

experimenter

environment

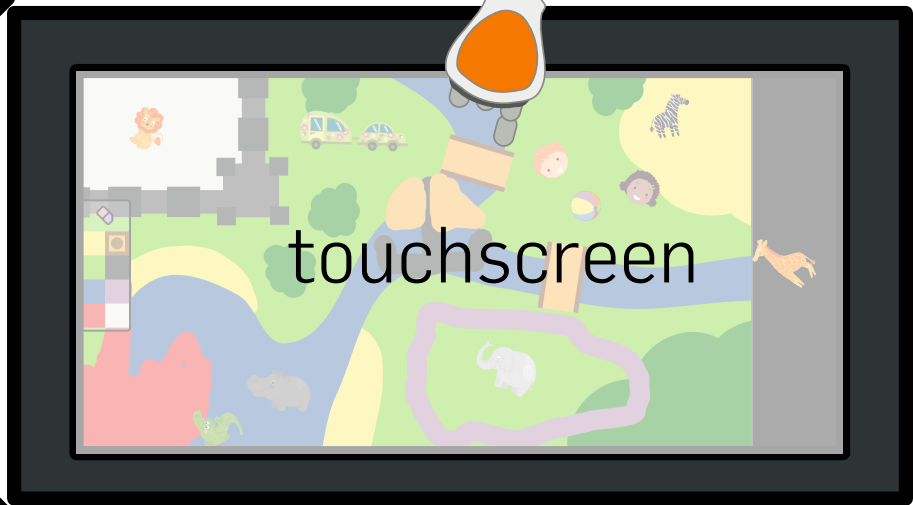
camera



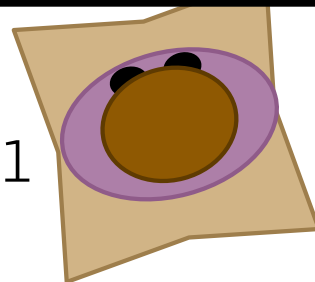
RGB-D camera 2
+ microphone



RGB-D camera 1
+ microphone



robot



child 1