$\mathsf{Hedge}(\eta)$ 

## Online Convex Optimization

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Material follows Chapters 1,2,3 of "Online Convex Optimization" / Elad Hazan.

#### Outline

OCO

Standard Convex Optimization

Online Convex optimization

## Online Linear Optimization

- ▶ Instance:  $(\mathbf{x}_t, y_t) \in \mathbb{R}^d \times \mathbb{R}$
- ▶ Predictor:  $\mathbf{w}_t \in \mathbb{R}^d$
- ► Loss  $\ell$ (**w** · **x**, **y**) (online regression = square loss)
- ▶ Regret:  $\mathbf{R}_t(\mathbf{u}) = \sum_{i=1}^t \left[ \ell(\mathbf{w}_t \cdot \mathbf{x}_t, y_t) \ell(\mathbf{u} \cdot \mathbf{x}_t, y_t) \right]$

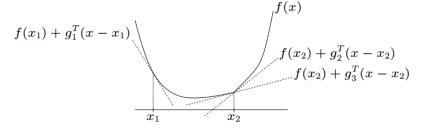
#### Online convex Optimization

- ▶ Optimizer chooses point: $\mathbf{x}_t \in \mathbb{R}^d$
- Adversary chooses convex loss function  $f_t : \mathbb{R}^d \to \mathbb{R}$
- optimizer chooses Loss  $f_t(\mathbf{x}_t)$
- ▶ Regret:  $\mathbf{R}_T = \sup_{f_1,...,f_T} \left[ \sum_{t=1}^T f_t(\mathbf{x}_t) \min_{\mathbf{u}} \sum_{t=1}^T f_t(\mathbf{u}) \right]$

## Standard convex optimization

- not online convex optimization (CO) has been studied much longer than Online convex optimization (OCO)
- OCO bounds use measures of convexity from CO.
- f is a given convex function.
- K is a convex set.
- ► Goal: find  $\mathbf{x}^* = \operatorname{argmin}_{\mathbf{x} \in \mathcal{K}} f(\mathbf{x})$
- Method: gradient descent.
- rate of convergence: rate at which  $h_t = f(\mathbf{x}_t) f(\mathbf{x}^*)$  decreases.

## The sub-gradient

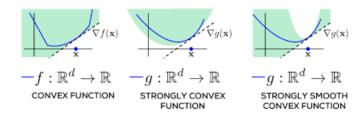


- ▶  $f: \mathbb{R}^d \to \mathbb{R}$  is convex.
- ▶  $\nabla f(\mathbf{x})$  is the set of vectors  $\mathbf{g} \in \mathbb{R}^d$  such the  $\forall \mathbf{y}, f(\mathbf{y}) \geq f(\mathbf{x}) + \mathbf{g} \cdot (\mathbf{y} \mathbf{x})$
- ▶ If f is differentiable at x, then  $\nabla f(x)$  has only one element.
- ▶ Otherwise  $\nabla f(\mathbf{x})$  is a continuously infinite set.

#### Basic Gradient descent

- 1. **input:** f, T initial point  $\mathbf{x}_1 \in \mathcal{K}$ , sequence of step sizes  $\{\eta_t\}$
- 2. For t = 1, ..., T do:
- 3. Update:  $\mathbf{y}_{t+1} = \mathbf{x}_t \eta_t \nabla f(\mathbf{x}_t)$
- 4. Project:  $\mathbf{x}_{t+1} = \Pi_{\mathcal{K}}(\mathbf{y}_{t+1})$
- 5. End For
- 6. Return  $\mathbf{x}_{t+1}$

## Degrees of convexity



- ▶ f(x) is convex if  $\forall x, y, f(y) \ge f(x) + \nabla f(x) \cdot (y x)$
- ► f(x) is  $\alpha$ -strongly convex if  $\forall \mathbf{x}, \mathbf{y}, f(\mathbf{y}) \geq f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot (\mathbf{y} \mathbf{x}) + \frac{\alpha}{2} ||\mathbf{x} \mathbf{y}||^2$
- ► f(x) is  $\beta$ -smooth if  $\forall \mathbf{x}, \mathbf{y}, f(\mathbf{y}) \leq f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot (\mathbf{y} \mathbf{x}) + \frac{\beta}{2} ||\mathbf{x} \mathbf{y}||^2$

## Conditioning number

- ▶ If *f* is both α-strongly convex and β-smooth we say it is γ-well conditioned where:  $\gamma = \frac{\alpha}{\beta} \le 1$
- ▶ What is the meaning of  $\gamma = 1$ ?

#### **Basic Bound on Basic Gradient Descent**

- If f is  $\gamma$ -well conditioned.
- and  $\eta_t = \frac{1}{\beta}$
- $h_{t+1} \leq h_1 \exp\left(\frac{\gamma t}{4}\right)$

# Reduction to smooth, not strongly convex functions

# Reduction to non-smooth, strongy convex functions

## Reduction to convex functions

#### Online Gradient Descent

 $f_t(\mathbf{x}_t)$  instead of  $f(\mathbf{x}_t)$