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You can download the sources of this presentation here:
github.com/severin-lemaignan/module-mobile-and-humanoid-robots

ROC0318

Mobile and Humanoid Robots

Practical 1 – Sensors Projects

Tony Belpaeme and Séverin Lemaignan

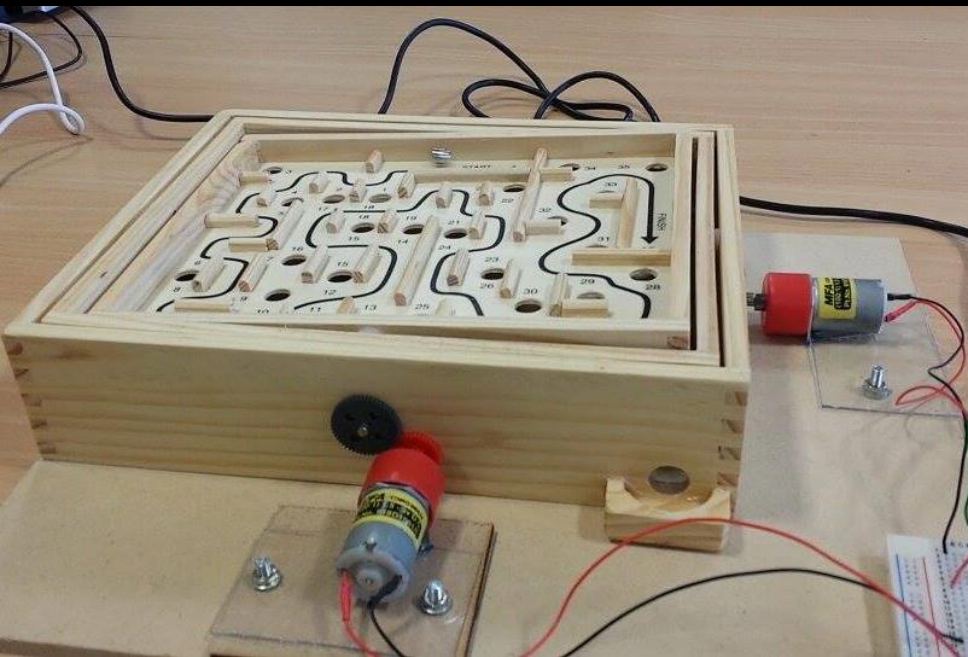
Centre for Neural Systems and Robotics
Plymouth University



SENSORS PROJECTS

OBJECTIVE

1. Pick a sensor (or more than one)
2. Figure out a cool application
3. Build it!





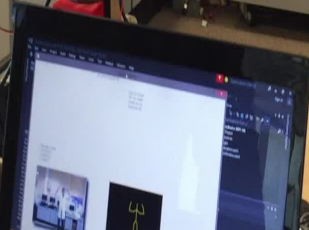


Department of Communication and Electronic Engineering

ROBOT FOOTBALL

- UHF Radio Control
- Digital Signal Processing
- Control Electronics
- Video Imaging
- Computing
- Artificial Intelligence
- Microelectronics
- International Collaboration

The winning robot teams will compete in a series of matches to be held at the University of Cambridge. A prize of £10,000 will be awarded to the winning team. The prize will be awarded to the winning team. The prize will be awarded to the winning team.





Set up I

TIMEFRAME

This week – 09:00 to 12:00

- make groups (2-3 persons/group)
- play with sensors (including installation of SDKs)
- discuss a project idea within the group & get our feedback

Next week – 09:00 to 12:00

- I'm away – you can come to the lab anyway
- hack hack hack

Week 3 & 4 – 12:00 to 15:00

- hack hack hack

Bonus labs on the Monday 23/10 & 30/10; Tuesday 24/10 & 31/10

Week 5 – 03/11 – 12:00 to 15:00: **demonstrations!**

CONSTRAINTS

Not many: you choose the language, the OS, the platform

DELIVERABLES

- project demonstrations will be marked
- a report (max 10 pages) on the sensor(s) you have been using + detailed presentation of your project –
accompanying video is encouraged!

Let's get to work!