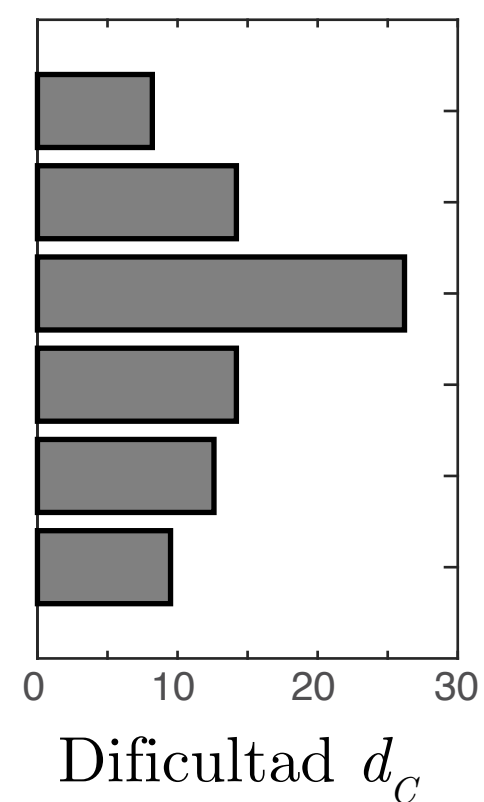
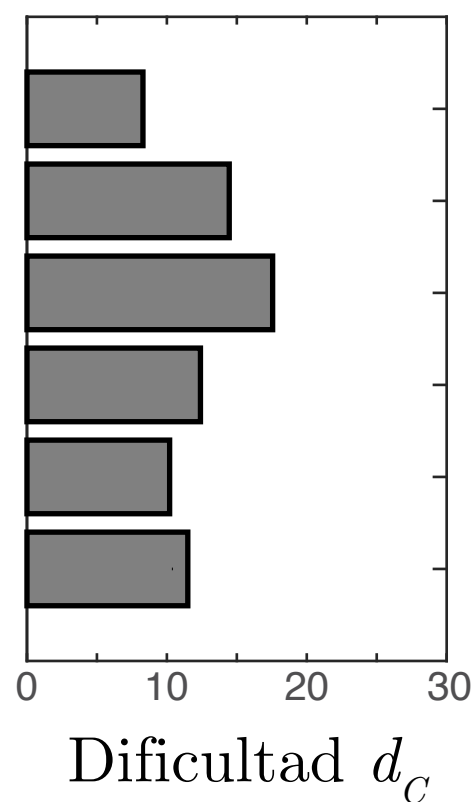
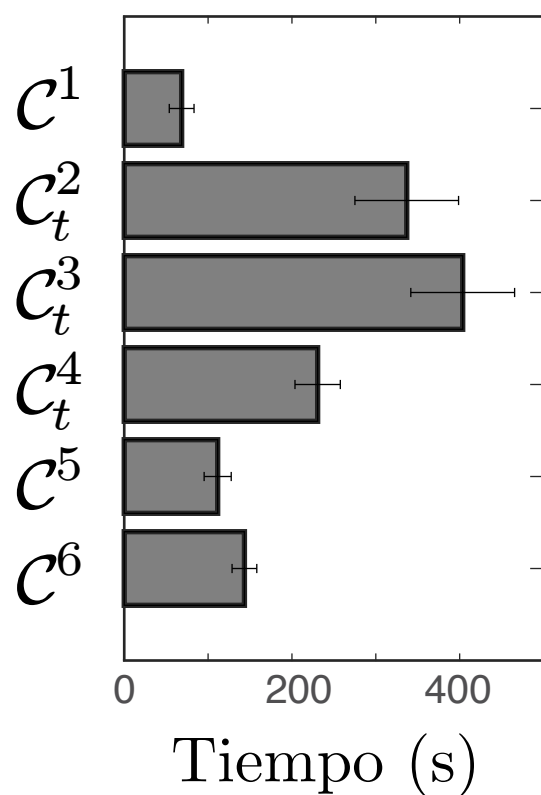


Participantes

Modelo dinámico

Modelo estático

Objetivo



Control

