

experimenter

environment

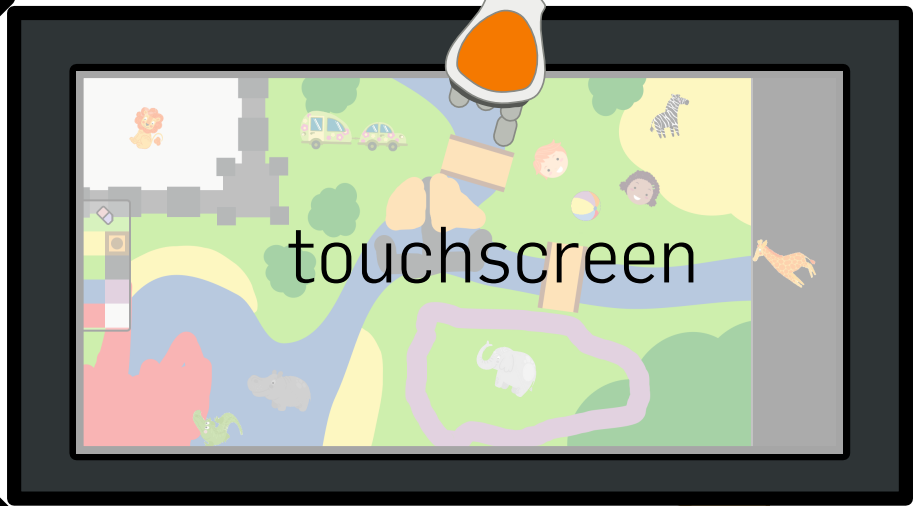
camera



RGB-D camera 2
+ microphone



RGB-D camera 1
+ microphone



robot

child 1

