t:

 $C^*(t) = O(t) + \max_{\tau=0...t} \{\alpha F(t-\tau, \tau_p) + C^*(\tau)\}$

P*(t) - many - (nF(t = =) | C*(s))

 $r_{-}(t) = \operatorname{argmax}_{\tau=0...t} \{\alpha F(t-\tau, \tau_p) + C^*(\tau)\}$

he best score C* for time t is the local onset strength, plus ti ast score to the preceding beat time \tau that maximizes the su f that best score and the transition cost from that time in 2007.

^{12.} Ellis 2007.

$$F(\Delta t, au) = -\Big(\log rac{\Delta t}{ au}\Big)^2$$

In practice, only need to search a limited range of τ since the penalty term F grows the further you are from τ_p – search in $\tau=t-2\tau_p...t-\frac{\tau_p}{2}$

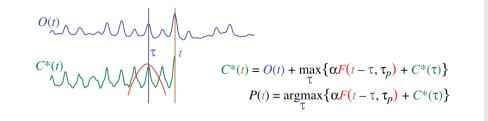


Figure: Beat tracking by dynamic programming¹³

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13. Ellis 2013.

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b spatics, only need to use in Fact.*)

Pennalty term

Figure But tracing.

Figure But tracing.

Penalty term Function F is a squared-error applied to the log-ratio of actual to ideal time specing: $F(\Delta t, \tau) = -\left(\log\frac{\Delta t}{T}\right)^2$ In practice, only read to award. In limit range of τ ideas the penalty term F power the further you set from τ_p - search in $\tau = t - 2\tau_{p-1} - \frac{\tau_p}{2}$ $O(\Delta_{p-1}, \Delta_{p-1}, \Delta_{p-1})$.

Beat tracking with dynamic programming

- To find the set of beat times that optimize the objective function for a given onset envelope, start by calculating C^* and P^* for every time starting from zero
- Look for the largest value of C^* (which will typically be within τ_p of the end of the time range)
- This forms the final beat instant t_N where N, the total number of beats, is still unknown
- Then "backtrace" via P^* , finding the preceding beat time $t_{N-1} = P^*(t_N)$, and progressively working backwards until we reach the beginning of the signal
- Gives the entire optimal beat sequence t_i*

Dynamic Programming for Beat Tracking

Beat tracking with dynamic programming

Beat tracking with dynamic programming

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- Thanks to dynamic programming, we have effectively searched the entire exponentially-sized set of all possible time sequences in a linear-time operation.
- This was possible because, if a best-scoring beat sequence includes a time t_i , the beat instants chosen after t_i will not influence the choice (or score contribution) of beat times prior to t_i , so the entire best-scoring sequence up to time t_i can be calculated and fixed at time t_i without having to consider any future events
- By contrast, a cost function where events subsequent to t_i could influence the cost contribution of earlier events would not be amenable to this optimization.

Algorithm availability and performance

librosa¹⁴'s beat_track algorithm¹⁵ is Ellis' Dynamic Programming

MIREX 2006 Audio Beat Tracking Summary Results

Contestant
dixon
davies
klapuri
ellis
brossier
dixon davies klapuri ellis

download these results as csv

MIREX 2006 Audio Beat Tracking Runtime Data

Contestant	Machine	Run-time(seconds)
brossier	LINUX	139
davies	FAST	1394
dixon	FAST	639
ellis	LINUX	498
klapuri	LINUX	1218

download these results as csv

Figure: Results from MIREX 2006¹⁶

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-Algorithm availability and performance



 Brian McFee et al. 2015. "Broux: Audio and Music Signal Analysis in Pythe 24d. Innaury, https://doi.org/10.1009/his/pica-70.006664-003.
 Brouxs Indicated 503. "Broux Section of the Section of

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^{14.} Brian McFee et al. 2015. "librosa: Audio and Music Signal Analysis in Python," 18–24. January. https://doi.org/10.25080/Majora-7b98e3ed-003.

^{15.} librosa.beat.beat_track - librosa 0.8.0 documentation. https://librosa.org/doc/main/generated/librosa.beat.beat_track.html.

Origins of dynamic programming

Invented by Richard Bellman¹⁷

- I spent the Fall quarter (of 1950) at the RAND Corporation (R&D group employed at the time by the Air Force). My first task was to find a name for multistage decision processes.
- Programming, not like coding, but like scheduling or planning
- Dynamic, multistage, time-varying and dynamic is impossible to use prejoratively
- Chose the name "dynamic programming" to shield it from the Secretary of Defense, Wilson, who was anti math research:

 he actually had a pathological fear and hatred of the word, research. I'm not using the term lightly; I'm using it precisely. His face would suffuse, he would turn red, and he would get violent if people used the term, research, in his presence

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 S.E. Dreyfux. 2002. "Richard Bellman on the Birth of Dynamic Programming." Opreations Research 50 (February): 48–51. https://doi.org/10.1287/opre.50.1.48.17791 http://www.cos.memaster.co/~esGe03/journal_papers/dy_birth.pdf.

^{17.} S.E. Dreyfus. 2002. "Richard Bellman on the Birth of Dynamic Programming." *Operations Research* 50 (February): 48–51. https://doi.org/10.1287/opre.50.1.48.17791. http://www.cas.mcmaster.ca/~se3c03/journal_papers/dy_birth.pdf.

More dynamic programming in MIR

From MIR survey¹⁸:

- Cambouropoulos, E., Crochemore, M., Iliopoulos, C. S., Mohamed, M., and Sagot, M. (2005) A Pattern Extraction Algorithm for Abstract Melodic Representations that Allow Partial Overlapping of Intervallic Categories. In, T. Crawford, M. Sandler, editors, Proceedings of the 6th International Conference on Music Information Retrieval (ISMIR 2005), pp. 167–174
- Adams, N. H., Bartsch, M., Shifrin J., and Wakefield, G. (2004) Time series alignment for music information retrieval. In Proceedings of the International Conference on Music Information Retrieval. 303–310
- Cambouropoulos, E. (2006) Musical Parallelism and Melodic Segmentation: A Computational Approach. Music Perception 23(3):249-269

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^{18.} Ryan Demopoulos and Michael Katchabaw. 2007. "Music Information Retrieval: A Survey of Issues and Approaches" (February). https://www.csd.uwo.ca/~mkatchab/ pubs/tr677.pdf.

^{23(3):249-269} 18. Ryan Demogoulos and Michael Katchabaw. 2007. "Music Information Retrieval: Survey of Issues and Approaches" (February), https://www.csd.uwo.ca/-sukutchah