

19 Dec.

## MACHINE LEARNING ALGORITHMS.

No need to explicitly program, the machine learns by itself.

- Supervised learning: Huge, labelled data.
- Unsupervised learning: Clustering; unlabelled data.
- Semi-supervised learning: Some are labelled, some not.
- Reinforcement learning: Carrot & stick method?
- Deep (Generative) learning: language model, generate something, layers of Neural Nets.

### (1) Supervised Learning:

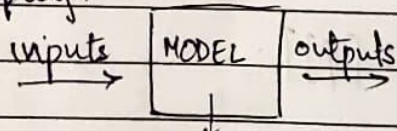
Regression problem: Outputs a real number.

Classification problem: Binary or Multiclass.

$\mathcal{H}$  - Clearly  $\mathcal{H}$ : All possible hypotheses(?)  
 $h \in \mathcal{H}$ ,  $h$  is the needed hypothesis.

31 Dec

Mapping:



Mathematical model:

family of math equations.

Training a model: finding parameters that predict outputs 'well' from inputs for a training dataset of input/output pairs.



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Parameters:  $y = mx + b$ .

Here,  $m$  &  $b$  influence the relationship  
blw  $y$  &  $x$ .

Regression: finding the best possible relationship  
blw  $x$  &  $y$ .

Need for a generalized model: a model that  
isn't made specifically for the dataset alone,  
but works for more data with good results.

\* Capital bold  $X$  - matrix.

\* Bold variable - ~~scalar~~ vector.

\* normal variable - scalar value; single value.

\* Parameters:  $\Phi$ ; Model:  $y = f[x, \Phi]$ .

\* Loss function:

Measures how bad the model is.

Find the parameter that minimize the loss:

$$\hat{\Phi} = \underset{\Phi}{\operatorname{argmin}} [L[\Phi]].$$

Testing a model: Separate test data with  
input/output pairs.

↳ checks how well it generalizes.

Supervised: mapping from one input to multiple output  
[classification model].

mapping from multiple input to one  
output [regression model].

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$$J[\theta] = \frac{1}{2} \sum_{i=1}^n (\theta_0 + \theta_1 x_i - y_i)^2$$

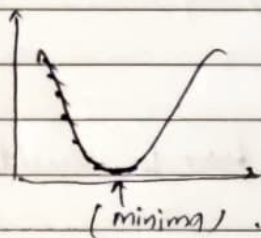
↳ least square loss function.

Gradient Descent Algorithm:

Take / Compute the slope at a point;

Equate to 0;

Check next point, if it is greater than current point, current point is a minimum.



16 Jan.

\* Hypothesis:

$$h(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots$$

$$\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{bmatrix} \text{ - parameter / weights.}$$

$$h(x) = \sum_{i=0}^n \theta_i x_i$$

\* Cost Function:

$$J(\theta) = \frac{1}{2} \sum_{i=1}^n (h(x_i) - y_i)^2$$



NEW  
PLAY

Take house price dataset and write code for Gradient Descent with only 2 features, in python [Find convergence rate, experiment with different learning rate.]

\* Gradient Descent Algorithm:

$$\theta_j := \theta_j - \alpha \nabla_{\theta_j} J(\theta).$$

where  $\nabla = \frac{\partial}{\partial \theta_j}$ .

$\alpha$  = learning rate.

$$\frac{\partial}{\partial \theta_j} J(\theta) = \frac{\partial}{\partial \theta_j} \frac{1}{2} (h_{\theta}(x) - y)^2.$$

[Partial deriv cause  $\theta_j$  has is multivariate].

$$\begin{aligned} \frac{\partial}{\partial \theta_j} J(\theta) &= 2 \cdot \frac{1}{2} (h_{\theta}(x) - y) \frac{\partial}{\partial \theta_j} (h_{\theta}(x) - y) \\ &= (h_{\theta}(x) - y) \frac{\partial}{\partial \theta_j} \left( \sum_{i=0}^n \theta_i x_i - y \right). \end{aligned}$$

$$\nabla_{\theta_j} J(\theta) = (h_{\theta}(x) - y) x_j.$$

in case  $\rightarrow$  Multiple variables, then it is Hessian matrix.

$$\Rightarrow \theta_j := \theta_j + \alpha (y_i - h_{\theta}(x_i)) x_j.$$

$\rightarrow$  LMS - update rule: Least Mean Square Update Rule.  
Also called: Widrow - Hoff Learning Rule.

Repeat until convergence; when the error term  $(y_i - h_{\theta}(x_i)) x_j$  does not change, hence  $\theta_j$  does not change.

28 Jan

## \* Logistic Regression:

Email classifier [Binary]:

$$y = \{\text{Spam}, \text{Ham}\}.$$

$$h_{\theta}(x) = g(\theta^T x).$$

$$= \left[ \frac{1}{1 + e^{-\theta^T x}} \right]. \quad (\text{Sigmoid}).$$

$$g(z) = \frac{1}{1 + e^{-z}}.$$

$g(z)$  is always bounded between 0 & 1.

$$g'(z) = \frac{d}{dz} \frac{1}{1 + e^{-z}}.$$

$z$  vs  $z^{\wedge}$ ?

$$= \frac{1}{(1 + e^{-z})^2} e^{-z}.$$

$$= \left[ \frac{1}{(1 + e^{-z})} \right] \left[ 1 - \frac{1}{(1 + e^{-z})} \right].$$

$$g'(z) = g(z)(1 - g(z)).$$

Assume that:

$$P(y=1 | x; \theta) = h_{\theta}(x).$$

$$P(y=0 | x; \theta) = (1 - h_{\theta}(x)).$$

$$P(y | x; \theta) = (h_{\theta}(x))^y (1 - h_{\theta}(x))^{1-y}$$

Likelihood:  $L(\theta) = P(y | x; \theta)$

$$= \prod_{i=1}^n P(y^i | x^i; \theta).$$



HW: Compare the standard stochastic descent rule of linear regression and stochastic ascent rule of logistic regression. What similarities do you observe? Is it a coincidence?

$$L(\theta) = P(y | x; \theta)$$

$$= \prod_{i=1}^n P(y_i | x_i; \theta)$$

$$= \prod_{i=1}^n (h_{\theta}(x_i))^{y_i} (1 - h_{\theta}(x_i))^{1-y_i}$$

log likelihood:

$$l(\theta) = \log L(\theta)$$

$$l(\theta) = \sum_{i=1}^n y_i \log(h_{\theta}(x_i)) + (1-y_i) \log(1 - h_{\theta}(x_i))$$

Maximize likelihood:

$$\frac{\partial l(\theta)}{\partial \theta_j} = \left[ y \frac{1}{g(\theta^T x)} - (1-y) \frac{1}{1-g(\theta^T x)} \right] \frac{\partial g(\theta^T x)}{\partial \theta_j}$$

$$y \in \{0, 1\} \Rightarrow h_{\theta}(x) = g(x) = g(\theta^T x)$$

$$\frac{\partial l(\theta)}{\partial \theta_j} = \left[ y \frac{1}{g(\theta^T x)} - (1-y) \frac{1}{1-g(\theta^T x)} \right] \frac{\partial g(\theta^T x)}{\partial \theta_j}$$

$$= (y(1-g(\theta^T x)) - (1-y)g(\theta^T x)) z_j$$

$$= (y - h_{\theta}(x)) z_j$$

Stochastic Gradient Ascent

$$\theta_j := \theta_j + \alpha (y_i - h_{\theta}(x_i)) z_j$$

$$\text{From } \theta = \theta + \alpha \nabla_{\theta} l(\theta)$$

## \* Bayesian Decision Theory:

Classification: class  $w_1$ , class  $w_2$ .  
Accept product. ← Reject product.

Decision Rule:

REJECTED  
 $P(w_1) > P(w_2) \Rightarrow w_1$ .  
 $P(w_1) < P(w_2) \Rightarrow w_2$ . } Sometimes good, but not always.

$P(w_1), P(w_2)$  are called Apriori probabilities.  
Decision is based on some feature  $x$ .

Probability density function of variable  $x$  given  $w_1$  or  $w_2$ :

$P(x|w_1)$ ;  $P(x|w_2)$ . → Class conditional probabilities

Decision is based on:  $P(w_1|x)$ ;  $P(w_2|x)$ .

Joint probability:  $P(w_i, x) = P(w_i|x)P(x)$  or  $P(x|w_i)P(w_i)$ . [Product rule]

$$\Rightarrow P(w_i|x) = \frac{P(x|w_i)P(w_i)}{P(x)}$$

where  $P(x) = \sum P(x|w_i)P(w_i)$ .

Decision Rule:

$$P(w_1|x) > P(w_2|x) \Rightarrow w_1.$$

$$P(w_1|x) < P(w_2|x) \Rightarrow w_2.$$



(Jan 31  
1996)

Exam portion: Moodle - first 4 chapters of textbook.  
Exam time 9-11?? Why not 10-12?  
Adat se majhane

$$P(x|w_1)P(w_1) > P(x|w_2)P(w_2) \rightarrow w_1$$

Here, the decision is made based on a priori probabilities and class conditional probabilities.

6 Feb

\* Parametric methods:

- Maximum Likelihood estimation (MLE):

Bayes' Theorem:  $P(\theta|x) \propto P(x|\theta)P(\theta)$   
Posterior Likelihood  $\rightarrow$  joint?

$P(x|\theta)$   $\leftarrow$  likelihood.

$$L(\theta|x) = P(x|\theta) = \prod_{t=1}^N P(x_t|\theta).$$

$x = \{x_t\}_{t=1}^N \leftarrow$  Draw some (N) data from a known distribution,  $P(x|\theta)$ .

$$x_i \sim P(x|\theta). ; \theta = \begin{bmatrix} \mu \\ \sigma \end{bmatrix}. \theta_1 = \begin{bmatrix} \mu_1 \\ \sigma_1 \end{bmatrix} \infty \theta_p = \begin{bmatrix} \mu_p \\ \sigma_p \end{bmatrix}.$$

log likelihood function:

$$\begin{aligned} L(\theta|x) &= \log L(\theta|x) \\ &= \sum_{t=1}^N \log P(x_t|\theta). \end{aligned}$$

Bernoulli Distribution:  $\text{Ber}(p)$ ; Binomial( $n, p$ ).  
 $P(x) = p^x(1-p)^{1-x}$ ;  $x \in \{0, 1\}$ .

$$\begin{aligned} L(p|x) &= \log \prod_{t=1}^N P(x_t^0)(1-p)^{(1-x_t^0)} \\ &= \sum_{t=1}^N x_t \log p + (N - \sum_{t=1}^N x_t) \log(1-p). \end{aligned}$$



# Galyan!

→ Method?

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Maximize: Estimate  $\hat{P} = \frac{\sum x_t}{N}$   $\mathbb{E}$

$$\hat{P} = \frac{\sum_t x_t}{N}$$

It is called estimate.

\* Bias and Variance:

$X \neq \theta$ . Bias of a graph distribution, not necessarily.

Estimator of  $\theta \leftarrow d = d(X) \rightarrow \hat{P}(\theta)$ .

$$\text{Error} = (d(X) - \theta)^2$$

$$v(d, \theta) = E[(d(X) - \theta)^2]$$

Mean Square Error.

$$\text{Bias of an estimator: } b_\theta(d) = \underline{E[d(X)]} - \theta$$

What does unbiased estimator mean?

For all  $\theta$ ,  $b_\theta = 0$ , we call it unbiased estimator.

→ number of samples.

$$E[m] = E\left[\frac{\sum x_t}{N}\right] = \frac{1}{N} \sum \frac{x_t}{N} = \frac{N\mu}{N} = \mu$$

→ concept used similar to.

Law of large numbers: When sample size  $\uparrow$ , sample mean  $\rightarrow$  actual mean.

$$\text{Variance: } \text{Var}(m) = \text{Var}\left[\frac{\sum x_t}{N}\right] = \frac{\sigma^2}{N}$$

$$\text{Var} = E[X^2] - (E[X])^2$$

Mean Square Error:

$$V(d, \theta) = E[\hat{d}(x) - \theta]^2$$

$$V(d, \theta) = E[(d(x) - \theta)^2]$$

$$= E \left[ \underbrace{(d - E[d])^2}_{\text{variance}} + \underbrace{(E[d] - \theta)^2}_{\text{bias}} \right]$$

\*

$$V(d, \theta) = \text{Var}(d) + \text{bias}^2$$

$$\text{Error} = \text{variance} + \text{bias}^2$$