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You can download the sources of this presentation here:
github.com/severin-lemaignan/module-introduction-sensors-actuators

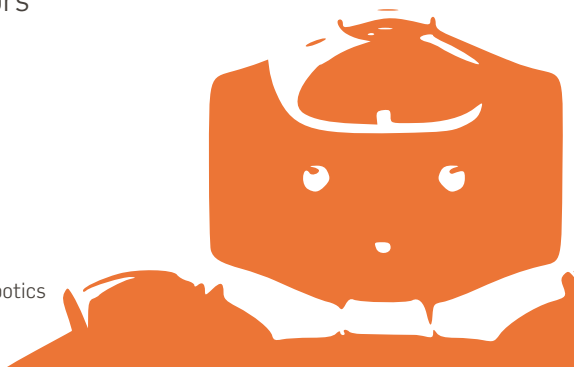
ROC0222

Intro to Sensors and Actuators

Force and Torque Sensors

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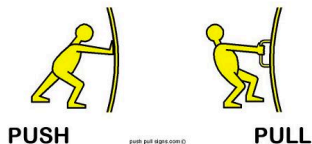
TODAY'S OBJECTIVES

- Know how to measure force and torque
- (prep' for ROC0318 next year)

MEASURING FORCE

DEFINITION OF FORCE

- A push or a pull
- The ability to do work
- Is is a vector quantity
- Has magnitude and direction



- Measured in Newtons (N)
- **Newton's Second Law**
- A force acting on a mass will accelerate or decelerate it
- $F = ma$

where F is Force (N), m is mass (Kg), a is acceleration (ms^{-2})

FOUR FUNDAMENTAL FORCES IN NATURE

1. Gravity

Dominates at large distances



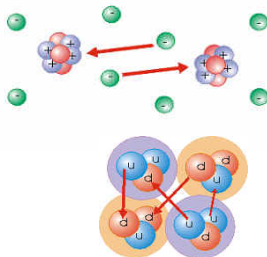
2. Electromagnetic forces

Observed in the interactions between atoms

3 . & 4. Nuclear forces

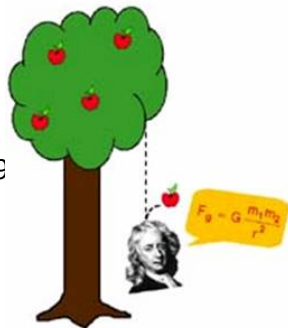
Strong & weak

Both very short range



FORCE ARISES FROM GRAVITY ACTING ON A MASS

- Force arises from gravity acting on a mass
- $F = mg$
 - where F is Force (N),
 - m is mass (Kg),
 - g is acceleration due to gravity ≈ 9



MEASURING FORCE BY BALANCING KNOWN FORCE

- Use gravity acting on a known mass as source of known force



- Search for equilibrium position to find gravitational mass of test object

MEASURING FORCE BY MEASURING STRAIN

- Stress defined as "force per area"
- Strain is defined as: "deformation of a solid due to stress"
- When we apply force
- Induced **stress** results in a **strain**

$$E = \text{stress} / \text{strain} = (F / A_0) / (\Delta L / L_0)$$

Where

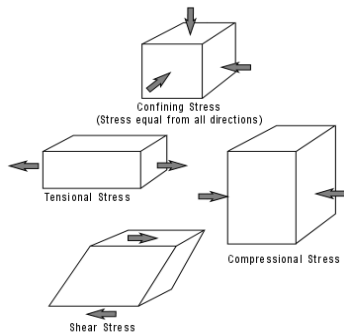
E is the Young's modulus (modulus of elasticity)

F is the force exerted on an object under tension

A_0 is the cross-sectional area

ΔL is the amount by which object length changes

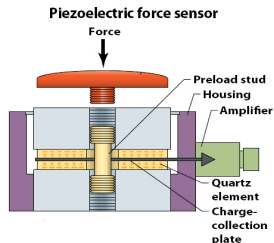
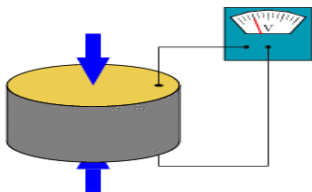
L_0 is the original length of the object



- By measuring strain of a material of known properties can estimate force

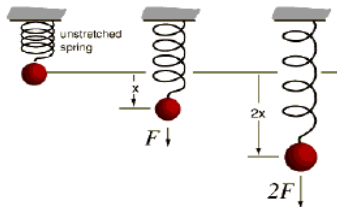
PIEZO-ELECTRIC EFFECT

- Some materials generate electric charge under mechanical stress

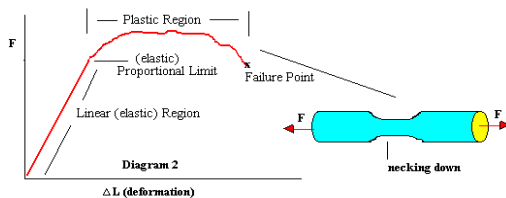


- Force results in a separation of charges within structure
- Capacitive effect generates output voltage.
- Leakage causes charge dissipation and voltage decay over time
- Suitable for dynamic measurements

MEASUREMENT OF ELASTIC DEFORMATION



Hooke's law: $F = -kx$



Hooke's law only holds over the elastic region

DIRECT MEASUREMENT OF ELASTIC DEFORMATION



Can simply observe extension
to estimate force

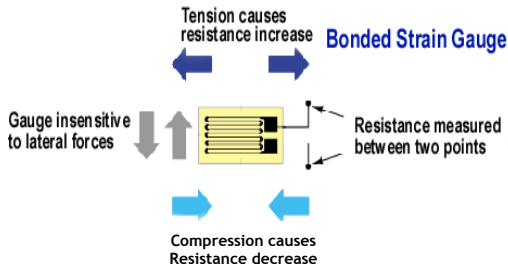


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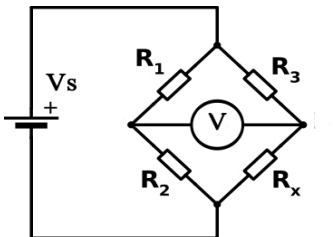
Other mechanical methods
Proving ring - Displacement
measured directly using
micrometer or dial gauge

STRAIN GAUGE



- This is an electrical method of force measurement
 - The gauge measures strain of substrate to which it is attached
 - Provided substrate load operated in elastic region of the material, this is linearly relates to the applied force by Young's modulus
-
- Strain gauge measures strain because when film stretches it becomes narrower and longer and this increases its resistance
 - Gauge is much more sensitive to strain is direction along the longer thin regions
 - Overall during use such a sensor delivers only a fraction of percent change in resistance
 - Resistance change is usually measured using a Wheatstone bridge

WHEATSTONE BRIDGE CIRCUIT



$$I_{LeftBranch} = \frac{V_s}{R_1 + R_2}$$

$$V_{R2} = \frac{V_s R_2}{R_1 + R_2}$$

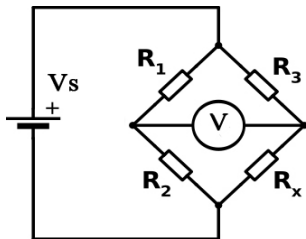
$$I_{RightBranch} = \frac{V_s}{R_3 + R_x}$$

- Wheatstone bridge converts change in resistance to change in voltage

$$V_{R_x} = \frac{V_s R_x}{R_3 + R_x}$$

$$V = \left(\frac{R_x}{R_3 + R_x} - \frac{R_2}{R_1 + R_2} \right) V_s$$

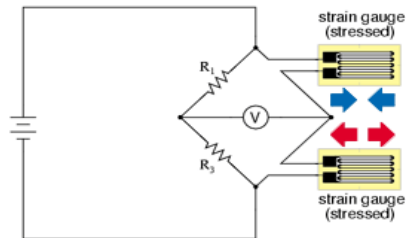
WHEATSTONE BRIDGE CIRCUIT



$$V = \left(\frac{R_x}{R_3 + R_x} - \frac{R_2}{R_1 + R_2} \right) V_s$$

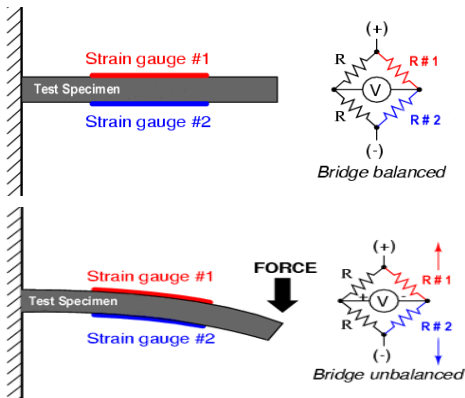
- By placing strain gauges into the bridge, changes in their resistance resulting from the strain in the substrate gives rise to changes in voltage that can be measured

Half-bridge strain gauge circuit



- Bridge arrangement cancels out changes that occur in all the resistive elements
- This compensates for resistance changes due to changes on temperature and also for strains in unwanted directions

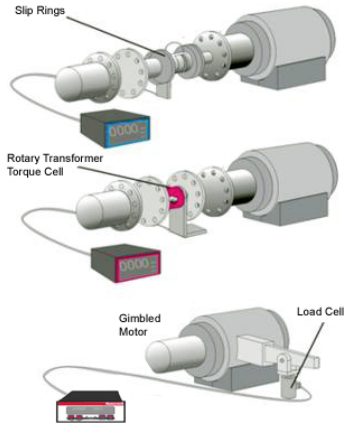
SIMPLE CANTILEVER LOAD CELL



- If gauges are centrally mounted then
- no change in output voltage due to a side load

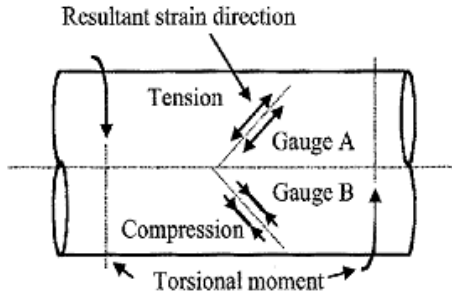
MEASURING TORQUE

MEASURING TORQUE



- Two common ways to obtain torque measurements are by strain-gauging the shaft and by using in-line torque cells.
- Both have two technical obstacles: getting power to the gauges over the stationary/rotating gap and getting the signal back.

MEASURING TORQUE USING A GAUGE ON SHAFT



- The gauges lie perpendicular to one another at 45 deg to the plane about which the tensional moment is applied.

6 DOF LOAD CELLS



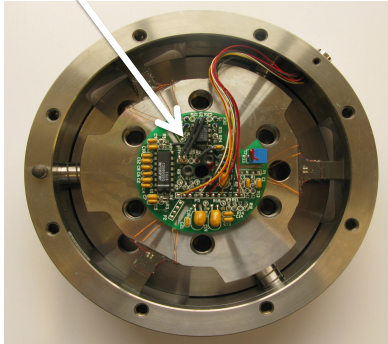
1 translational DOF



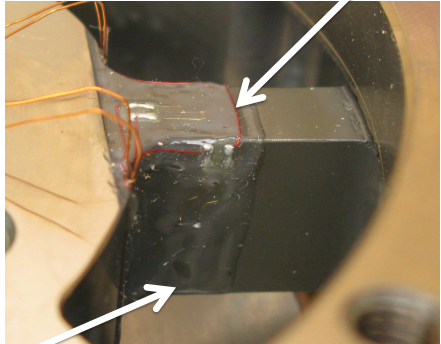
3 translational & 3 rotational DOFs

INSIDE A LARGE 6 DOF FT

Signal conditioning circuitry

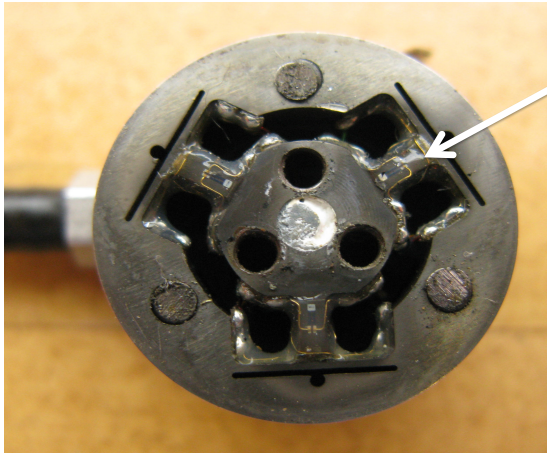


Silicon strain gauges



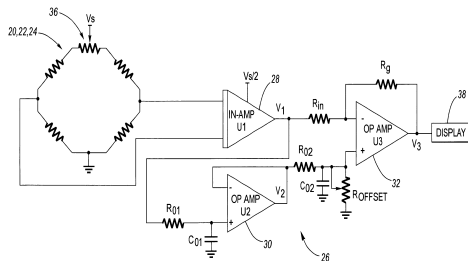
Massive structure which deforms under stress

INSIDE A SMALL 6 DOF FT



Silicon strain gauges

A SIGNAL CONDITIONING AMPLIFIER IS NEEDED



- The amplifier needed because voltage changes generated by Wheatstone bridge are small
- Need differential input to cancel interference
- Also it can filter unwanted signal outside the bandwidth of interest

That's all, folks!

Questions:

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Slides:

github.com/severin-lemaignan/module-introduction-sensors-actuators