

# **Sparse optimization Algorithms in Medical Imaging**

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13 March 2023



## Faculty member

- ▶ Inverse Problems
- ▶ Numerical Analysis
- ▶ Medical Imaging
- ▶ Optimal Transport
- ▶ Machine Learning

University of Graz



## PhD Mathematics

- ▶ PDEs
- ▶ Calculus of Variations
- ▶ Materials Science

University of Sussex



# **Sparse optimization Algorithms in Medical Imaging**

based on joint works with

Kristian Bredies, Marcello Carioni, Francisco Romero, Daniel Walter

## **Outline**

- ① Minimization Problem / Sparsity**
- ② Sparse optimization Algorithm**
- ③ Application: Particle Tracking**

# Minimization Problem

$X$  Banach space. Solve

$$\min_{u \in X} L(u) + R(u)$$

- **L**  $\leadsto$  **Loss function:** Smooth + Convex

(Close to data)

$$L : X \rightarrow [0, \infty)$$

- **R**  $\leadsto$  **Regularizer:** Convex + 1-homogeneous

(Promotes Sparsity)

$$R : X \rightarrow [0, \infty]$$

**Note:** Compactness assumptions  $\implies$  Minimizer exists

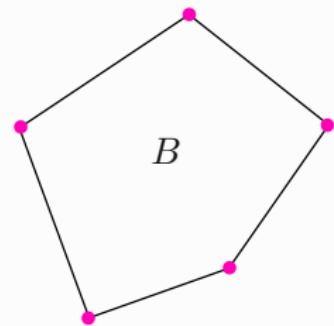
# Sparsity

**Unit Ball** of regularizer  $R$

$$B := \{u \in X : R(u) \leq 1\}$$

**Extremal Points:**  $u \in B$  s.t.

$$\begin{cases} u = \alpha u_1 + (1 - \alpha) u_2 \\ \alpha \in (0, 1), u_1, u_2 \in B \end{cases} \implies u = u_1 = u_2$$



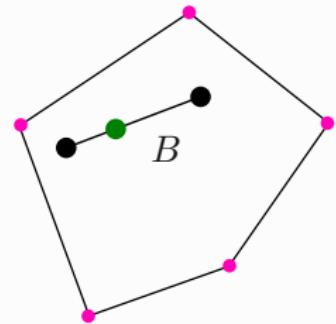
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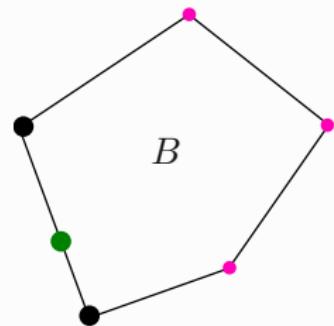
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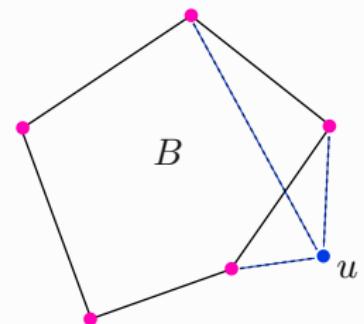
# Sparsity

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**Definition:**  $u \in X$  **sparse**

Conic combination

$$u = \sum_{i=1}^N \lambda_i u_i, \quad \lambda_i \geq 0, \quad u_i \in \text{Ext}(B)$$

# Main Task

Numerical **Algorithm** to compute  $\bar{u}$  solution of

$$\min_{u \in X} L(u) + R(u)$$

which is **sparse**

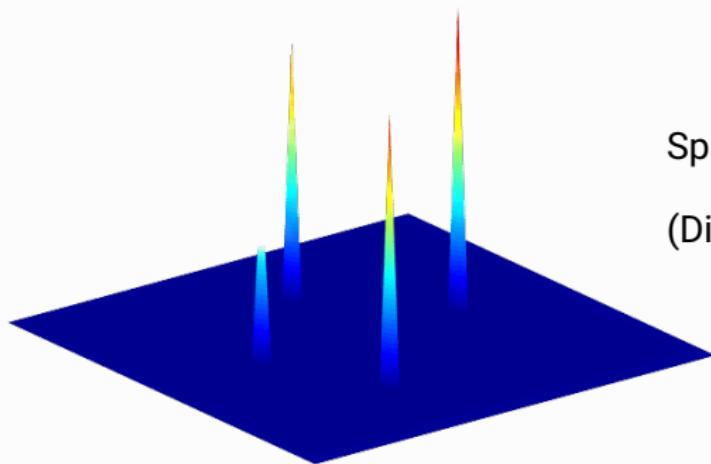
$$\bar{u} = \sum_{i=1}^N \lambda_i u_i, \quad \lambda_i \geq 0, \quad u_i \in \text{Ext}(B)$$

## Examples:

- ▶ Portfolio optimization  $\rightsquigarrow \mathbb{R}^d$
- ▶ Training 2-Layer Neural Networks  $\rightsquigarrow \mathcal{M}(\mathbb{R}^d)$  Radon Measures
- ▶ Microstructures in Materials  $\rightsquigarrow \text{BV}(\mathbb{R}^d)$  Bounded Variation

# Example: Radon Measures

Banach space:  $X = \mathcal{M}(\mathbb{R}^d)$  Radon measures



Sparse Source Identification  
(Diffusion-Advection Equation)

$$\mu = \sum_i \lambda_i \delta_{x_i}$$

Regularizer:  $R(\mu) := \|\mu\|_{\mathcal{M}}$  ,  $\text{Ext}(B) = \{\pm \delta_x : x \in \mathbb{R}^d\}$

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Figure from: Monge, Zuazua. **Systems & Control Letters** (2020)

# Sparse Algorithm

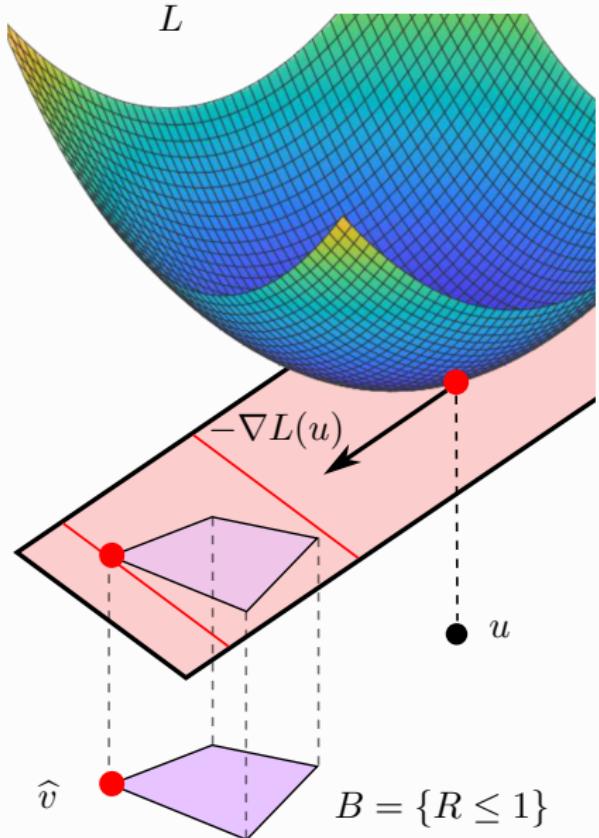
$$\min_{u \in X} G(u), \quad G := L + R$$

**Idea:** Gradient descent (Frank-Wolfe)

**Descent Direction:**  $\hat{v} \in B$

$$\hat{v} \in \arg \min_{v \in B} \langle \nabla L(u), v \rangle$$

**Lemma [1].**  $\hat{v} \in \text{Ext}(B)$

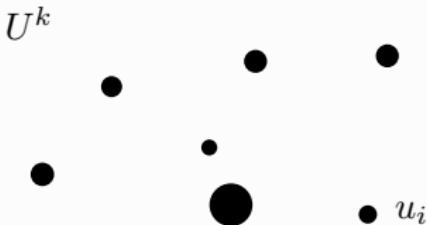


# Algorithm: Generalized Frank-Wolfe

Sparse  $k$ -th iterate

$$U^k = \sum_{i=1}^n \lambda_i u_i$$

$$\lambda_i \geq 0, \quad u_i \in \text{Ext}(B)$$

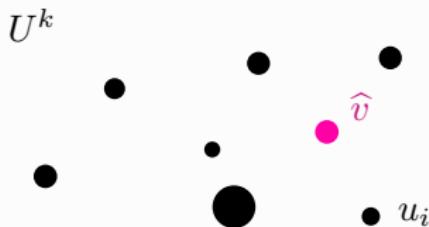


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① **Insertion Step:** Solve

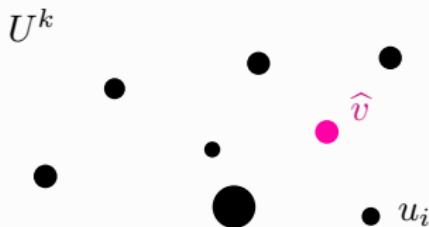
$$\hat{v} \in \arg \min_{v \in \text{Ext}(B)} \langle \nabla L(U^k), v \rangle$$

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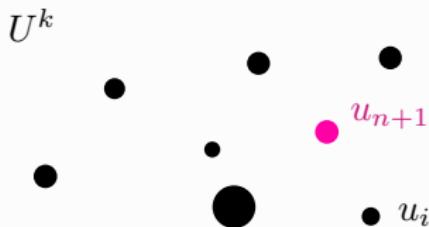
② **Correction Step:** Set  $u_{n+1} := \hat{v}$

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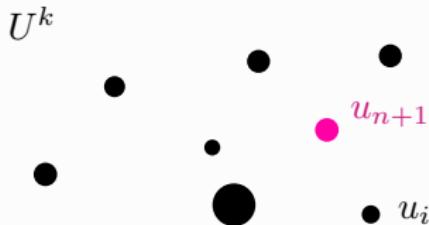
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② **Correction Step:** Set  $u_{n+1} := \hat{v}$ . Optimize coefficients

$$(\lambda_1^*, \dots, \lambda_{n+1}^*) \in \arg \min_{\lambda_i \geq 0} G \left( \sum_{i=1}^{n+1} \lambda_i u_i \right) \quad \leadsto \quad U^{k+1} := \sum_{i=1}^{n+1} \lambda_i^* u_i$$

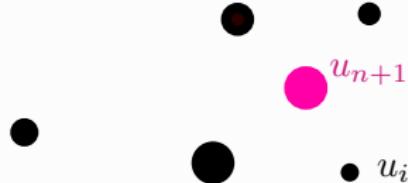
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$$U^k = \sum_{i=1}^n \lambda_i u_i$$

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$$U^{k+1}$$



① **Insertion Step:** Solve

$$\hat{v} \in \arg \min_{v \in \text{Ext}(B)} \langle \nabla L(U^k), v \rangle$$

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# Convergence Analysis

## Theorem [1]

$U^k$  sparse iterate generated by Algorithm. Then

$$U^k \xrightarrow{*} \bar{u}, \quad \bar{u} \in \arg \min G, \quad G := L + R$$

General convergence is **sublinear**

$$G(U^k) - \min G \lesssim \frac{1}{k}$$

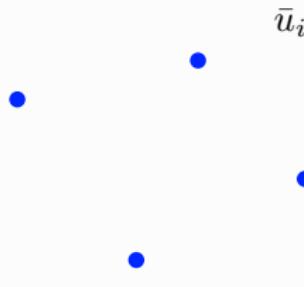
**Highlight:**  $\bar{u}$  **sparse** + “**source condition**”  $\implies$  **linear** convergence

$$G(U^k) - \min G \lesssim \frac{1}{2^k}$$

# Fast Convergence Assumptions

① Minimizer is **sparse**

$$\bar{u} = \sum_{i=1}^M \bar{\lambda}_i \bar{u}_i , \quad \bar{u}_i \in \text{Ext}(B)$$



② **Source condition:** dual variable

$$\bar{p} := -\nabla L(\bar{u})$$

is maximized exactly at  $\bar{u}_i$

$$\arg \max_{v \in \text{Ext}(B)} \langle \bar{p}, v \rangle = \{\bar{u}_1, \dots, \bar{u}_M\}$$



**Note:**

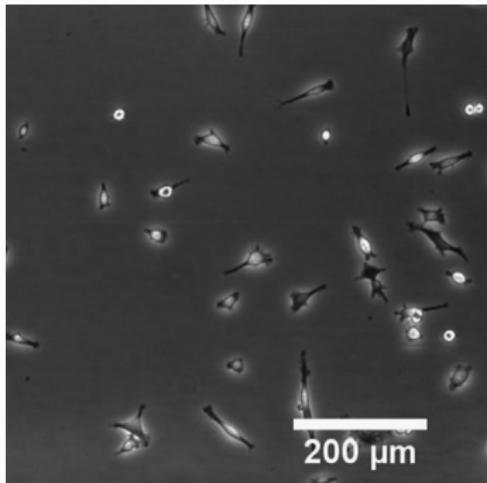
- ▶ Verifiable a posteriori
- ▶ Proven in some cases

# Application: Particle Tracking

Imaging Method



- ▶ Stars from ground-based telescope
- ▶ Microbubbles in blood vessels
- ▶ Cell migration



Microscopy image of cells

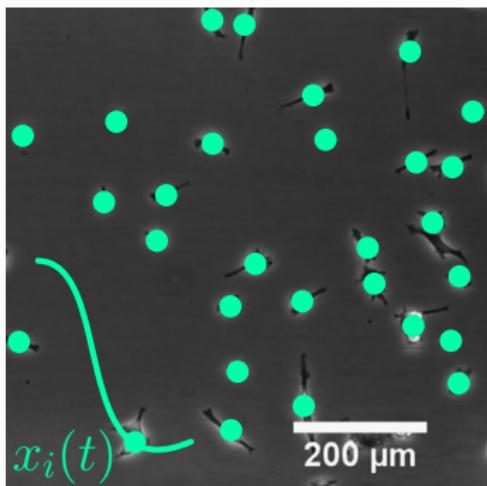
Image from: Yang, Venkataraman, Styles, et al. **Journal of Biomechanics** (2016)

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$\implies$

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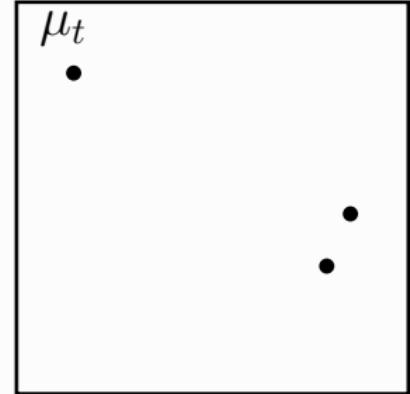
$$\mu_t = \sum_{i=1}^M \delta_{x_i(t)}$$

Image from: Yang, Venkataraman, Styles, et al. **Journal of Biomechanics** (2016)

# Magnetic Resonance Imaging (MRI)



$y_t$

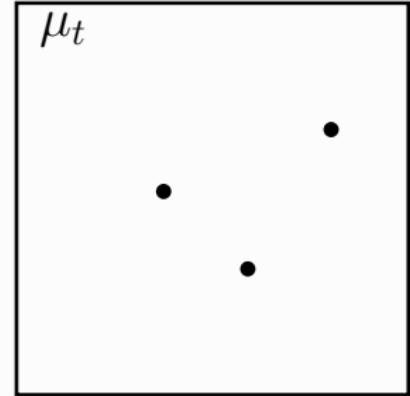


**Frame-by-Frame:** MRI Data  $y_t \rightsquigarrow$  Image  $\mu_t$

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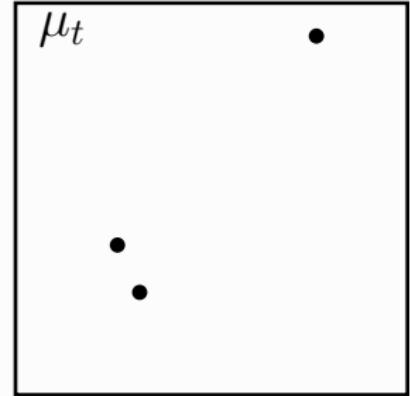


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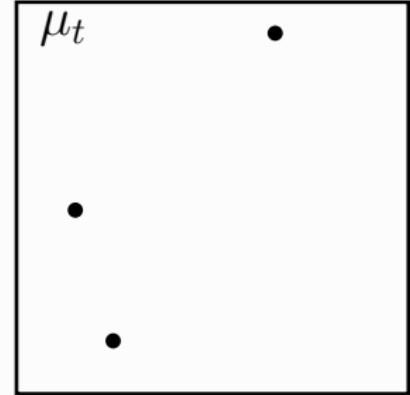


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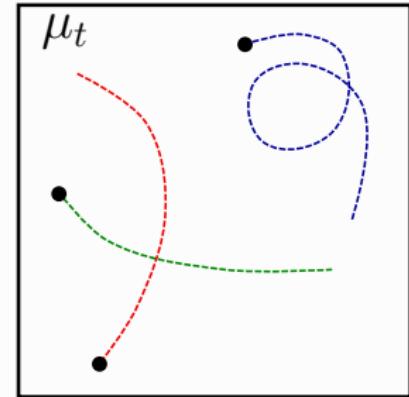


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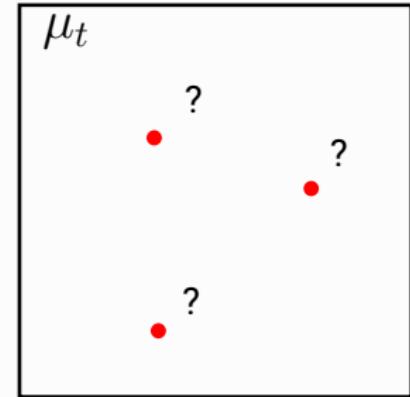


**Frame-by-Frame:** MRI Data  $y_t \rightsquigarrow$  Image  $\mu_t \implies$  Interpolate Trajectories

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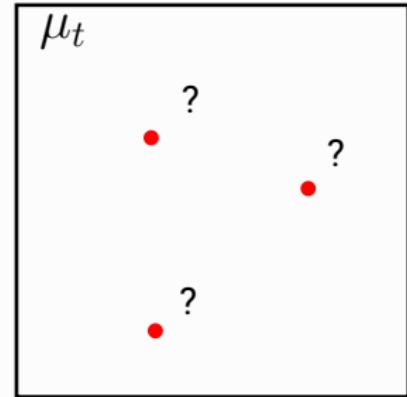
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Motion  $\implies$  Ultra-Low Scan Time  $\implies$  **Ultra-Low Data**  $y_t \rightsquigarrow$  **Particles?**

# Magnetic Resonance Imaging (MRI)



$y_t$



**Frame-by-Frame:** MRI Data  $y_t \rightsquigarrow$  Image  $\mu_t \implies$  Interpolate Trajectories

Motion  $\implies$  Ultra-Low Scan Time  $\implies$  **Ultra-Low Data**  $y_t \rightsquigarrow$  **Particles?**

**Global-in-Time:** Full Time-Series  $t \mapsto y_t \rightsquigarrow$  Trajectories  $t \mapsto \mu_t$

# Motion-Aware Regularization

**Video:** Curve of measures

$$t \mapsto \mu_t \in \mathcal{M}(\mathbb{R}^2), \quad t \in [0, 1]$$

**Assumptions:**

- $\mu_t$  satisfies **Continuity Equation**

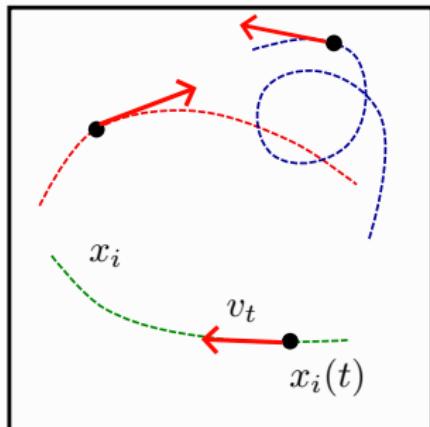
$$\partial_t \mu_t + \operatorname{div}(v_t \mu_t) = 0$$

for some velocity field (to find)

$$v_t : \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

- Finite **Kinetic Energy**

$$\int_0^1 \int_{\mathbb{R}^2} |v_t(x)|^2 d\mu_t(x) dt < \infty$$



$$\mu_t = \sum_i \delta_{x_i(t)}$$

# Motion-Aware Regularization

**Minimization Problem:** Given MRI data  $t \mapsto y_t$

$$\min_{\mu, v} L(\mu) + R(\mu, v)$$

- $L \rightsquigarrow$  **Loss Function:** Fits  $t \mapsto \mu_t$  to given MRI data  $t \mapsto y_t$
- $R \rightsquigarrow$  **Regularizer:**

$$R(\mu, v) := \underbrace{\int_0^1 \int_{\mathbb{R}^2} |v_t(x)|^2 d\mu_t(x) dt}_{\text{Kinetic Energy}} \quad \text{s.t. } \partial_t \mu_t + \operatorname{div}(v_t \mu_t) = 0$$

# Extremal Points

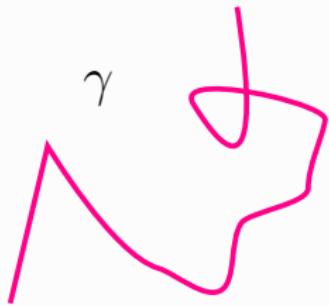
$$R(\mu, v) := \int_0^1 \int_{\mathbb{R}^2} |v_t(x)|^2 d\mu_t(x) dt \quad \text{s.t.} \quad \partial_t \mu_t + \operatorname{div}(v_t \mu_t) = 0$$

## Theorem [3]

Let  $B = \{R \leq 1\}$ . Then  $\operatorname{Ext}(B)$  are measures

$t \mapsto \mu_t$  supported on **Sobolev Curves**

$$t \mapsto \mu_t = \delta_{\gamma(t)}, \quad \gamma \in H^1([0, 1]; \mathbb{R}^2)$$



**Proof Idea:** Probabilistic Superposition Principle  
for measure solutions to

$$\partial_t \mu_t + \operatorname{div}(v_t \mu_t) = 0 \quad (= g_t \mu_t)$$

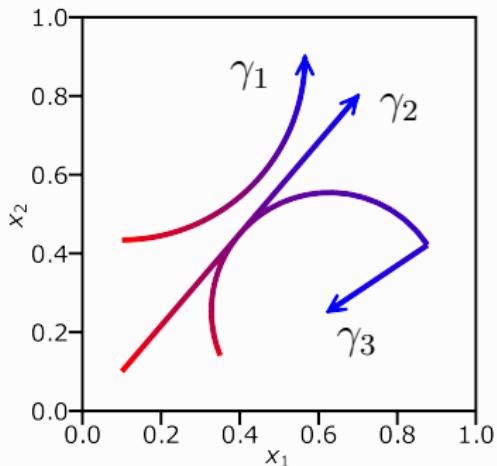
[3] Bredies, Carioni, **Fanzon**, Romero. **Bulletin London Mathematical Society** (2021)

[4] Bredies, Carioni, **Fanzon**. **Communications in PDEs** (2022)

# Reconstructions

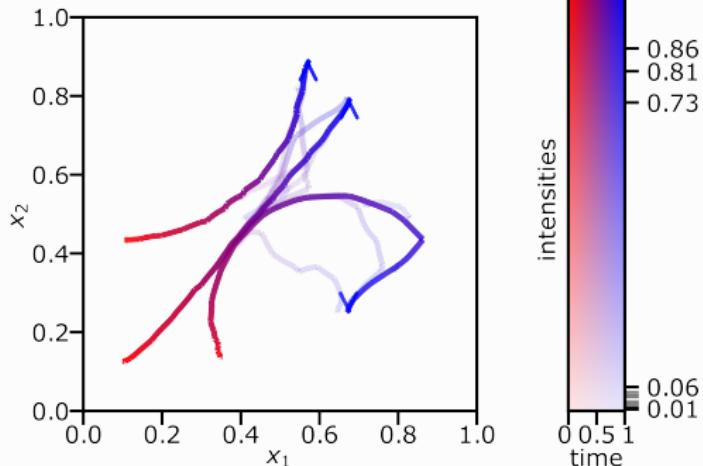
Algorithm: Generalized Frank-Wolfe

$$\leadsto t \mapsto \mu_t^k = \sum_{i=1}^M \lambda_i \delta_{\gamma_i(t)}$$



Real Trajectories

$$\bar{\mu}_t = \delta_{\gamma_1(t)} + \delta_{\gamma_2(t)} + \delta_{\gamma_3(t)}$$



Reconstruction

$$\text{MRI Data } t \mapsto y_t$$

# Conclusion

- ① Algorithm for computing **sparse** solutions to

$$\min_{u \in X} L(u) + R(u)$$

- ② **Fast** convergence when solution is **sparse**

- ③ Application to **particles tracking**

Thank You!

# References

## Sparse optimization Algorithm

- [1] Bredies, Carioni, **Fanzon**, Walter. **Mathematical Programming** (2023)

## Particles Tracking

- [2] **Fanzon**, Bredies. **ESAIM: Mathematical Modelling and Numerical Analysis** (2020)
- [3] Bredies, Carioni, **Fanzon**, Romero. **Bulletin London Mathematical Society** (2021)
- [4] Bredies, Carioni, **Fanzon**. **Communications in PDEs** (2022)
- [5] Bredies, Carioni, **Fanzon**, Romero. **Found. of Computational Mathematics** (2022)