

30/12/2020, Wednesday

page 373, Example 7, skipped, now to be done:

Ex 7 Find bases for the eigenspaces of the matrix

$$A = \begin{bmatrix} 4 & -2 & 1 \\ 2 & 0 & 1 \\ 2 & -2 & 3 \end{bmatrix}$$

$$|A - \lambda I| = \begin{vmatrix} 4-\lambda & -2 & 1 \\ 2 & 0-\lambda & 1 \\ 2 & -2 & 3-\lambda \end{vmatrix} = -\lambda^3 + 7\lambda^2 - 16\lambda + 12 = 0$$

$\lambda^3 - 7\lambda^2 + 16\lambda - 12 = 0$: if two have an integer sol,

it must be a divisor of the constant term: It's

possible that the numbers $\pm 1, \pm 2, \pm 3, \pm 4, \pm 6,$

are, possible to be a root of this eq. ± 12

Indeed: $\lambda=2$: $2^3 - 7 \cdot 2^2 + 16 \cdot 2 - 12 = 8 - 28 + 32 - 12 = 0$

$$P(\lambda) = \lambda^3 - 7\lambda^2 + 16\lambda - 12 = (\lambda - 2) Q(\lambda)$$

$Q(\lambda)$: a second-degree polynomial

$$\begin{array}{r} \lambda^3 - 7\lambda^2 + 16\lambda - 12 \\ \ominus \lambda^3 - 2\lambda^2 \\ \hline -5\lambda^2 + 16\lambda - 12 \\ -5\lambda^2 + 10\lambda \\ \hline 6\lambda - 12 \\ 6\lambda - 12 \\ \hline 0 \end{array} \quad \begin{array}{l} \lambda - 2 \\ \hline \lambda^2 - 5\lambda + 6 \end{array}$$

$$P(\lambda) = (\lambda - 2)(\lambda^2 - 5\lambda + 6)$$

$$= (\lambda - 2)(\lambda - 2)(\lambda - 3)$$

$$P(\lambda) = (\lambda - 2)^2 (\lambda - 3)$$

Case 1

$$\boxed{\lambda = 2}$$

$$(A - \lambda I) \underline{v} = \underline{0}$$

$$\boxed{2x - 2y + z = 0}$$

$$\begin{bmatrix} 4-2 & -2 & 1 \\ 2 & 0-2 & 1 \\ 2 & -2 & 3-2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 2 & -2 & 1 \\ 2 & -2 & 1 \\ 2 & -2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$2x - 2y + z = 0 \rightarrow y = 1, z = 0 \rightarrow x = 2$$

$$y = 0, z = 2 \rightarrow x = -1$$

$$V_1 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}, \quad V_2 = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix} \text{ are two eigenvectors corresponding to } \lambda = 2.$$

The base of the eigenspace corresponding to $\lambda = 2$ is

$$\begin{aligned} \{v_1, v_2\} &= \left\{ \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix} \right\} = \{(2, 1, 0), (-1, 0, 2)\} \\ &= \left\{ [2 \ 1 \ 0]^T, [-1 \ 0 \ 2]^T \right\} \end{aligned}$$

$$\boxed{\lambda = 3} \quad (A - \lambda I) \underline{v} = \underline{0}$$

$$\begin{bmatrix} 4-3 & -2 & 1 \\ 2 & -3 & 1 \\ 2 & -2 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & -2 & 1 \\ 2 & -3 & 1 \\ 2 & -2 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & 1 \\ 2 & -3 & 1 \\ 2 & -2 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$x - 2y + z = 0 \quad (1)$$

$$2x - 3y + z = 0 \quad (2)$$

$$2x - 2y = 0 \quad (3)$$

(3) implies $x = y$: $\left. \begin{array}{l} (1) \quad -x + z = 0 \\ (2) \quad -x + z = 0 \end{array} \right\} x = z$

$$x = y = z \Rightarrow \text{Let } x = 1 = y = z \quad v_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \\ x \\ x \end{bmatrix} = x \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \xrightarrow{x=1} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = v_3$$

The eigenspace corresponding to the
eigenvalue $\lambda = 3$ is

$$\{v_3\} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$$

Comment When finding the eigenvector $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ corr.

to $\lambda=2$, we solved $2x - 2y + z = 0$, there's
no other cond. on x, y, z .

$$v = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} (2y - z)/2 \\ y \\ z \end{bmatrix} = y \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + z \begin{bmatrix} -1/2 \\ 0 \\ 1 \end{bmatrix}$$

Let $y=1, z=0$

$$\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1/2 \\ 0 \\ 1 \end{bmatrix} \right\}$$

Let $y=0, z=2$

$$\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix} \right\}$$

p 381, 6.2 Diagonalization of Matrices

Th.1 An $n \times n$ A is diagonalizable iff A has n linearly independent eigenvectors.

Th.2 The eigenvectors of a matrix A corresponding to different eigenvalues are linearly independent.

Th.3 If an $n \times n$ matrix A has n distinct eigenvalues, then A is diagonalizable.

page 381, Example 8

Is $A = \begin{bmatrix} 4 & -2 & 1 \\ 2 & 0 & 1 \\ 2 & -2 & 3 \end{bmatrix}$ diagonalizable??

A is a 3×3 matrix; $\{A \text{ is diagonalizable}\} \Leftrightarrow \{A \text{ has } n=3$

Th.1 linearly ind. eigenvectors

$$\lambda_1 = \lambda_2 = \lambda = 2 \rightarrow v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \quad v_2 = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$$

$$\lambda_3 = 3 \rightarrow v_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Since A has 3 linearly independent eigenvectors, then A is diagonalizable.

$$P = \begin{bmatrix} 1 & 1 & 1 \\ v_1 & v_2 & v_3 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}, \quad P^{-1} = \begin{bmatrix} -2 & 3 & -1 \\ -1 & 1 & 0 \\ 2 & -2 & 1 \end{bmatrix}$$

$$D = P^{-1} A P = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

Theorem 4 Complete independence of eigenvectors

Let $\lambda_1, \lambda_2, \dots, \lambda_k$ be the distinct eigenvalues of the $n \times n$ matrix A ($k \leq n$). For each k , let S_1, S_2, \dots, S_k be the bases of eigenspaces of A , associated with $\lambda_1, \lambda_2, \dots, \lambda_k$.

Then, the union S of the bases S_1, S_2, \dots, S_k is a linearly independent set of eigenvectors of A .

6.3 Applications Involving Powers of Matrices , p 383

Remark Suppose A is an $n \times n$ diagonalizable matrix.

$$\boxed{D = P^{-1} A P} \Rightarrow P D = A P \Rightarrow P D P^{-1} = A$$

$$A = P D P^{-1}$$

$$A^2 = (P D P^{-1})(P D P^{-1}) = P D^2 P^{-1}$$

$$A^3 = A^2 A = (P D^2 P^{-1})(P D P^{-1}) = P D^3 P^{-1}$$

$$\vdots$$
$$A^k = P D^k P^{-1}$$

$$A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$$

In order to calculate A^k , we need to perform k matrix product ops.

For this 3×3 matrix A , $D = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}$

$$D^2 = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} = \begin{bmatrix} \lambda_1^2 & 0 & 0 \\ 0 & \lambda_2^2 & 0 \\ 0 & 0 & \lambda_3^2 \end{bmatrix}$$

$$D^k = \begin{bmatrix} \lambda_1^k & 0 & 0 \\ 0 & \lambda_2^k & 0 \\ 0 & 0 & \lambda_3^k \end{bmatrix}$$

$$A^k = P D^k P^{-1}$$

requires k
ops. of matrix
product

requires 2 products
as we directly
know D^k !!!

This reduces computational cost drastically!!!

Example

Find A^5 if

$$A = \begin{bmatrix} 4 & -2 & 1 \\ 2 & 0 & 1 \\ 2 & -2 & 3 \end{bmatrix}$$

Remember that $\lambda_1 = 3$ $v_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$,

$$\lambda_2 = 2 \quad v_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \quad v_3 = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$$

$$\textcircled{v_1} \quad \textcircled{v_2} \quad \textcircled{v_3}$$

$$P = \begin{bmatrix} 1 & 1 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 2 \end{bmatrix}, \quad P^{-1} = \begin{bmatrix} 2 & -2 & 1 \\ -2 & 3 & -1 \\ -1 & 1 & 0 \end{bmatrix}$$

$$D = P^{-1} A P = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \Rightarrow D^5 = \begin{bmatrix} 3^5 & 0 & 0 \\ 0 & 2^5 & 0 \\ 0 & 0 & 2^5 \end{bmatrix}$$

Example

Find A^5 if

$$A = \begin{bmatrix} 4 & -2 & 1 \\ 2 & 0 & 1 \\ 2 & -2 & 3 \end{bmatrix}$$

$$A^k = P D^k P^{-1}$$

$$= \begin{bmatrix} 1 & 1 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} 243 & 0 & 0 \\ 0 & 32 & 0 \\ 0 & 0 & 32 \end{bmatrix} \begin{bmatrix} 2 & -2 & 1 \\ -2 & 3 & -1 \\ -1 & 1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 454 & -422 & 211 \\ 422 & -350 & 211 \\ 422 & -422 & 243 \end{bmatrix}$$

$$D = P^{-1} A P = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \Rightarrow D^5 = \begin{bmatrix} 3^5 & 0 & 0 \\ 0 & 2^5 & 0 \\ 0 & 0 & 2^5 \end{bmatrix}$$

Remember that the eigenvalue equation of $n \times n$ matrix A

$$|A - \lambda I| = \begin{vmatrix} a_{11} - \lambda & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} - \lambda & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} - \lambda \end{vmatrix} = 0$$

gives us an n -th degree algebraic equation

$$(-1)^n \lambda^n + c_{n-1} \lambda^{n-1} + \dots + c_1 \lambda + c_0 = 0.$$

Let's call the LHS as $p(\lambda)$, the characteristic polynomial:

$$p(\lambda) = (-1)^n \lambda^n + c_{n-1} \lambda^{n-1} + \dots + c_1 \lambda + c_0.$$

* $p(\lambda) = 0 \Leftrightarrow \lambda$ is an eigenvalue of A .

The Cayley-Hamilton Theorem

If the $n \times n$ matrix A has the characteristic polynomial

$$p(\lambda) = (-1)^n \lambda^n + c_{n-1} \lambda^{n-1} + \dots + c_1 \lambda + c_0,$$

then

$$p(\underset{\sim}{A}) = (-1)^n \underset{\sim}{A}^n + c_{n-1} \underset{\sim}{A}^{n-1} + \dots + c_1 \underset{\sim}{A} + c_0 \underset{\sim}{I} = \underset{\sim}{0}$$

This means: Any matrix A satisfies its own eigenvalue equation, when considered as a matrix equation !!

Example

$$A = \begin{bmatrix} 5 & 7 \\ -2 & -4 \end{bmatrix}$$

$$|A - \lambda I| = \begin{vmatrix} 5 - \lambda & 7 \\ -2 & -4 - \lambda \end{vmatrix} = \lambda^2 - \lambda - 6 = 0 \quad \begin{cases} \lambda_1 = -2 \\ \lambda_2 = 3 \end{cases}$$

$$p(\lambda) = \lambda^2 - \lambda - 6$$

$$p(A) = A^2 - A - 6I =$$

$$= \begin{bmatrix} 5 & 7 \\ -2 & -4 \end{bmatrix} \begin{bmatrix} 5 & 7 \\ -2 & -4 \end{bmatrix} - \begin{bmatrix} 5 & 7 \\ -2 & -4 \end{bmatrix}$$

$$- 6 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \dots = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Example 6, p 392

Consider $A = \begin{bmatrix} 4 & -2 & 1 \\ 2 & 0 & 1 \\ 2 & -2 & 3 \end{bmatrix}$

$$p(\lambda) = -\lambda^3 + 7\lambda^2 - 16\lambda + 12$$

$$p(A) = -A^3 + 7A^2 - 16A + 12I = \underset{\sim}{0}$$

We can calculate $A^2 = \begin{bmatrix} 14 & -10 & 5 \\ 10 & -6 & 5 \\ 10 & -10 & 9 \end{bmatrix}$

$$A^3 = 7A^2 - 16A + 12I = \begin{bmatrix} 46 & -38 & 19 \\ 38 & -30 & 19 \\ 38 & -38 & 27 \end{bmatrix}$$

$$A^4 = A^3 A, \quad A^6 = A^3 \cdot A^3, \dots$$

Furthermore, $-A^3 + 7A^2 - 16A + 12I = \underline{0}$

Multiply by A^{-1}
to get $-A^{-1}A^3 + 7A^{-1}A^2 - 16A^{-1}A + 12A^{-1}I = \underline{0}$

$$A^{-1} = \frac{1}{12} (A^2 - 7A + 16I)$$

$$= \frac{1}{6} \begin{bmatrix} 1 & 2 & -1 \\ -2 & 5 & -1 \\ -2 & 2 & 2 \end{bmatrix}$$

Remark

$$(-1)^n \lambda^n + c_{n-1} \lambda^{n-1} + \dots + c_1 \lambda + c_0 = 0$$

$$(-1)^n \lambda^n + c_{n-1} \lambda^{n-1} + \dots + c_1 \lambda + (-1)^n \det A = 0$$

$\det A = 0 \Rightarrow c_0 = 0 \Rightarrow$ Cayley-Ham. does not give A^{-1} ,
AS IT SHOULD NOT!!!

Next week

Chapter 7
Linear System of Diff. Eqs

Read 7.1, 7.2

