

1. Objektorientierte Implementierung endlicher Automaten

Lösungsideen:

faOf():

Beim Durchdenken des Algorithmus habe ich festgestellt, dass Epsilon-Alternativen in der reguläre Grammatik die Umsetzung erschweren könnten. Deshalb wird zunächst die reguläre Grammatik mit der Methode **newEpsilonFreeGrammarOf** aus dem ersten Übungszettel Epsilon-frei gemacht. Man kann dann die reguläre Grammatik relativ einfach in einen endlichen Automaten umwandeln, indem man jede Alternative einer Regel (z.B. **S** -> **a B**) in einen Zustandsübergang vom NTSymbol der Regel (**S**) auf den Zustand (NTSymbol an zweiter Stelle in der Alternative **B**) mit dem Band-Symbol (TSymbol an erster Stelle in der Alternative **a**) umwandelt. Alle Alternativen, die nur aus einem TSymbol bestehen, bekommen einen Zustandsübergang auf einen allgemeinen End-Zustand (**END**). Da die reguläre Grammatik Epsilon-frei ist, gibt es höchstens ein Epsilon, welches sich im Satz-Symbol befinden könnte. In diesem Fall wird der Zustand für das Satz-Symbol auch als End-Zustand markiert.

grammarOf():

Es kann ein beliebiger **FA** übergeben werden. Damit ich DFA und NFA bei der Implementierung des Algorithmus gleich behandeln kann, habe ich die Sichtbarkeit der Methode **virtual StateSet FA::deltaAt(const State &src, TapeSymbol tSy) const = 0;** auf public geändert und immer mit **StateSets** gearbeitet.

Es werden alle Kombinationen von Zuständen und Band-Symbolen auf die Zustandsüberföhrungsfunktion angewandt (verschachtelte Schleife). Um nicht zwischen DFA und NFA unterscheiden zu müssen, wurde die Sichtbarkeit von der Methode **deltaOf()** der Klasse **FA** von **protected** auf **public** geändert und immer mit **StateSets** gearbeitet. Bei jeder Anwendung der Zustandsüberföhrungsfunktion ist der **State** (Variable in der Schleife) die Regel der Grammatik. Das Band-Symbol (Variable in der Schleife => TSymbol) und die von **deltaOf()** gelieferten Zustände (NTSymbol) bilden Sequenzen dieser Regel. Falls die **deltaOf()** von gelieferten Zustände keine ausgehenden Zustandsüberföhrungen mehr haben, dann werden diese in der Grammatik einfach ignoriert und das Band-Symbol hat in der Alternative kein nachfolgendes NTSymbol. Falls der Start-Zustand bereits ein End-Zustand ist, bekommt die Regel dieses Zustandes eine Epsilon-Alternative.

Code:

```
FA *faOf(const Grammar *g)
{
    bool deleteG = false;
    FABuilder fab{};
    const Grammar* gToUse = g;
    // ensure g is epsilon-free
    if (!g->isEpsilonFree()) {
        deleteG = true;
        gToUse = newEpsilonFreeGrammarOf(g);
    }
}
```

```

// set final states
if (deleteG) { // means that g has S' => is end state
    fab.addFinalState(g->root->name);
} else {
    // if rule of root already contained epsilon,
    // mark it as end state
    for (auto rootAlternatives : g->rules[g->root]) {
        if (rootAlternatives->size() == 0)
            fab.addFinalState(g->root->name);
    }
}

fab.setStartState(g->root->name);
// generic end state "END" for alternatives without NT
fab.addFinalState("END");

for (auto [ntSy, alternatives] : g->rules) {
    for (auto alternative : alternatives) {

        if (alternative->size() > 0) { // ignore eps alternatives
            char ts = alternative->at(0)->name[0];
            if (alternative->size() == 1) {
                // no ntSy in alternative =>
                // ntSy has edge to artificial end state with ts
                fab.addTransition(ntSy->name, ts, "END");
            } else if (alternative->size() == 2) {
                // ntSy has edge to nextState with ts
                string nextState = alternative->at(1)->name;
                fab.addTransition(ntSy->name, ts, nextState);
            }
        }
    }
}

// delete generated epsilon-free grammar
if (deleteG) delete g;

return fab.buildNFA();
}

Grammar* grammarOf(const FA* fa) {

    SymbolPool sp{};
    GrammarBuilder gb{sp.ntSymbol(fa->s1)};

    // iterate over each state
    for (const State& state : fa->S) {
        // iterate over each tape symbol
        for (const TapeSymbol& ts : fa->V) {
            // get all possible transition destinations from state using tape symbol
            auto destinations = fa->deltaAt(state, ts);
            for (const State& dest : destinations) {
                // add this transition to grammar as alternative
            }
        }
    }
}

```

```

    // takes care of states like S' or END
    // if dest does not have any outgoing tape symbols
    // => ignore dest in grammar
    bool hasOutgoing = false;
    for (const TapeSymbol& ts1 : fa->V) {
        if (fa->deltaAt(dest, ts1).size() > 0) {
            hasOutgoing = true;
        }
    }

    if (hasOutgoing) {
        gb.addRule(sp.ntSymbol(state),
            new Sequence({
                sp.tSymbol(string{ts}),
                sp.ntSymbol(dest)}
            ));
    } else {
        gb.addRule(sp.ntSymbol(state),
            new Sequence({sp.tSymbol(string{ts})})
        );
    }

    // if dest is an end state, also add alternative without dest
    if (fa->F.contains(dest)) {
        gb.addRule(sp.ntSymbol(state),
            new Sequence(sp.tSymbol(string{ts}))
        );
    }
}

// if start state is also end state, add epsilon as alternative
if (fa->F.contains(fa->s1)) {
    gb.addRule(sp.ntSymbol(fa->s1), new Sequence());
}

return gb.buildGrammar();
}

```

Tests:

```

cout << "1.a) faOf" << endl;
cout << "-----" << endl;
cout << endl;

GrammarBuilder gb{string("G.txt")};

Grammar* g = gb.buildGrammar();

```

```

FA* faOfG = faOf(g);
vizualizeFA("faOfG", faOfG);

cout << "1.b) grammarOf" << endl;
cout << "-----" << endl;
cout << endl;

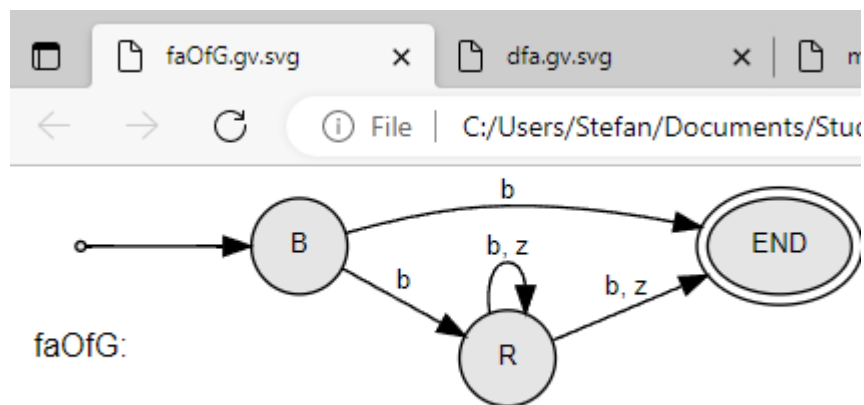
Grammar* gOfFaOfG = grammarOf(faOfG);
std::cout << *gOfFaOfG;

delete g;
delete faOfG;
delete gOfFaOfG;

```

Testfall 1

G(B):
 B → b | b R
 R → b | z | b R | z R



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START: Main

1. DFA

1.a) faOf

writing faOfG to faOfG.gv ...

rendering faOfG.gv to faOfG.gv.svg ...

displaying faOfG.gv.svg ...

1.b) grammarOf

G(B):

B -> b | b R

R -> b | b R | z | z R

VNt = { B, R }, deletable: { }

VT = { b, z }

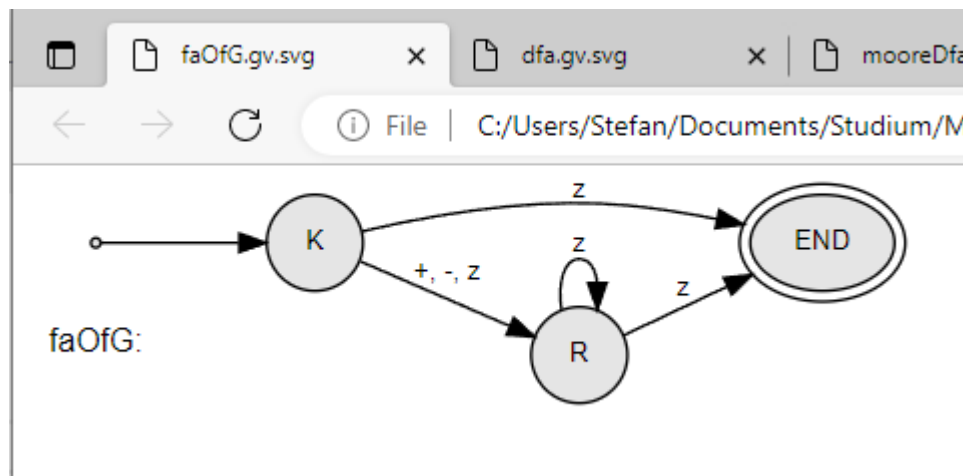
gOfFaOfG und Eingabe-Grammatik sind wieder gleich.

Testfall 2

G(K):

K -> z | z R | + R | - R

R -> z | z R



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1.a) faOf

```

writing    faOfG to faOfG.gv ...
rendering  faOfG.gv to faOfG.gv.svg ...
displaying faOfG.gv.svg ...

```

1.b) grammarOf

```

G(K):
K -> + R | - R | z | z R
R -> z | z R
---
VNt = { K, R }, deletable: {  }
VT  = { +, -, z }

```

2.a) DFA

gOfFaOfG und Eingabe-Grammatik sind wieder gleich.

Testfall 3 - Grammatik mit Epsilon (vom Übungszettel 2 geklaut)

Anmerkung: Die Grammatik ist bereits Epsilon-Frei. Bei dem Test geht es nur darum, zu sehen, ob der Zustand für das Satz-Symbol (Start-Zustand) auch als End-Zustand markiert wird.

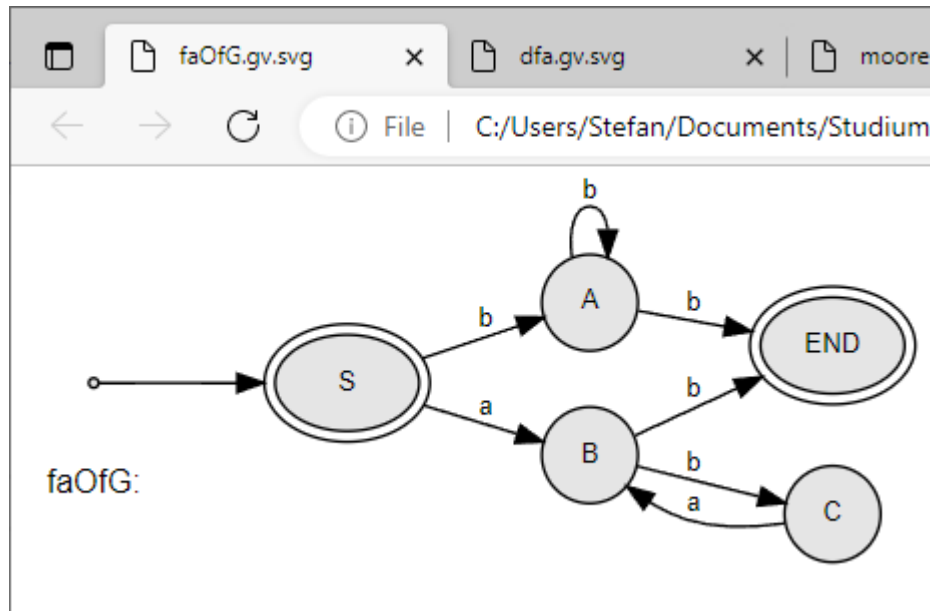
$G(S)$:

$S \rightarrow b A \mid a B \mid \epsilon$

$A \rightarrow b A \mid b$

$B \rightarrow b C \mid b$

$C \rightarrow a B$



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1. DFA

1.a) faOf

```
writing    faOfG to faOfG.gv ...
rendering  faOfG.gv to faOfG.gv.svg ...
displaying faOfG.gv.svg ...
```

1.b) grammarOf

G(S):

S -> eps | a B | b A

B -> b | b C

A -> b | b A

C -> a B

VNT = { A, B, C, S }, deletable: { S }

VT = { a, b }

2.a) DFA

gOfFaOfG und Eingabe-Grammatik sind wieder gleich, Start-Zustand auch als End-Zustand markiert.

2. DFA, Erkennung und Mealy- oder Moore-Automat

a)

Code:

```
cout << "2.a) DFA" << endl;
cout << "-----" << endl;
cout << endl;
```



```

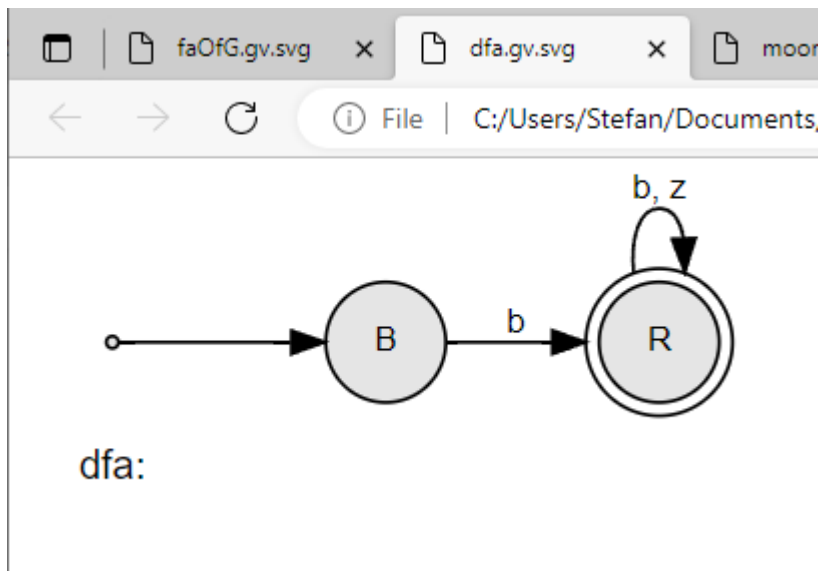
fab = new FABuilder();
fab->setStartState("B").
    addFinalState("R").
    addTransition("B", 'b', "R").
    addTransition("R", 'b', "R").
    addTransition("R", 'z', "R");

dfa = fab->buildDFA();
vizualizeFA("dfa", dfa);

cout << "dfa->accepts(\"bzb\") = " << boolalpha << dfa->accepts("bzb") << endl;
cout << "dfa->accepts(\"bbbbzbzz\") = " << boolalpha << dfa->accepts("bbbbzbzz")
<< endl;
cout << "dfa->accepts(\"zbb\") = " << boolalpha << dfa->accepts("z") << endl;
cout << endl;

delete fab;

```



```

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VT  = { b, z }

2.a) DFA
-----

writing    dfa to dfa.gv ...
rendering  dfa.gv to dfa.gv.svg ...
displaying dfa.gv.svg ...

dfa->accepts("bzb")      = true
dfa->accepts("bbbbzbzz") = true
dfa->accepts("zbb")      = false

3.b) MooreDFA

```

Tests:

b)

Eigentlich benötigt der MooreDFA nur eine Map, in der definiert ist, bei welchem State durch welches Symbol ausgegeben wird. Diese Map muss dann beim Erkennen des Band-Inhaltes verwendet werden (hier geben wir den Wert für den State einfach auf der Konsole aus).

Code:

```

// MooreDFA.h:                                                    SWE, 2022
// -----
// Objects of class MooreDFA represent deterministic finite automata.
//=====

#ifndef MooreDFA_h
#define MooreDFA_h

#include "ObjectCounter.h"
#include "TapeStuff.h"
#include "StateStuff.h"
#include "DFA.h"

class FABuilder;

class MooreDFA: public DFA
/*OC+*/ , private ObjectCounter<MooreDFA> /*+OC*/ {

    friend class FABuilder;

```

```

private:
    typedef DFA Base;

protected: // allows derived classes, e.g., for Mealy and or Moore
    // constructor called by FABuilder::build... methods and derived classes
    MooreDFA(const StateSet &S, const TapeSymbolSet &V,
              const State &s1, const StateSet &F,
              const DDelta &delta,
              const std::map<State, char> &mooreLambda);

public:
    const std::map<State, char> mooreLambda;
    MooreDFA(const MooreDFA &mooredfa) = default;
    MooreDFA(MooreDFA &&mooredfa) = default;

    virtual ~MooreDFA() = default;
    virtual bool accepts(const Tape &tape) const;

}; // DFA

#endif

// end of MooreDFA.h
//=====

// MooreDFA.cpp: SWE, 2022
// -----
// Objects of class MooreDFA represent deterministic finite automata.
//=====

#include <cmath>
#include <cstring>

#include <iostream>
#include <fstream>
#include <map>
#include <sstream>

using namespace std;

#include "TapeStuff.h"
#include "StateStuff.h"
#include "MbMatrix.h"
#include "FABuilder.h"
#include "MooreDFA.h"

// --- implementation of class MooreDFA ---

MooreDFA::MooreDFA(const StateSet &S, const TapeSymbolSet &V,
                  const State &s1, const StateSet &F,
                  const DDelta &delta,
                  const std::map<State, char> &mooreLambda)
: DFA(S, V, s1, F, delta), mooreLambda(mooreLambda) {
} // MooreDFA::MooreDFA

```

```

bool MooreDFA::accepts(const Tape &tape) const {
    int i = 0; // index of first symbol
    TapeSymbol tSy = tape[i]; // fetch first tape symbol
    State s = s1; // start state
    cout << mooreLambda.at(s);
    while (tSy != eot) { // eot = end of tape
        s = delta[s][tSy];
        if (!defined(s))
            return false; // s undefined, so no acceptance
        cout << mooreLambda.at(s);
        i++;
        tSy = tape[i]; // fetch next symbol
    } // while
    cout << " ";
    return F.contains(s); // accepted <==> s element of F
} // MooreDFA::accepts

// end of MooreDFA.cpp
//=====

```

Tests:

```

cout << "2.b) MooreDFA" << endl;
cout << "-----" << endl;
cout << endl;

fab = new FABuilder();
fab->setStartState("S").
    addFinalState("B").
    addFinalState("Z").
    addTransition("S", 'b', "B").
    addTransition("B", 'b', "B").
    addTransition("B", 'z', "Z").
    addTransition("Z", 'z', "Z").
    addTransition("Z", 'b', "B").
    setSetMooreLambda({
        {"S", ' '},
        {"B", 'c'},
        {"Z", 'd'}
    });

MooreDFA* mooreDfa = fab->buildMooreDFA();

cout << "mooreDfa->accepts(\"bzb\") = " << boolalpha << mooreDfa->accepts("bzb")
<< endl;
cout << "mooreDfa->accepts(\"bbbbzbzz\") = " << boolalpha << mooreDfa-
>accepts("bbbbzbzz") << endl;
cout << "mooreDfa->accepts(\"zbb\") = " << boolalpha << mooreDfa->accepts("z")
<< endl;
cout << endl;

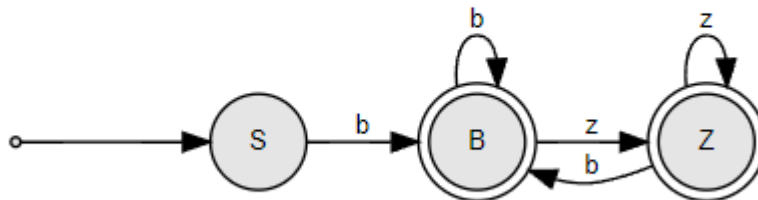
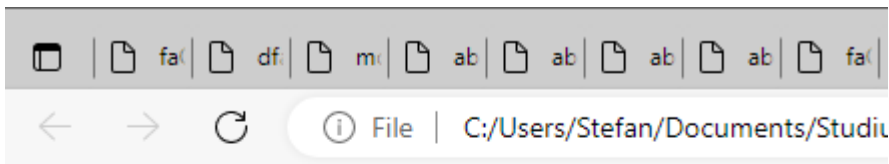
```

```

vizualizeFA("mooreDfa", mooreDfa);

delete mooreDfa;
delete fab;

```



mooreDfa:

```

addFinalState( Z );

```

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2.b) MooreDFA

```

mooreDfa->accepts("bzb")      =  cdc true
mooreDfa->accepts("bbbbzbzz") =  ccccdcd true
mooreDfa->accepts("zbb")      =  false

writing    mooreDfa to mooreDfa.gv ...
rendering  mooreDfa.gv to mooreDfa.gv.svg ...
displaying mooreDfa.gv.svg ...

```

3. NFA, Transformation NFA -> DFA und Zustandsminimierung

a)

Code:

```

cout << "3.a)" << endl;
cout << "-----" << endl;

```

```

cout << endl;

fab = new FABuilder();
fab->setStartState("S").
    addFinalState("R").
    addTransition("S", 'a', "S").
    addTransition("S", 'b', "S").
    addTransition("S", 'c', "S").
    addTransition("S", 'a', "A").
    addTransition("S", 'b', "B").
    addTransition("S", 'c', "C").
    addTransition("A", 'a', "A").
    addTransition("A", 'b', "A").
    addTransition("A", 'c', "A").
    addTransition("B", 'a', "B").
    addTransition("B", 'b', "B").
    addTransition("B", 'c', "B").
    addTransition("C", 'a', "C").
    addTransition("C", 'b', "C").
    addTransition("C", 'c', "C").
    addTransition("A", 'a', "R").
    addTransition("B", 'b', "R").
    addTransition("C", 'c', "R");

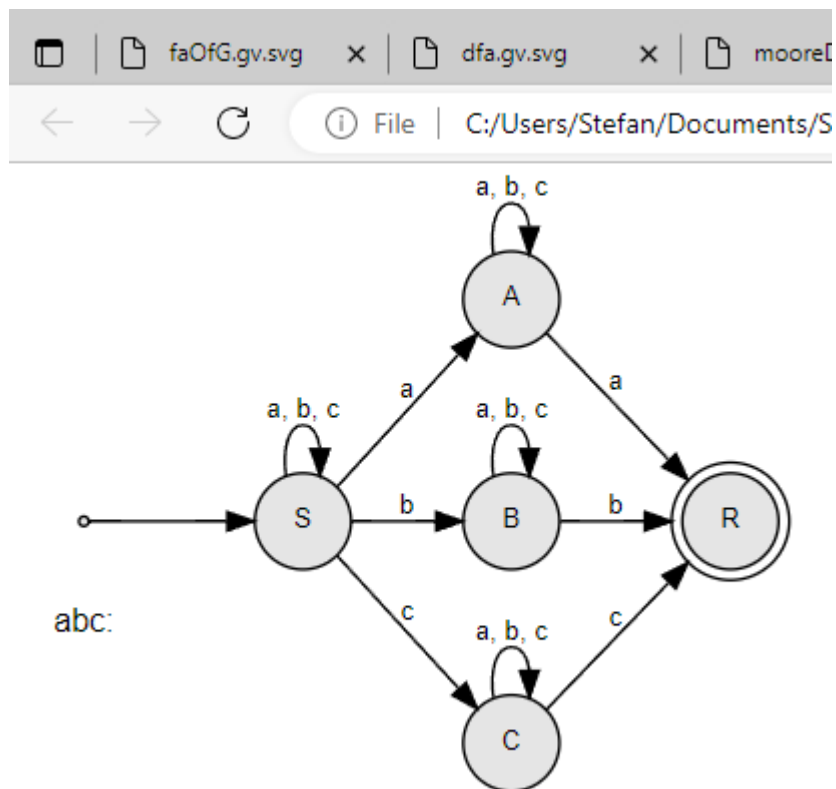
NFA* abc = fab->buildNFA();
cout << "abc->accepts1(\"cabcabcabcc\") = " << abc-
>accepts1("cabcabcabcc") << endl;
cout << "abc->accepts2(\"cabcabcabcc\") = " << abc-
>accepts2("cabcabcabcc") << endl;
cout << "abc->accepts3(\"cabcabcabcc\") = " << abc-
>accepts3("cabcabcabcc") << endl;

cout << "abc->accepts1(\"caaaaaaaaaaaaaad\") = " << abc-
>accepts1("caaaaaaaaaaaaaad") << endl;
cout << "abc->accepts2(\"caaaaaaaaaaaaaad\") = " << abc-
>accepts2("caaaaaaaaaaaaaad") << endl;
cout << "abc->accepts3(\"caaaaaaaaaaaaaad\") = " << abc-
>accepts3("caaaaaaaaaaaaaad") << endl;

delete abc;
delete fab;

```

Tests:



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3.a)

M

```

abc->accepts1("cabcabcabcc") = true
abc->accepts2("cabcabcabcc") = true
abc->accepts3("cabcabcabcc") = true
abc->accepts1("caaaaaaaaaaaaaaad") = false
abc->accepts2("caaaaaaaaaaaaaaad") = false
abc->accepts3("caaaaaaaaaaaaaaad") = false

```

3.b)

b)

Code:

```

void TimeAccept(NFA* abc, void (*func)(NFA* abc)) {
    stopwatch::Stopwatch sw{}; // not going to post this entire class here
    sw.start();
    func(abc);
    cout << "Elapsed time: " << sw.elapsed<TimeFormat::MICROSECONDS>() << " micro

```

```

sec" << endl;
}

// ... same as 3a)

TimeAccept(abc, [])(NFA* abc) {
    cout << "abc->accepts1(\"cabcabcabcc\") = " << abc-
>accepts1("cabcabcabcc") << endl;
});
TimeAccept(abc, [])(NFA* abc) {
    cout << "abc->accepts2(\"cabcabcabcc\") = " << abc-
>accepts2("cabcabcabcc") << endl;
});
TimeAccept(abc, [])(NFA* abc) {
    cout << "abc->accepts3(\"cabcabcabcc\") = " << abc-
>accepts3("cabcabcabcc") << endl;
});

TimeAccept(abc, [])(NFA* abc) {
    cout << "abc->accepts1(\"caaaaaaaaaaaaaad\") = " << abc-
>accepts1("caaaaaaaaaaaaaad") << endl;
});
TimeAccept(abc, [])(NFA* abc) {
    cout << "abc->accepts2(\"caaaaaaaaaaaaaad\") = " << abc-
>accepts2("caaaaaaaaaaaaaad") << endl;
});
TimeAccept(abc, [])(NFA* abc) {
    cout << "abc->accepts3(\"caaaaaaaaaaaaaad\") = " << abc-
>accepts3("caaaaaaaaaaaaaad") << endl;
});

// ... same as 3a)

```


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```
abc->accepts2("caaaaaaaaaaaaaaad") = false
abc->accepts3("caaaaaaaaaaaaaaad") = false
3.b)
-----
```

```
abc->accepts1("cabcabcabcabcc") = true
Elapsed time: 7849 micro sec
abc->accepts2("cabcabcabcabcc") = true
Elapsed time: 383 micro sec
abc->accepts3("cabcabcabcabcc") = true
Elapsed time: 482 micro sec
abc->accepts1("caaaaaaaaaaaaaaad") = false
Elapsed time: 9202 micro sec
abc->accepts2("caaaaaaaaaaaaaaad") = false
Elapsed time: 396 micro sec
abc->accepts3("caaaaaaaaaaaaaaad") = false
Elapsed time: 467 micro sec
3.c)
-----
```

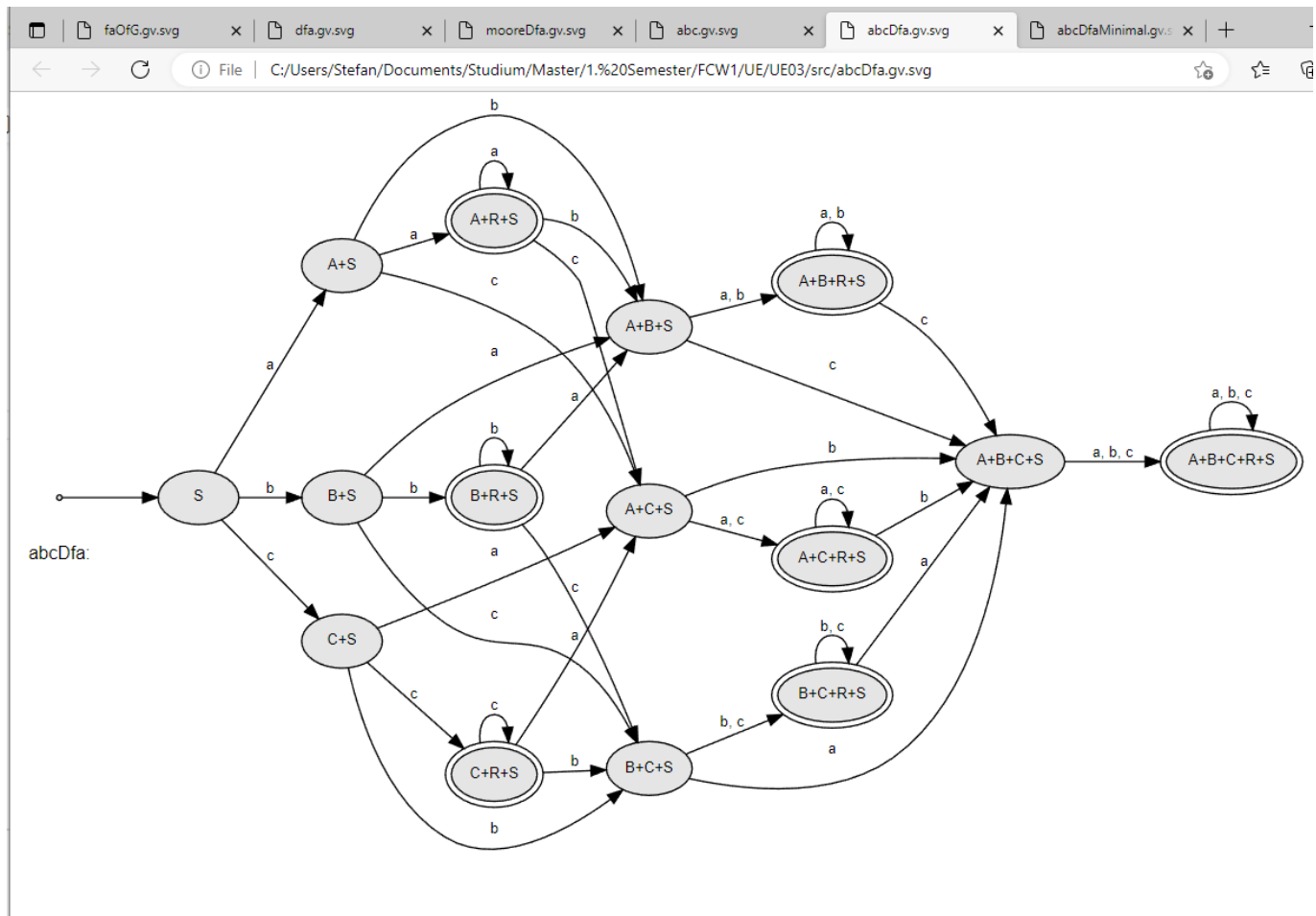
c)

Code:

```
// ... same as 3a)

DFA* abcDfa = abc->dfaOf();
vizualizeFA("abcDfa", abcDfa);
delete abcDfa;

// ... same as 3a)
```



d)

Code:

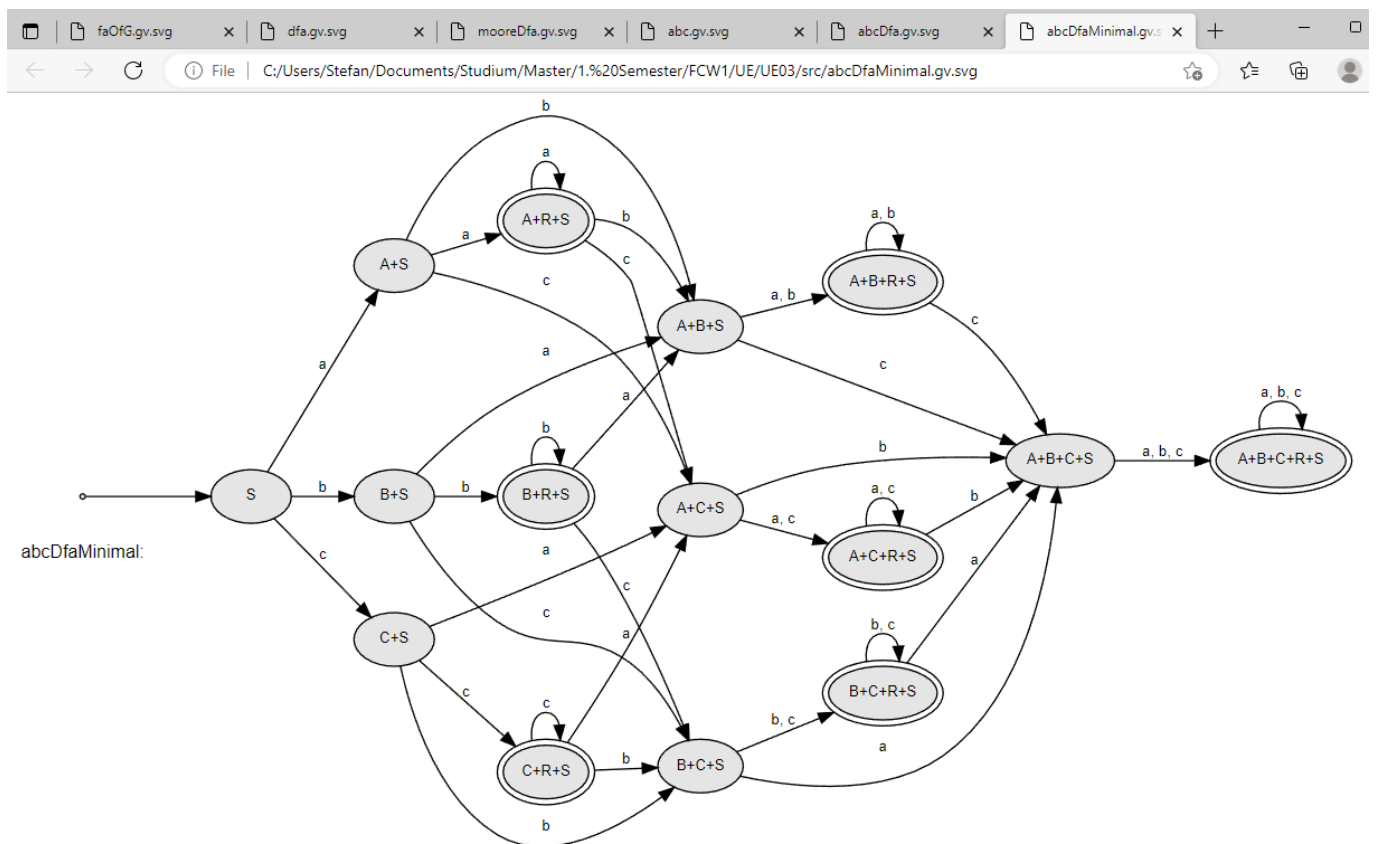
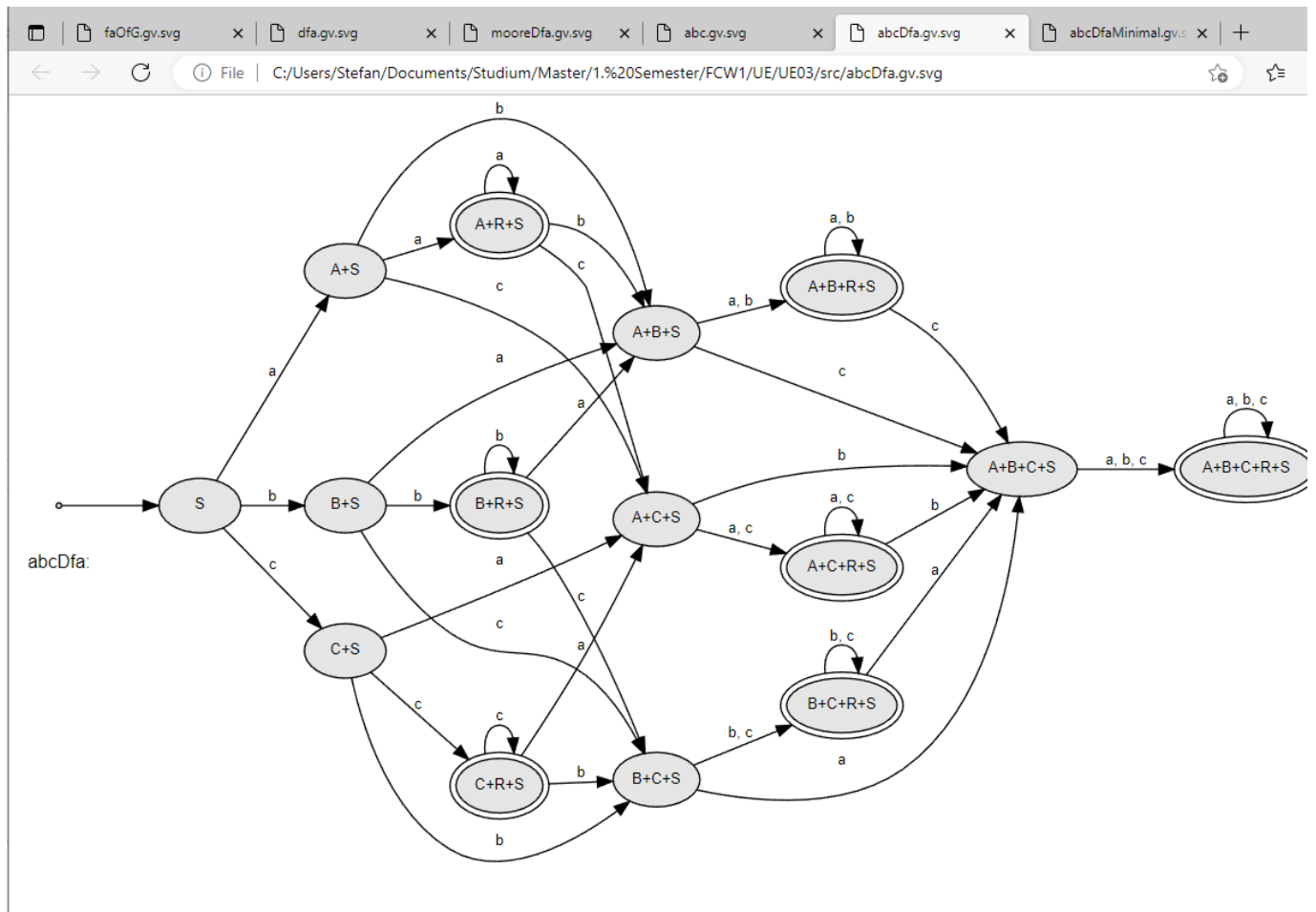
```
// ... same as 3a)

abcDfa = abc->dfaOf();
DFA* abcDfaMinimal = abcDfa->minimalOf();

vizualizeFA("abcDfa", abcDfa);
vizualizeFA("abcDfaMinimal", abcDfaMinimal);

delete abcDfaMinimal;
delete abcDfa;

// ... same as 3a)
```



abcDfa war bereits minimal, da sich **abcDfa** nach der Minimierung nicht verändert hat.

4. Kellerautomat und erweiterter Kellerautomat

a)

```

Declaration    -> VAR | VAR VarDeclList .
VarDeclList    -> VarDecl ";" | VarDecl ";" VarDeclList .
VarDecl        -> IdentList ":" Type .
IdentList       -> ident | ident "," IdentList .
Type           -> ARRAY "(" number ")" OF TypeIdent | TypeIdent .
TypeIdent      -> INTEGER | BOOLEAN | CHAR .

```

b)

```

DKA = (Z, VT , V, d, z1 , S, F)
VT = {VAR, ident, number, ";", ":", ",", ")", "(", OF, ARRAY, INTEGER, BOOLEAN,
CHAR}
V = {Declaration, VarDeclList, VarDecl, IdentList, Type, TypeIdent}
Z = {z1}
S = Declaration
F = {z1}

```

```

S1:
d(Z, e, Declaration)    = (Z, VAR)
d(Z, e, Declaration)    = (Z, VarDeclList VAR)
d(Z, e, VarDeclList)    = (Z, ";" VarDecl)
d(Z, e, VarDeclList)    = (Z, VarDeclList ";" VarDecl)
d(Z, e, VarDecl)        = (Z, Type ":" IdentList)
d(Z, e, IdentList)      = (Z, ident)
d(Z, e, IdentList)      = (Z, IdentList "," ident)
d(Z, e, Type)           = (Z, TypeIdent OF ")" number "(" ARRAY)
d(Z, e, Type)           = (Z, TypeIdent)
d(Z, e, TypeIdent)      = (Z, INTEGER)
d(Z, e, TypeIdent)      = (Z, BOOLEAN)
d(Z, e, TypeIdent)      = (Z, CHAR)

```

```

S2:
d(Z, VAR, VAR)          = (Z, e)
d(Z, ";", ";")          = (Z, e)
d(Z, ident, ident)      = (Z, e)
d(Z, ":", ":")          = (Z, e)
d(Z, ",", ",")          = (Z, e)
d(Z, ARRAY, ARRAY)      = (Z, e)
d(Z, number, number)    = (Z, e)
d(Z, OF, OF)            = (Z, e)
d(Z, ")", ")")          = (Z, e)
d(Z, "(", "(")          = (Z, e)

```

```
d(Z, INTEGER, INTEGER) = (Z, e)
d(Z, BOOLEAN, BOOLEAN) = (Z, e)
d(Z, CHAR, CHAR)       = (Z, e)
```

c)

```
DKA = (Z, VT , V, d, z1 , S, F)
VT = {VAR, ident, number, ";", ":", ",", ")", "(", OF, ARRAY, INTEGER, BOOLEAN,
CHAR}
V = {Declaration, VarDeclList, VarDecl, IdentList, Type, TypeIdent, $(nur am
Start)}
Z = {z1}
S = Declaration
F = {z1}
```

```
S1:
d(Z, e, VAR) = (Z, Declaration)
d(Z, e, VAR VarDeclList) = (Z, Declaration)
d(Z, e, VarDecl ";") = (Z, VarDeclList)
d(Z, e, VarDecl ";" VarDeclList) = (Z, VarDeclList)
d(Z, e, IdentList ":" Type) = (Z, VarDecl)
d(Z, e, ident) = (Z, IdentList)
d(Z, e, ident "," IdentList) = (Z, IdentList)
d(Z, e, ARRAY "(" number ")" OF TypeIdent) = (Z, Type)
d(Z, e, TypeIdent) = (Z, Type)
d(Z, e, INTEGER) = (Z, TypeIdent)
d(Z, e, BOOLEAN) = (Z, TypeIdent)
d(Z, e, CHAR) = (Z, TypeIdent)
```

```
S2:
d(Z, VAR, $) = (Z, $ VAR)
d(Z, ";", $) = (Z, $ ";")
d(Z, ident, $) = (Z, $ ident)
d(Z, ":", $) = (Z, $ ":")
d(Z, ",", $) = (Z, $ ",")
d(Z, ARRAY, $) = (Z, $ ARRAY)
d(Z, number, $) = (Z, $ number)
d(Z, OF, $) = (Z, $ OF)
d(Z, ")", $) = (Z, $ ")")
d(Z, "(", $) = (Z, $ "(")
d(Z, INTEGER, $) = (Z, $ INTEGER)
d(Z, BOOLEAN, $) = (Z, $ BOOLEAN)
d(Z, CHAR, $) = (Z, $ CHAR)
d(Z, VAR, Declaration) = (Z, Declaration VAR)
d(Z, ";", Declaration) = (Z, Declaration ";")
+ 76 more
```

(|VT| * |V| == 13 * 7 == 91 mögliche Kombinationen, um Papier zu sparen,
enumeriere ich die jetzt nicht)

```
S3:
S(Z, e, $Declaration) = (R, e)
```

d)

für b) (nur erfolgreiche Züge)

```
(Z, Declaration .VAR a, b: INTEGER;) |--
(Z, VarDeclList VAR .VAR a, b: INTEGER;) |--
(Z, VarDeclList .a, b: INTEGER;) |--
(Z, ; VarDecl .a, b: INTEGER;) |--
(Z, ; Type : IdentList .a, b: INTEGER;) |--
(Z, ; Type : IdentList , ident .a, b: INTEGER;) |--
(Z, ; Type : IdentList , ., b: INTEGER;) |--
(Z, ; Type : IdentList .b: INTEGER;) |--
(Z, ; Type : ident .b: INTEGER;) |--
(Z, ; Type : .: INTEGER;) |--
(Z, ; Type .INTEGER;) |--
(Z, ; TypeIdent .INTEGER;) |--
(Z, ; .;) |--
(Z, .) erkannt! (Keller leer)
```

für c) (nur erfolgreiche Züge)

```
(Z, $ .VAR a, b: INTEGER;) |--
(Z, $VAR .a, b: INTEGER;) |--
(Z, $VAR a ., b: INTEGER;) |--
(Z, $VAR ident ., b: INTEGER;) |--
(Z, $VAR ident, . b: INTEGER;) |--
(Z, $VAR ident, b .: INTEGER;) |--
(Z, $VAR ident, ident .: INTEGER;) |--
(Z, $VAR ident, IdentList .: INTEGER;) |--
(Z, $VAR IdentList .: INTEGER;) |--
(Z, $VAR IdentList : .INTEGER;) |--
(Z, $VAR IdentList : INTEGER .;) |--
(Z, $VAR IdentList : Type .;) |--
(Z, $VAR VarDecl .;) |--
(Z, $VAR VarDecl ; .) |--
(Z, $VAR VarDeclList .) |--
(Z, $Declaration .) |--
(R, .) erkannt!
```

5. Term. Anfänge/Nachfolger, LL(k)-Bedingung u. Transformation