

Pepper at the Mendip School - teacher's feedback

Dear Mendip School Staff,

We would like first to thank you immensely for supporting our research at the Mendip school over the last 3 weeks. The study has been extremely valuable, and we are now starting to explore and analyse our data.

If you can kindly elaborate for us, below, any thoughts, aspects or moments when Pepper was in your school, we'd be very grateful. No word limits, so any insights you can offer would be extremely helpful.

If you'd like to use your pupils' real names this will help us in tracking this data to others that we have. We will remove the name immediately and use a nom de plume.

Firstly, what's your role at the school (Teacher, TA, Head Teacher, etc..) and in what class do you mostly teach:

Pepper's impact on the pupils

Q1: Can you comment on the impact of Pepper on your pupils, either at an individual level or on a group level:

Q2: Have you observed any impact on the school itself?

(eg positive and/or negative impact on the school routines or on the children' routines)

Q3: Have you interacted with Pepper?

Q4: Would you say that Pepper has had an impact on your teaching practice or routine? If so, how did you use or integrate Pepper in your teaching -- and why?

How you perceived Pepper

Q5: Three things you liked or disliked about Pepper in your school:

Like:

1

2

3

Dislike:

1

2

3

Q6: If it were possible, would you like for Pepper to stay in your school?

Q7: What do you miss about Pepper (if anything)?

Q8: Would you change anything about Pepper?

For instance: interaction, activities, size/design, handling, performance, usability, ...

Your ideas about the future of robots in (SEN) education

Q9: Would you recommend other colleagues/schools to use a robot like Pepper?

Q10: What role do you think social robots like Pepper should have alongside staff and pupils (SEN or not)?

Q11: Finally, how do you personally feel about robots in a/your school?

Thank you very much for your time!

Nigel, Louis, Joe and Séverin