Deep Learning for Audio

Lecture 3

Pavel Severilov

Al Masters

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Outline

1. RNN-Transducer (RNN-T)

- 2. Language models for ASR
- 3. Byte-pair encoding (BPE)
- 4. State-of-the-art ASR

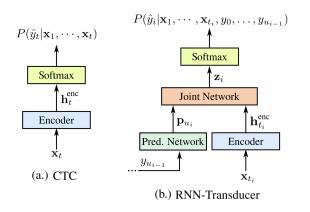
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CTC and Attention models: recap

	стс	Listen, Attend and Spell: LAS	?
Summary	Maximize probability of all possible CTC-paths leading to target.	Encoder-decoder architecture with attention.	???
Online	+	-	+
Context dependent	-	+	+
Multiple outputs for each input	-	-	+

RNN-T: idea



- Predictor is autoregressive: takes as input the previous outputs.
- ▶ Joiner feedforward network, combines the encoder vector h_t and predictor vector p_u

He et al. Streaming End-to-end Speech Recognition for Mobile Devices / 2019, Google, Inc.

RNN-T: model

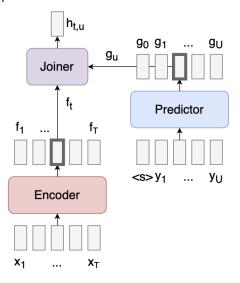


Figure: RNN-T architecture

RNN-T: model

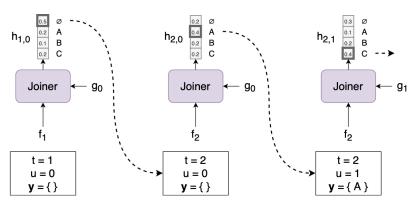


Figure: Steps example of RNN-T inference: t – audio-encoder timestamp, u – Predictor (char network) step

RNN-T: training

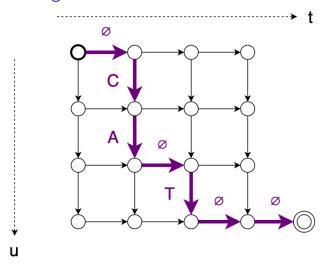


Figure: Alignment $\{\emptyset, C, A, \emptyset, T, \emptyset, \emptyset\}$ for input sequence of length T=4 and an output sequence "CAT" of length U=3

RNN-T: training

We need to get p(y|x) as the sum of the probabilities of all possible alignments between x and y

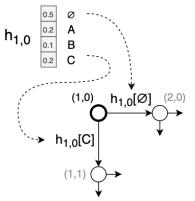


Figure:

$$z = \emptyset, C, A, \emptyset, T, \emptyset, \emptyset$$

$$p(\mathbf{z} \mid \mathbf{x}) = h_{1,0}[\varnothing] \cdot h_{2,0}[C] \cdot h_{2,1}[A] \cdot h_{2,2}[\varnothing] \cdot h_{3,2}[T] \cdot h_{3,3}[\varnothing] \cdot h_{4,3}[\varnothing]$$

RNN-T: training

Objective: minimize the loss function -log p(y|x)

To compute the sum efficiently, compute $\alpha_{t,u}$, for $1 \le t \le T$ and $0 \le u \le U$

$$\alpha_{t,u} = \alpha_{t-1,u} \cdot h_{t-1,u}[\varnothing] + \alpha_{t,u-1} \cdot h_{t,u-1}[y_{u-1}]$$

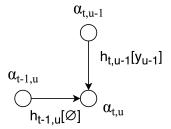


Figure: Computing $\alpha_{t,u}$ to get $p(\mathbf{y} \mid \mathbf{x}) = \alpha_{T,U} \cdot h_{T,U}[\varnothing]$

Losses in ASR: summary

- CTC Loss
 - Pros: output can be computed parallel, very fast, goes well with LMs
 - Cons: no context dependences; often LMs are big and slow (can't do on devices)
- CrossEntropyLoss (Autoregressive Encoder-Decoder, LAS)
 - Pros: High Quality because of autoregression, often has attention (good for seq-to-seq tasks)
 - Cons: hard inference, hard to do in production (slow), not online
- RNN-T Loss (Transducer)
 - Pros: can be online, better quality because of autoregression, often used in devices
 - Cons: hard inference, hard to build in attention, need a lot of GPUs to train, output are computed not in parallel

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Language models (LM): why need in ASR?

- Language models recap: a model that estimates the probability of a text.
 - N-gramms
 - ► Neural networks (BERT, GPT-3, ...)
 - Example:P(let's go two a movie) = 0.01P(let's go to a movie) = 0.6
- ► ASR problem:
 - Spelling of a word heavily depends on its context
 - Labeled audio data is difficult to obtain
- ► How LM helps:
 - ► Improves final WER
 - Improves performance for small audio datasets
 - Can be used to adapt model to new domain

LM: how to integrate in ASR?

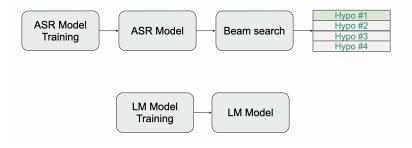


Figure: ASR pipeline VS Language models pipeline

HSE DLA course 14/33

LM: final hypothesis rescoring

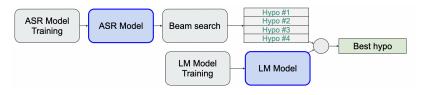


Figure: Final hypothesis rescoring: rescore beam-search output with LM probs

$$\boldsymbol{y}^* = \arg\max_{\boldsymbol{y}} \log p(\boldsymbol{y} \mid \boldsymbol{x}) + \lambda \log p_{LM}(\boldsymbol{y}) + \beta \cdot \operatorname{len}(\boldsymbol{y})$$

len(y) – function of word length, anti-penalty for long words

LM: shallow fusion

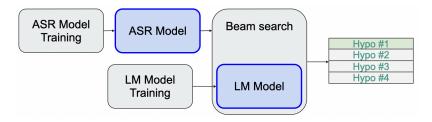


Figure: Shallow fusion: use LM rescoring after each beam search step

Practice:

- requires much more LM runs
- use light LM for shallow fusion
- use heavy LM for second-pass rescoring

LM: Deep fusion

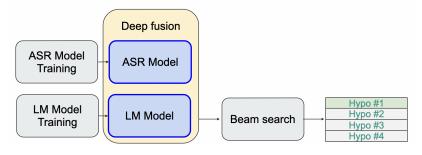


Figure: Deep fusion: integrates the external LM into the encoder-decoder model (ASR) by fusing together the hidden states of the external LM and the decoder

Toshniwal, Shubham et al. "A Comparison of Techniques for Language Model Integration in Encoder-Decoder Speech Recognition." 2018 IEEE

LM: Cold fusion

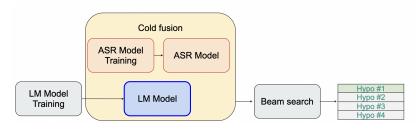


Figure: Cold fusion: train like in Deep fusion, but jointly with ASR model

Toshniwal, Shubham et al. "A Comparison of Techniques for Language Model Integration in Encoder-Decoder Speech Recognition." 2018 IEEE

LM in ASR: comparison of approaches

Model	SWB	CH	Full
LAS	17.1	27.9	22.6
Shallow Fusion	15.6	26.6	21.1
Deep Fusion	16.3	27.2	21.7
Cold Fusion	16.3	27.3	21.8

Table: Word error rates (%) on Eval2000 for the LAS baseline model and fusion approaches. SWB=Switchboard, CH=CallHome, Full=Eval2000.

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BPE: motivation & idea

- Motivation: a lot of characters have different pronunciation in different contexts
- ▶ Idea: let's use n-gramms as tokens in addition
- Advantages:
 - ▶ Less decoder steps → faster training and inference
 - ▶ Better generalization → better WER

BPE: algorithm

- 1. Each character token
- 2. Most popular n-gram: add new token
- 3. Replace n-gram with a new token
- 4. Restrict maximum length of tokens
- 5. New vocabulary = all characters + new tokens

Iteration	Sequence	Vocabulary
0	ababcabc	{a, b, c}
1	ab ab c ab c	{a, b, c, ab}
2	ab abc abc	$\{a, b, c, ab, abc\}$
3	ababc abc	{a, b, c, ab, abc, ababc}
4	ababcabc	{a, b, c, ab, abc, ababc, ababcabc}

Table: BPE: example for sequence {ababcabc}

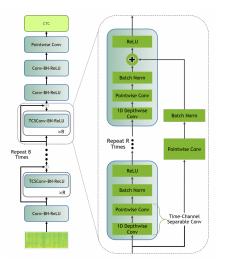
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ASR: SOTA models

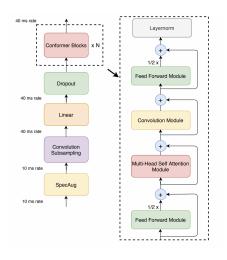
- ► RNN-T (2018, Google)
- ► MoChA (2018, Google) (Tricks to make LAS online)
- wav2vec (2019, Facebook AI Research) (SSL, use WAV not spectrograms)
- Jasper (2019, Nvidia) (Encoder: CNN; Loss: CTC)
- QuartzNet (2019, Nvidia) (Encoder: TDS CNN; Loss CTC)
- ContextNet (2020, Google) (Encoders: CNN and LSTM; Loss – RNN-T)
- wav2vec2 (2020, Facebook AI Research)
- Conformer (2020, Google) (Encoder: Convolutions + Transformers,)
- Whisper (2022, OpenAi) (Encoder: Transformer; Loss multitask)

QuartzNet



- Multiple blocks with residual connections (no transformers)
- ▶ Block: 1D time-channel separable convolutional layers + batch normalization + ReLU
- Loss: CTC (can be RNN-T)
- ▶ very fast: 2500 SPS on V100 (\approx 45mins in a second)

Conformer



- Combines convolution and transformers blocks
- Loss: CTC, Transducer
- ▶ 1900 SPS on V100 (\approx 30mins in a second)

Whisper

- ► ASR system trained on 680,000 hours of multilingual and multitask data collected from the web
- Shows that large and diverse dataset leads to improved robustness to accents, background noise and technical language
- Can translate text into English
- 99 languages in train

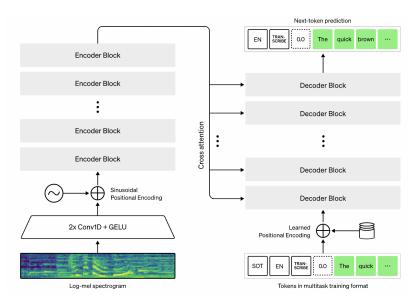
Radford, Kim et al. "Robust Speech Recognition via Large-Scale Weak Supervision", 2022 IEEE

Whisper: training data

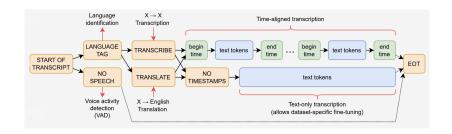


Figure: 17% Multilingual Speech Recognition (117k hours), 18% Translation (126k hours), 65% English Speech Recognition (438k hours)

Whisper: architecture



Whisper: multitask learning



Whisper: results

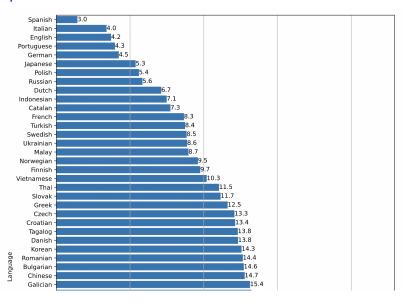


Figure: WER, %, Fleurs dataset

SOTA in production cookbook

- ▶ Use CTC/CrossEntropy/Transducer loss
- Add LMs or N-grams
- ► Models:
 - Quartznet: very fast, worse quality
 - Conformer: medium speed, medium quality
 - wav2vec 2.0: slow, best quality
 - ► Whisper: ? most robust ?
 - Ansambles

SOTA ASR: summary

Model	Average WER	LS Clean	LS Other
Human	-	5.83	12.69
Kaldi	-	8.01	22.49
DeepSpeech2 (CTC)	-	5.15	12.73
LAS	-	3.2	9.8
[PwC] QuartzNet	-	2.69	7.25
[PwC] Conformer large	-	1.9	3.9
[HF] wav2vec2-large	14.47	1.73	3.74
[HF] fastconformer_	8.34	1.69	3.4
ctc_xxlarge	0.34		
[HF] whisper-large-v2	8.16	2.87	5.16
[HF] fastconformer_ transducer_xlarge	8.06	1.5	2.88

Average WER: on datasets AMI, Earnings22, Gigaspeech, LibriSpeech, SPGISpeech, Tedlium, Voxpopuli, Common Voice HuggingFace Open ASR Leaderboard