

client

Environment Provider



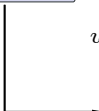
world static environment only



Linked
image
not found

client

Human
Monitoring



client



Robot State Monitor

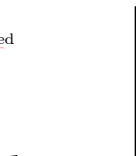
world robot and human and object added



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client

Object
Monitoring



client

Computation of
spatial relations



client



Physics filter



world stable



client

Perspective filter

world human 1 beliefs



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image
not found

world human 2 beliefs



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