

# **ADA8**

# **SPARSITY TUTORIAL**

Samuel Farrens

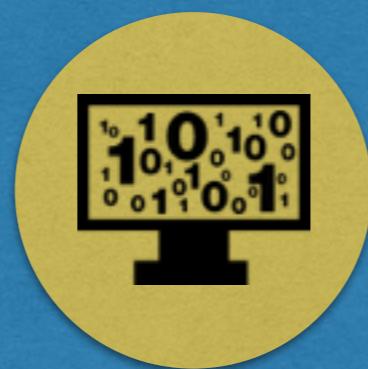
22nd May 2016 - Xaviá



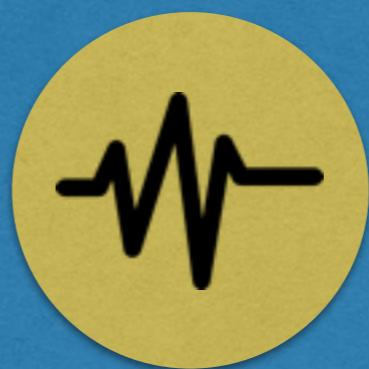
# OVERVIEW



Inverse  
Problems



Sparsity



Wavelets



Blind Source  
Separation



# Inverse Problems

# INVERSE PROBLEMS

Data      →      Model Parameters

$$Y = MX$$

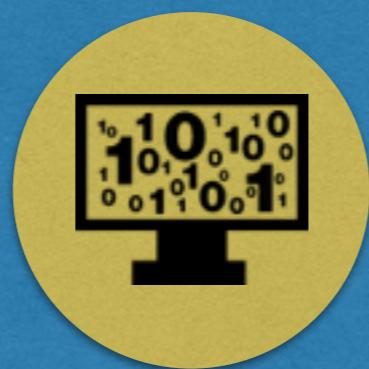
$$X = M^{-1}Y$$

$$X = (M^T M)^{-1} M^T Y$$

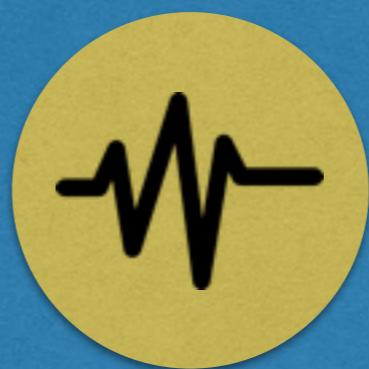
# OVERVIEW



Inverse  
Problems



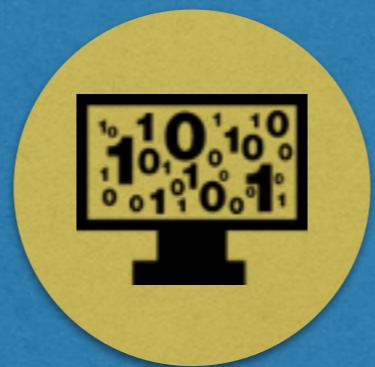
Sparsity



Wavelets



Blind Source  
Separation

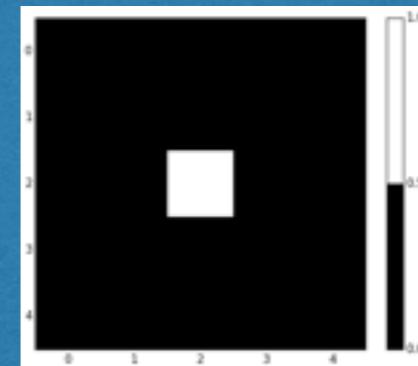


Sparsity

# SPARSITY

A sparse signal is one comprised mostly of zeros.

$$X = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$



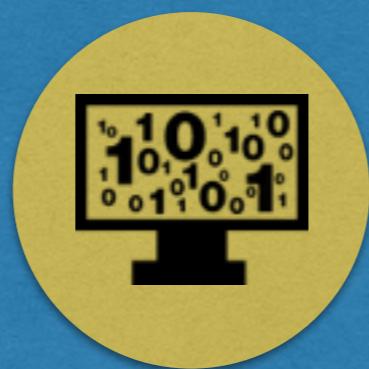
A signal maybe sparse in a different domain.

$$X = \begin{bmatrix} 0.04 & -0.032 & 0.012 & 0.012 & -0.032 \\ -0.032 & 0.012 & 0.012 & -0.032 & 0.04 \\ 0.012 & 0.012 & -0.032 & 0.04 & -0.032 \\ 0.012 & -0.032 & 0.04 & -0.032 & 0.012 \\ -0.032 & 0.04 & -0.032 & 0.012 & 0.012 \end{bmatrix} \rightarrow \mathcal{F}(X) = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0.5 & 0 & 0 \\ 0 & 0 & 0 & 0.5 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

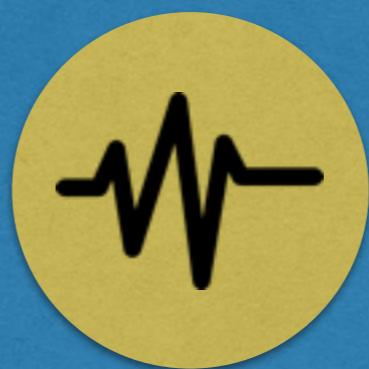
# OVERVIEW



Inverse  
Problems



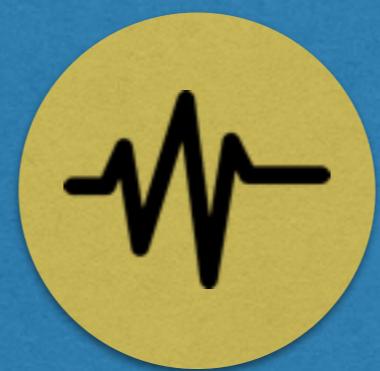
Sparsity



Wavelets



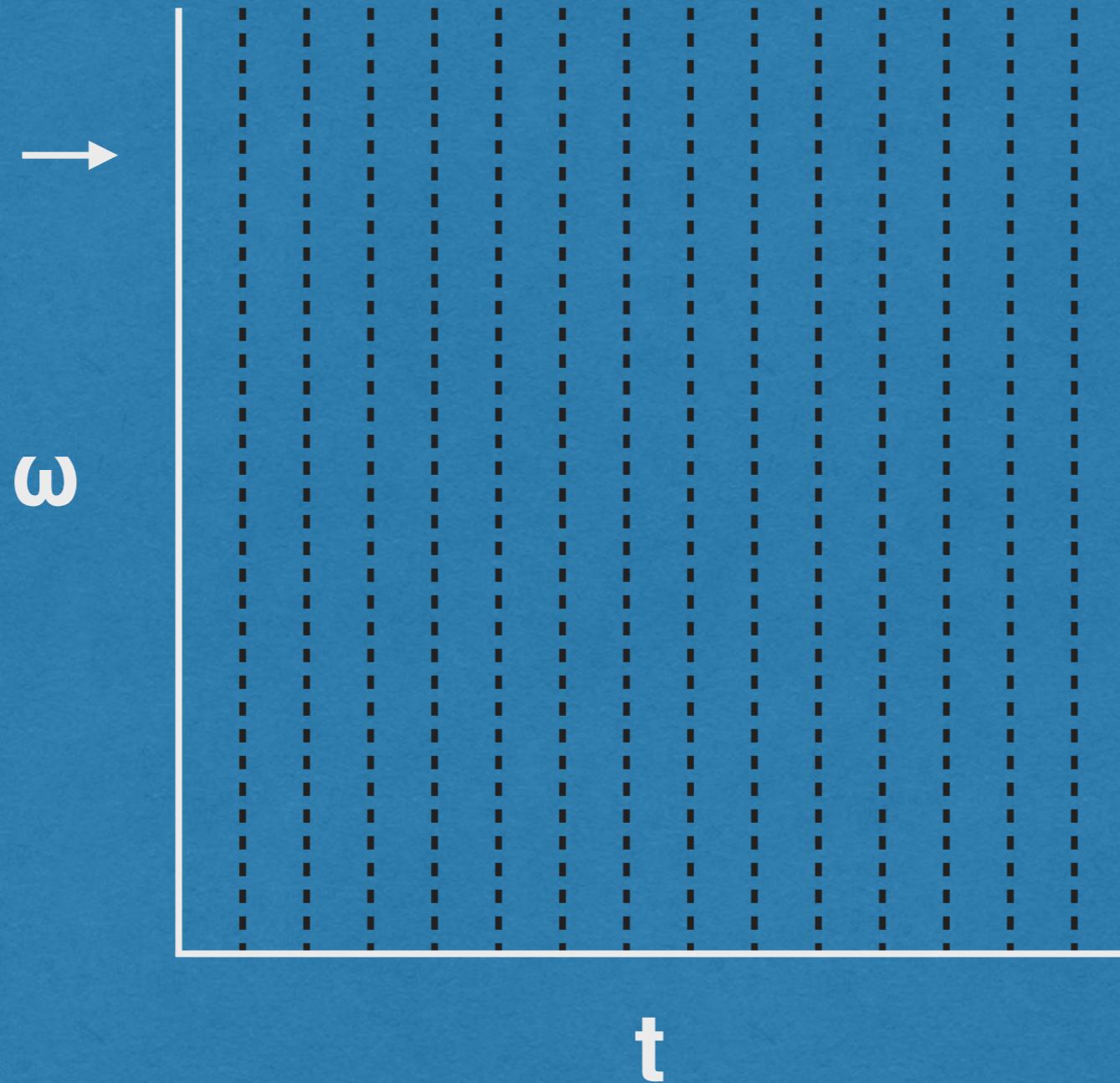
Blind Source  
Separation



Wavelets

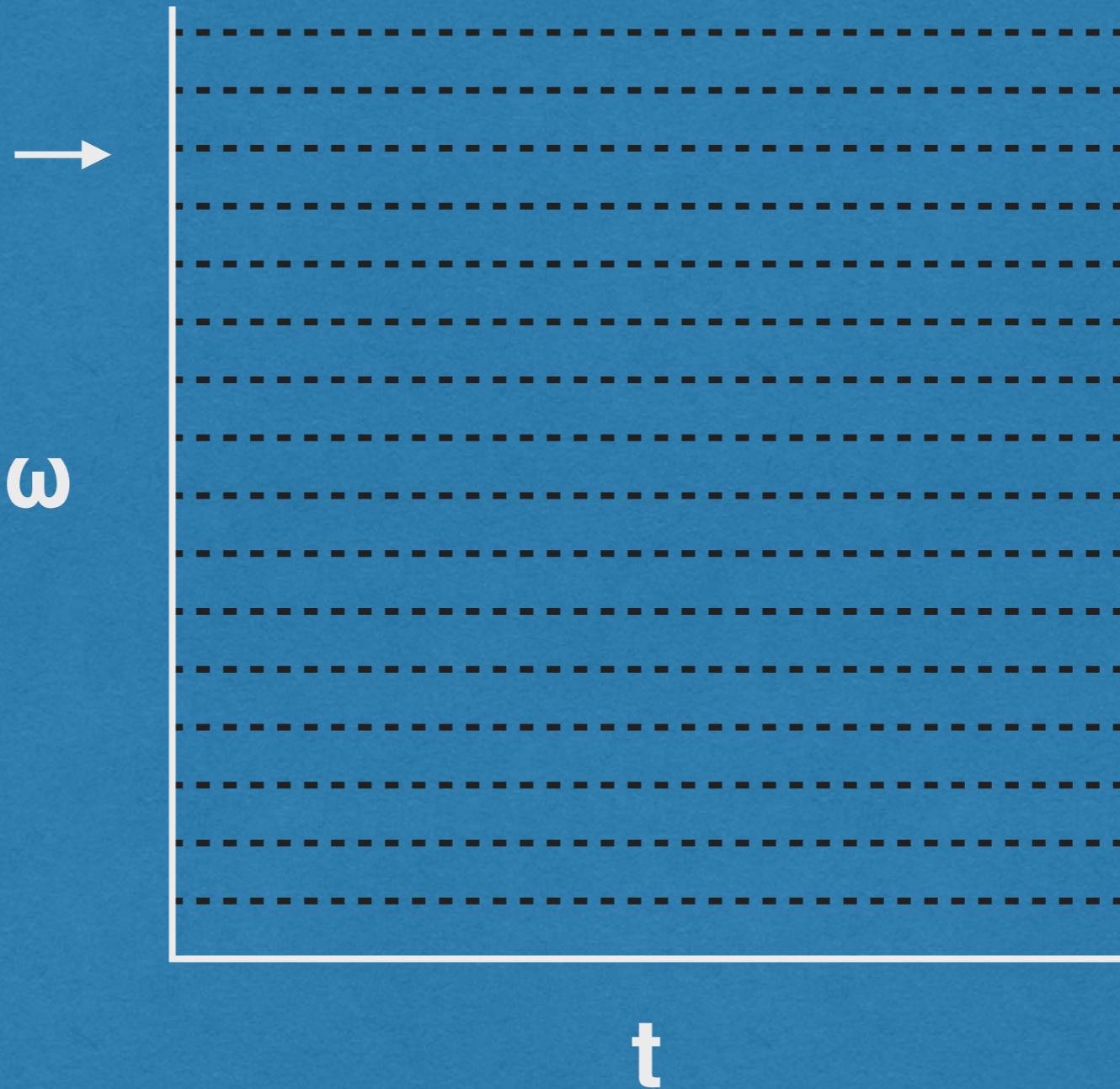
# WAVELETS

No frequency  
information



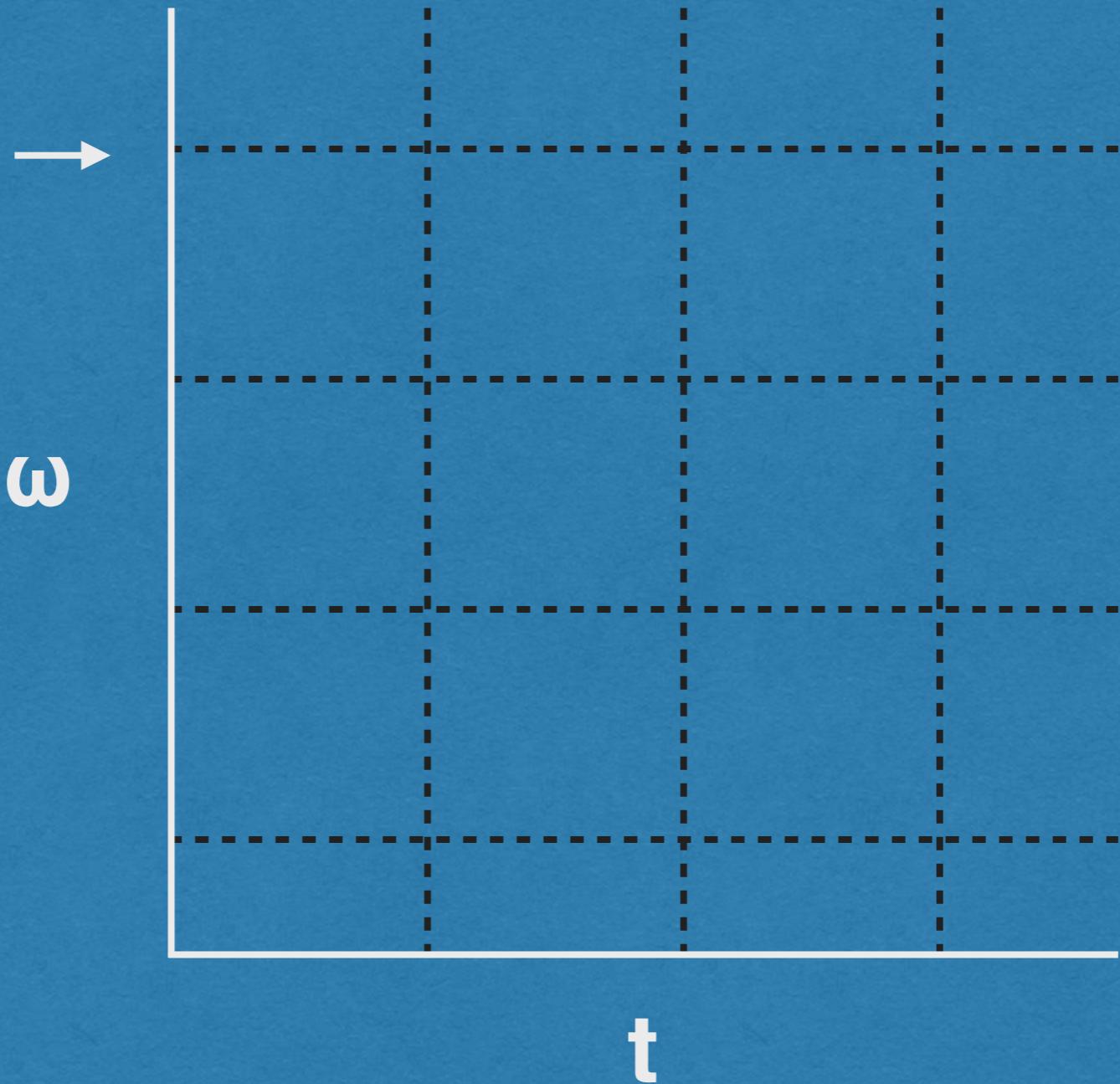
# WAVELETS

No time  
information



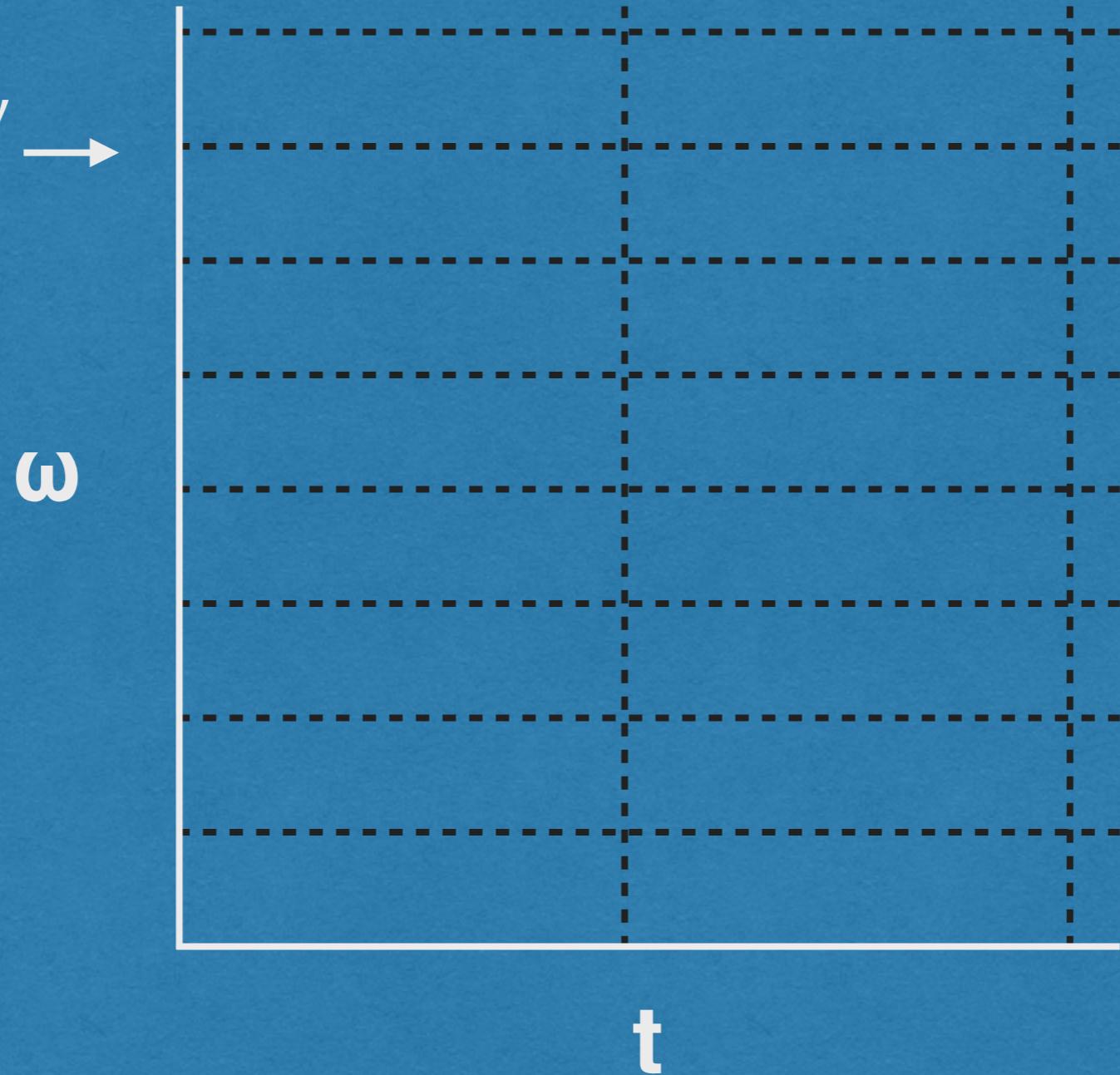
# WAVELETS

Some time and  
frequency  
information

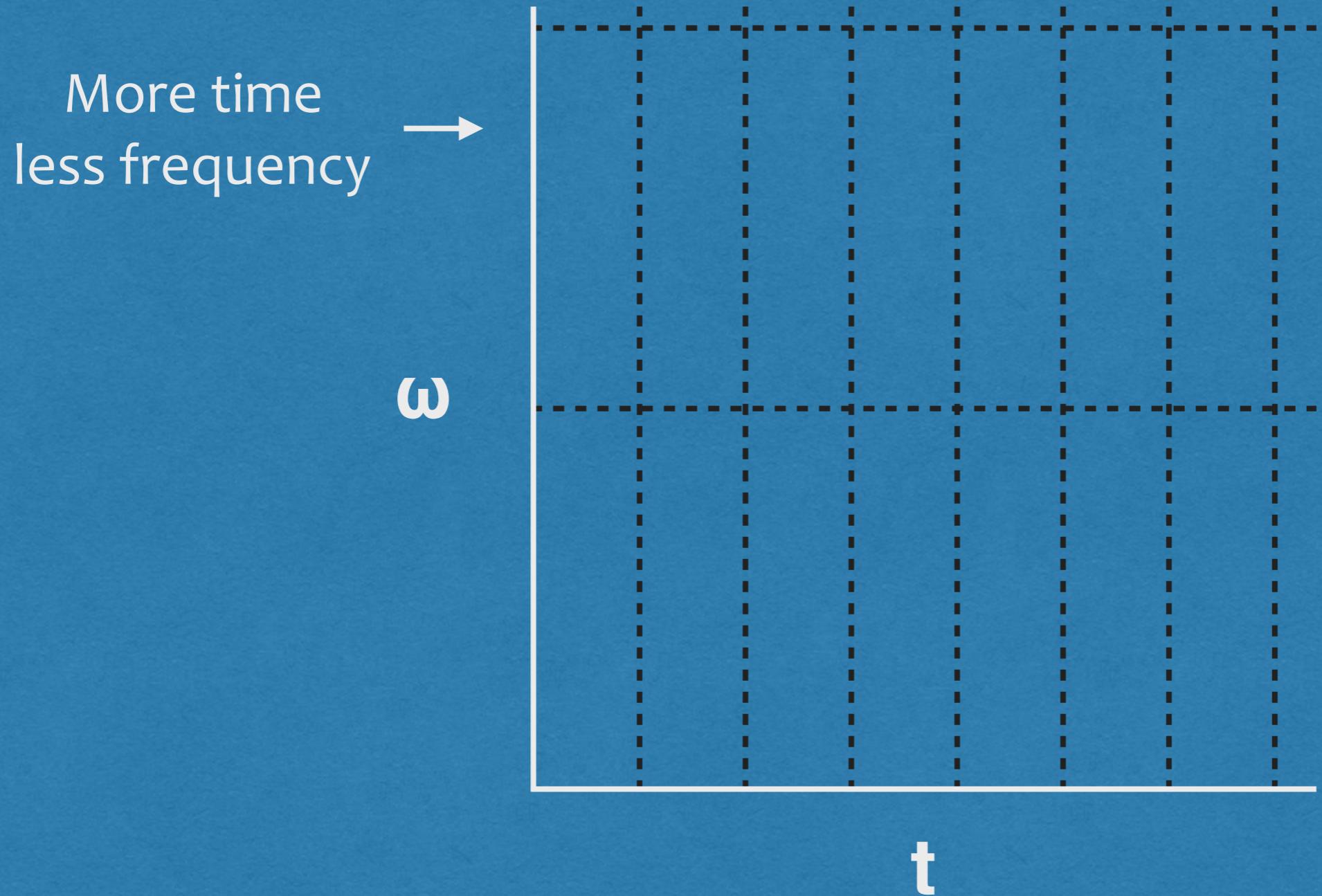


# WAVELETS

More frequency  
less time

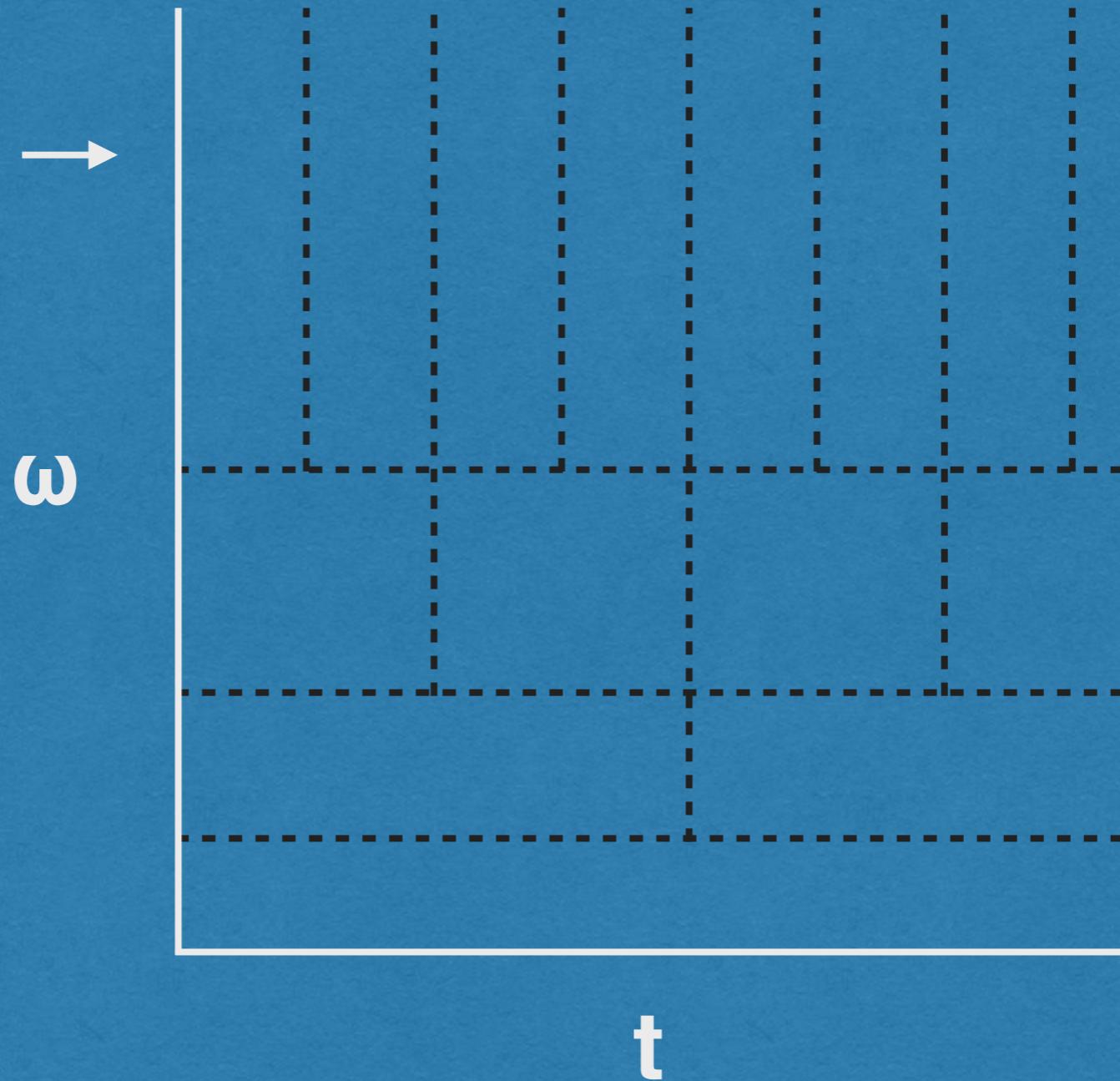


# WAVELETS



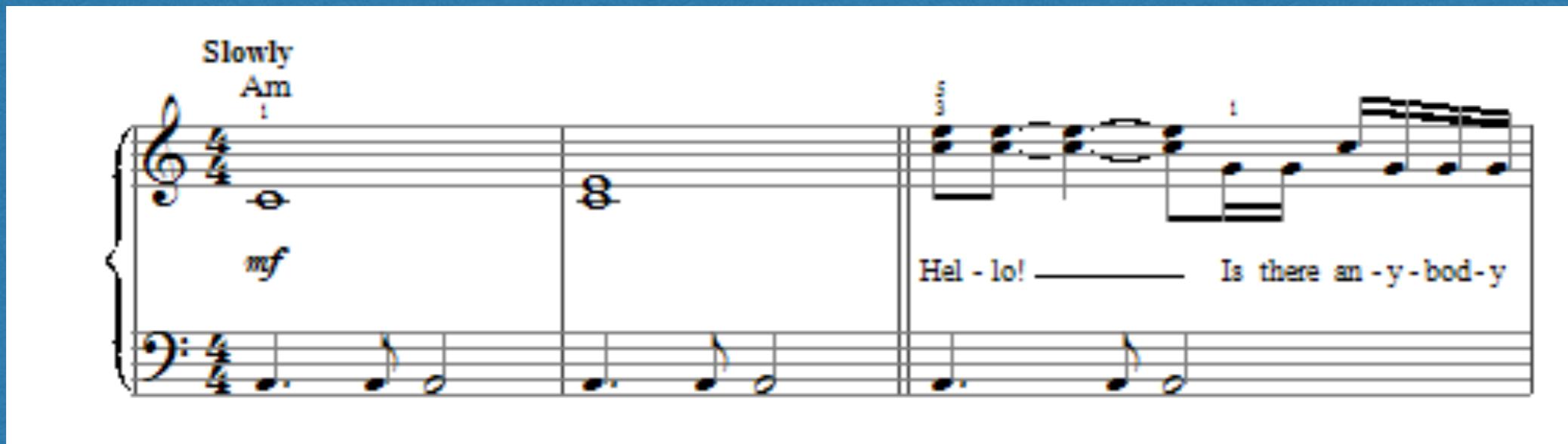
# WAVELETS

Multiesolution  
Analysis



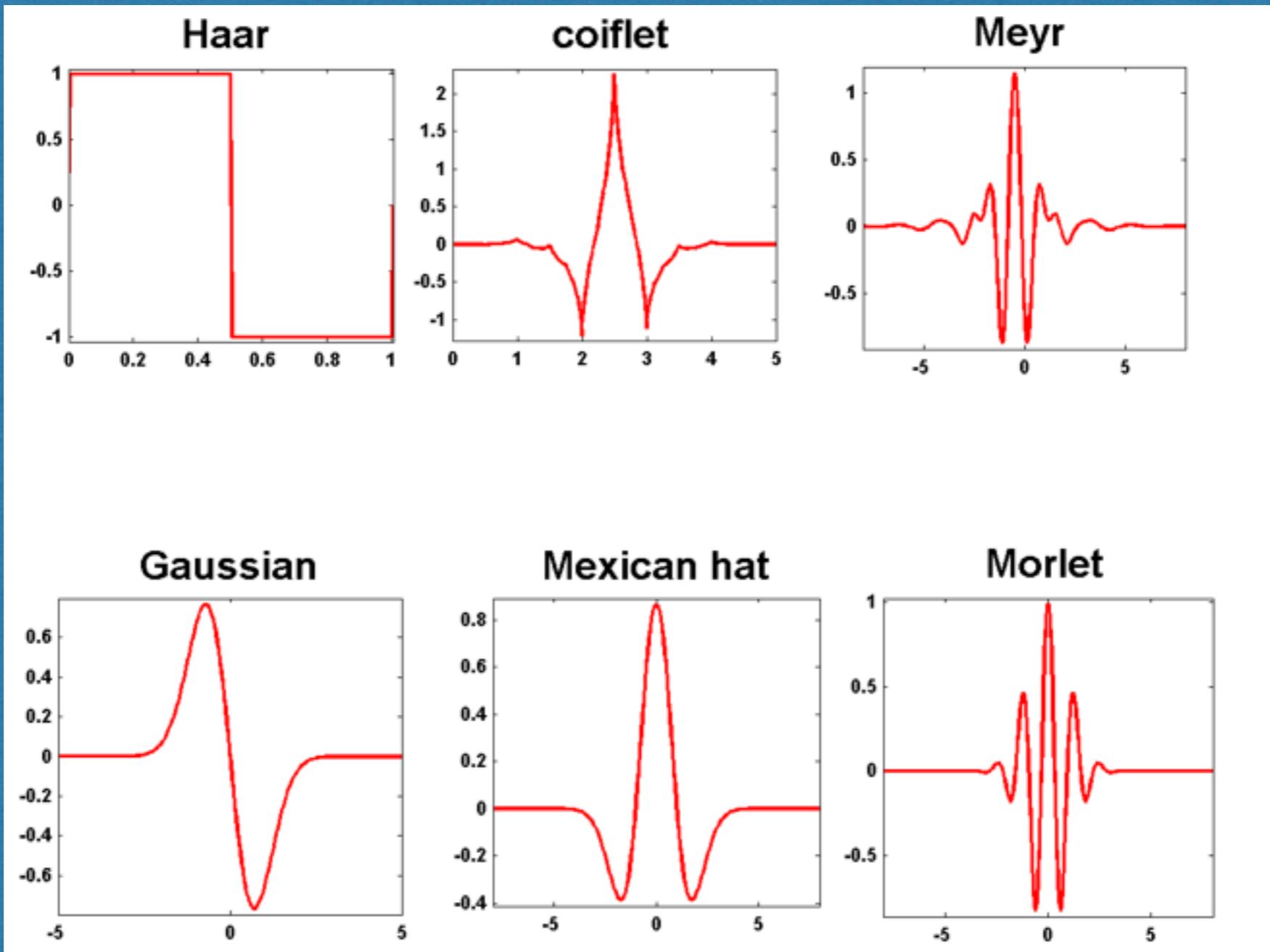
# WAVELETS

## Time-Frequency Trade-Off



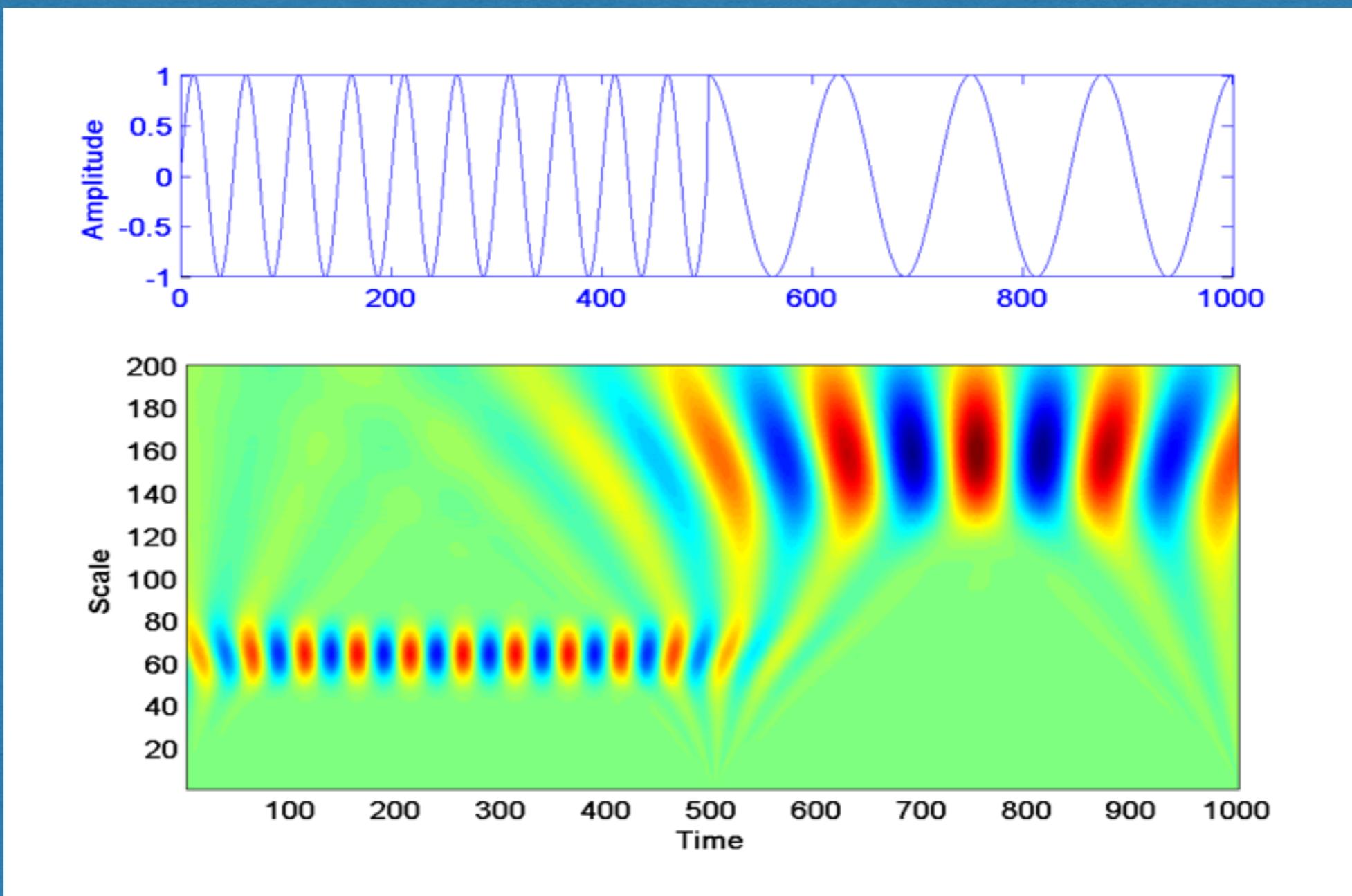
# WAVELETS

## Wavelet Shapes

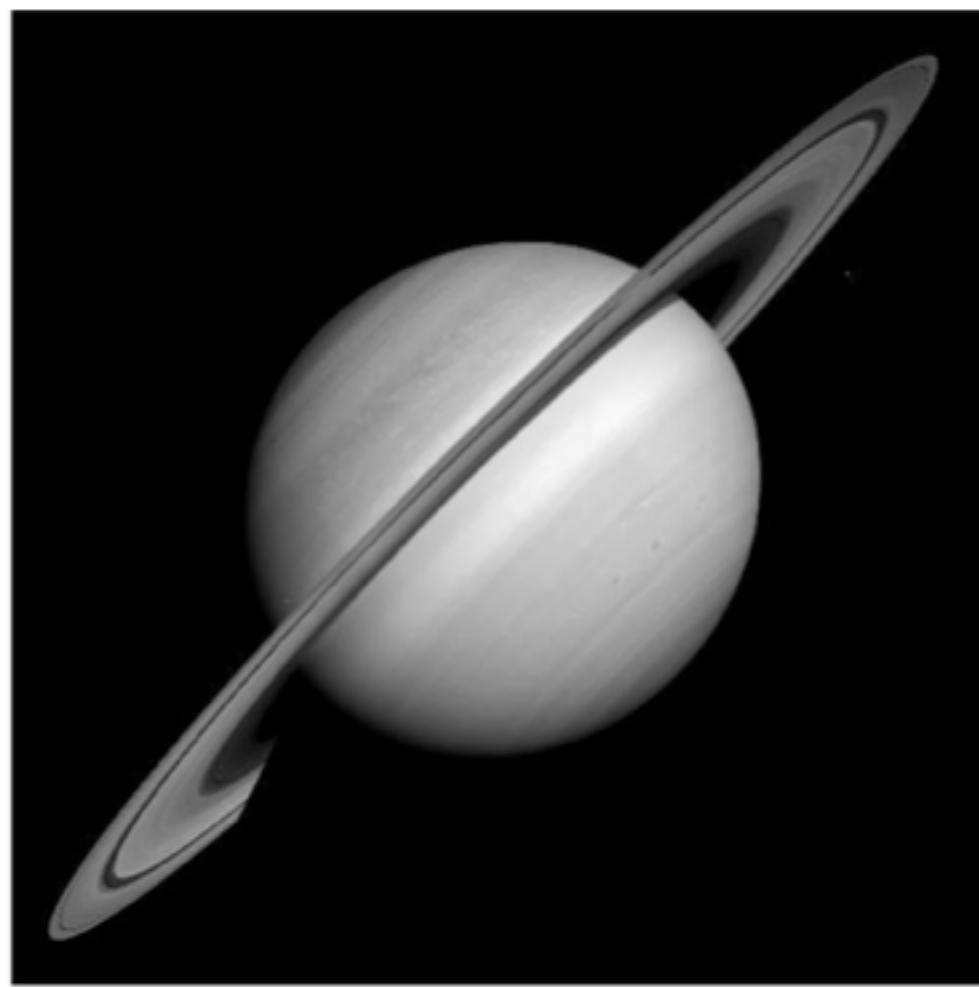


# WAVELETS

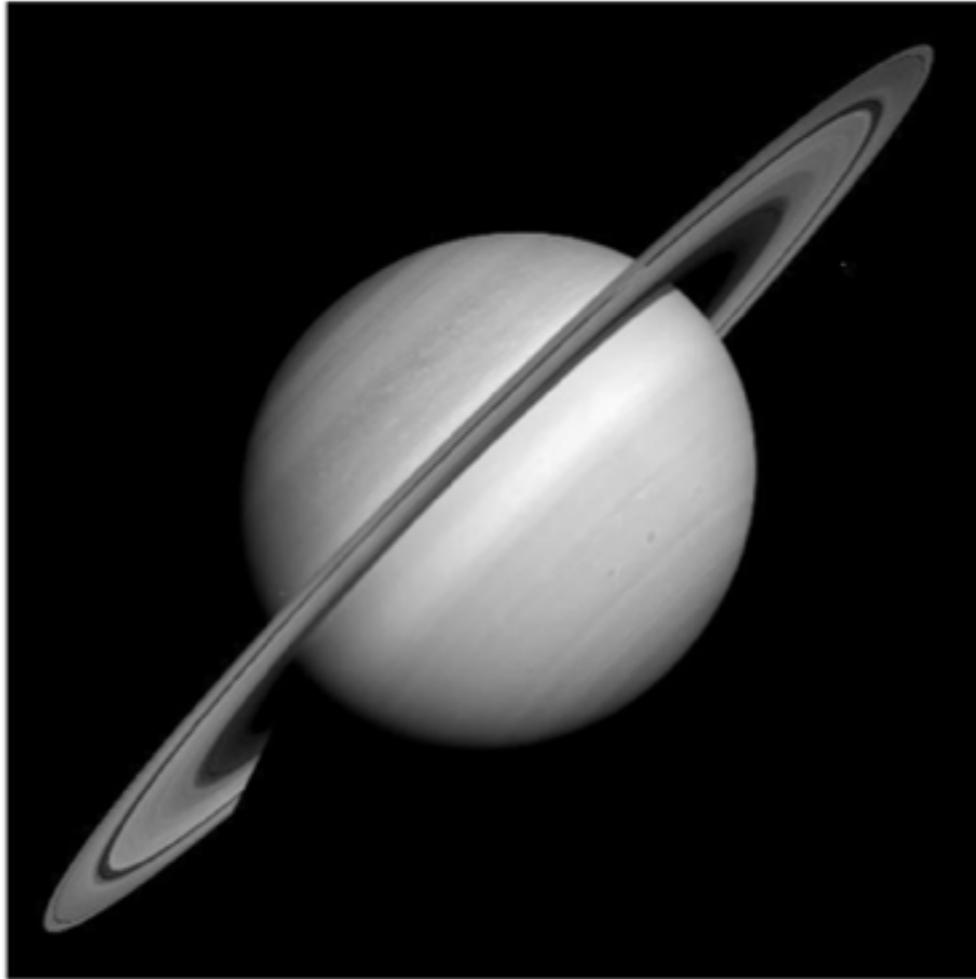
## Spectrogram



# WAVELETS



# WAVELETS

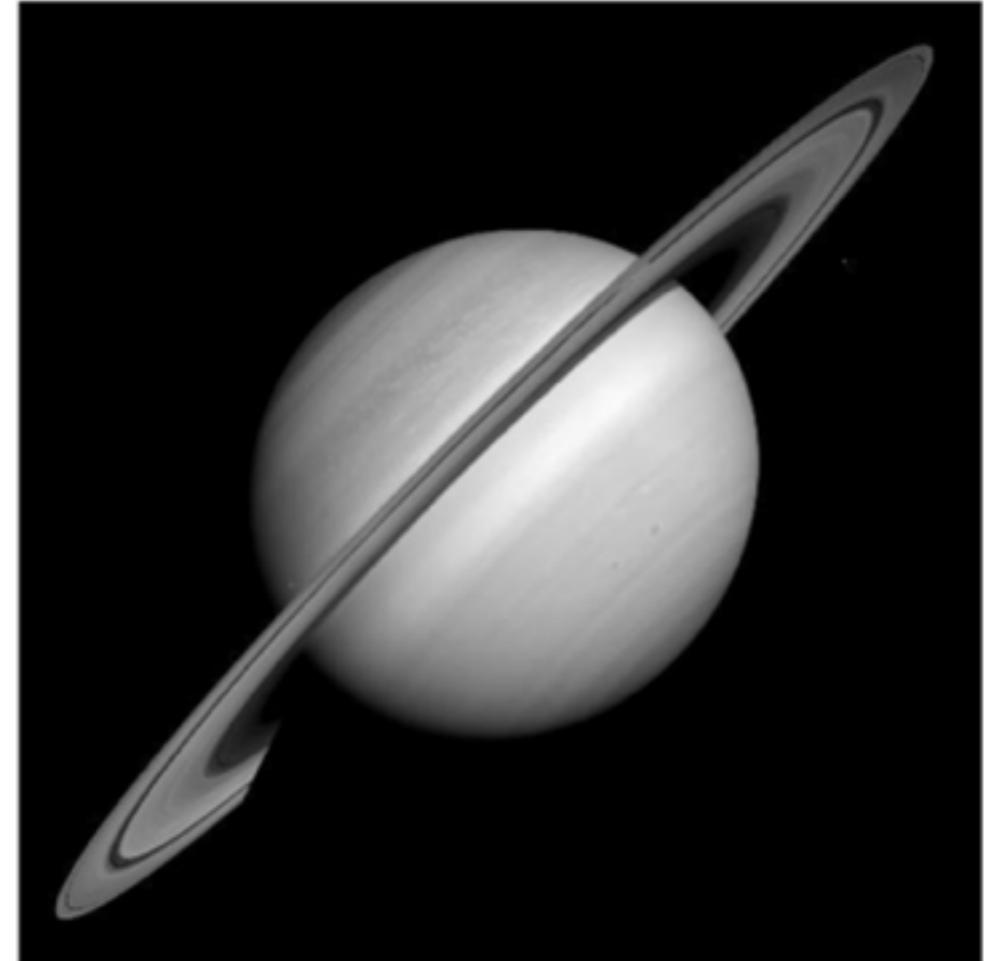
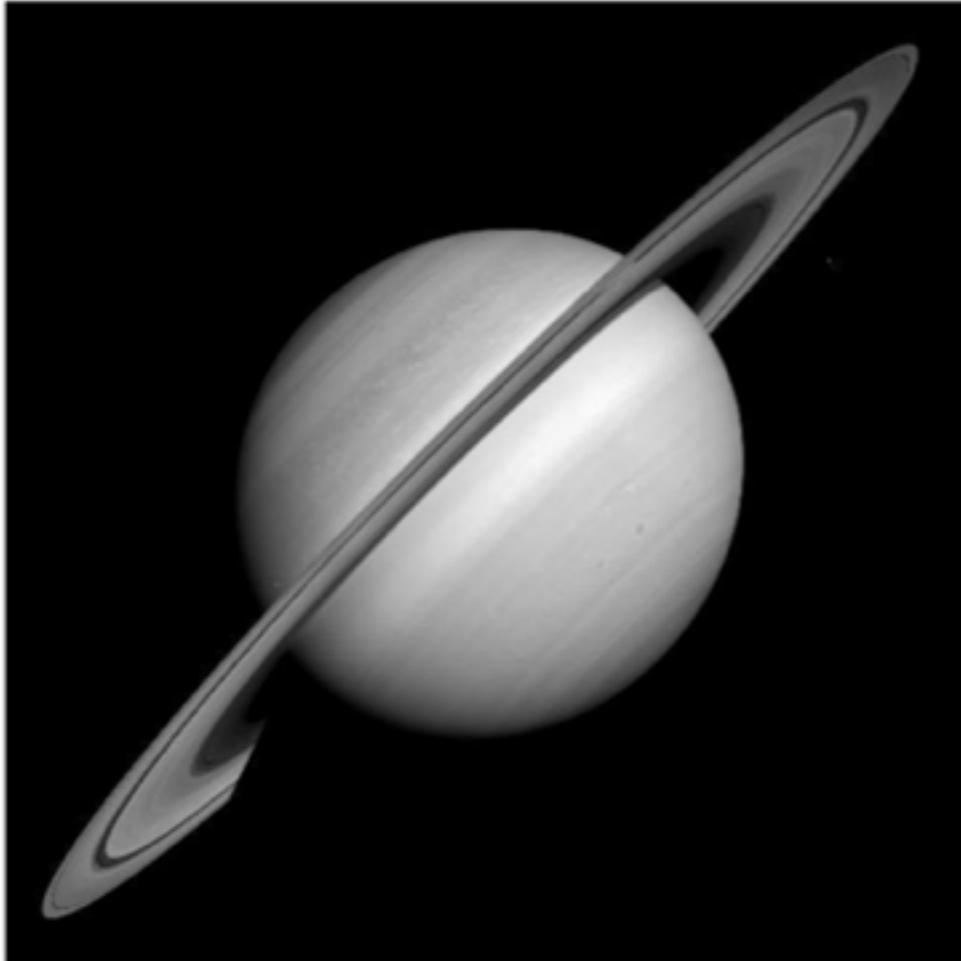


The top 1% of the  
coefficients concentrate  
only 8.66% of the energy.  
Not sparse...



1% largest coefficients in real space  
(the others are set to 0)

# WAVELETS



**1% of the wavelet coefficients  
concentrate 99.96% of the energy:  
This can be used as a *prior*.**

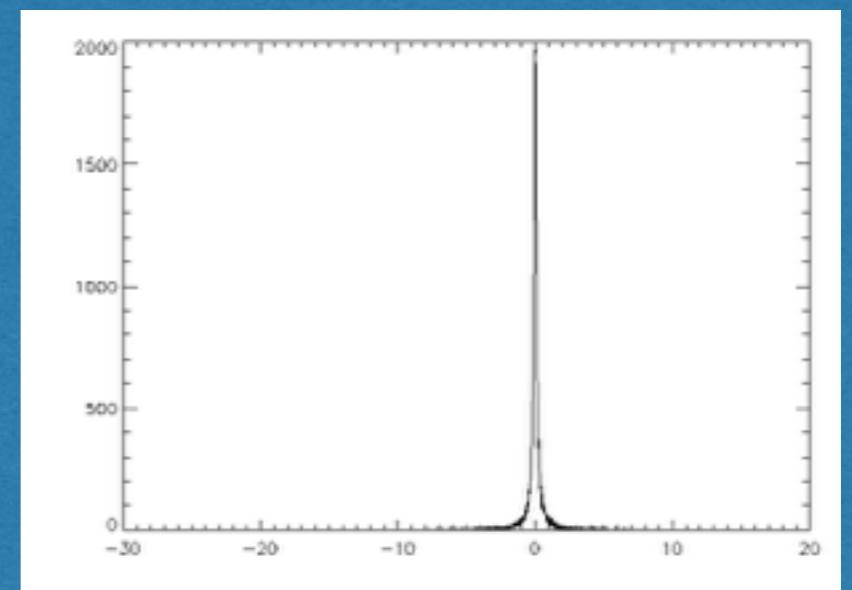
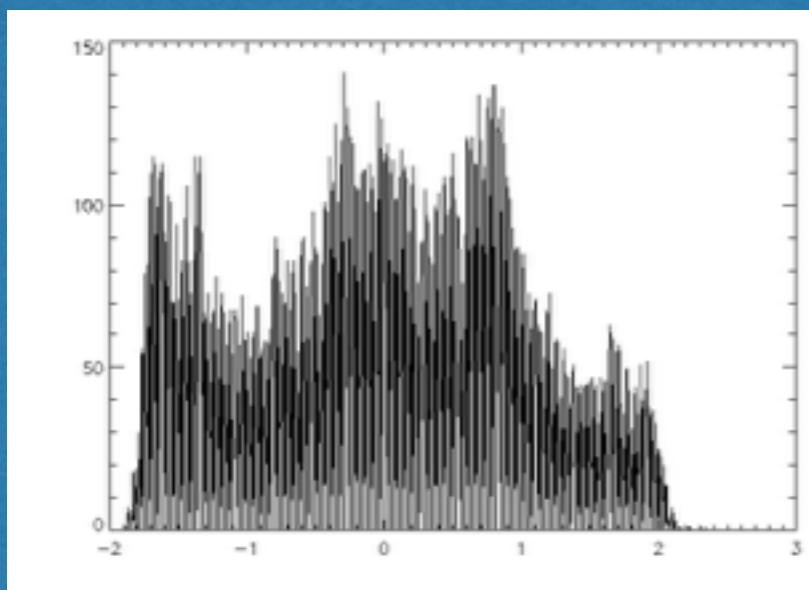
Reconstruction, after throwing away  
99% of the wavelet coefficients

# WAVELETS

Direct Space



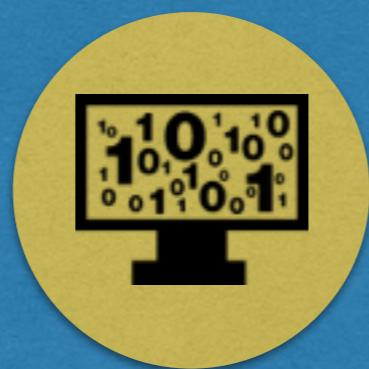
Curvelet Space



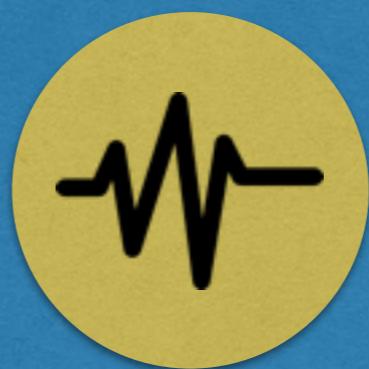
# OVERVIEW



Inverse  
Problems



Sparsity



Wavelets



Blind Source  
Separation



Blind Source  
Separation

# BLIND SOURCE SEPARATION

## Definition

Blind source separation (BSS) is the separation of a set of source signals from a set of mixed signals, with little to no information about the source signals or the mixing process.

This technique is used in various fields such as astrophysics, biology, biomedicine, chemistry, geology, physics, remote sensing, ...

# BLIND SOURCE SEPARATION

## Electrocardiography (ECG)

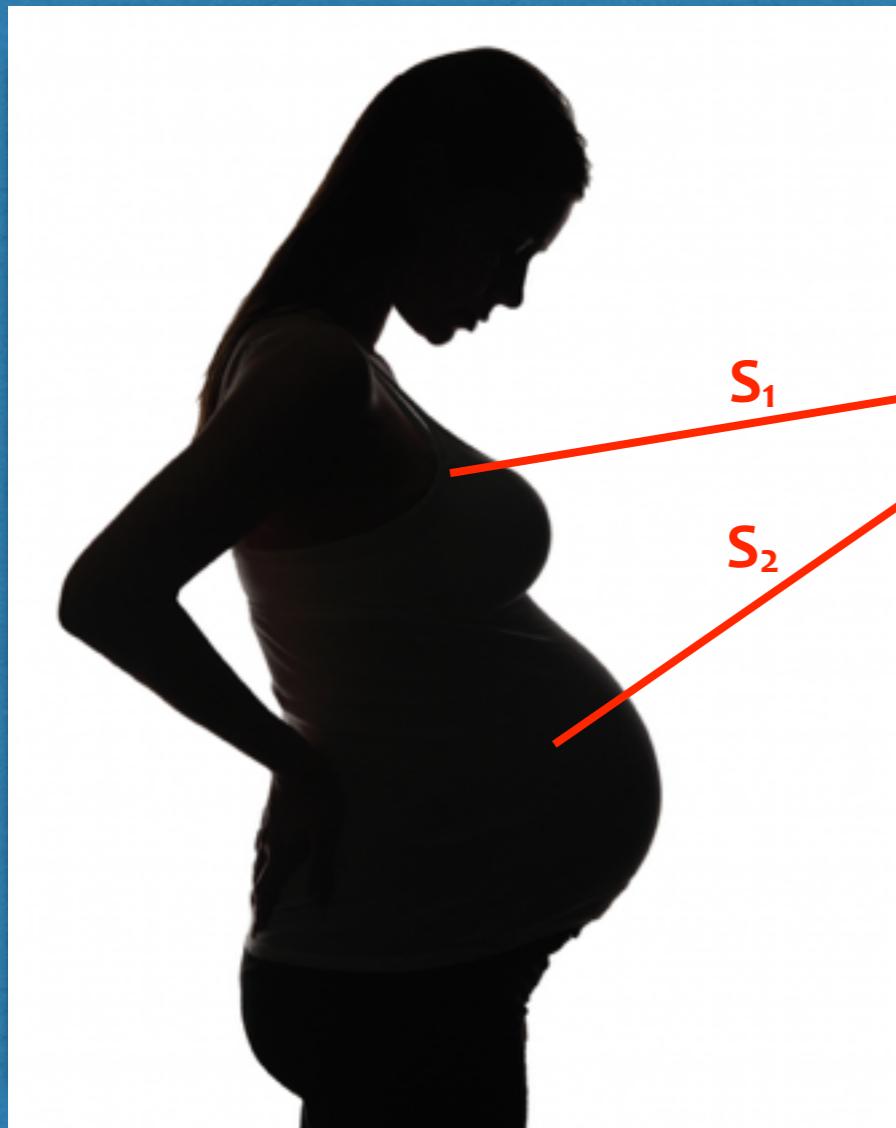


Extract the pulse of a foetus



# BLIND SOURCE SEPARATION

## Electrocardiography (ECG)

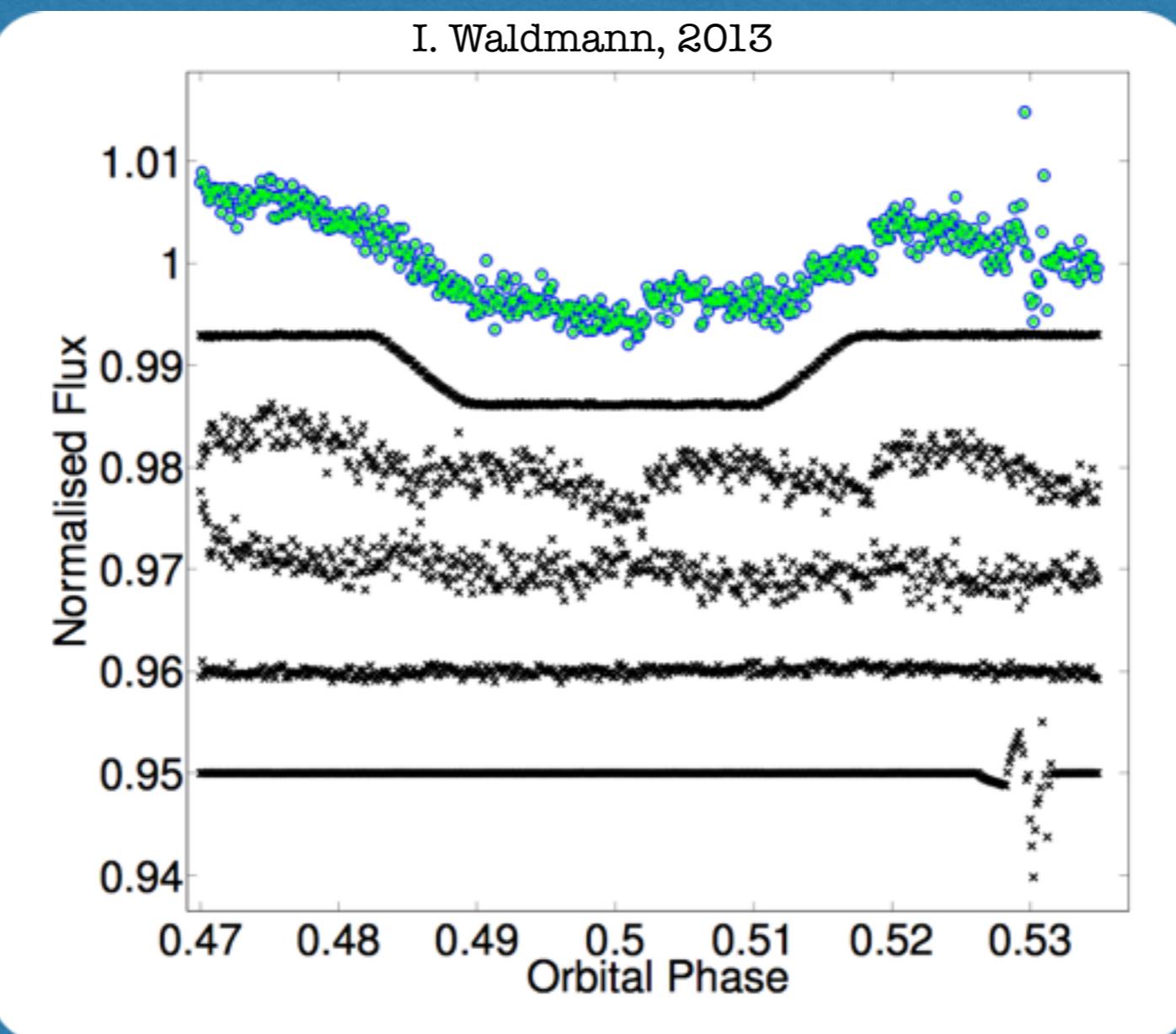


Extract the pulse of a foetus



# BLIND SOURCE SEPARATION

## Exoplanet Analysis



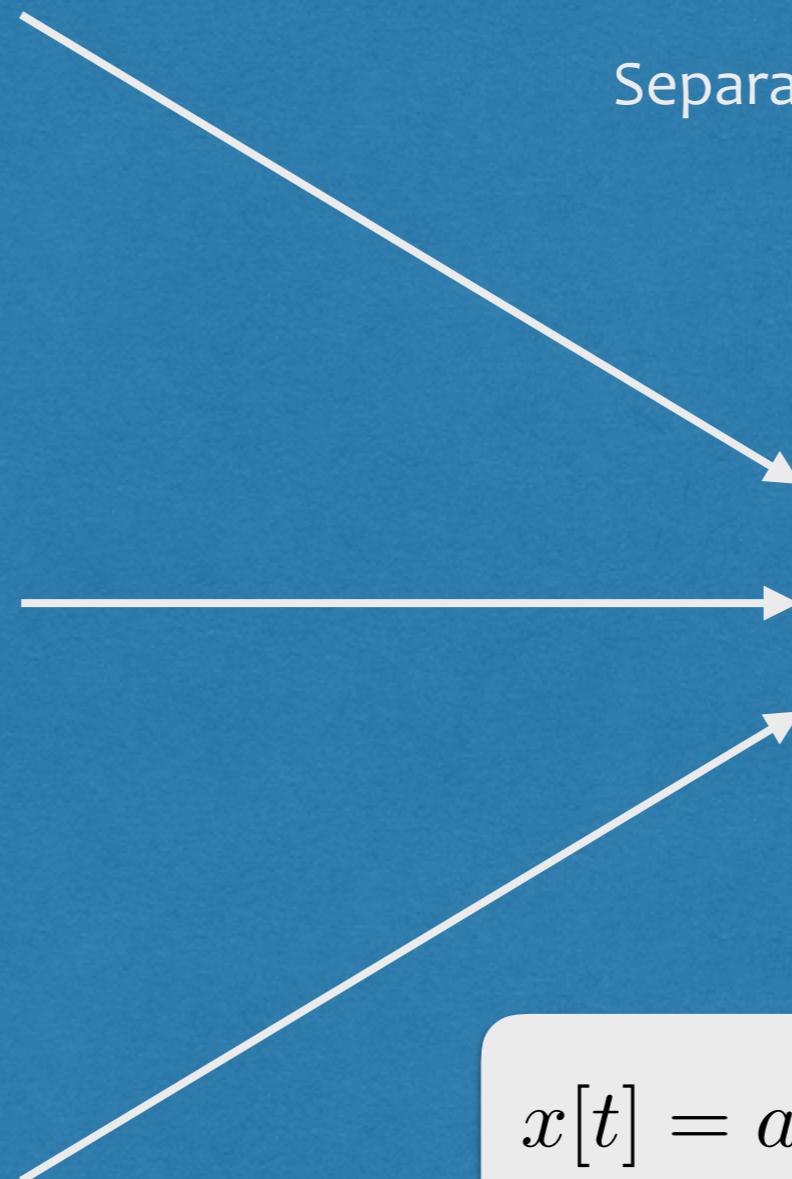
Extraction/de-trending of transit time series

# BLIND SOURCE SEPARATION

## Cocktail Party Problem



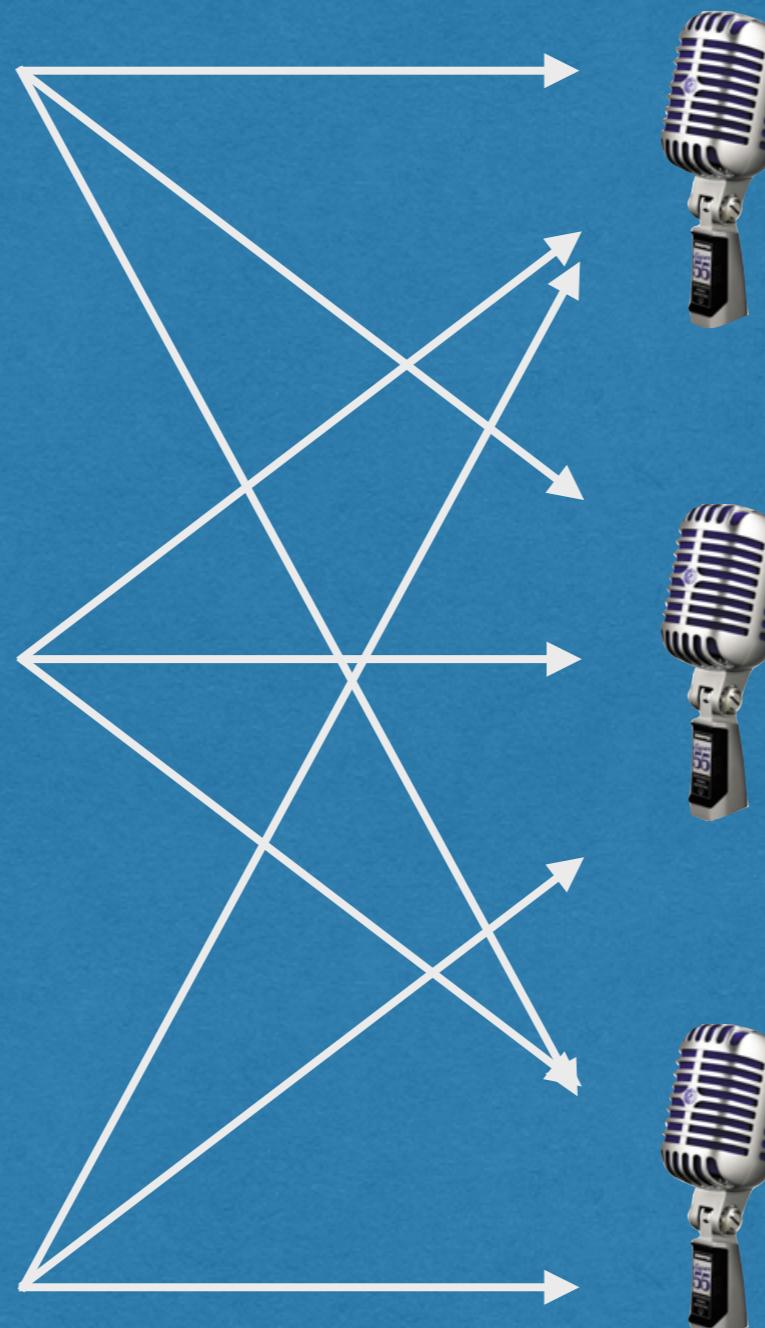
# BLIND SOURCE SEPARATION



Separation is essentially impossible

$$x[t] = a_1 s_1[t] + a_2 s_2[t] + a_3 s_3[t]$$

# BLIND SOURCE SEPARATION



Different linear combinations

Now it may be possible

$$x_1[t] = a_{11}s_1[t] + a_{12}s_2[t] + a_{13}s_3[t]$$

$$x_2[t] = a_{21}s_1[t] + a_{22}s_2[t] + a_{23}s_3[t]$$

$$x_3[t] = a_{31}s_1[t] + a_{32}s_2[t] + a_{33}s_3[t]$$

# BLIND SOURCE SEPARATION

## Common Theme

- Multivalued data provide simultaneous observations of the same physical phenomena.
- Each observation is composed of the combination of the same elementary components/sources/etc ...

# BLIND SOURCE SEPARATION

## The Model

**assumed to be known**

$$\mathbf{X} = \sum_{k=1}^n a^k s_k = \mathbf{AS}$$

**sources**

**mixing matrix**

The diagram illustrates the BSS model equation  $\mathbf{X} = \sum_{k=1}^n a^k s_k = \mathbf{AS}$ . Red annotations and arrows identify components: 'assumed to be known' points to the summation index  $n$ ; 'sources' points to the matrix  $\mathbf{S}$ ; and 'mixing matrix' points to the matrix  $\mathbf{A}$ .

Number of observations > number of sources

# BLIND SOURCE SEPARATION

## The Model

**assumed to be known**

$$\mathbf{X} = \sum_{k=1}^n a^k s_k = \mathbf{A} \mathbf{S}$$

**sources**

**mixing matrix**

The diagram illustrates the BSS model equation  $\mathbf{X} = \sum_{k=1}^n a^k s_k = \mathbf{A} \mathbf{S}$ . A red arrow points from the text "assumed to be known" to the summation symbol  $\sum$ . Another red arrow points from the text "sources" to the matrix  $\mathbf{S}$ . A third red arrow points from the text "mixing matrix" to the matrix  $\mathbf{A}$ .

Number of observations > number of sources

# BLIND SOURCE SEPARATION

## The Model

**assumed to be known**

$$\mathbf{X} = \sum_{k=1}^n a^k s_k = \mathbf{AS}$$

**sources**

**mixing matrix**

The diagram illustrates the BSS model equation  $\mathbf{X} = \sum_{k=1}^n a^k s_k = \mathbf{AS}$ . A red arrow points from the text "assumed to be known" to the summation symbol  $\sum$ . Another red arrow points from the text "sources" to the term  $\mathbf{AS}$ , which is enclosed in a pink rounded rectangle. A third red arrow points from the text "mixing matrix" to the term  $\mathbf{AS}$ .

Number of observations > number of sources

# BLIND SOURCE SEPARATION

## III-Posed Problem

There exists an infinite number of solutions such that :

$$X = AS = A'S'$$

Specifically for any invertible matrix U :

$$A' = AU \text{ & } S' = U^{-1}S$$

So, how do we solve this kind of problem?

# BLIND SOURCE SEPARATION

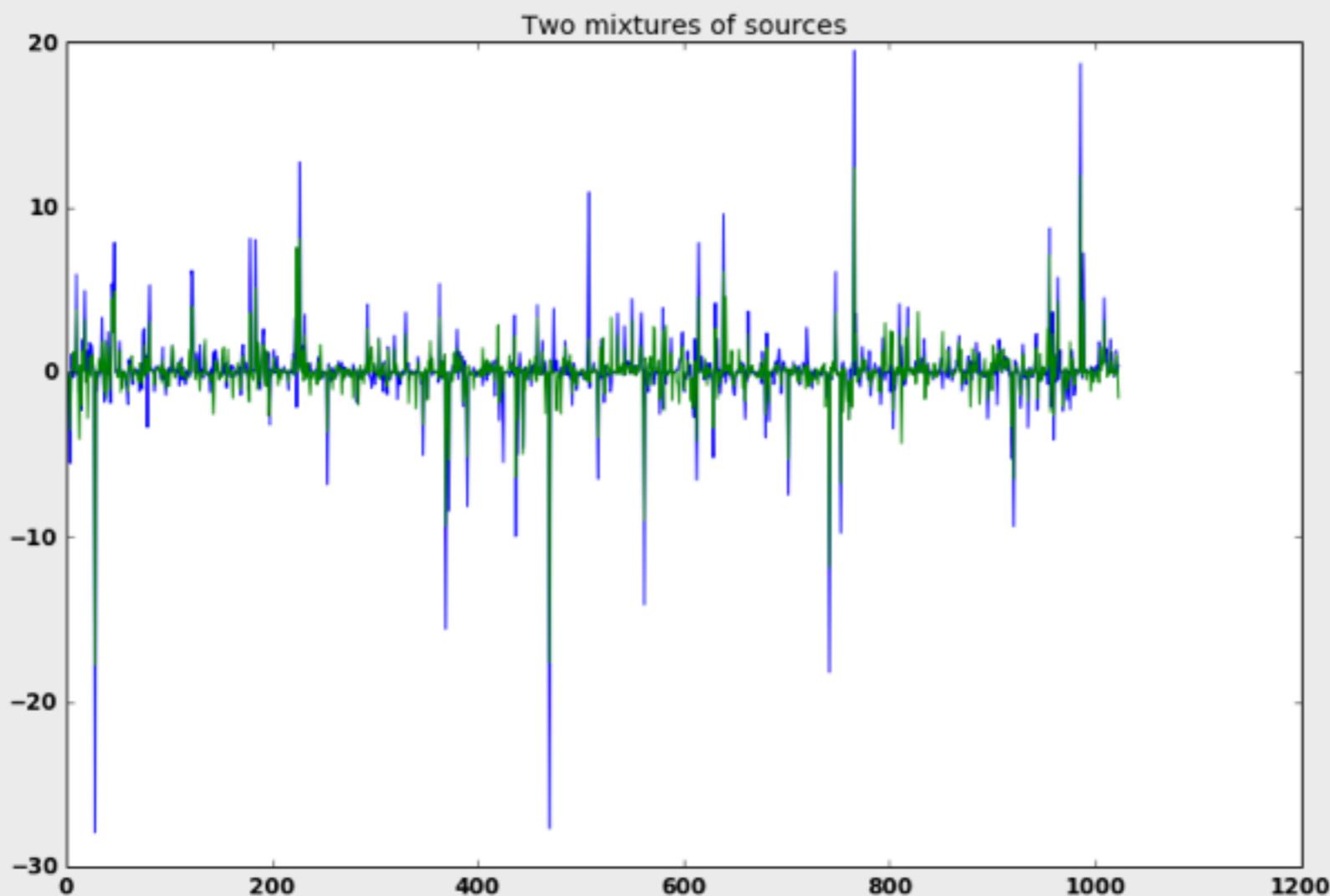
## Source Properties

To solve these problems we need to exploit additional information about the sources such as:

- **Decorrelation**
- **Independence**
- **Sparsity**

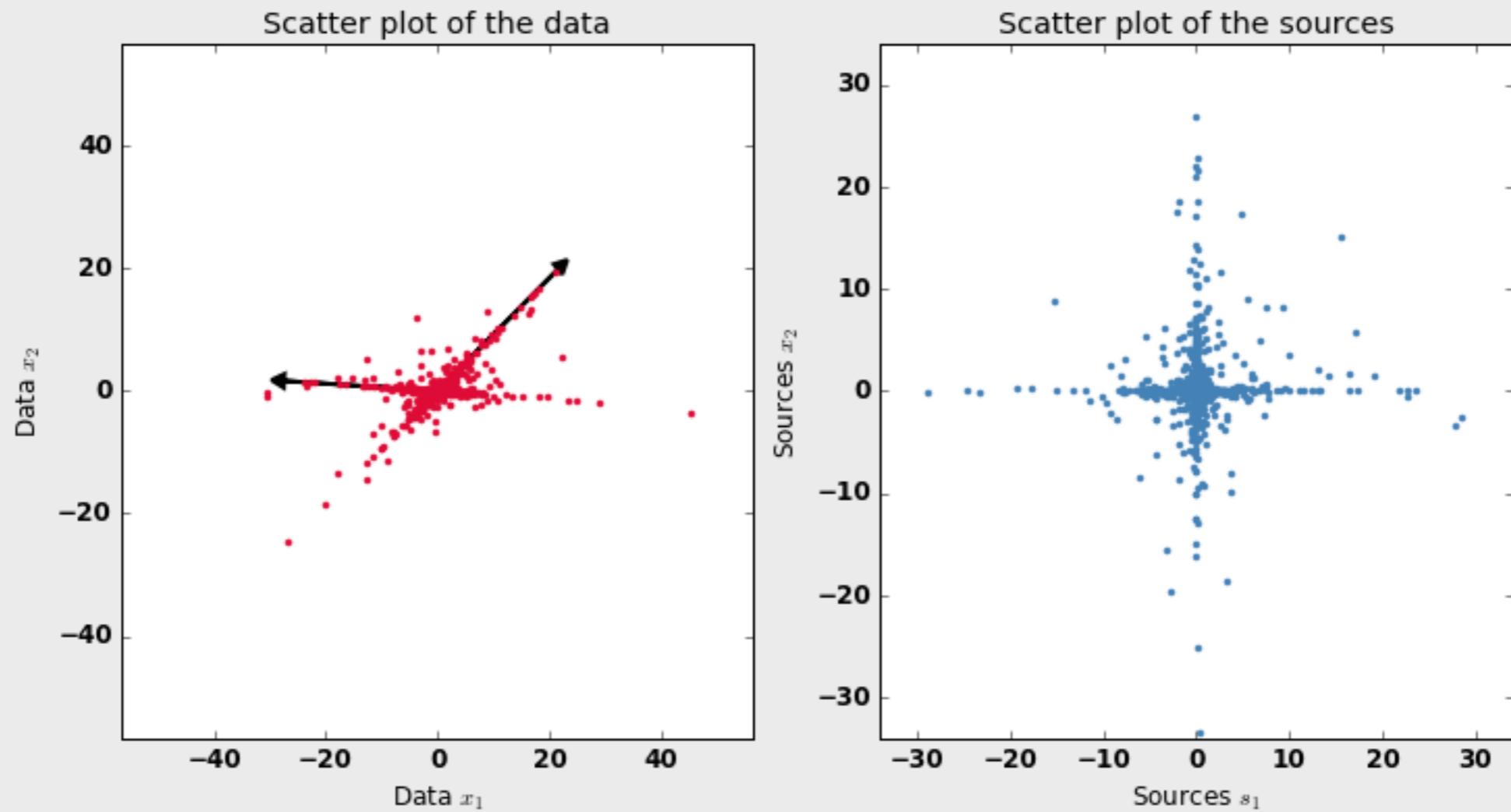
# BLIND SOURCE SEPARATION

## Source Properties



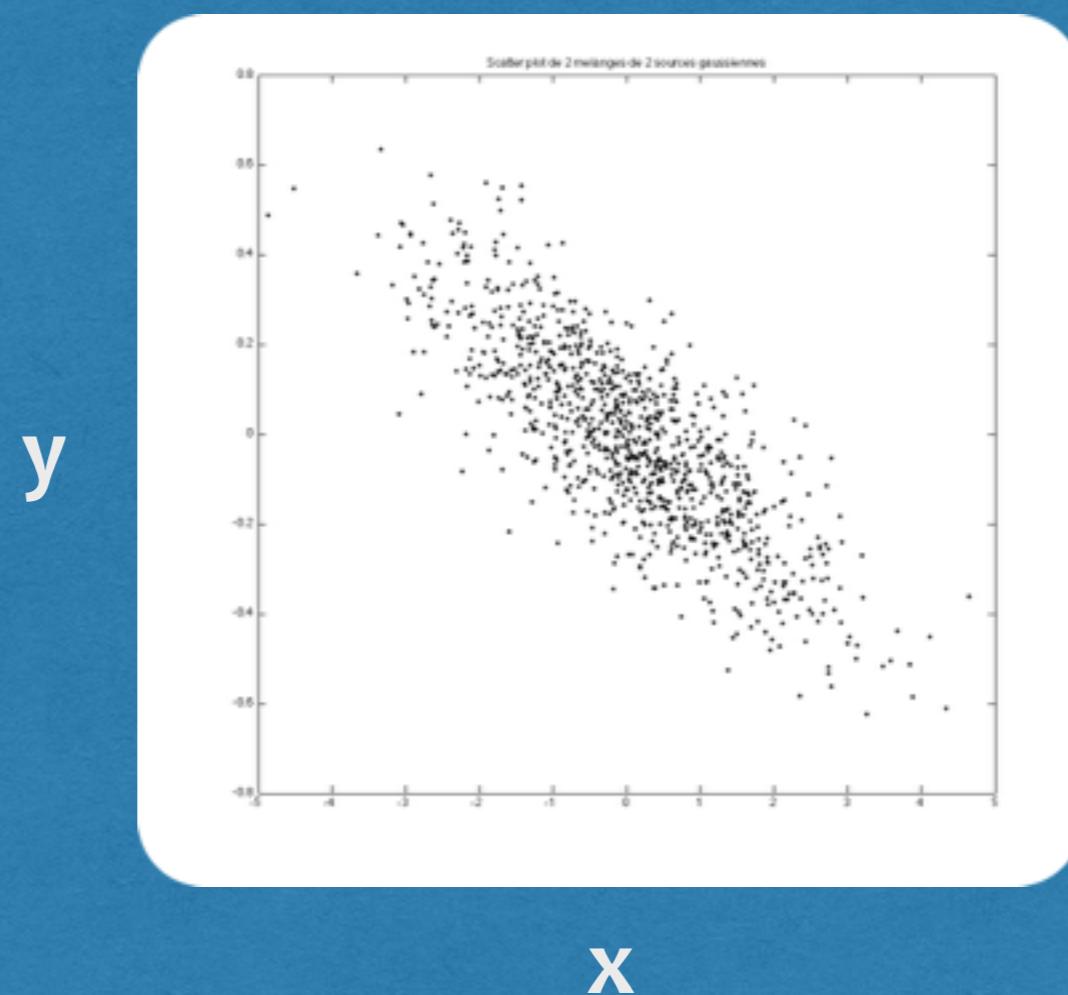
# BLIND SOURCE SEPARATION

## Source Properties



# BLIND SOURCE SEPARATION

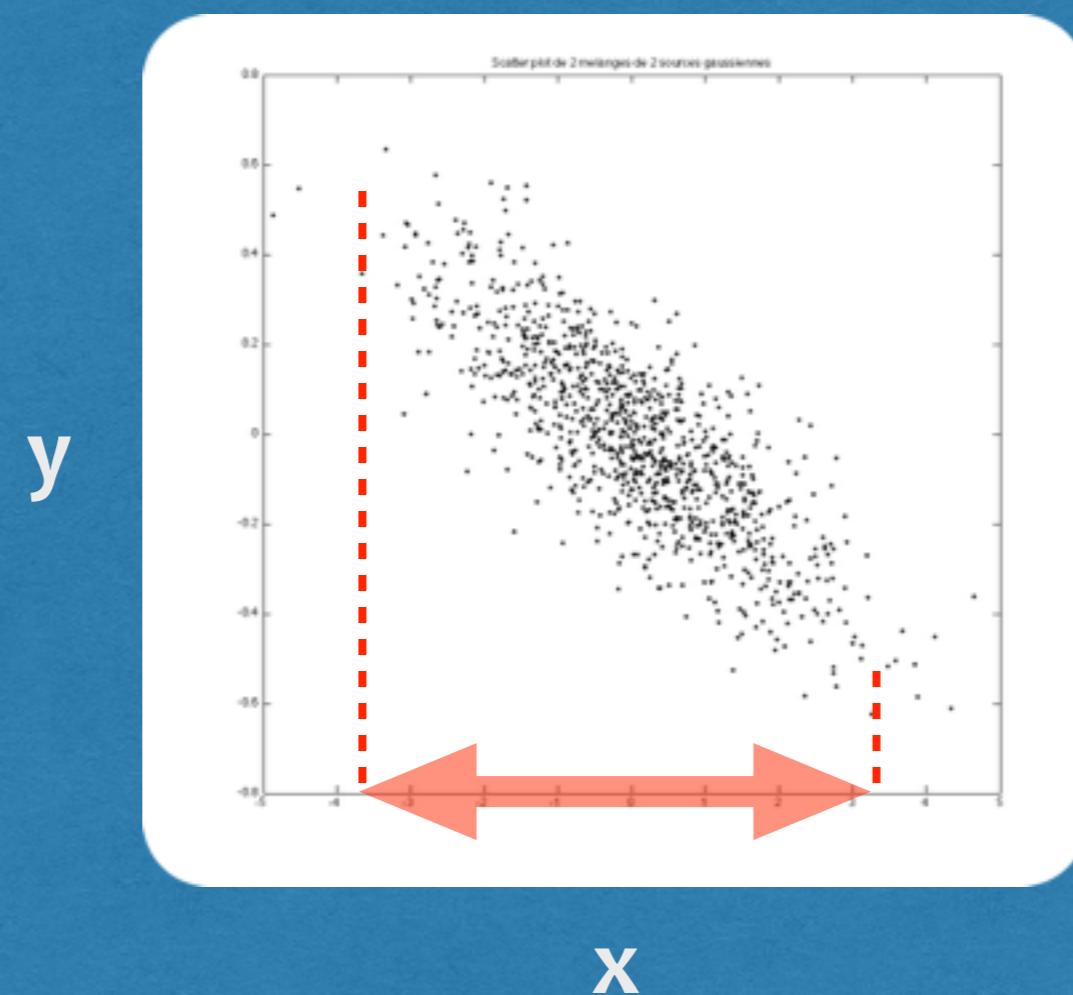
## Principal Component Analysis (PCA)



Find direction of maximal variance ( $2^{\text{nd}}$  order statistic) in the data that gives the best reconstruction error.

# BLIND SOURCE SEPARATION

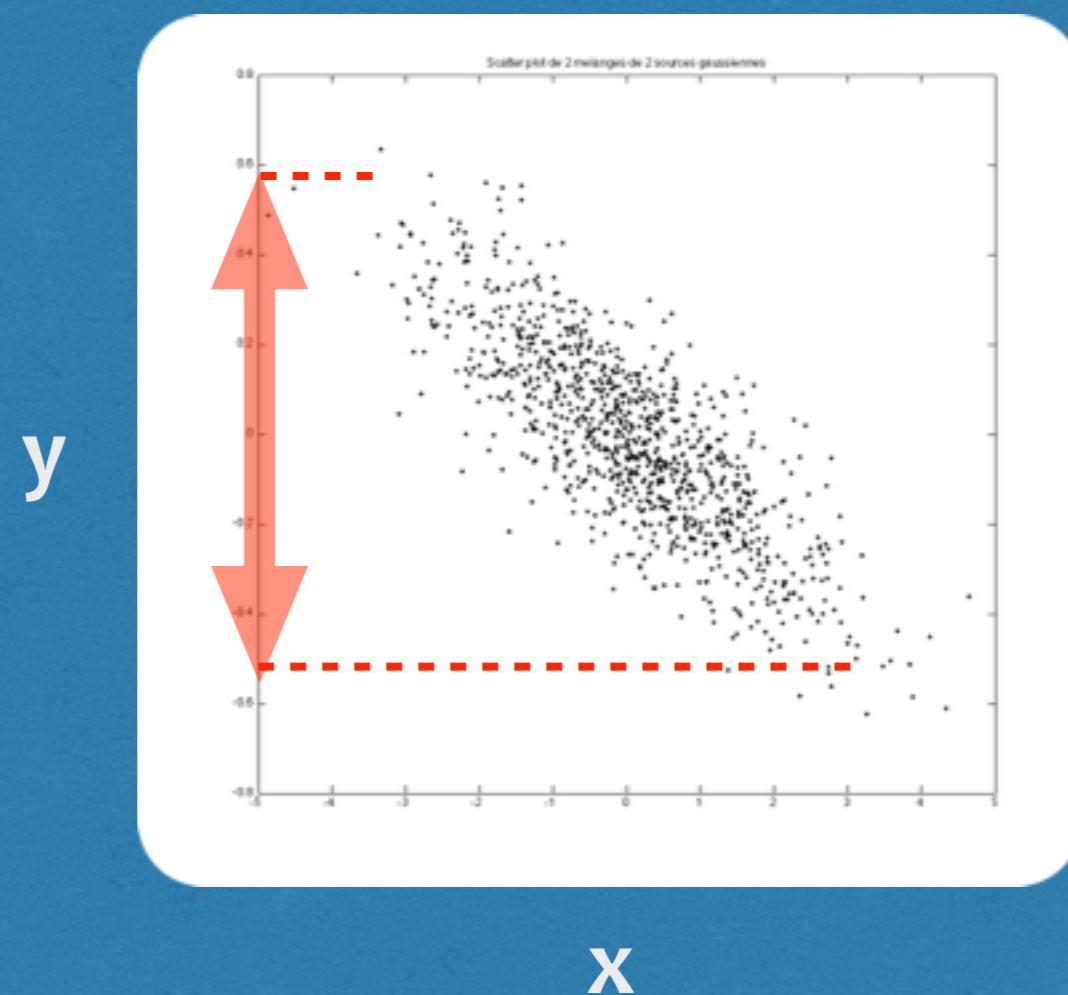
## Principal Component Analysis (PCA)



Find direction of maximal variance ( $2^{\text{nd}}$  order statistic) in the data that gives the best reconstruction error.

# BLIND SOURCE SEPARATION

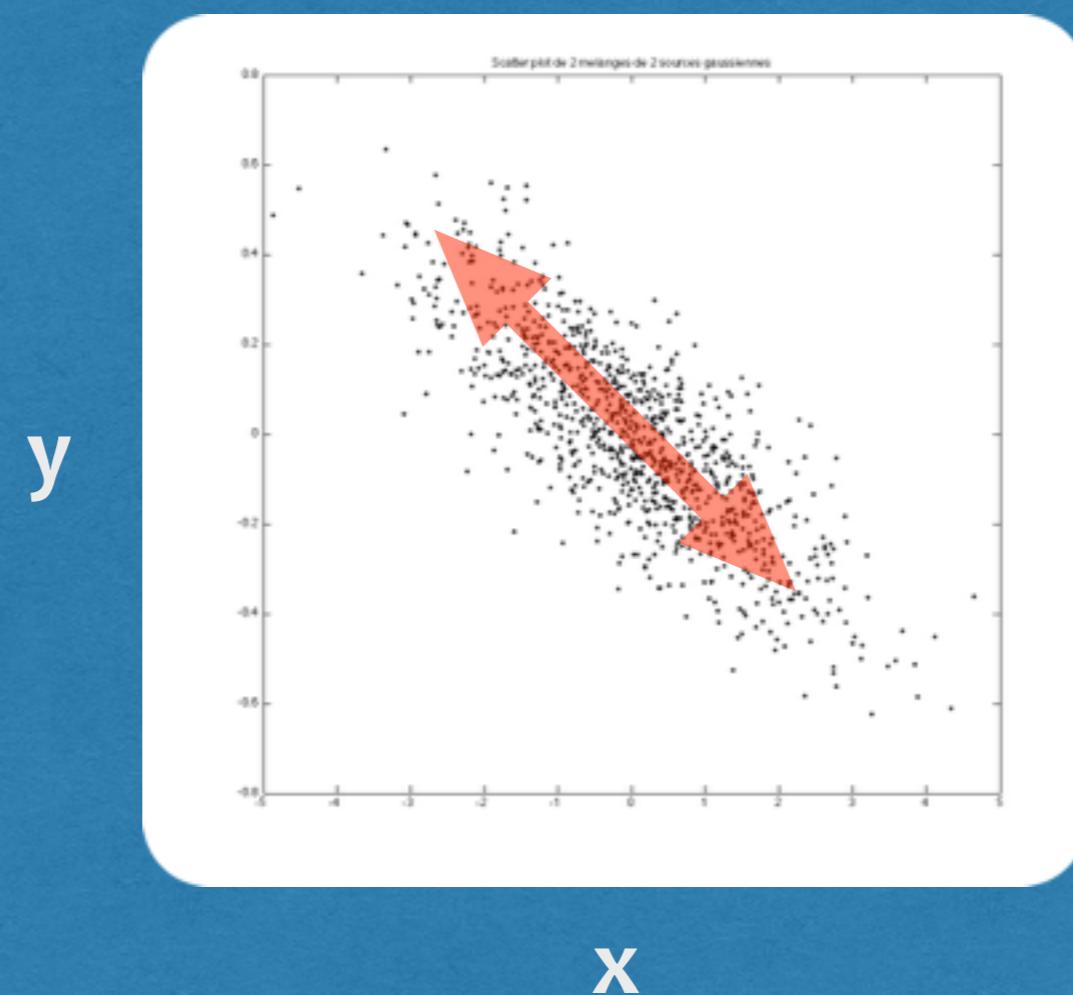
## Principal Component Analysis (PCA)



Find direction of maximal variance ( $2^{\text{nd}}$  order statistic) in the data that gives the best reconstruction error.

# BLIND SOURCE SEPARATION

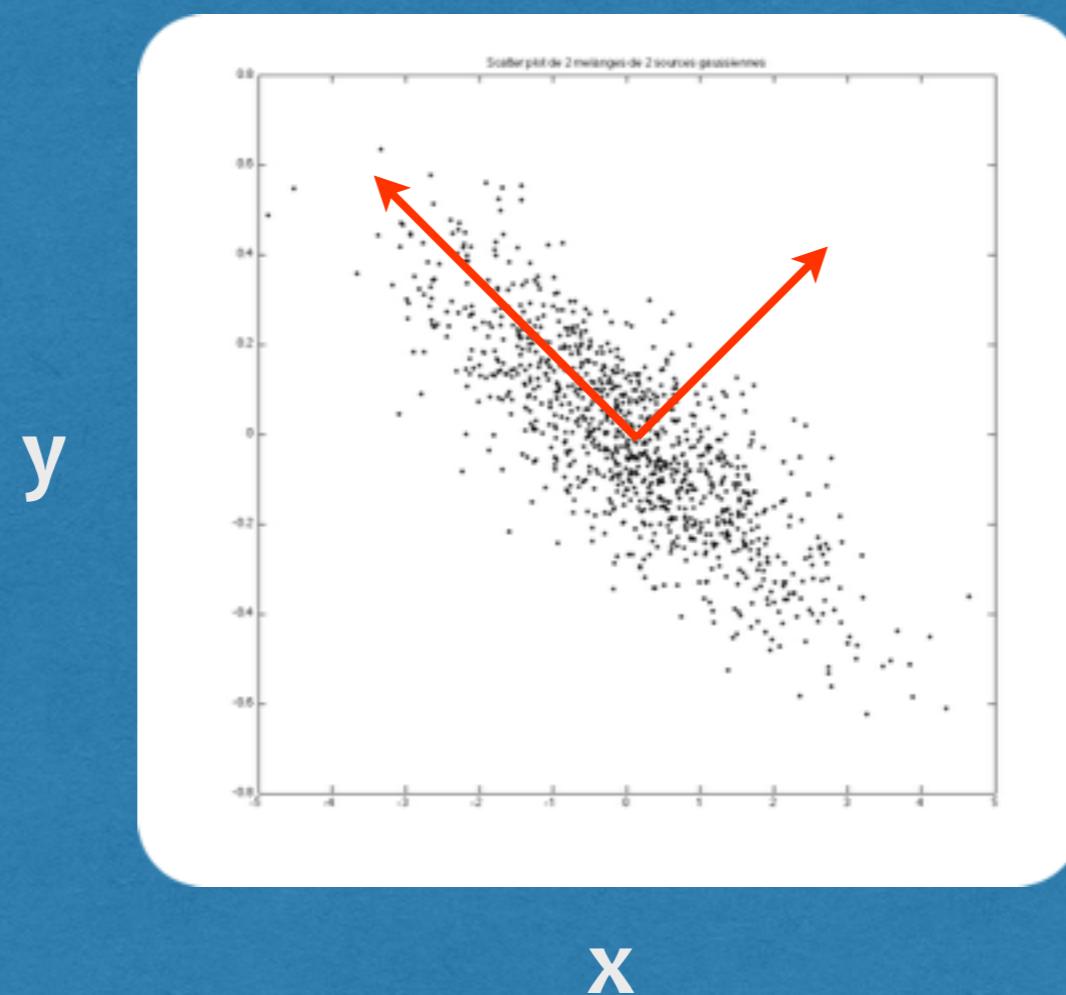
## Principal Component Analysis (PCA)



Find direction of maximal variance ( $2^{\text{nd}}$  order statistic) in the data that gives the best reconstruction error.

# BLIND SOURCE SEPARATION

## Principal Component Analysis (PCA)



Find direction of maximal variance ( $2^{\text{nd}}$  order statistic) in the data that gives the best reconstruction error.

# BLIND SOURCE SEPARATION

## Decorrelation

Decorrelation can be measured via the **covariance matrix** of the estimated sources : it should be diagonal .

$$R_X = X X^T \quad \text{is the covariance matrix of the data}$$

Don't forget that :  $X = AS$

$$R_X = A S S^T A^T = A R_S A^T$$

Diagonal

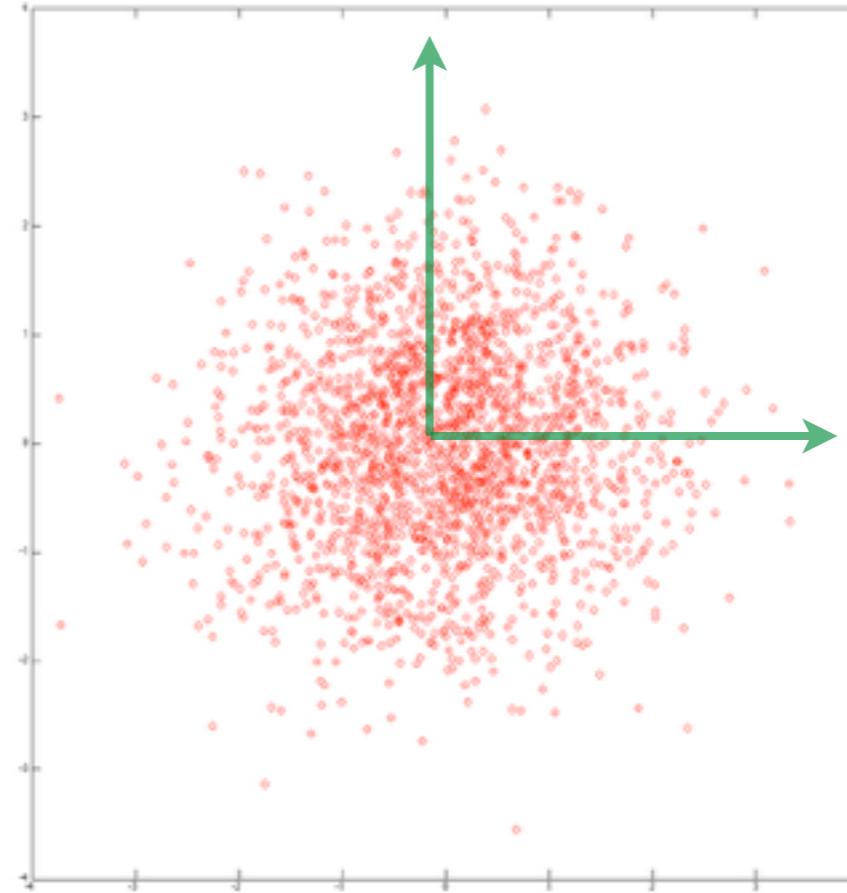
# BLIND SOURCE SEPARATION

Second-order statistics provide a “Gaussian” approximation of the sources

$s_2$

Decorrelation

Rotational Invariance

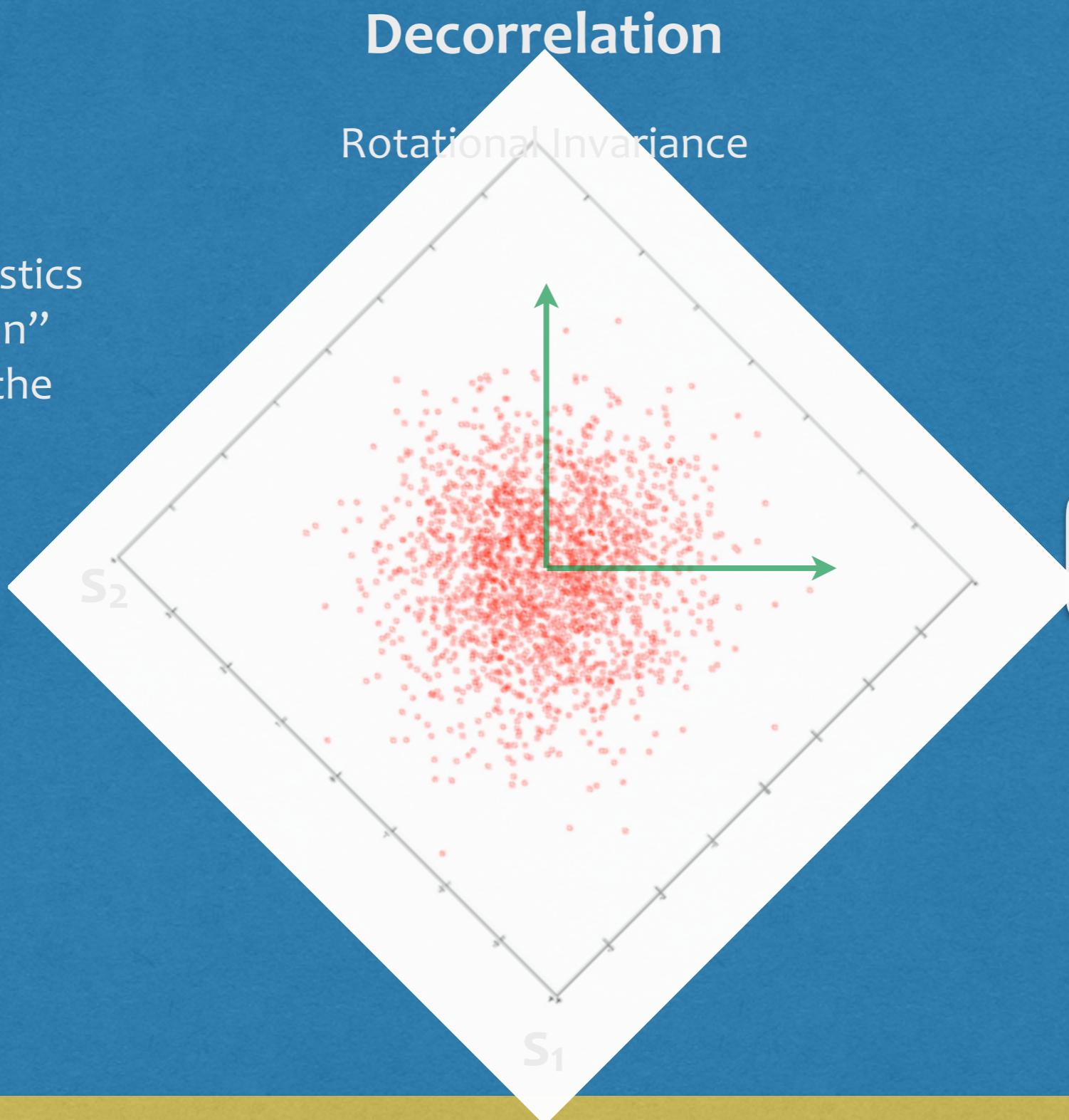


$$R_{S'} = R_S$$

$s_1$

# BLIND SOURCE SEPARATION

Second-order statistics provide a “Gaussian” approximation of the sources



# BLIND SOURCE SEPARATION

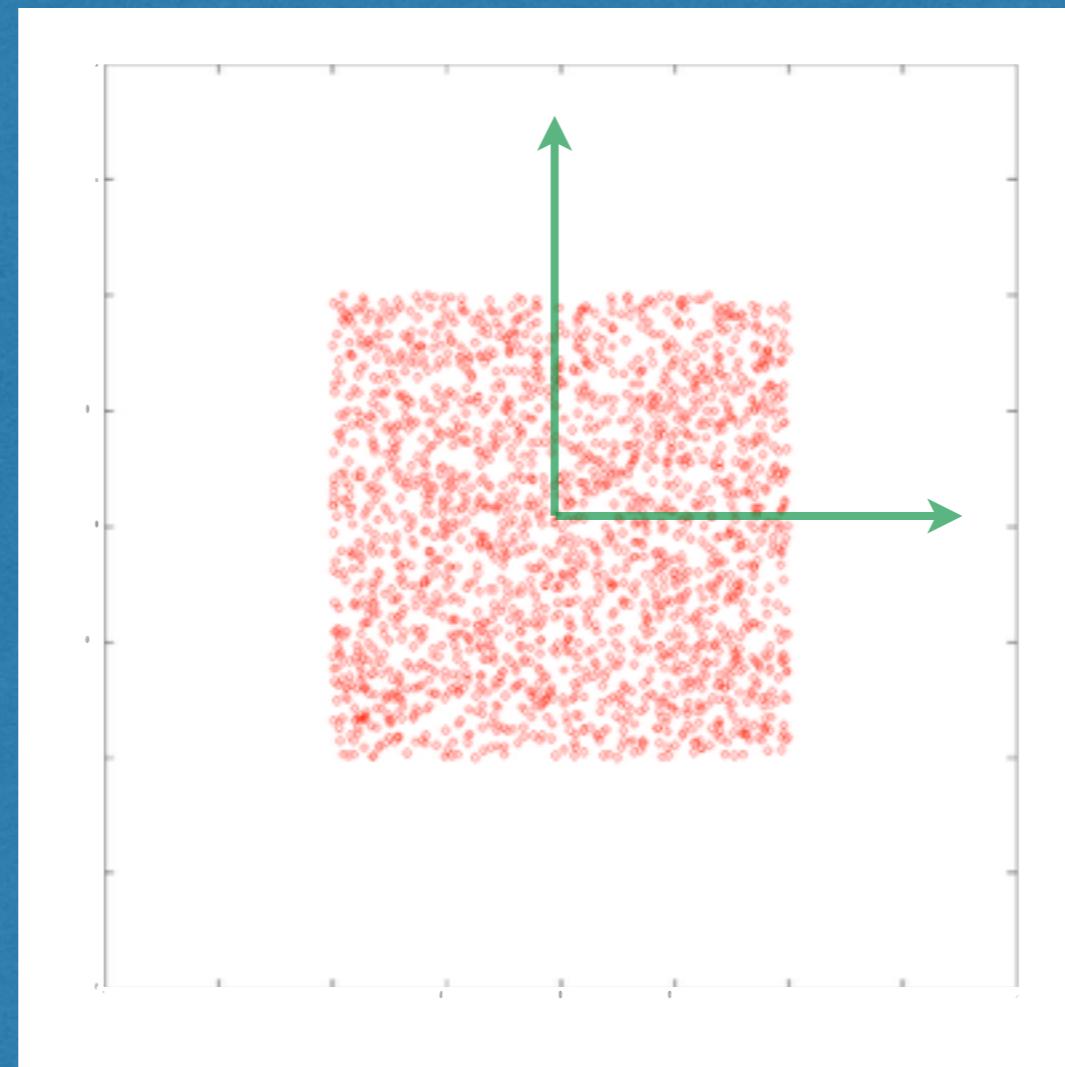
Independence

Rotational Variance

Uniform (non-Gaussian)  
sources

$S_2$

$S_1$



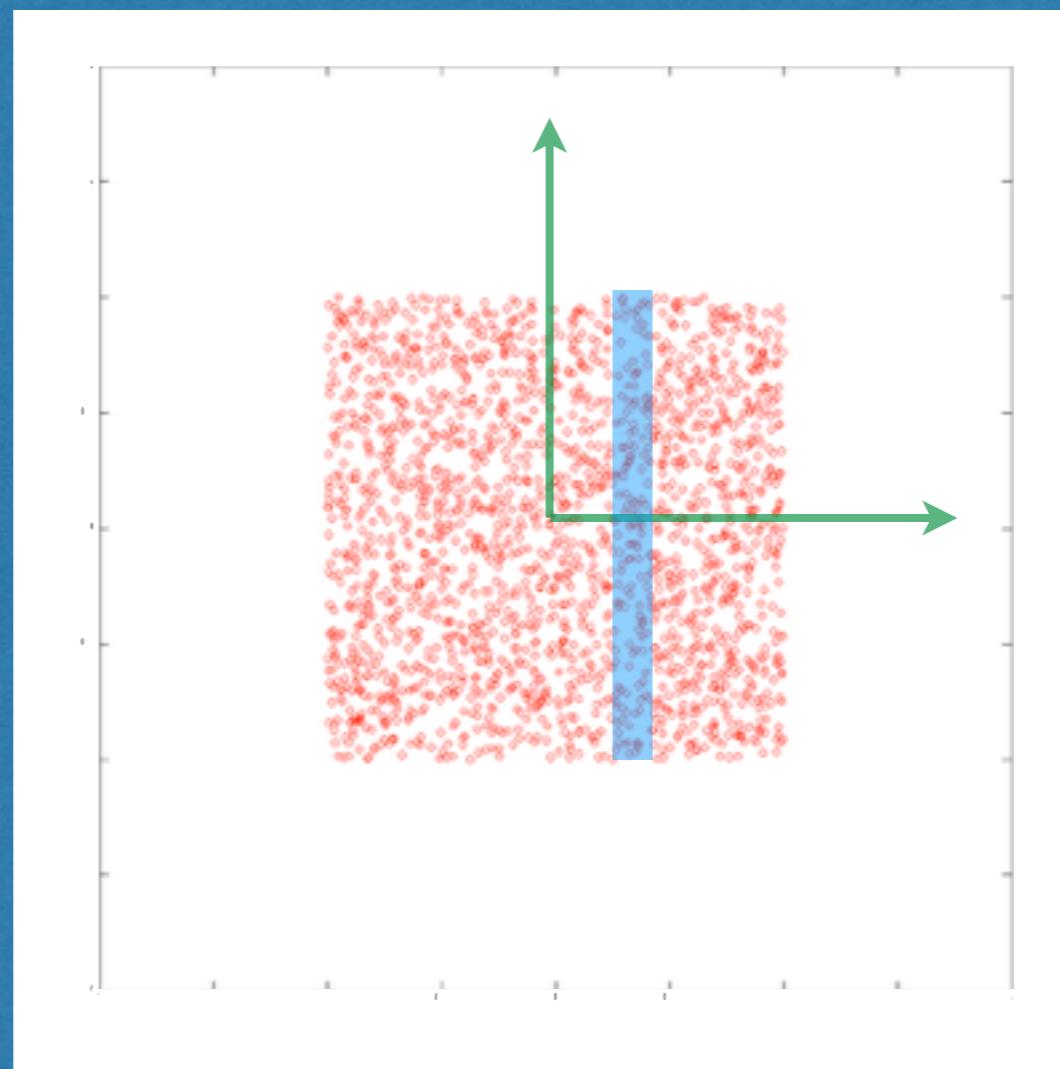
# BLIND SOURCE SEPARATION

Uniform (non-Gaussian)  
sources

$S_2$

Independence

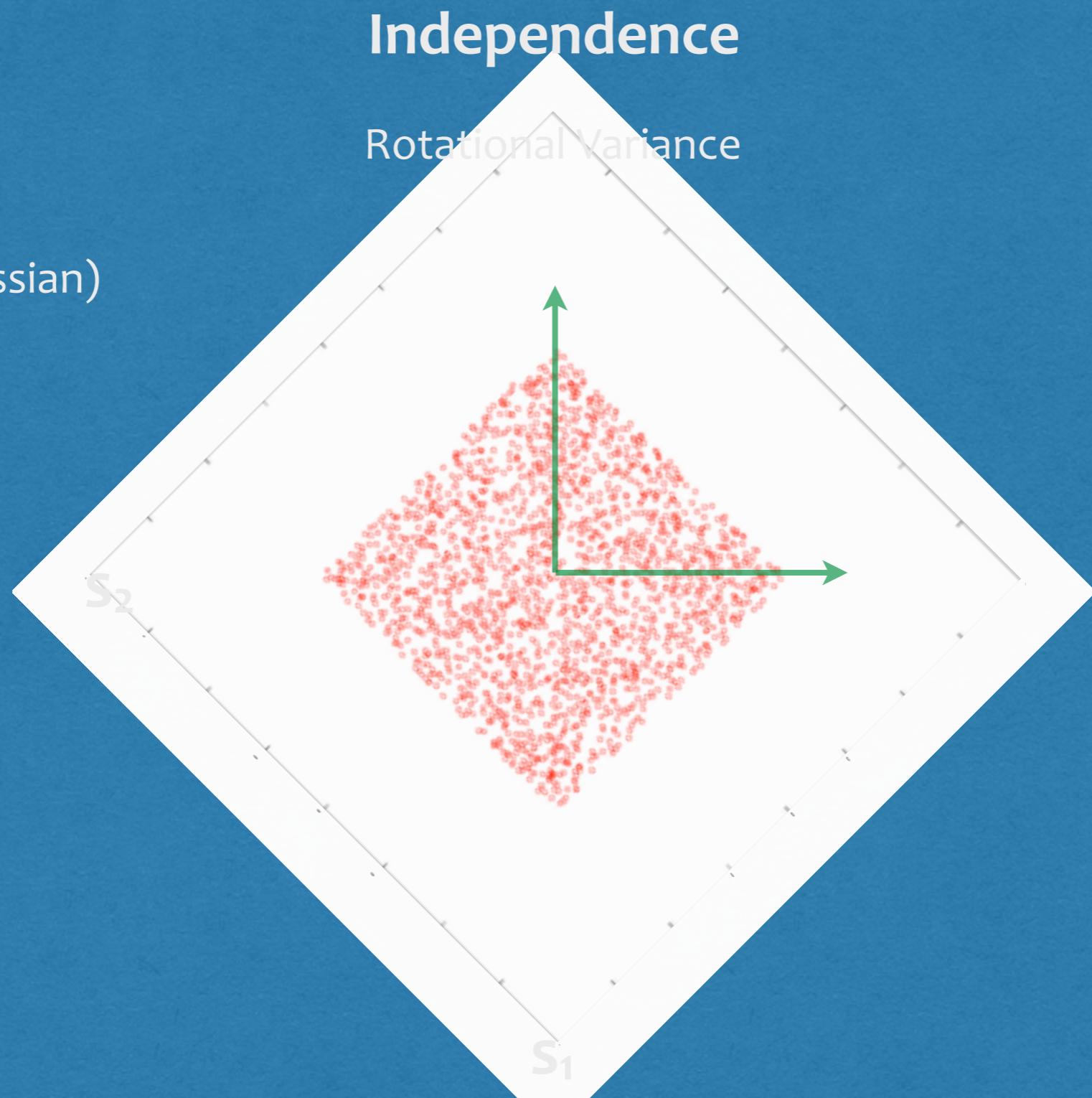
Rotational Variance



$S_1$

# BLIND SOURCE SEPARATION

Uniform (non-Gaussian)  
sources



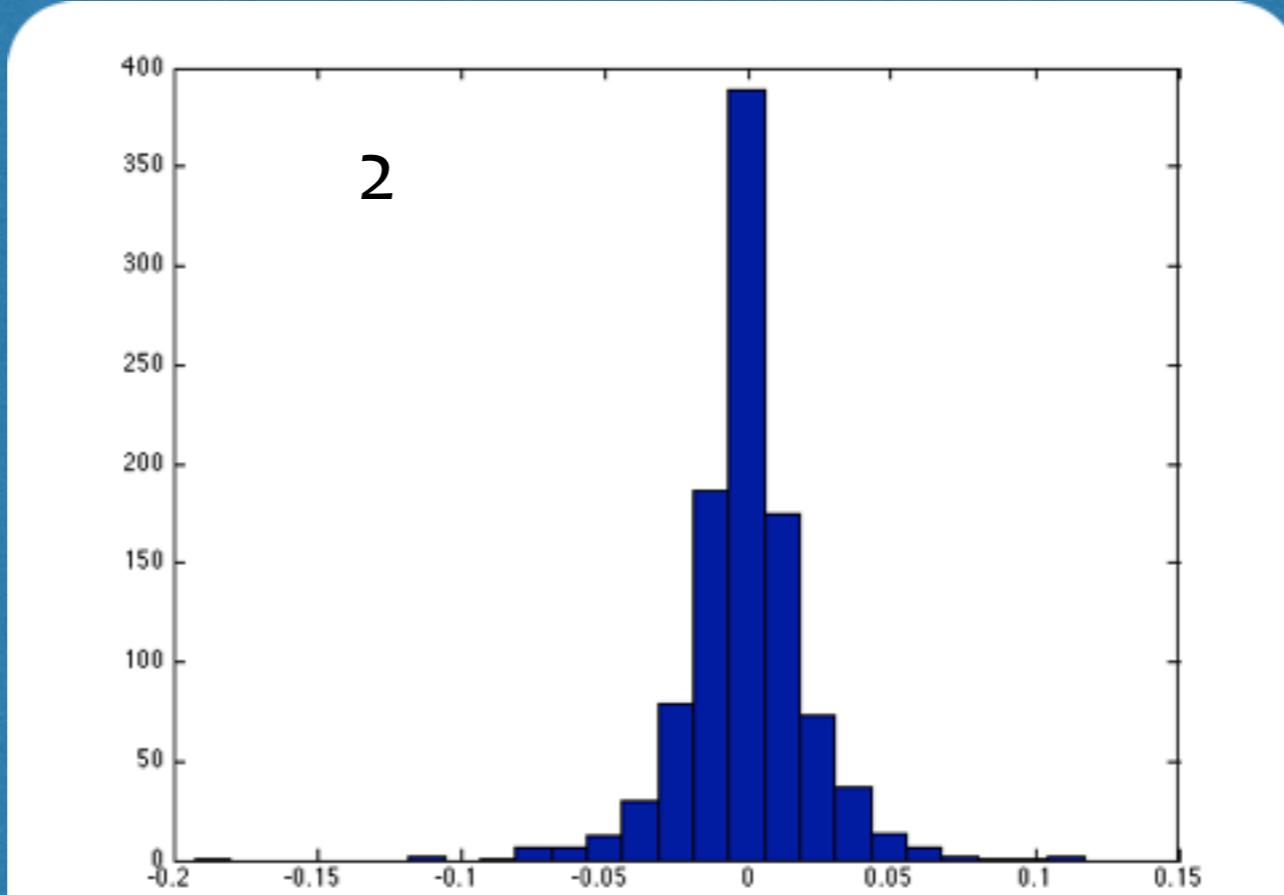
# BLIND SOURCE SEPARATION

## Independence

$$\forall t; \quad \frac{1}{n}x_i[t] = \frac{1}{n} \sum_{j=1}^n s_j \longrightarrow x \sim \mathcal{N}(0, \sigma^2)$$

Central limit theorem

As more independent sources are mixed the signal becomes more Gaussian.



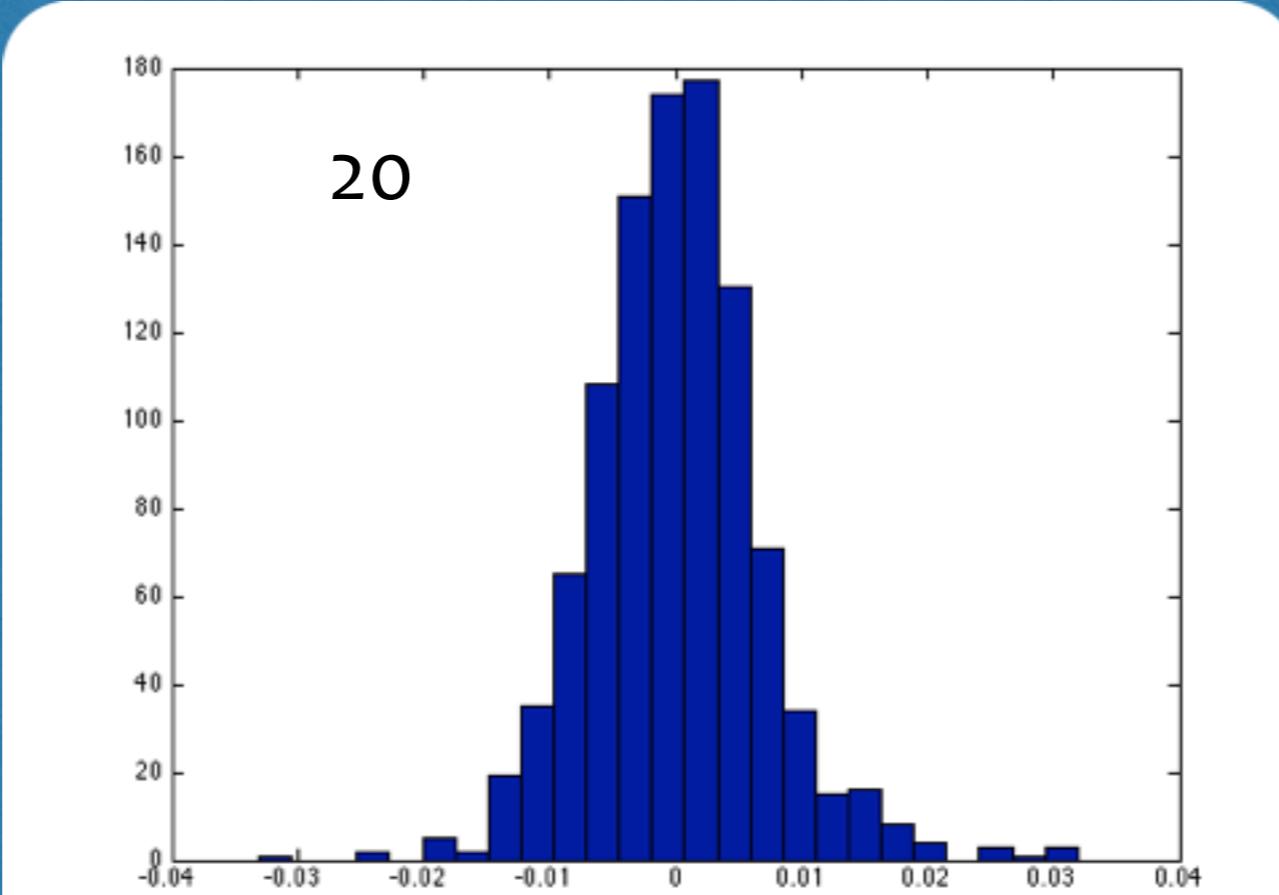
# BLIND SOURCE SEPARATION

## Independence

$$\forall t; \quad \frac{1}{n}x_i[t] = \frac{1}{n} \sum_{j=1}^n s_j \longrightarrow x \sim \mathcal{N}(0, \sigma^2)$$

Central limit theorem

As more independent sources are mixed the signal becomes more Gaussian.



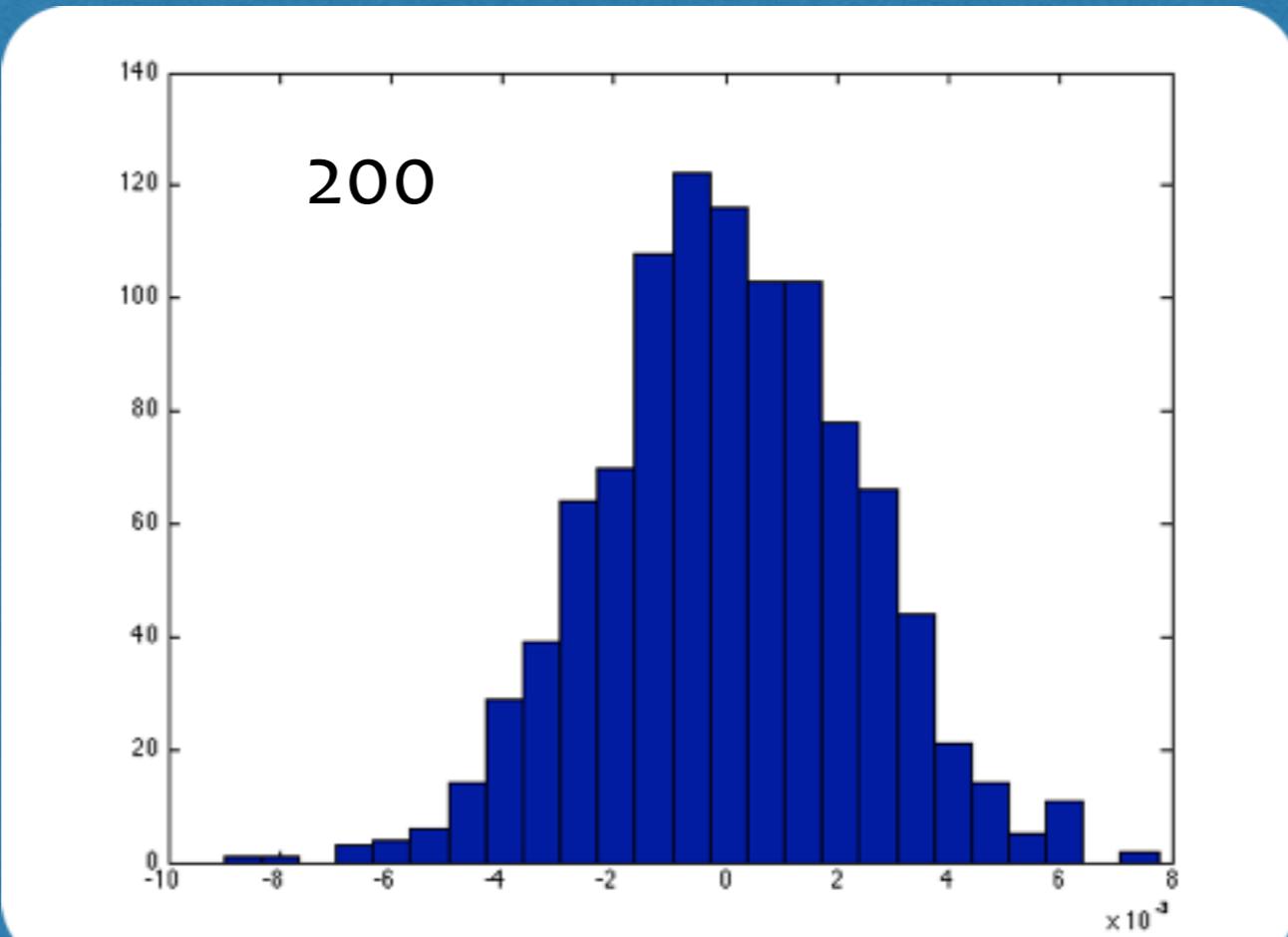
# BLIND SOURCE SEPARATION

## Independence

$$\forall t; \quad \frac{1}{n}x_i[t] = \frac{1}{n} \sum_{j=1}^n s_j \longrightarrow x \sim \mathcal{N}(0, \sigma^2)$$

Central limit theorem

As more independent sources are mixed the signal becomes more Gaussian.



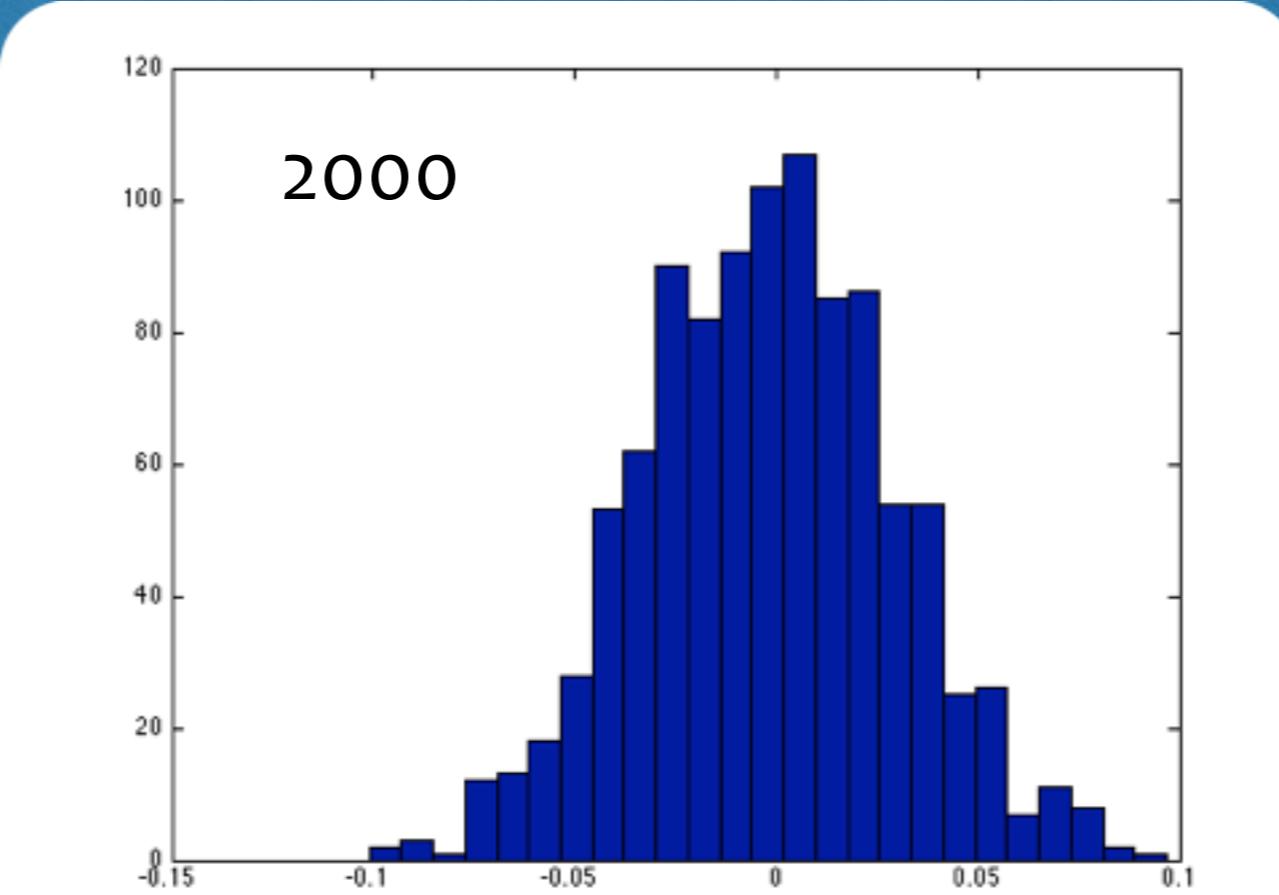
# BLIND SOURCE SEPARATION

## Independence

$$\forall t; \quad \frac{1}{n}x_i[t] = \frac{1}{n} \sum_{j=1}^n s_j \longrightarrow x \sim \mathcal{N}(0, \sigma^2)$$

Central limit theorem

As more independent sources are mixed the signal becomes more Gaussian.



# BLIND SOURCE SEPARATION

## Independent Component Analysis (ICA)

The separation of sources makes the signal less Gaussian. Therefore, by maximising the non-Gaussianity one can attempt to separate the sources.

We can measure the non-Gaussianity using higher order statistics (*i.e. skewness and kurtosis*)

Project the data onto a new feature space

$$X \rightarrow X'$$

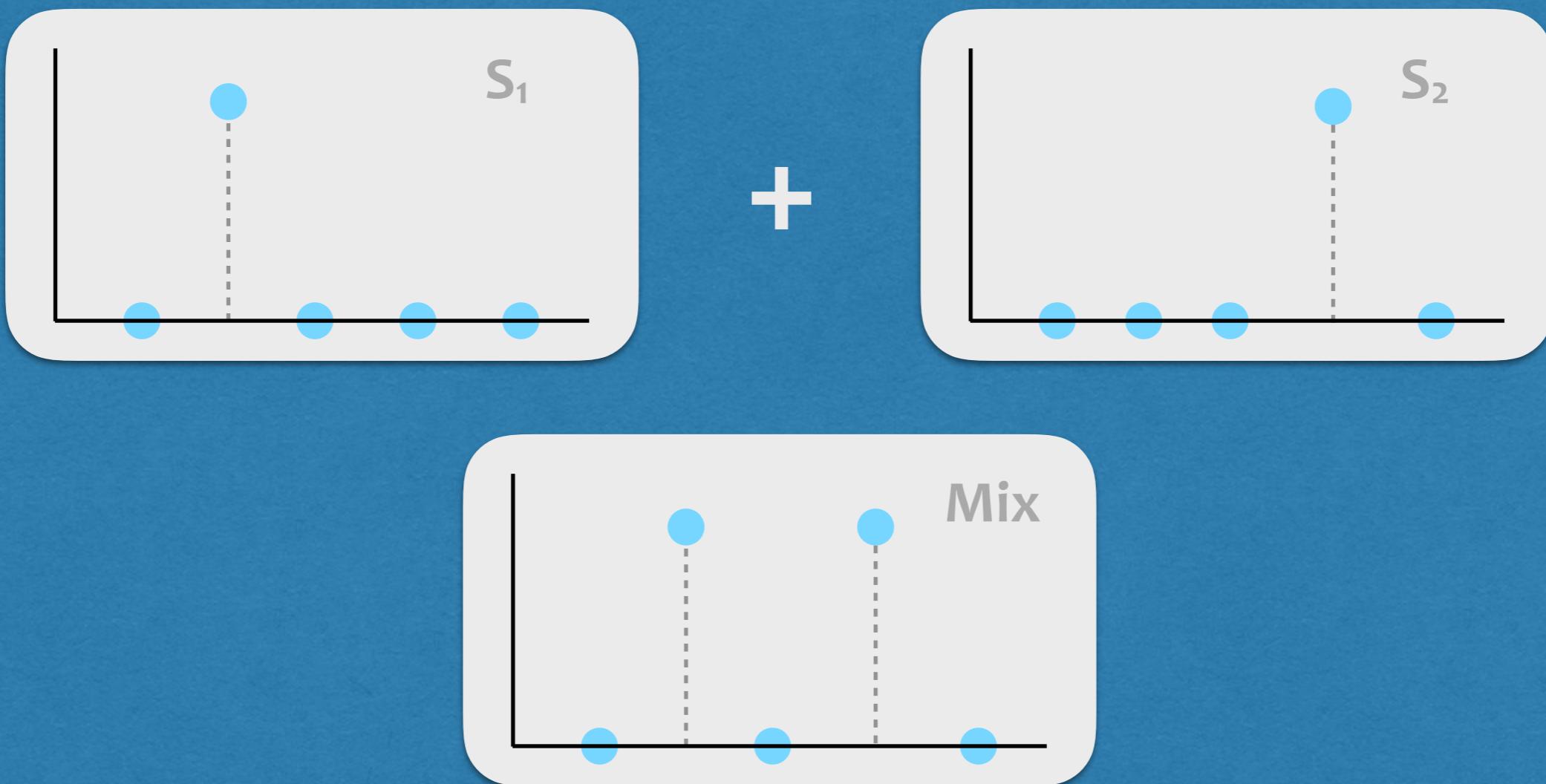
such that

$$x'_i \perp x'_j$$

# BLIND SOURCE SEPARATION

## Sparsity

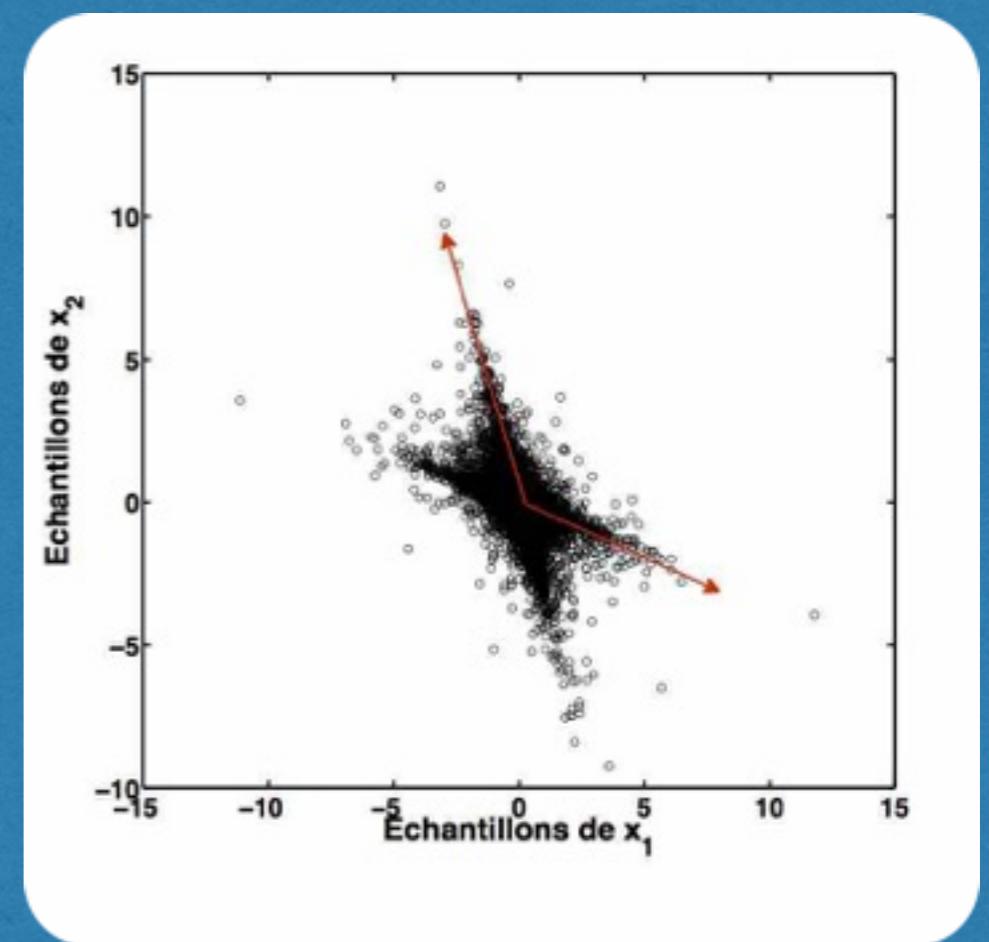
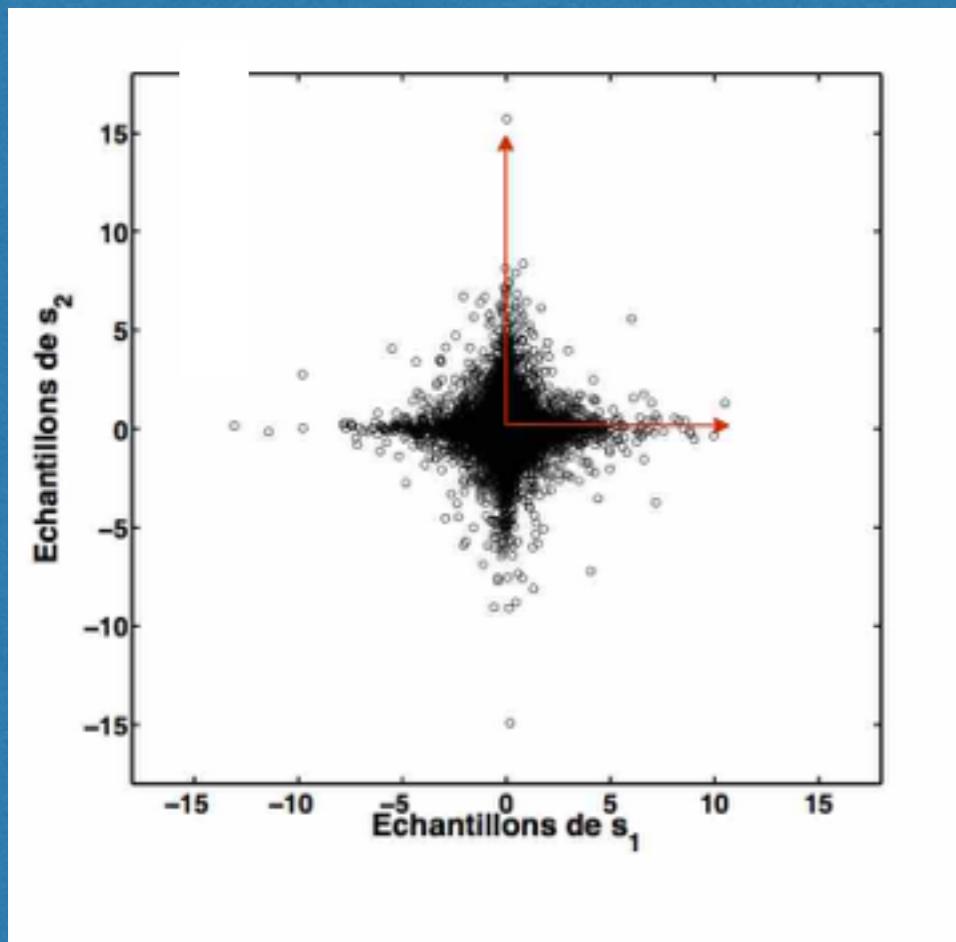
Mixtures are less sparse than sources!



# BLIND SOURCE SEPARATION

## Sparsity

Mixtures are less sparse than sources!



# BLIND SOURCE SEPARATION

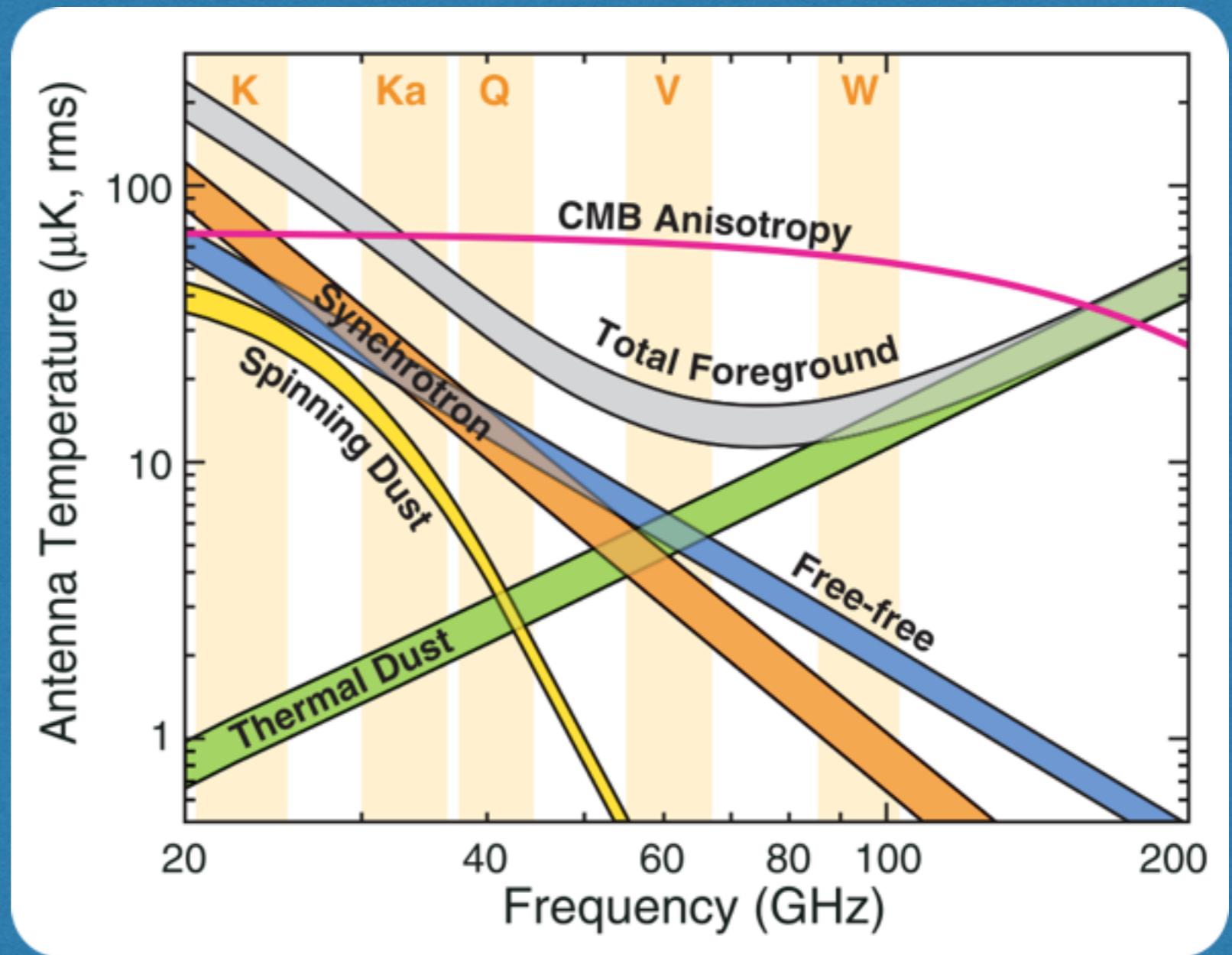
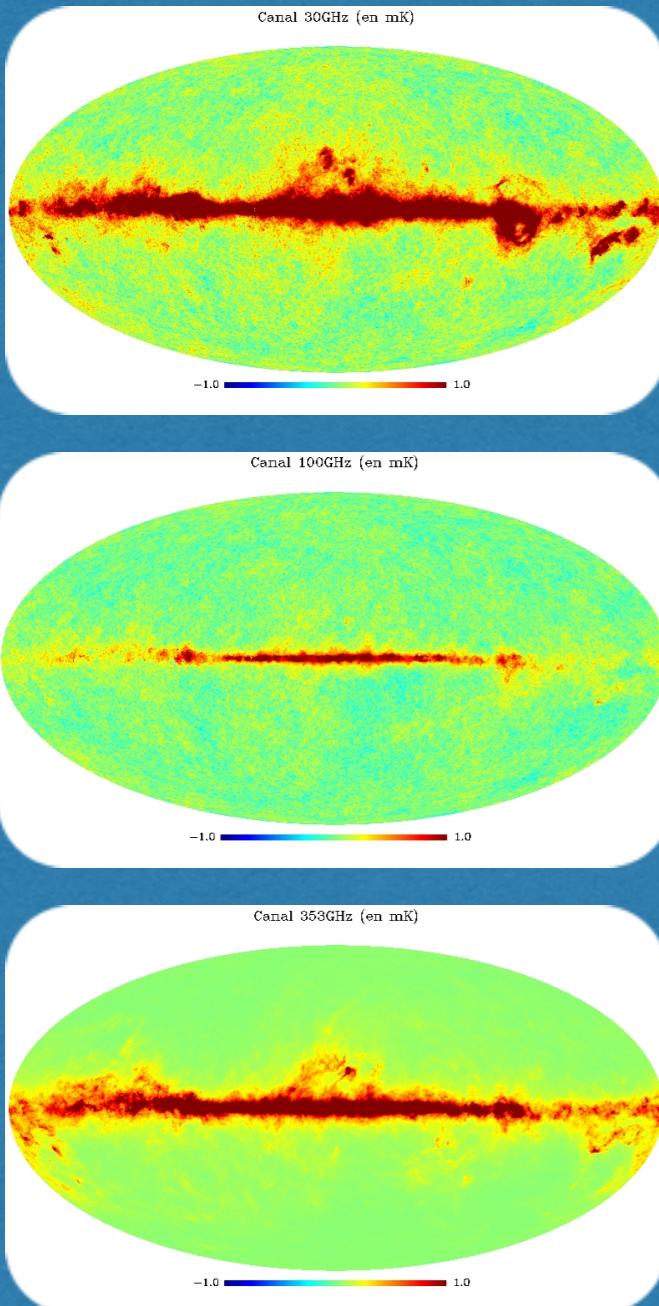
## Sparsity

Since mixed sources are less sparse, we can estimate the sources by maximising the sparsity.

This method is less sensitive to noise than any other method which makes it more robust.

# BLIND SOURCE SEPARATION

## CMB Example



# BLIND SOURCE SEPARATION

# CMB Example

Not a fully blind problem as we assume the CMB spectrum is known.

Can model the problem as follows

Other components have dominant contribution over CMB

$$\|R\| \gg \|as\|$$

# BLIND SOURCE SEPARATION

## CMB Example

The industry standard

Internal Linear Combination (**ILC**)

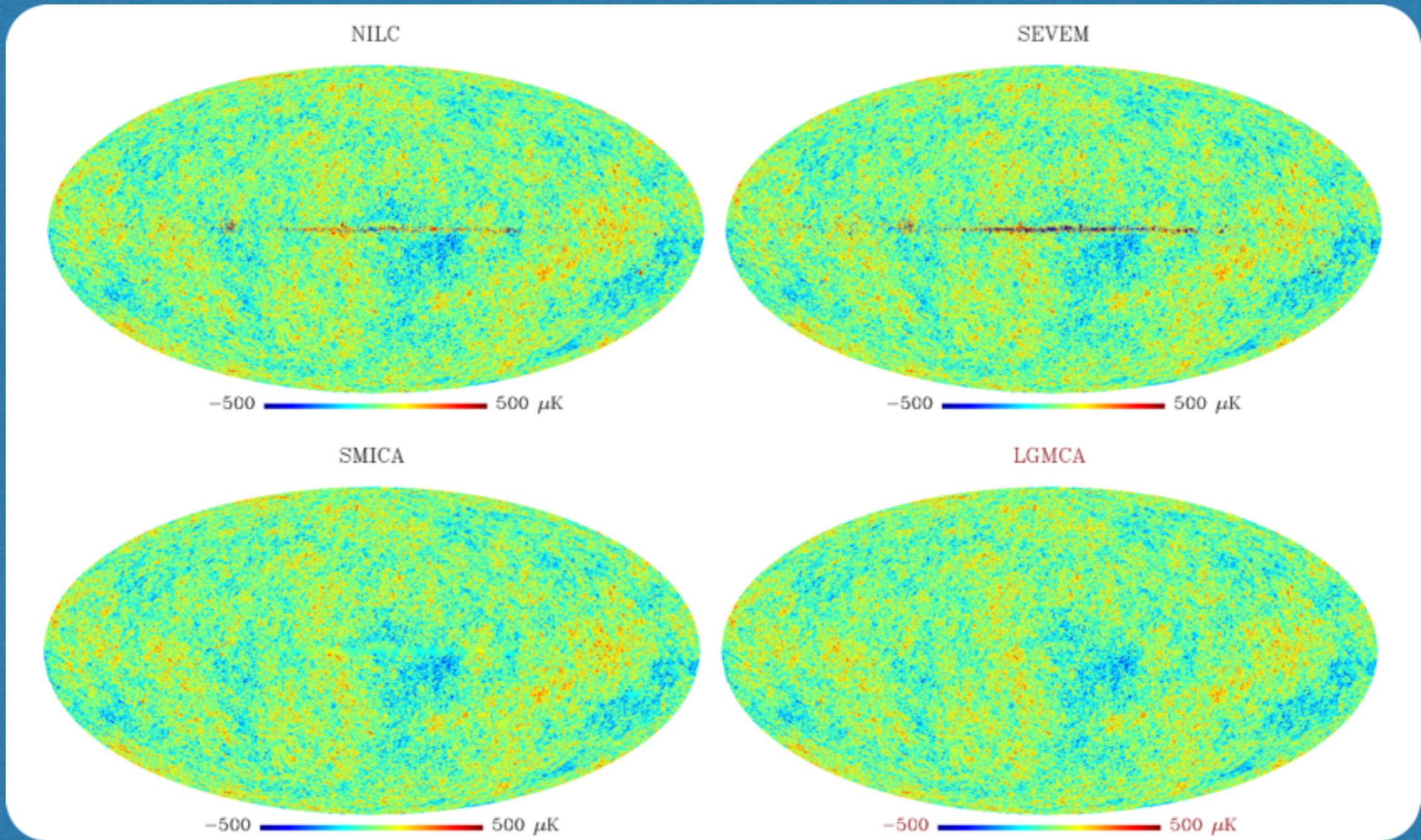
used officially on WMAP

$$\hat{s} = \text{Argmin}_s (X - as) R_X^{-1} (X - as)^T$$

  
neglected

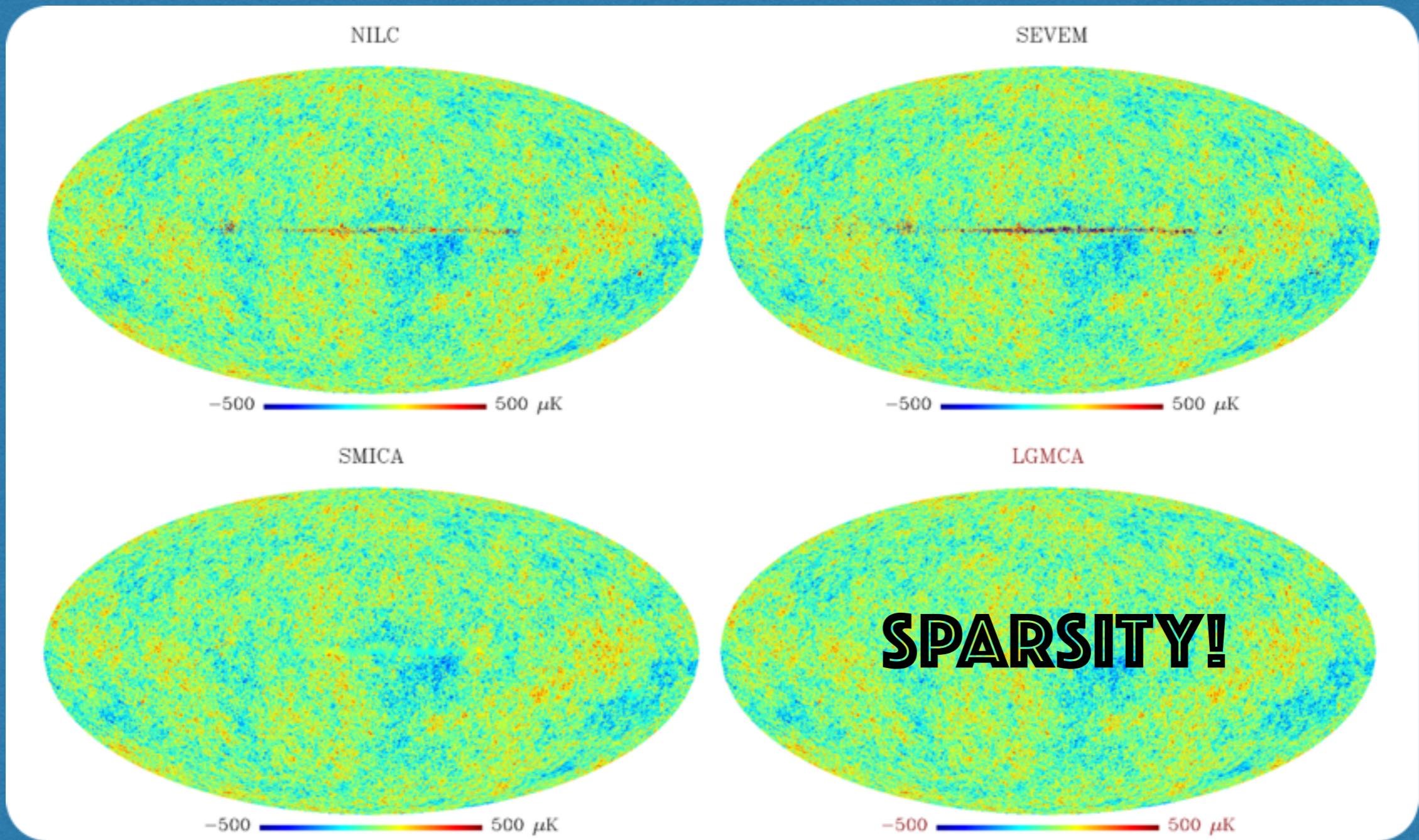
# BLIND SOURCE SEPARATION

## CMB Example



# BLIND SOURCE SEPARATION

## CMB Example

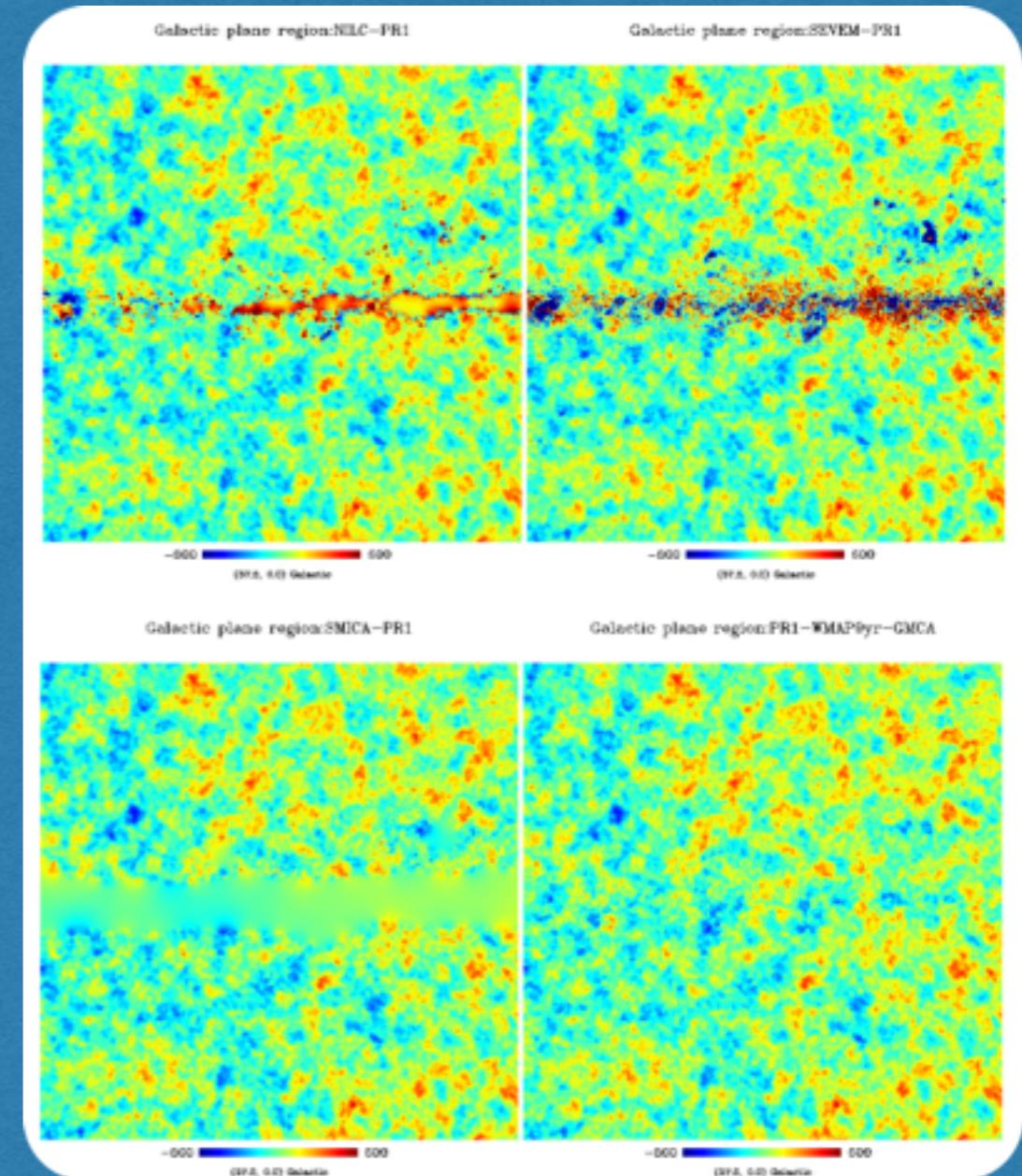


# BLIND SOURCE SEPARATION

## CMB Example

Sparsity allows for better modelling of the foregrounds.

Other methods use second order statistics.



**ΕΥΧΑΡΙΣΤΩ**