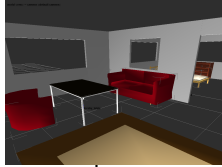
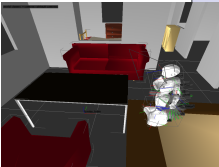


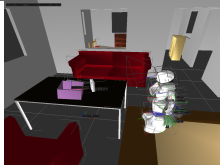
Environment Provider



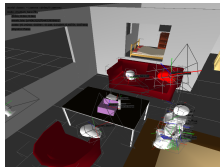
Robot State Monitoring



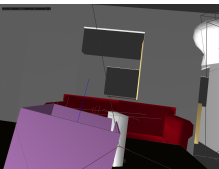
Object Monitoring



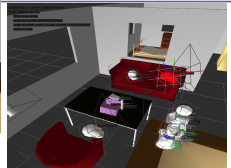
Physics filter



Perspective filter



Human Monitoring



Computation of spatial relations

