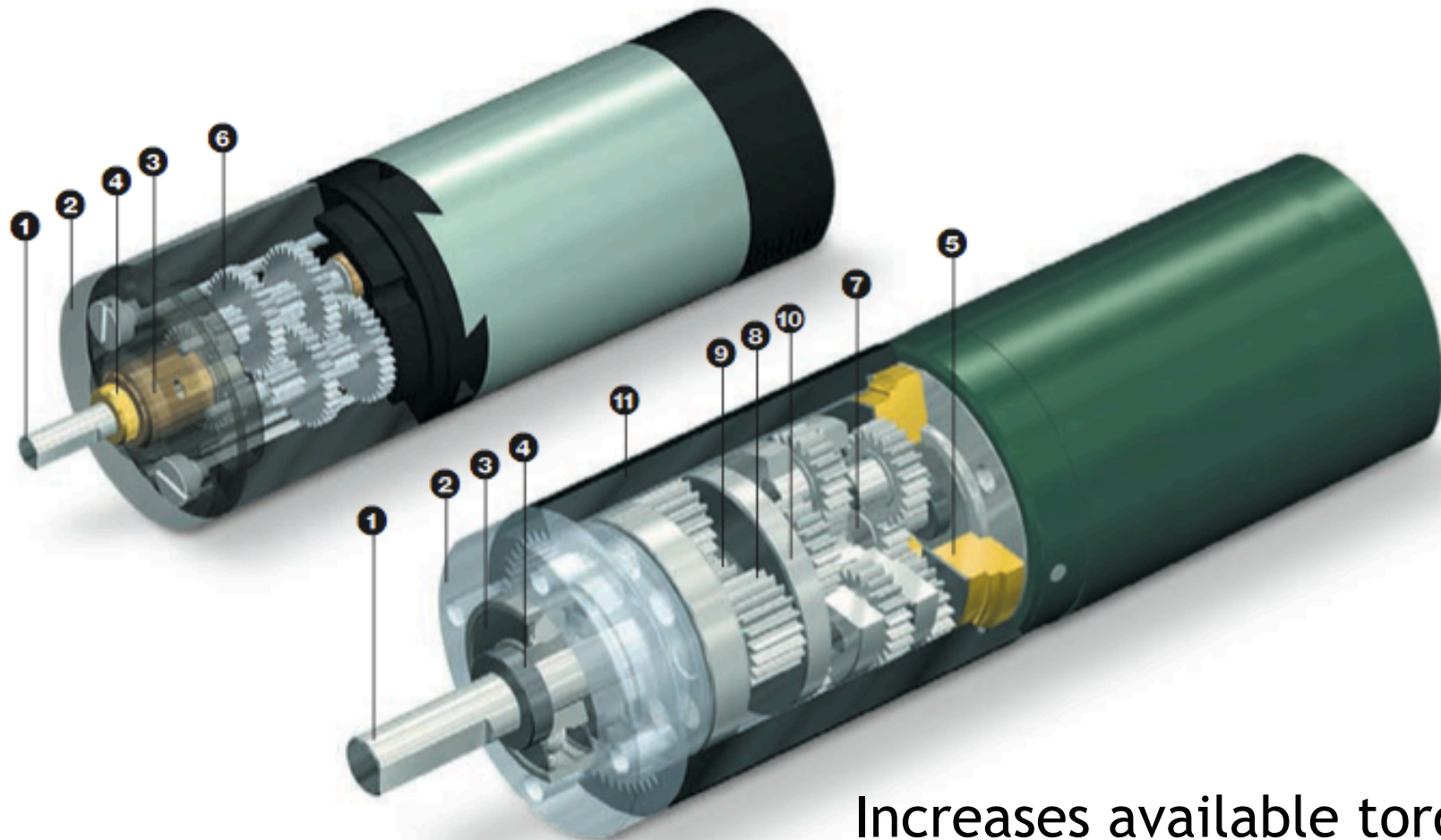


# **ROCO222: Intro to sensors and actuators**

## Lecture 7

### Maxon gearboxes

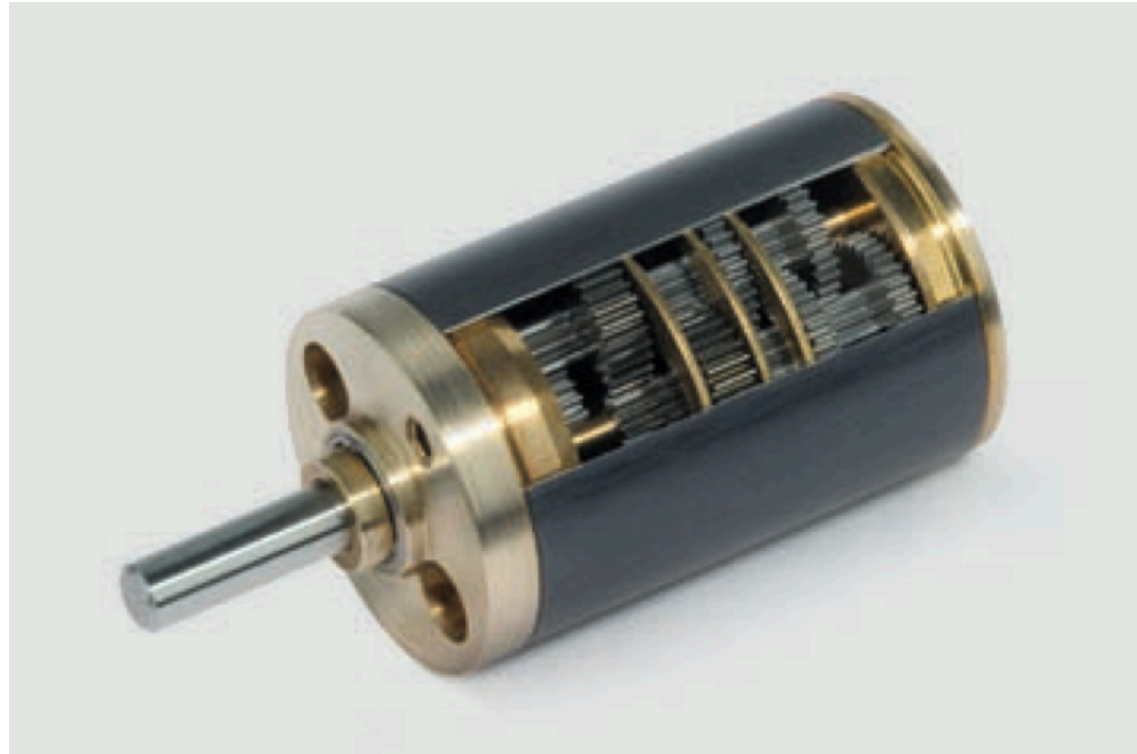
# Maxon motors with gearing



Increases available torque

# Maxon spur gear head

- Favorably priced
- For low torques
- Output torque up to 2 Nm
- Ratios of 6:1 to 5752:1
- Low noise level
- High efficiency



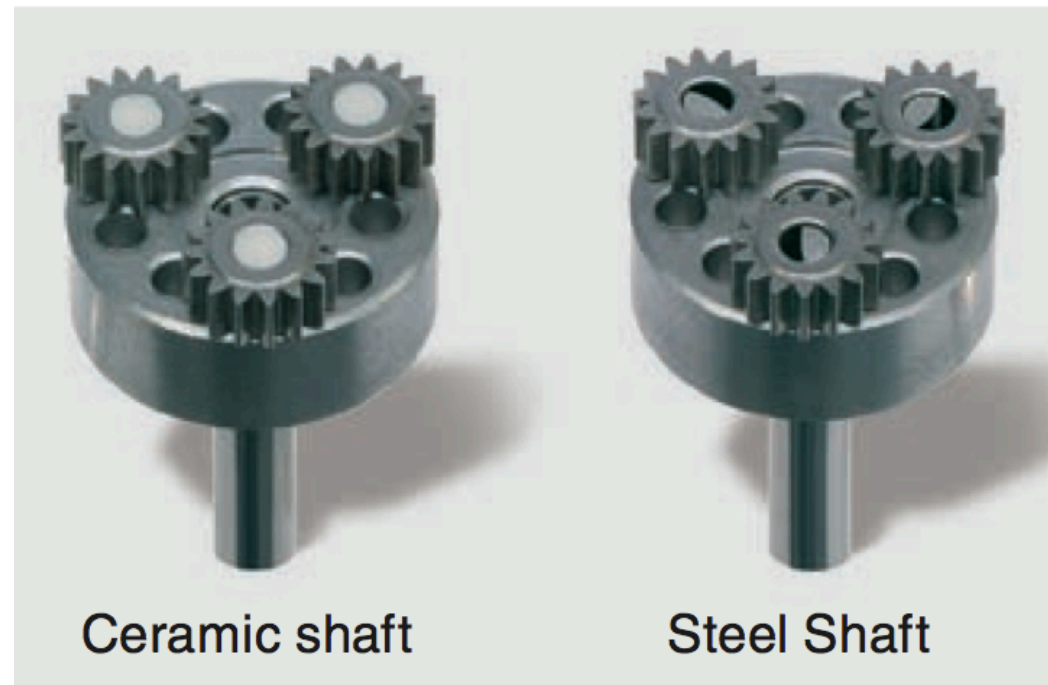
# Maxon planetary gear head

- For transferring high torques up to 180 Nm
- Reduction ratios of 4:1 to 6285:1
- External diameter 6 - 81 mm
- High performance in a small space
- High reduction ratio in a small space
- Concentric gear input and output



# Ceramic versus steel gears

- Ceramic has longer service life
- Wear much less than steel
- Higher continuous torques
- Higher intermittent torques
- Higher input speeds



# Spur versus planetary gearboxes



## Spur Gearheads

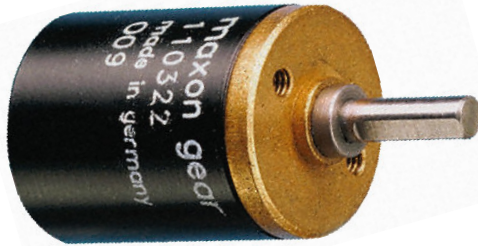
## Planetary Gearheads

Power Transfer per volume  
High Power option  
Price  
Low price option  
Noise level  
Efficiency

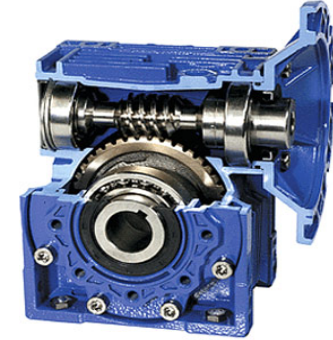
Low  
None  
Favourable  
Plastic also available  
Lower  
Very high

High  
Ceramic  
Expensive  
Plastic also available  
Higher  
High

# Gearbox mechanical losses



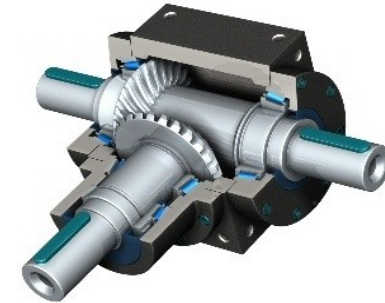
Spur Gear  
efficiency: 85% typical



Worm gear  
efficiency: 50-90%



Planetary Gear  
efficiency: 75% typical



Bevel gear  
efficiency: typical 90%

- Energy is wasted in the forms of
- Heat (from friction of gears meshing)
- Noise



# Gearboxes losses increases with stages

