

Team unimi  
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2. TREES

2.1. Lca.

```
// LCA with binary lifting -----//d7
// just add node with pointer to father -----//83
// be careful as memory is MAXN * MAXJ -----//21
// MAXJ should be >= log2(N) -----//40
const int MAXN = 1e5; -----//3e
const int MAXJ = 20; -----//d0
struct node { -----//cd
- node *p, *jmp[MAXNJ]; -----//cd
- int depth; -----//07
- node(node *_p = NULL) : p(_p) { -----//14
--- depth = p ? 1 + p->depth : 0; -----//92
--- memset(jmp, 0, sizeof(jmp)); -----//f3
--- jmp[0] = p; -----//40
--- for (int i = 1; (1<<i) <= depth; i++) -----//b1
----- jmp[i] = jmp[i-1]->jmp[i-1]; } }; -----//c0
node* st[MAXN]; -----//88
node* lca(node *a, node *b) { -----//a7
- if (!a || !b) return NULL; -----//90
- if (a->depth < b->depth) swap(a,b); -----//ac
- for (int j = 19; j >= 0; j--) -----//5b
--- while (a->depth - (1<<j) >= b->depth) a = a->jmp[j]; -----//47
- if (a == b) return a; -----//dc
- for (int j = 19; j >= 0; j--) -----//1c
--- while (a->depth >= (1<<j) && a->jmp[j] != b->jmp[j]) -----//bf
----- a = a->jmp[j], b = b->jmp[j]; -----//b9
- return a->p; } -----//3d
```

2.2. Hld.

```
vector<int> g[MN]; //graph -----//78
vector<int> parent(n),hldpos(n),chain(n),chain_d(n),dim(n); //2b
//computes subtree dimensions, stores parent of each node --//d6
void hlddffs0(int p){ -----//9c
--- dim[p]=1; -----//b2
--- for(auto i:g[p]){ -----//e8
----- if(i!=parent[p]){ -----//29
----- parent[i]=p; -----//d6
----- dfs1(i); -----//f8
----- dim[p]+=dim[i]; -----//75
----- } -----//01
--- } -----//41
} -----//94
//heavy light decomp/hldposition -----//df
```

```
void hlddfs1(int p, int chain_id, int cd){ -----//1e
--- hldpos[p]=cnt++; //hldposition in base array for rt queries
--- chain[p]=chain_id; // highest node in chain -----//4b
--- chain_d[p]=cd; // chain depth -----//db
--- int hldson=-1; -----//86
--- for(auto i:g[p])if(i!=parent[p]&&(hldson== -1 || dim[i]>dim[hldson])){
--- if(hldson!=-1){ //not a leaf node -----//fe
----- buildhld(hldson,chain_id,cd); //heavy child -----//d7
----- for(auto i:G[p]){ -----//75
----- if(i!=parent[p] && i!=hldson[p]) //light edge --//bf
----- buildhld(i,i,cd+1); -----//76
----- } -----//4d
--- } -----//12
} -----//16
parent[0]=-1; -----//23
hlddfs0(0); -----//45
hlddfs1(0,0,0); -----//d3
// build ds with new indeces (in hldpos) -----//e4
int query(int x, int y){ -----//a8
--- int ans=0; -----//c7
--- if(chain_d[chain[x]]>chain_d[chain[y]]) -----//96
----- swap(x,y); -----//f2
--- for(int dif = chain_d[chain[y]]-chain_d[chain[x]]; dif; --dif){
----- ans=max(ans,rmq(hldpos[chain[y]],hldpos[y])); -----//6c
----- y=chain[y]; y=parent[y]; -----//30
--- } -----//12
--- while(chain[x]!=chain[y]){ -----//9e
----- ans=max(ans,rmq(hldpos[chain[y]],hldpos[y])); -----//f1
----- y=chain[y]; y=parent[y]; -----//18
----- ans=max(ans,rmq(hldpos[chain[x]],hldpos[x])); -----//dc
----- x=chain[x]; x=parent[x]; -----//e9
--- } -----//81
--- if(hldpos[x]<hldpos[y]) -----//73
----- ans=max(ans,rmq(hldpos[x],hldpos[y])); -----//78
--- else -----//69
----- ans=max(ans,rmq(hldpos[y],hldpos[x])); -----//ed
--- return ans; -----//8f
} -----//c9
-----//f0
```

2.3. Centroid Decomp.

```
/* Centroid decomposition, O(NlogN) memory/time -----//59
- Given a 0-rooted tree, build a tree of height logN -----//7d
- then process it in order to answer A to B (path) queries //e7
- Can also be used in other situations -----//6c
*/ -----//e3
struct centroid_decomposition{ -----//7f
- vvi &g, c; -----//f2
- vi size; -----//8e
- vi parent; -----//11
- int n, root; -----//d7
- vvi memo; -----//5d
- int height; -----//97
- vector<char> level; -----//a2
- int dfs(int i){ -----//f9
--- size[i] = 1; -----//46
```

```

-- for(int x : g[i]) -----//b5
-- dfs(x), size[i] += size[x]; -----//85
-- return size[i]; -----//18
- } -----//05
- bool is_centroid(int i, int r){ -----//02
-- for(int x : g[i]) -----//ba
-- if(size[x] > size[r]/2) -----//aa
-- return 0; -----//3f
-- return 1; } -----//ed
- int preferred(int i){ -----//bd
-- if(g[i].size() == 0) -----//e8
-- return i; -----//72
-- int x = g[i].front(); -----//02
-- for(int e : g[i]) -----//75
-- if(size[e] > size[x]) -----//6f
-- x = e; -----//a9
-- return x; } -----//14
- int centroidify(int i, int p){ -----//ff
-- int curr = i; -----//e5
-- vi path; -----//51
-- while(!is_centroid(curr, i)){ -----//59
-- path.push_back(curr); -----//84
-- curr = preferred(curr); -----//24
-- } -----//1d
-- for(int p : path) -----//a3
-- size[p] -= size[curr]; -----//79
-- size[curr] = 0; -----//e0
-- parent[curr] = p; -----//9f
-- if(i != curr) -----//5c
-- c[curr].push_back(centroidify(i, curr)); -----//00
-- for(int x : g[curr]) if(size[x]) -----//70
-- c[curr].push_back(centroidify(x, curr)); -----//f3
-- return curr; } -----//4c
- // i think this should be done in centroidify -----//8e
- void level_dfs(int i){ -----//07
-- for(int x : c[i]){ -----//40
-- level[x] = level[i]+1; -----//cd
-- level_dfs(x); -----//66
-- } } -----//c5
-----//9b
- /* IMPORTANT: -----//b0
-- if you need to answer query, -----//90
-- you can just precompute PATHS -----//0e
-- from/to each centroid to all his -----//26
-- childs. Then you can answer A->B queries using -----//3d
-- LCA and this precomputed paths */ -----//a1
-----//a1
- void decompose(){ -----//51
-- dfs(0); -----//5f
-- int root = centroidify(0, -1); -----//cb
-- level[root] = 0; -----//96
-- level_dfs(root); -----//d8
-- height = *max_element(level.begin(), level.end()) + 1; //83
-- fill(size.begin(), size.end() , 1); -----//40
- } -----//f8
- centroid_decomposition(vvi &source) : g(source), n(source.size()),
-- c(source.size()), size(source.size()), level(source.size()),
-- parent(source.size()) { -----//40
-- decompose(); -----//6c
- } -----//50
}; -----//d7

3. STRINGS

3.1. Suffix Tree2.
#include <bits/stdc++.h> -----//84
using namespace std; -----//16
-----//11
const int MAXN = 2e5; -----//19
-----//a3
string s; -----//d0
int n; -----//42
-----//2c
struct node { -----//8b
-- int l, r, par, link; -----//d3
-- map<char,int> next; -----//b2
-----//86
-- node (int l=0, int r=0, int par=-1) -----//9a
-- : l(l), r(r), par(par), link(-1) {} -----//d3
-- int len() { return r - l; } -----//b1
-- int &get (char c) { -----//01
-- if (!next.count(c)) next[c] = -1; -----//0d
-- return next[c]; -----//dc
-- } -----//cd
-- void print(){ -----//fa
-- cout << l << ' ' << r << ' ' << par << ' ' << link << '\n'; -----//8c
-- } -----//8c
}; -----//fb
node t[MAXN]; -----//00
int sz; -----//5f
-----//1a
struct state { -----//b9
-- int v, pos; -----//0a
-- state (int v, int pos) : v(v), pos(pos) {} -----//fe
}; -----//0e
state ptr (0, 0); -----//4b
-----//a0
state go (state st, int l, int r) { -----//91
-- while (l < r) -----//01
-- if (st.pos == t[st.v].len()) { -----//2f
-- st = state (t[st.v].get( s[l] ), 0); -----//f1
-- if (st.v == -1) return st; -----//c4
-- } -----//fa
-- else { -----//de
-- if (s[ t[st.v].l + st.pos ] != s[l]) -----//51
-- return state (-1, -1); -----//28
-- if (r-l < t[st.v].len() - st.pos) -----//ec
-- return state (st.v, st.pos + r-l); -----//0f
-- l += t[st.v].len() - st.pos; -----//11
-- st.pos = t[st.v].len(); -----//e9
-- } -----//55
-- return st; -----//c2
} -----//45

int split (state st) { -----//d9
-- if (st.pos == t[st.v].len()) -----//d1
-- return st.v; -----//59
-- if (st.pos == 0) -----//b3
-- return t[st.v].par; -----//b7
-- node v = t[st.v]; -----//2a
-- int id = sz++; -----//99
-- t[id] = node (v.l, v.l+st.pos, v.par); -----//27
-- t[v.par].get( s[v.l] ) = id; -----//67
-- t[id].get( s[v.l+st.pos] ) = st.v; -----//bf
-- t[st.v].par = id; -----//da
-- t[st.v].l += st.pos; -----//0a
-- return id; -----//1c
} -----//cc
-----//fa
int get_link (int v) { -----//ce
-- if (t[v].link != -1) return t[v].link; -----//07
-- if (t[v].par == -1) return 0; -----//68
-- int to = get_link (t[v].par); -----//0f
-- return t[v].link = split (go (state(to,t[to].len()), t[v].l +
} -----//33
-----//d6
void tree_extend (int pos) { -----//75
-- for(;;) { -----//18
-- state nptr = go (ptr, pos, pos+1); -----//0a
-- if (nptr.v != -1) { -----//ce
-- ptr = nptr; -----//5d
-- return; -----//6d
-- } -----//70
-----//fb
-- int mid = split (ptr); -----//7f
-- int leaf = sz++; -----//0f
-- t[leaf] = node (pos, n, mid); -----//be
-- t[mid].get( s[pos] ) = leaf; -----//a4
-----//24
-- ptr.v = get_link (mid); -----//7c
-- ptr.pos = t[ptr.v].len(); -----//76
-- if (!mid) break; -----//76
-- } -----//8f
} -----//d7
-----//45
void build_tree() { -----//e1
-- sz = 1; -----//71
-- for (int i=0; i<n; ++i) -----//75
-- tree_extend (i); -----//96
} -----//fa
-----//f6
-----//69
int main() { -----//3a
-- cin >> s; -----//c9
-- n = s.size(); -----//79
-- build_tree(); -----//f6
-----//f4
-- node root = t[0]; -----//60
-----//82
```

```
- vector<bool> exists(1000); -----//0c // O(N * logAlfa) Suffix Tree construction -----//70
- for(char c : s) -----//af -----//f3
- exists[c] = 1; -----//c5 const int inf = 1e9; -----//ef
-----//08 const int maxn = 1e4; -----//74
-----//ff char s[maxn]; -----//47
- while(){ -----//f1 map<int, int> to[maxn]; -----//0d
- string x; cin >> x; -----//e4 int len[maxn], f_pos[maxn], link[maxn]; -----//52
- bool ok = 1; -----//11 int node, pos; -----//20
- for(char c : x) -----//50 int sz = 1, n = 0; -----//4b
- if(exists[c] == 0){ -----//8b int make_node(int _pos, int _len){ -----//ad
- ok = 0; -----//74 - f_pos[sz] = _pos; -----//c5
- break; -----//ea - len[sz] = _len; -----//3c
- } -----//18 - return sz++; -----//33
- if(!ok) { -----//5b } -----//05
- cout << -1 << '\n', 0; -----//0f void go_edge(){ -----//43
- continue; -----//85 - while(pos > len[to[node][s[n - pos]]){ -----//28
- } -----//67 - node = to[node][s[n - pos]]; -----//76
- node curr = root; -----//78 - pos -= len[node]; -----//f5
- int l = 0, r = 0; -----//b7 - } -----//27
- int blocks = 1; -----//90 } -----//df
- for(int i = 0; i < x.size(); i++) { -----//2d void add_letter(int c){ -----//b2
- if(l >= r) { -----//62 - s[n++] = c; pos++; -----//70
- int next = curr.get(x[i]); -----//a5 - int last = 0; -----//8f
- // cout << "block is over, next is " << next << '\n'; -----//75
- if(next == -1) { -----//6b go_edge(); -----//ce
- blocks++; -----//5b int edge = s[n - pos]; -----//8e
- // cout << "finished matching, new block\n"; -----//02 int &v = to[node][edge]; -----//05
- curr = root; -----//71 int t = s[f_pos[v] + pos - 1]; -----//83
- // repeat this letter, but from root -----//01 if(v == 0){ -----//b6
- i--; -----//99 v = make_node(n - pos, inf); -----//c6
- continue; -----//5d link[last] = node; -----//2d
- } -----//7e last = 0; -----//65
- curr = t[next]; -----//08 } else if(t == c){ -----//2d
- l = curr.l, r = curr.r; -----//61 link[last] = node; -----//fc
- // cout << "could match " << l << " to " << r << '\n'; -----//3e
- } -----//e9 } else{ -----//39
- // match next one -----//f7 int u = make_node(f_pos[v], pos - 1); -----//a2
- if(s[l] != x[i]) { -----//c6 to[u][c] = make_node(n - 1, inf); -----//1e
- blocks++; -----//a7 to[u][t] = v; -----//37
- // cout << "new block in " << i << '\n'; -----//f0 f_pos[v] += pos - 1; -----//b6
- curr = root; -----//8f len[v] -= pos - 1; -----//3f
- l = curr.l, r = curr.r; -----//aa v = u; -----//94
- i--; -----//60 link[last] = u; -----//3e
- } else{ -----//da last = u; -----//27
- // cout << "match " << i << " in " << l << '\n'; -----//b2 } -----//ce
- l++; -----//d3 if(node == 0) pos--; -----//93
- } -----//7b else node = link[node]; -----//9a
- } -----//ad } -----//3f
- // cout << "\nsolved in " << blocks << "\n\n"; -----//be } -----//3f
- cout << blocks << '\n'; -----//79 int main(){ -----//b0
- } -----//79 - len[0] = inf; -----//8b
-----//c1 - string s; -----//f6
-----//0e - cin >> s; -----//ba
- int ans = 0; -----//92
- for(int i = 0; i < s.size(); i++) -----//a2
- add_letter(s[i]); -----//4d
- for(int i = 1; i < sz; i++) -----//53
- ans += min((int)s.size() - f_pos[i], len[i]); -----//51
- cout << ans << "\n"; -----//2d
} -----//99
3.3. Suffix Array.
//O(NlogN) suffixarray - add a $ char at the end -----//36
-----//53
struct suffarray{ -----//76
- vi sa; -----//94
- string &s; -----//52
- void radix_sort(vi &rank, int k){ -----//fd
- vi count(max(256, (int)sa.size())); -----//54
- for(int i : sa) count[((i + k) < rank.size() ? rank[i+k]+1 : 1); -----//23
- int last = 0; -----//23
- for(int &i : count) i = last += i; -----//00
- vi temp(sa.size()); -----//4d
- for(int i : sa) temp[count[(i + k < rank.size() ? rank[i] + k) -----//2c
- fill(count.begin(), count.end(), 0); -----//2c
- for(int &i : rank) count[i+1]++; -----//78
- last = 0; -----//96
- for(int &i : count) i = last += i; -----//e6
- for(int i : temp) sa[count[rank[i]]++] = i; -----//d9
- } -----//46
- void update_ranks(vi &rank, int k){ -----//e4
- vi old(rank); -----//73
- int r = rank[sa[0]] = 0; -----//2c
- for(int i = 1; i < rank.size(); i++) -----//23
- rank[sa[i]] = (old[sa[i]] == old[sa[i-1]] && (sa[i] + k < o -----//1d
- old[sa[i]+k] : 0) <= (sa[i-1]+k < old.size() ? old[sa[i-1]]+1) -----//1d
- } -----//1d
- suffarray(string &s) : sa(s.size()), s(s){ -----//dd
- int n = s.size(); -----//0c
- for(int i = 0; i < n; i++) -----//1c
- sa[i] = i; -----//ad
- vi rank(s.size()); -----//c8
- for(int i = 0; i < s.size(); i++) -----//44
- rank[i] = s[i]; -----//11
- for(int k = 1; k <= n; k<=1){ -----//2b
- radix_sort(rank, k); -----//44
- update_ranks(rank, k); -----//fc
- if(rank[sa.back()] == s.size()-1) break; -----//e3
- } -----//e2
- } -----//cf
}; -----//df
// O(N) to compute LCP array -----//ff
//ignore the $ sign? -----//63
vi lcp_kasai(suffarray &x){ -----//7d
- vi &sa = x.sa; -----//95
- string &s = x.s; -----//34
- int n = sa.size(); -----//06
- vi rev(n), lcp(n); -----//ad
- for(int i = 1; i < n; i++) -----//87
- rev[sa[i]] = i; -----//f6
- for(int i = 1, k = 0; i < n; i++){ -----//9d
- if(rev[i] == n-1) continue; -----//4d
```

```
--- int next = sa[rev[i]+1]; -----//8a
--- while(i+k < n && next+k < n && s[i+k] == s[next+k]) ---//6c
--- k++; -----//dc
--- lcp[rev[i]] = k; -----//ae
--- if(k) k--; -----//9e
- } -----//5c
- return lcp; -----//ee
} -----//e5

3.4. Polynomial Hashing.
pair<ll,ll> diofante(ll a, ll b){ -----//e2
    if(!a)return {0,1}; -----//9d
    auto t = diofante(b%a,a); -----//3d
    return {t.second-(b/a)*t.first,t.first}; -----//8b
} -----//75
ll modinv(ll x, ll m){ -----//fe
    return (diofante(x,m).first%m+m)%m; -----//cd
} -----//93
template<class T, ll a, ll mod> //use int sized stuff, does not handle overflow over 64 bit -----//61
struct prefix_hash{ -----//80
    int n; -----//1f
    vector<ll> a_inv; -----//15
    vector<ll> psum; -----//14
    prefix_hash(T& arr, int n):n(n),a_inv(n),psum(n+1){ -----//40
        a_inv[0]=1; -----//1f
        a_inv[1]=modinv(a,mod); -----//99
        for(int i=2; i<n; ++i){ -----//15
            a_inv[i]=(a_inv[1]*a_inv[i-1])%mod; -----//a3
        } -----//a1
        psum[n]=0; -----//e1
        psum[n-1]=arr[n-1]; -----//8f
        ll powa=a; -----//15
        for(int i=n-2; i>=0; --i){ -----//29
            psum[i]=(psum[i+1]+powa*arr[i]%mod)%mod; -----//cb
            powa=(powa*a)%mod; -----//19
        } -----//c2
        match = p[match - 1]; -----//ea
        match += c == s[match]; -----//e1
        int ans=0; -----//01
        while(match <= n){ -----//0d
            match = p[match]; -----//47
        } -----//f4
        return ans; -----//23
    }
}; -----//2e
-----//9a
```

3.4. Polynomial Hashing.

```
pair<ll,ll> diofante(ll a, ll b){ -----//e2
    if(!a)return {0,1}; -----//9d
    auto t = diofante(b%a,a); -----//3d
    return {t.second-(b/a)*t.first,t.first}; -----//8b
} -----//75
ll modinv(ll x, ll m){ -----//fe
    return (diofante(x,m).first%m+m)%m; -----//cd
} -----//93
template<class T, ll a, ll mod> //use int sized stuff, does not handle overflow over 64 bit -----//61
struct prefix_hash{ -----//80
    int n; -----//1f
    vector<ll> a_inv; -----//15
    vector<ll> psum; -----//14
    prefix_hash(T& arr, int n):n(n),a_inv(n),psum(n+1){ -----//40
        a_inv[0]=1; -----//1f
        a_inv[1]=modinv(a,mod); -----//99
        for(int i=2; i<n; ++i){ -----//15
            a_inv[i]=(a_inv[1]*a_inv[i-1])%mod; -----//a3
        } -----//a1
        psum[n]=0; -----//e1
        psum[n-1]=arr[n-1]; -----//8f
        ll powa=a; -----//15
        for(int i=n-2; i>=0; --i){ -----//29
            psum[i]=(psum[i+1]+powa*arr[i]%mod)%mod; -----//cb
            powa=(powa*a)%mod; -----//19
        } -----//c2
        match = p[match - 1]; -----//ea
        match += c == s[match]; -----//e1
        int ans=0; -----//01
        while(match <= n){ -----//0d
            match = p[match]; -----//47
        } -----//f4
        return ans; -----//23
    }
}; -----//2e
-----//9a

3.5. Manacher.
// O(N) algorithm to find longest -----//36
// palindromic substring with center -----//08
// in each index -----//c4
// first[i] = longest ODD size pal. in i -----//71
// second[i] = longest EVEN size pal. in i -----//0e
pair<vi, vi> manacher (string s) { -----//1f
- vi d1(s.size()), d2(s.size()); -----//9b
- int n = s.size(); -----//ca
- int l = 0, r = -1; -----//fa
- for (int i = 0; i < n; ++i) { -----//21
--- int k = (i > r ? 0 : min (d1[l + r - i], r - i)) + 1; -----//0c
--- while (i + k < n && i - k >= 0 && s[i + k] == s[i - k]) ++k; -----//08
--- d1[i] = k--; -----//2d
} -----//21

3.6. Kmp.
//c@(|S| + |T|) string matchin with KMP -----//1b
// Computes occurrences of S in T -----//01
vi pref_func(const string &s){ -----//2c
    vi p(s.size()); -----//a4
    for(int i = 1, match = 0; i < s.size(); i++){ -----//8e
        while(match && s[i] != s[match]) -----//62
            match = p[match - 1]; -----//d9
        match = s[i] == s[match]; -----//96
        p[i] = match; -----//f9
    } -----//66
    return move(p); -----//e6
} -----//e1
int count_matches(string &s, string &t){ -----//8f
    vi p = pref_func(s); -----//dc
    int ans=0, match = 0; -----//16
    for(char c = t[0]; -----//cb
        while(match <= t.size() -----//19
            match = p[match]; -----//c2
            match += c == s[match]; -----//ea
            if(match == s.size()){ -----//e1
                ans++; -----//01
            }
        }
    }
    return ans;
}

3.7. Aho Corasick2.
// Aho corasick for -----//21
// "Count pattern occurencies" queries -----//ad
// O(N) time/memory complexity -----//cd
struct node{ -----//b2
    node *parent, *fall, *output; -----//71
    char c = '$'; -----//a6
    int ending = -1, taken = 0; -----//b8
    unordered_map<char, node*> f; -----//bf
    node(node *p, char c) : parent(p), c(c){} -----//d3
    node(){} -----//4b
    vector<node*> rev_out; -----//43
}; -----//db
```

3.5. Manacher.

```
pair<vi, vi> manacher (string s) { -----//1f
- vi d1(s.size()), d2(s.size()); -----//9b
- int n = s.size(); -----//ca
- int l = 0, r = -1; -----//fa
- for (int i = 0; i < n; ++i) { -----//21
--- int k = (i > r ? 0 : min (d1[l + r - i], r - i)) + 1; -----//0c
--- while (i + k < n && i - k >= 0 && s[i + k] == s[i - k]) ++k; -----//08
--- d1[i] = k--; -----//2d
} -----//21

3.7. Aho Corasick2.
// Aho corasick for -----//21
// "Count pattern occurencies" queries -----//ad
// O(N) time/memory complexity -----//cd
struct node{ -----//b2
    node *parent, *fall, *output; -----//71
    char c = '$'; -----//a6
    int ending = -1, taken = 0; -----//b8
    unordered_map<char, node*> f; -----//bf
    node(node *p, char c) : parent(p), c(c){} -----//d3
    node(){} -----//4b
    vector<node*> rev_out; -----//43
}; -----//db

3.8. Aho Corasick.
struct aho_trie{ -----//fe
- node *root = new node(); -----//27
- int l = 0; -----//e6
- void insert(string s){ -----//1c
    node *curr = root; -----//cb
    for(char c : s) -----//f8
        curr = curr->f.count(c) ? curr->f[c] : (curr->f[c] = new node(c)); -----//1b
    curr->ending = l++; -----//6d
} -----//6d
- void set_falls(){ -----//ac
    queue<node*> q; -----//3c
    q.push(root); -----//31
    while(!q.empty()){ -----//8f
        node *curr = q.front(); q.pop(); -----//52
        for(auto &x : curr->f) -----//1d
            q.push(x.second); -----//d6
        if(curr == root) continue; -----//70
        // compute suffix link -----//2d
        curr->fall = curr->parent->fall; -----//05
        while(curr->fall->f.count(curr->c) == 0 && curr->fall != root) -----//a3
            curr->fall = curr->fall->fall; -----//e0
        if(curr->fall != curr->parent && curr->fall->f.count(curr->c) == 0) -----//e0
            curr->fall = curr->fall->f[curr->c]; -----//e0
        curr->output = curr->fall->ending != -1 ? curr->fall : curr->parent->output; -----//20
        curr->output->rev_out.push_back(curr); -----//07
    }
}
- vi query(string s){ -----//e1
    node *stato = root; -----//34
    for(char c : s){ -----//6a
        while(stato != root && stato->f.count(c) == 0) -----//ec
            stato = stato->fall; -----//9b
        if(stato->f.count(c)) -----//3e
            stato = stato->f[c]; -----//52
        stato->taken++; -----//c6
    }
}
- vi ans(l); -----//de
function<int(node*)> dfs = [&](node *i){ -----//38
    int taken = 0; -----//37
    for(auto x : i->rev_out) -----//a5
        taken += dfs(x); -----//cd
    taken += i->taken; -----//54
    if(i->ending != -1) ans[i->ending] = taken; -----//73
    i->taken = 0; -----//49
    return taken; -----//c9
}; -----//85
dfs(root); -----//84
return ans; -----//d9
} -----//ec
- aho_trie(){ -----//33
    root->parent = root->fall = root->output = root; -----//23
} -----//37
}; -----//2f
```

3.8. Aho Corasick.

```
// Two-phase simplex algorithm for solving linear programs of the
// -----//f0
// maximize c^T x -----//e0
```



```
- VVD A(m); -----//10 // Linear sieve: returns the smallest divisor -----//dc
- VD b(_b, _b + m); -----//de // for all numbers in [0, N] -----//fa
- VD c(_c, _c + n); -----//3c vi divs(int n){ -----//6f
- for (int i = 0; i < m; i++) A[i] = VD(_A[i], _A[i] + n); //c7 - vi ans(n+1), primes; -----//73
-----//bf - iota(ans.begin(), ans.end(), 0); -----//9f
- LPSolver solver(A, b, c); -----//e2 - for(int k = 2; k <= n; k++){ -----//cc
- VD x; -----//d8 - if(ans[k] == k) -----//60
- DOUBLE value = solver.Solve(x); -----//1d - primes.push_back(k); -----//48
-----//09 - for(int p : primes){ -----//ea
- cerr << "VALUE: " << value << endl; // VALUE: 1.29032 -----//e3 - if(p > ans[k]) break; -----//46
- cerr << "SOLUTION: "; // SOLUTION: 1.74194 0.451613 1 -----//ae - if(p * k <= n) ans[p * k] = p; -----//f6
- for (size_t i = 0; i < x.size(); i++) cerr << " " << x[i]; -----//f3
- cerr << endl; -----//b0 - } -----//f5
- return 0; -----//5b - } -----//ad
} -----//a1 - return move(ans); -----//0a
} -----//cf
```

4.2. Sieve 2.

```
// Linear sieve variant:\ -----//75
- also computes euler totient (coprimes <= i),\ -----//ef
- number of distinct divisors,\ -----//7d
- sum of divisors,\ -----//9f
- for all i in [1, N] -----//d1
-----//41
struct sieve{ -----//7c
- vi d, s0, fi; // smallest div, number of divs, euler fi -----//bc
- vector<ll> s1; // sum of divisors -----//18
- sieve(int n) : d(n+1), s0(n+1), s1(n+1), fi(n+1){ -----//1d
- // just standard linear sieve -----//f5
- vi primes; -----//4b
- fi[1] = 1; -----//e7
- d[1] = 0; iota(d.begin() + 2, d.end(), 2); -----//81
- s0[1] = 1; -----//17
- s1[1] = 1; -----//81
- for(int k = 2; k <= n; k++){ -----//69
- if(d[k] == k) primes.push_back(k); -----//98
- for(int p : primes){ -----//41
- if(p > d[k]) break; -----//25
- if(p * (1ll)k <= n) d[p * k] = p; -----//68
- else break; -----//d1
- } -----//22
- // smallest div -----//ac
- ll p1 = d[k]; -----//85
- // fi function -----//b8
- if(d[k/p1] != p1) fi[k] = fi[k/p1] * (p1-1); -----//ac
- else fi[k] = fi[k/p1] * p1; -----//7e
- // distinct divisors -----//4c
- int times = 0; -----//f6
- for(int i = k / p1; d[i] == p1; i /= p1, times++); -----//01
- s0[k] = s0[k / p1] / (times+1) * (times+2); -----//65
- // sum of divisors -----//e3
- ll sum_prev = s1[k / bin_exp(p1, times + 1)]; -----//85
- s1[k] = s1[k/p1] + sum_prev * bin_exp(p1, times+1); -----//b0
- } -----//da
- } -----//0d
}; -----//4f
```

4.3. Sieve.

4.4. Segmented Sieve.

```
/* Returns primality for each number -----//c0
- in range [l, r], given a sieve -----//46
- up to sqrt(r), shifted by l -----//aa
- O(max(sqrt(r), r - l) * log(r-l)) */ -----//a7
-----//e1
vb seg_sieve(vi &sieve, int l, int r){ -----//13
- vb prime(r - l + 1); -----//b7
- for(int i = 2; i<sieve.size();i++){ -----//95
- if(sieve[i] != i) continue; -----//d1
- for(int j = i*(l/i); j<=r; j+=i){ -----//0b
- if(j < l) continue; -----//6d
- int tmp = j; -----//69
- while(tmp && tmp % i == 0){ -----//21
- tmp /= i; -----//64
- prime[j - l] = 1; -----//71
- } -----//11
- } -----//ee
- } -----//25
- return prime; -----//1d
} -----//3a
```

4.5. Rabin Miller.

```
using u64 = uint64_t; -----//fe
using u128 = __uint128_t; -----//27
-----//6f
u64 binpower(u64 base, u64 e, u64 mod) { -----//f2
- u64 result = 1; -----//f3
- base %= mod; -----//0c
- while (e) { -----//64
- if (e & 1) -----//1d
- result = (u128)result * base % mod; -----//2c
- base = (u128)base * base % mod; -----//23
- e >>= 1; -----//41
- } -----//f9
- return result; -----//57
} -----//78
-----//bc
bool check_composite(u64 n, u64 a, u64 d, int s) { -----//b0
- u64 x = binpower(a, d, n); -----//24
```

```
--- if (x == 1 || x == n - 1) -----//9f
----- return 0; -----//fd
--- for (int r = 1; r < s; r++) { -----//6e
----- x = (u128)x * x % n; -----//ad
----- if (x == n - 1) -----//41
----- return 0; -----//36
--- } -----//40
--- return 1; -----//64
}; -----//bj
-----//bf
bool MillerRabin(u64 n) { -----//23
- if (n < 2) -----//63
- return 0; -----//87
- int r = 0; -----//78
- u64 d = n - 1; -----//8e
- while ((d & 1) == 0) { -----//2c
- d >>= 1; -----//b9
- r++; -----//53
- } -----//8e
- for(int a:{2, 3, 5, 13, 19, 73, 193, 407521, 299210837})if(n==
- for (int a : {2, 325, 9375, 28178, 450775, 9780504, 179526502
- if (check_composite(n, a, d, r)) -----//5b
- return 0; -----//66
- return 1; -----//a9
} -----//b8
-----//34
```

4.6. Fft.

```
// FFT, it multiplies two polynomials in O(NlogN) -----//23
// Extremely powerful, but I've no idea how it works -----//2f
// Call mul and give the polynomials as -----//9d
// arrays of their coefficients :) -----//17
-----//06
namespace FFT { -----//16
- struct complex { -----//ea
- double a, b; -----//6a
- complex() { a = b = 0; } -----//bd
- complex(double _a, double _b) { a = _a; b = _b; } -----//86
- complex(double _a) { a = _a; b = 0; } -----//9c
- complex operator + (complex o) { return complex(a + o.a, b + o.b); } -----//04
- complex operator - (complex o) { return complex(a - o.a, b - o.b); } -----//04
- complex operator * (complex o) { -----//04
- return complex(a * o.a - b * o.b, a * o.b + b * o.a); }
- void operator += (complex o) { -----//1a
- double na = a * o.a - b * o.b; -----//e9
- double nb = a * o.b + b * o.a; -----//01
- a = na, b = nb; -----//86
- } -----//3e
- void operator /= (double x) { a /= x, b /= x;} -----//1f
- double real() { return a; } -----//e0
- double imag() { return b; } -----//08
- }; -----//53
- const int M = 21; -----//36
- const int N = (1 << M); -----//1d
- int pre[N][M]; -----//69
- int reverse(int num, int lg_n) { -----//1a
```

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```
--- if(pre[num][lg_n]) return pre[num][lg_n] - 1; -----//c6
--- int res = 0; -----//b1
--- for (int i = 0; i < lg_n; i++) { -----//5d
---     if (num & (1 << i)) -----//ef
---         res |= 1 << (lg_n - 1 - i); -----//95
--- } -----//fc
--- pre[num][lg_n] = res + 1; -----//9e
--- return res; -----//8b
- } -----//a5
- void fft(vector<complex> & a, bool invert) { -----//57
--- int n = a.size(); -----//39
--- int lg_n = 0; -----//fe
--- while ((1 << lg_n) < n) lg_n++; -----//bd
--- for (int i = 0; i < n; i++) { -----//7b
---     if (i < reverse(i, lg_n)) swap(a[i], a[reverse(i, lg_n)]);
--- } -----//3d
--- for (int len = 2; len <= n; len <= 1) { -----//0e
---     double ang = 2 * PI / len * (invert ? -1 : 1); -----//82
---     complex wlen(cos(ang), sin(ang)); -----//6b
---     for (int i = 0; i < n; i += len) { -----//67
---         complex w(1); -----//47
---         for (int j = 0; j < len / 2; j++) { -----//23
---             complex u = a[i+j], v = a[i+j+len/2] * w; -----//1f
---             a[i+j] = u + v; -----//36
---             a[i+j+len/2] = u - v; -----//a7
---             w *= wlen; -----//3b
---         } -----//44
---     } -----//39
--- } -----//83
--- if (invert) { -----//5c
---     for (complex & x : a) x /= n; -----//32
--- } -----//9c
- } -----//9f
- inline vi mul(vi const& a, vi const& b) { -----//ba
--- vector<complex> fa(a.begin(), a.end()), fb(b.begin(), b.end());
--- int n = 1; -----//74
--- while (n < a.size() + b.size()) n <= 1; -----//74
--- fa.resize(n); -----//aa
--- fb.resize(n); -----//dc
--- fft(fa, false); -----//2a
--- fft(fb, false); -----//bd
--- for (int i = 0; i < n; i++) fa[i] *= fb[i]; -----//e2
--- fft(fa, true); -----//54
--- vi result(n); -----//6e
--- for (int i = 0; i < n; i++) { -----//b2
---     ll x = fa[i].real() + 0.5; -----//6b
---     result[i] = x; -----//6e
--- } -----//cc
--- while(result.size() && !result[result.size() - 1]) result.pop_back();
--- return result; -----//6a
- } -----//91
- inline vi moduloMul(vi const& a, vi const& b, ll MOD) { -----//64
--- vector<complex> fa(a.begin(), a.end()), fb(b.begin(), b.end());
--- int n = 1; -----//35
--- while (n < a.size() + b.size()) n <= 1; -----//05
--- fa.resize(n); fb.resize(n); -----//58
--- fft(fa, false); fft(fb, false); -----//63
--- for (int i = 0; i < n; i++) fa[i] *= fb[i]; -----//5b
--- fft(fa, true); -----//89
--- vi result(n); -----//90
--- for (int i = 0; i < n; i++) { -----//bb
---     ll x = fa[i].real() + 0.5; -----//67
---     if(x >= MOD) x %= MOD; -----//96
---     result[i] = x; -----//38
--- } -----//fd
--- while(result.size() && !result[result.size() - 1]) result.pop_back();
--- return result; -----//52
- } -----//70
}; -----//be
4.7. Extended Gcd.
// Extended GCD -----//70
-----//78
/* Solves diophantine equation -----//89
-- a*x + b*y = gcd(a, b) -----//7d
-- and return {x, y, gcd(a, b)} -----//da
-- if ll, might require __int128 */ -----//e3
vector<ll> exgcd(ll a, ll b){ -----//85
    if(!b) return {1, 0, a};
    auto x = exgcd(b, a % b);
    return {x[1], x[0] - x[1] * (a/b), x[2]};
} -----//33
4.8. Crt.
// Chinese remainder theorem -----//e0
-----//d2
/* Call gcr1(a, b) to find smallest {x, y} such -----//77
- that (x + k * y) % a[i] = b[i] for all i, k */ -----//79
-----//38
#define rep(i,a,b) for (__typeof(a) i=(a); i<(b); ++i) ----//39
-----//8f
#define iter(it,c) for (__typeof((c).begin()) \ -----//71
- it = (c).begin(); it != (c).end(); ++it) -----//36
-----//a0
ll egcd(ll a, ll b, ll& x, ll& y) { -----//e8
- if (b == 0) { x = 1; y = 0; return a; } -----//43
- ll d = egcd(b, a % b, x, y); -----//0c
- x -= a / b * y; swap(x, y); return d; } -----//44
-----//2e
template <class T> int size(const T &x) { return x.size(); }
template <class T> T smod(T a, T b) { return (a % b + b) % b; }
-----//ec
ll crt(vector<ll> &as, vector<ll> &ns) { -----//14
- ll cnt = size(as), N = 1, x = 0, r, s, l; -----//33
- rep(i,0,cnt) N *= ns[i]; -----//94
- rep(i,0,cnt) egcd(ns[i], l = N/ns[i], r, s), x += as[i]*s*l;
- return smod(x, N); } -----//26
-----//b5
pair<ll,ll> gcr1(vector<ll> &as, vector<ll> &ns) { -----//db
- map<ll,pair<ll,ll> > ms; -----//de
- rep(at,0,size(as)) { -----//5e
-     ll n = ns[at]; -----//ef
-     for (ll i = 2; i*i <= n; i = i == 2 ? 3 : i + 2) { -----//3a
----- ll cur = 1; -----//98
----- while (n % i == 0) n /= i, cur *= i; -----//df
----- if (cur > 1 && cur > ms[i].first) -----//55
-----     ms[i] = make_pair(cur, as[at] % cur); } -----//af
----- if (n > 1 && n > ms[n].first) -----//73
-----     ms[n] = make_pair(n, as[at] % n); } -----//43
- vector<ll> as2, ns2; ll n = 1; -----//22
- iter(it,ms) { -----//03
-     as2.push_back(it->second.second); -----//7f
-     ns2.push_back(it->second.first); -----//2a
-     n *= it->second.first; } -----//eb
- ll x = crt(as2,ns2); -----//a5
- rep(i,0,size(as)) if (smod(x,ns[i]) != smod(as[i],ns[i])){ -----//a9
-     return pii(0,0); -----//b3
-     return make_pair(x,n); } -----//c1
4.9. Bin Exp.
// Binary exponentiation -----//d8
// in case needed, add % mod whenever -----//6d
// you see some computations going on -----//34
// can be modified into bin_mul easily, -----//a9
// just replace * with + -----//b7
-----//fe
ll bin_exp(ll b, ll p){ -----//50
- if(p == 0) return 1; -----//2b
- if(p == 1) return b; -----//f9
- ll ans = 1; -----//02
- if(p % 2 == 1){ -----//1f
-     ans *= b; -----//24
-     p--; -----//d8
- } -----//f8
- ll x = bin_exp(b, p/2); -----//b0
- return ans * x * x; -----//6d
} -----//49
4.10. Big Integers.
// Library from some japanese coder -----//87
// Supposedly a good implementation, but doesn't -----//e9
// use FFT for multiplications, so not giga fast -----//c5
-----//ba
const ll base=1000000000; -----//c5
struct bignum{ -----//d1
- int len; -----//dc
- ll data[bignumlen]; -----//23
- ll &operator [] (int x){ return(data[x]);} -----//6a
- const ll &operator [] (int x)const { return(data[x]);} -----//cc
- bignum (){} -----//25
- memset(data,0,sizeof(data)); -----//01
- len=0; -----//0b
- } -----//a5
- void clear(){ -----//f4
-     for(int i=len;i>=1;--i)data[i]=0; -----//ad
-     len=0; -----//fd
- } -----//ba
- int check (const bignum &a,const bignum &b){ -----//70
-     if(a.len>b.len)return(0); -----//56
```

```
--- if(b.len>a.len)return(1); -----//f3
--- for(int i=a.len;i>=1;--i){ -----//b1
---     if(a.data[i]<b.data[i])return(1); -----//39
---     if(b.data[i]<a.data[i])return(0); -----//e6
--- } -----//fb
--- return 2; -----//5a
- } -----//b9
- bool operator < (const bignum &b){ return(check(*this,b)==1);}
- bool operator > (const bignum &b){ return(check(*this,b)==0);}
- bool operator <=(const bignum &b){ return(check(*this,b)>=1);}
- bool operator >=(const bignum &b){ return(check(*this,b)%2==0);}
- bool operator !=(const bignum &b){ return(check(*this,b)!=2);}
- bool operator ==(const bignum &b){ return(check(*this,b)==2);}
-----//3b
- bignum operator=(const bignum &x){ -----//4a
-     for(int i=x.len+1;i<=len;++i)data[i]=0; -----//60
-     for(int i=1;i<=x.len;++i)data[i]=x.data[i]; -----//07
-     len=x.len; -----//3c
-     return *this; -----//03
- } -----//fe
- bignum operator=(ll x){ -----//a9
-     for(int i=len;i>=0;--i)data[i]=0; -----//b4
-     len=0; -----//64
-     while(x){ -----//13
-         data[++len]=x/base; -----//40
-         x/=base; -----//7c
-     } -----//ab
-     return *this; -----//c6
- } -----//4e
- bignum(ll x){ -----//b1
-     memset(data,0,sizeof(data)); -----//c0
-     len=0; -----//1d
-     (*this)=x; -----//93
- } -----//5c
- bignum operator *(const bignum &b){ -----//ac
-     int i,j; -----//c1
-     bignum tmp; -----//69
-     for(i=1;i<=len;++i)if(data[i]!=0) -----//48
-         for(j=1;j<=b.len;++j)if(b.data[j]!=0){ -----//28
-             tmp.data[i+j-1]=data[i]*b.data[j]; -----//8f
-             tmp.data[i+j]+=tmp.data[i+j-1]/base; -----//99
-             tmp.data[i+j-1]%=base; -----//74
-         } -----//22
-     tmp.len=len+b.len-1; -----//a1
-     while(tmp.data[tmp.len+1])tmp.len++; -----//79
-     return tmp; -----//2a
- } -----//b8
- bignum operator *(ll x){ -----//e5
-     int i; -----//03
-     bignum tmp; -----//9b
-     for(i=1;i<=len;++i)tmp[i]=data[i]*x; -----//e7
-     tmp.len=len; -----//78
-     for(i=1;i<=len;++i){ -----//74
-         tmp[i+1]+=tmp[i]/base,tmp[i]%=base; -----//06
-         if(tmp[i+1]&& i+1>tmp.len)tmp.len++; -----//f6
-     } -----//56
-     return tmp; -----//fa
- } -----//ae
- bignum operator /(ll x){ -----//f9
-     int i; -----//72
-     bignum tmp; -----//ac
-     ll y=0; -----//d3
-     for(i=len;i>=1;--i){ -----//7e
-         y=y*base+data[i]; -----//80
-         tmp[i]=y/x; -----//0c
-         y%=x; -----//99
-     } -----//81
-     tmp.len=len; -----//c3
-     while(tmp[tmp.len]==0&&tmp.len>1)tmp.len--; -----//94
-     return tmp; -----//fa
- } -----//49
- bignum operator /(const bignum &b){ -----//b6
-     if(b.len<=1 && b[1]==0){ -----//48
-         printf("error!"); -----//58
-         for(;;); -----//91
-     } -----//5c
-     int i,l1=(len-1)*Blen,l2=(b.len-1)*Blen; -----//5d
-     ll x=data[len],y=b[b.len]; -----//06
-     while(x)x/=10,l1++; -----//17
-     while(y)y/=10,l2++; -----//3b
-     bignum tmp,chu,B; -----//aa
-     chu=*this; B=b; -----//30
-     } -----//7a
-     for(i=1;i*Blen<=l1-l2;++i)B*=base; -----//33
-     for(i=1;i<=(l1-l2)%Blen;++i)B*=10; -----//68
-     for(i=l1-l2;i>=0;--i){ -----//85
-         x=0; -----//ce
-         while(chu>=B)chu-=B,x++; -----//6d
-         tmp[i/Blen+1]=tmp[i/Blen+1]*10+x; -----//c0
-         B/=10; -----//f4
-     } -----//8c
-     tmp.len=(l1-l2)/Blen+1; -----//33
-     while(tmp.len>=1 && !tmp[tmp.len])tmp.len--; -----//32
-     return tmp; -----//22
- } -----//52
- bignum operator +(const bignum &b){ -----//27
-     bignum tmp; -----//50
-     int i,l=max(len,b.len); -----//c7
-     for(i=1;i<=l;++i)tmp[i]=data[i]+b[i]; -----//33
-     for(i=1;i<=l;++i)tmp[i+1]+=tmp[i]/base,tmp[i]%=base; -----//00
-     tmp.len=l; -----//4a
-     if(tmp[tmp.len+1])tmp.len++; -----//3b
-     return tmp; -----//a4
- } -----//98
- bignum operator +(ll x){ -----//27
-     bignum tmp; tmp=*this; -----//0a
-     tmp[1]+=x; -----//8c
-     for(int i=1;i<=len&&tmp[i]>=base;++i) -----//2a
-         tmp[i+1]+=tmp[i]/base,tmp[i]%=base; -----//3a
-     while(tmp[tmp.len+1])tmp.len++; -----//2d
-     return tmp; -----//83
- } -----//10
- bignum operator -(const bignum &b){ -----//db
-     int i; -----//e0
-     bignum tmp; -----//57
-     for(i=1;i<=len;++i)tmp.data[i]=data[i]-b.data[i]; -----//cd
-     for(i=1;i<=len;++i){ -----//3c
-         if(tmp[i]<0)tmp.data[i]+=base,tmp.data[i+1]--; -----//58
-     } -----//3b
-     tmp.len=len; -----//73
-     while(tmp[tmp.len]==0&&tmp.len>1)tmp.len--; -----//4c
-     return tmp; -----//83
- } -----//25
- bignum operator -(ll x){ -----//72
-     bignum tmp; tmp=*this; -----//bd
-     tmp[1]-=x; -----//f3
-     for(int i=1;i<=len&&tmp[i]<0;++i){ -----//73
-         tmp[i+1]+=(tmp[i]+1)/base-1; -----//71
-         tmp[i]=(tmp[i]+1)%base+base-1; -----//22
-     } -----//31
-     while(!tmp[tmp.len]&&tmp.len>1)tmp.len--; -----//b2
-     return tmp; -----//34
- } -----//55
- ll operator %(ll x){ -----//9e
-     int i; -----//d3
-     ll y=0; -----//49
-     for(i=len;i>=1;--i)y=(y*base+data[i])%x; -----//1a
-     return y; -----//87
- } -----//6b
- bignum operator %(const bignum &b){ -----//57
-     if(b.len<=1 && b[1]==0){ -----//ea
-         printf("error! 0 mod!"); -----//b0
-         for(;;); -----//3d
-     } -----//4f
-     int i,l1=(len-1)*Blen,l2=(b.len-1)*Blen; -----//20
-     ll x=data[len],y=b[b.len]; -----//18
-     while(x)x/=10,l1++; -----//c0
-     while(y)y/=10,l2++; -----//f2
-     bignum chu,B; -----//c1
-     chu=*this; B=b; -----//52
-     } -----//c7
-     for(i=1;i*Blen<=l1-l2;++i)B*=base; -----//cf
-     for(i=1;i<=(l1-l2)%Blen;++i)B*=10; -----//9c
-     for(i=l1-l2;i>=0;--i){ -----//ab
-         while(chu>=B)chu-=B; -----//48
-         B/=10; -----//44
-     } -----//b2
-     return chu; -----//d3
- } -----//1d
- } -----//0f
- bignum operator +=(const bignum &b){return *this=(*this+b);}
- bignum operator +=(const bignum &b){return *this=(*this*b);}
- bignum operator =(const bignum &b){return *this=(*this -b);}
- bignum operator /=(const bignum &b){return *this=(*this/b);}
- bignum operator %=(const bignum &b){return *this=(*this%b);}
- bignum operator =(ll x) {return (*this=(*this *x));} ---//25
- bignum operator +=(ll x) {return (*this=(*this +x));} ---//fa
- bignum operator -(ll x) {return (*this=(*this -x));} ---//ad
```



```
- bignum operator /(ll x) {return( *this=( *this /x));} ---//6d
- void read(){ ---//df
-   char c[bignumlen*Blen+10]; ---//48
-   scanf("%s",c+1); ---//01
-   int l=strlen(c+1); ---//bb
-   (*this).clear(); ---//7c
-   ll x; ---//a0
-   for(int i=1;i<=(l-1)/Blen+1;++i){ ---//73
-       x=0; ---//41
-       for(int j=1-Blen*i+1;j<=1-Blen*i+Blen;++j) ---//3a
-           if(j>=1)x=x*10+c[j]-48; ---//79
-       data[++len]=x; ---//39
-   } ---//25
- } ---//43
- void write(){ ---//94
-   printf("%I64d",data[len]); ---//25
-   for(int i=len-1;i>=1;--i)printf("%0*I64d",Blen,data[i]); ---//8c
- } ---//c6
}p,q,pp,qq; ---//14
bignum gcd(const bignum &A,const bignum &B){ ---//1c
-   bignum a=A,b=B,res=1; ---//8b
-   while(!(a[1]&1) && !(b[1]&1))a/=2,b/=2,res*=2; ---//83
-   for(;;){ ---//e0
-       if(a.len==1 && a[1]==0)return b*res; ---//bb
-       if(b.len==1 && b[1]==0)return a*res; ---//7e
-       while(!(a[1]&1))a/=2; ---//74
-       while(!(b[1]&1))b/=2; ---//4a
-       if(a>b)a-=b; ---//ba
-       else b-=a; ---//24
-   } ---//43
}
```

5. GRAPHS

5.1. Topological Sort.

```
// O(N) Topological sort for DAG ---//3e
// Returns array v, indexes in topo-sorted order ---//0d
// (for i < j, v[i] it NOT reachable by v[j]) ---//58
// Can be used (often reversed) instead of DP ---//90
// for DAG problems ---//c3
---//09
vi toposort(vvi &g){ ---//2f
-   const int n = g.size(); ---//b2
-   vector<bool> vis(n); ---//c6
-   vi topo; topo.reserve(n); ---//15
-   function<void(int)> dfs = [](int i){ ---//b4
-       vis[i] = 1; ---//80
-       for(int e : g[i]) if(!vis[e]) dfs(e); ---//95
-       topo.push_back(i); ---//a5
-   }; ---//2d
-   for(int i = 0; i < n; i++) ---//bd
-       if(!vis[i]) ---//9c
-           dfs(i); ---//81
-   reverse(topo.begin(), topo.end()); ---//fc
-   return topo; ---//27
} ---//49
```

5.2. Min Cost Max Flow.

```
// O(V^3M) (estimated) algorithm for MCMF ---//3d
// Uses an implementation of Pape-Levit ---//8b
// for shortest path (better in practice, ---//d2
// but not as good as Dijkstra asymptotically) ---//23
// Hope it's good enough :P ---//48
---//72
struct edge { ---//ea
-   int b, u; ---//7d
-   ll c, f; ---//8f
-   size_t back; ---//3a
}; ---//1d
---//06
using graph = vector<vector<edge>>; ---//b6
---//25
// a to b, capacity u, cost c ---//80
void add_edge (graph &g, int a, int b, ll u, ll c) { ---//4f
-   edge r1 = {b, u, c, 0, g[b].size ()}; ---//d0
-   edge r2 = {a, 0, -c, 0, g[a].size ()}; ---//ba
-   g[a].push_back (r1); ---//ab
-   g[b].push_back (r2); ---//79
} ---//f5
---//4e
// graph, source, sink ---//c9
// returns {flow, cost} ---//2f
pair<ll, ll> mcmf(graph &g, int s, int t){ ---//32
-   ll flow = 0, cost = 0; ---//8f
-   ll k = MAX_FLOW; // use Dinic :) ---//46
-   while(flow < k){ ---//2c
-       vi id(n), d(n, INF), q(n), p(n); ---//f0
-       vector<size_t> p_edge(n); ---//83
-       int qh = 0, qt = 0; ---//fd
-       q[qt++] = s; ---//2a
-       d[s] = 0; ---//1b
-       while (qh != qt) { ---//11
-           int v = q[qh++]; ---//ab
-           id[v] = 2; ---//af
-           if (qh == n) qh = 0; ---//c2
-           for (size_t i = 0; i < g[v].size(); ++i) { ---//18
-               edge & r = g[v][i]; ---//80
-               if (rf < ru && d[v] + rc < d[rb]) { ---//a5
-                   d[rb] = d[v] + rc; ---//90
-                   if (id[rb] == 0) { ---//bc
-                       q[qt++] = rb; ---//0d
-                       if (qt == n) qt = 0; ---//1a
-                   } ---//b9
-                   else if (id[rb] == 2) { ---//78
-                       if (--qh == -1) qh = n-1; ---//56
-                       q[qh] = rb; ---//e1
-                   } ---//07
-                   id[rb] = 1; ---//45
-                   p[rb] = v; ---//47
-                   p_edge[rb] = i; ---//2f
-               } ---//4d
-           } ---//84
-       } ---//5c
}
```

```
--- if (d[t] == INF) break; ---//16
--- ll addflow = k - flow; ---//39
--- for (int v = t; v! = s; v = p[v]) { ---//06
-   int pv = p [v]; size_t pr = p_edge[v]; ---//41
-   addflow = min(addflow, g[pv][pr].u - g[pv][pr].f); ---//45
- } ---//d6
--- for (int v = t; v! = s; v = p [v]) { ---//54
-   int pv = p [v]; ---//ee
-   size_t pr = p_edge[v], r = g[pv][pr].back; ---//00
-   g[pv][pr].f += addflow; ---//7b
-   g[v][r].f -= addflow; ---//51
-   cost += g[pv][pr].c * addflow; ---//0b
- } ---//49
-   flow += addflow; ---//8d
- } ---//71
- return {flow, cost}; ---//91
} ---//14
```

5.3. Kosaraju.

```
// O(N) algo to find SCC ---//fb
---//d5
void dfs_order(vvi &g, int i, vec<bool> &vis, vi &dfso){ ---//2b
-   vis[i] = 1; ---//21
-   for(int &p : g[i]) ---//e5
-       if(!vis[p]) ---//5a
-           dfs_order(g, p, vis, dfso); ---//34
-   dfso.push_back(i); ---//e6
} ---//fb
---//92
void l_dfs(vvi &g, int i, vec<bool> &vis, vi &labels, int &l){ ---//35
-   if(!vis[i]){ ---//eb
-       vis[i] = 1; ---//12
-       ++l; ---//c8
-   } ---//41
-   labels[i] = l; ---//2e
-   for(int &x : g[i]) ---//8f
-       if(!vis[x]){ ---//bc
-           vis[x] = 1; ---//2e
-           l_dfs(g, x, vis, labels, l); ---//b8
-       } ---//ad
-   } ---//8a
// Returns a graph (DAG) of SCC ---//c2
// g is the graph to build on ---//88
// labels[i] = SCC to which g[i] belongs ---//42
// dfs = order in which nodes were visited in the first ---//27
---//4d
vvi kosaraju(vvi &g, vi &labels, vi &dfso){ ---//26
-   //we make a stack based on dfs order (in a way that no node is \
-   before someone reachable by him - except for SCC case! //9e
-   dfso.reserve(g.size()); ---//08
-   vec<bool> vis(g.size()); ---//10
-   for(int i = 0; i < g.size(); i++) ---//d2
-       if(!vis[i]) ---//4f
-           dfs_order(g, i, vis, dfso); ---//5f
-   //we need the reverse graph ---//0c
```

```
- vvi rg(g.size()); -----//63
- for(int i = 0; i < g.size(); i++) -----//fb
-   for(int &p : g[i]) -----//10
-       rg[p].push_back(i); -----//70
- //now, we just go backwards from last node visited and build the scc
- fill(vis.begin(), vis.end(), 0); -----//c4
- int l = -1; -----//7b
- for(int i = g.size() - 1; i >= 0; i--) -----//9e
-   if(!vis[dfso[i]]) -----//22
-       l_dfs(rg, dfso[i], vis, labels, l); -----//64
- //labels are set, we construct the graph -----//76
- vvi scc(l+1); //l started as -1, so we add 1 -----//3e
- set<pii> edges; -----//e4
- for(int i = 0; i < g.size(); i++){ -----//9f
-   for(int &p : g[i]) -----//3d
-     if(labels[i] != labels[p]){ -----//94
-       if(edges.count({labels[i], labels[p]}) == 0){ -----//37
-         scc[labels[i]].push_back(labels[p]); -----//a0
-         edges.insert({labels[i], labels[p]}); -----//9f
-       } -----//79
-     } -----//a1
- } -----//e8
- return scc; -----//73
} -----//e7
```

5.4. Hungarian.

```
// O(N^3) Hungarian algorithm for the assignment problem --//42
// Min Cost Bipartite Matching -----//49
// cost[i][j] = cost to match i with j -----//07
// Returns {minCost, match[]}, -----//06
// where match[i] = who we matched i with -----//b4
// -----//fb
// Use 0-based, n <= m -----//70
template <typename T> -----//d3
pair<T, vi> min_cost_matching(const vector<vector<T>> &cost) {
    // internally, this will be 1-based, -----//70
    // but you must call 0-based ! -----//70
    const T T_INF = numeric_limits<T>::max() / 2.0; -----//70
    int n = cost.size(); -----//70
    int m = cost[0].size(); -----//70
    vector<T> u(n + 1); -----//70
    vector<T> v(m + 1); -----//70
    vector<T> p(m + 1); -----//70
    vector<T> way(m + 1); -----//70
    for (int i = 1; i <= n; ++i) { -----//70
        p[0] = i; -----//70
        int j0 = 0; -----//70
        vector<T> minv (m + 1, T_INF); -----//70
        vector<bool> used (m + 1, false); -----//70
        do { -----//70
            used[j0] = true; -----//70
            int i0 = p[j0], j1; -----//70
            T delta = T_INF; -----//70
            for (int j = 1; j <= m; ++j) -----//70
                if (!used[j]) { -----//70
                    int cur = cost[i0-1][j-1] using graph vvi; -----//70
```

```
if (cur < minv[j]) -----using edge_list = vector<edge>;//94 -----//07
    minv[j] = cur, way[j] = j0; -----//02 -----//39
    if (minv[j] < delta) -----//Also, we use i-1 to get back edge of i-th edge -----//9b
        delta = minv[j], gdnstexpr int back_edge(int i){ return a ^ 1;} -----//b0
    } -----//a3 -----//0a
    for (int j=0; j<=m; ++j) -----//Assumes directed edges -----//82
        if (used[j]) -----const bool IS_DIRECTED//f3; -----//bf
            u[p[j]] += delta, v[j] -= delta; -----//ba -----//76
        else -----void add_edge(graph &g, edge_list &e, int a, -----//b3
            minv[j] -= delta; -----int b, int c, bool directed = IS_DIRECTED){ -----//4f
                j0 = j1; -----int index = e.size(); -----//86
            } while (p[j0] != 0); -----g[a].push_back(index); -----//48
            do { -----g[b].push_back(back_edge(index)); -----//65
                int j1 = way[j0]; -----e.push_back({a, b, c}); -----//a9
                p[j0] = p[j1]; -----e.push_back({b, a, directed ? 0 : c}); -----//ac
                j0 = j1; -----} -----//b6
            } while (j0); -----//73 -----//4d
        } -----//64
    // returns both cost and matchings -----//71
    T sol = -v[0]; -----int level_dfs(graph &g, edge_list &el, vi &level, -----//f7
    vector<int> mates(n); -----//c9
    for(int i = 1; i <= m; i++) if(p[i] != 0) -----//e5
        mates[p[i]-1] = i-1; -----//4b if(source == sink) return lim; -----//19
    // build matchings -----//2c
    return {sol, mates}; -----//5d
```

5.5. Floyd Warshall.

```
// O(N^3) Floyd Warshall to find APSP -----//90
// Takes adj matrix (a[i][j] = INF means no edge!) -----//e0
// Return dist matrix. careful for overflows! -----//a7
// -----//d8
vvi floyd_warshall(vvi &adj){ -----//6b
    - vvi d(adj); -----//6e
    - int n = adj.size(); -----//4c
    - for(int k = 0; k < n; k++) -----//8c
        for(int i = 0; i < n; i++) -----//88
            for(int j = 0; j < n; j++) -----//1e
                if(max(d[i][k], d[k][j]) != INF) -----//b7
                    d[i][j] = min(d[i][j], d[i][k] + d[k][j]); -----//21
    return d; -----//1e
} -----//29
```

5.6. Dinic.

```
//40 (VE^2) Dinic algorithm for MaxFlow -----//bb
//30 Diff with Scaling Dinic (asymtotically faster) -----//b2
// comment above Dinic's code -----//e6
// -----//e4
// We represent the graph as an adjacency list -----//97
// of edge list indexes !!! -----//3c
// -----//84
// -----//3e
// -----//6a
// -----//17
// -----//0e
// -----//6f
// -----//05
// -----//09
```

```
if (cur < minv[j]) -----using edge_list = vector<edge>;//94 -----//07
    minv[j] = cur, way[j] = j0; -----//02 -----//39
    if (minv[j] < delta) -----//Also, we use i-1 to get back edge of i-th edge -----//9b
        delta = minv[j], gdnstexpr int back_edge(int i){ return a ^ 1;} -----//b0
    } -----//a3 -----//0a
    for (int j=0; j<=m; ++j) -----//Assumes directed edges -----//82
        if (used[j]) -----const bool IS_DIRECTED//f3; -----//bf
            u[p[j]] += delta, v[j] -= delta; -----//ba -----//76
        else -----void add_edge(graph &g, edge_list &e, int a, -----//b3
            minv[j] -= delta; -----int b, int c, bool directed = IS_DIRECTED){ -----//4f
                j0 = j1; -----int index = e.size(); -----//86
            } while (p[j0] != 0); -----g[a].push_back(index); -----//48
            do { -----g[b].push_back(back_edge(index)); -----//65
                int j1 = way[j0]; -----e.push_back({a, b, c}); -----//a9
                p[j0] = p[j1]; -----e.push_back({b, a, directed ? 0 : c}); -----//ac
                j0 = j1; -----} -----//b6
            } while (j0); -----//73 -----//4d
        } -----//64
    // returns both cost and matchings -----//71
    T sol = -v[0]; -----int level_dfs(graph &g, edge_list &el, vi &level, -----//f7
    vector<int> mates(n); -----//c9
    for(int i = 1; i <= m; i++) if(p[i] != 0) -----//e5
        mates[p[i]-1] = i-1; -----//4b if(source == sink) return lim; -----//19
    // build matchings -----//2c
    return {sol, mates}; -----//5d
} -----//5d
} -----//68
    edge &e = el[i]; -----//97
    if(level[e.to] == level[source] + 1 && e.f >= lim){ -----//80
        if(level[e.to] == level[source] + 1 && e.f > 0){ -----//ee
            // int pushed = level_dfs(g, el, level, pointer, -----//cf
            // e.to, sink, lim); -----//60
            int pushed = level_dfs(g, el, level, pointer, -----//2e
                e.to, sink, min(flow, e.f)); -----//c4
            if(pushed > 0){ -----//18
                el[i].f -= pushed; -----//52
                el[back_edge(i)].f += pushed; -----//53
                return pushed; -----//f1
            } -----//3d
        } -----//e9
    } -----//ca
    return 0; // couldn't push flow -----//1a
} -----//f5
} -----//66
// bool level_bfs(graph &g, edge_list &el, vi &level, -----//93
// int source, int sink, int lim){ -----//b4
bool level_bfs(graph &g, edge_list &el, vi &level, -----//53
    int source, int sink){ -----//44
    - fill(level.begin(), level.end(), INF); -----//64
    - level[source] = 0; -----//f8
    - queue<int> q; -----//fe
    - q.push(source); -----//2c
    - while(!q.empty() && level[sink] == INF){ -----//51
        - int curr = q.front(); q.pop(); -----//1a
        - for(int &i : g[curr]){ -----//e0
            - edge &e = el[i]; -----//3c
            - // if(e.f >= lim && level[e.to] == INF){ -----//cc
```

```
----- if(e.f > 0 && level[e.to] == INF){ -----//44
----- level[e.to] = level[curr] + 1; -----//a3
----- q.push(e.to); -----//64
----- } -----//25
-- } -----//a4
- } -----//53
- return level[sink] != INF; -----//fc
} -----//c8
-----//7c
ll dinic(graph &g, edge_list &el, int source, int sink){ --//6b
- vi level(g.size()); -----//22
- ll flow = 0; -----//7f
- // TODO: check for long long -----//d4
- // int lim = 1<<30; -----//99
- // while(lim > 0){ -----//04
- while(level_bfs(g, el, level, source, sink)){ -----//7e
-- // core optimization trick, for chained DFSs -----//ba
-- vi pointer(g.size()); -----//90
-- // if we can't send enough flow -----//b3
-- // if(!level_bfs(g, el, level, source, sink, lim)){ --//2b
-- // lim /= 2; -----//75
-- // continue; -----//dc
-- // } -----//ea
-- // while(level_dfs(g, el, level, pointer, source, sink, lim)){
-- // flow += lim; -----//de
-- // } -----//8c
- int tmp; -----//a7
- while((tmp = level_dfs(g, el, level, pointer, source, sink)){
- flow += tmp; -----//68
- } -----//6e
- } -----//36
- return flow; -----//b6
} -----//d0
```

5.7. Dijkstra.

```
// (untested) O(ElogV) Dijkstra with priority queue -----//2c
// takes a vector<vector<pii>> and return vector of -----//f6
// distances. watchout for int overflow -----//35
vi dijkstra(graph &g, int source){ -----//a1
- vi dist(g.size(), INF); -----//e7
- priority_queue<pii, vector<pii>, greater<pii>> pq; -----//39
- dist[source] = 0; -----//a2
- pq.push({0, source}); -----//90
- while(!pq.empty()){ -----//5c
- pii curr = pq.top(); pq.pop(); -----//70
- if(dist[curr].second < curr.first) -----//50
- continue; -----//8d
- for(pii &e : g[curr.second]) -----//3f
- if(curr.first + e.second < dist[e.first]){ -----//27
- dist[e.first] = curr.first + e.second; -----//c1
- pq.push({dist[e.first], e.first}); -----//4a
- } -----//2c
- } -----//65
- return dist; -----//27
} -----//8c
```

5.8. Articulation Points.

```
vector<int> dfs_low(n),dfs_num(n); -----//42
int cnt=0; -----//a8
void abdfs(int p){ -----//d1
- dfs_low[p]=dfs_num[p]++;cnt; -----//a3
- for(auto i:g[p]){ -----//03
- if(!dfs_num[i]){ -----//29
- if(p==root)rootChildren++;//for if root is articulation point
- dfs_parent[i]=p; -----//26
- abdfs(i); -----//d2
- if(dfs_low[i]>=dfs_num[p]){}/p is articulation point
- if(dfs_low[i]>dfs_num[p]){ } //p-i is bridge -----//fc
- dfs_low[p]=min(dfs_low[p],dfs_low[i]); -----//8c
- } else if(i!=dfs_parent[p]) dfs_low[p]=min(dfs_low[p],dfs_low[i]);
- } -----//81
} -----//8a
-----//f7
```

5.9. 2sat.

```
// O(N) algorithm to solve 2SAT -----//d6
-----//e5
// 1) make a graph of size 2 * N -----//75
// 2) add all implications (c1, i1) && (c2, i2)... -----//02
// 3) run Kosaraju on the obtained graph -----//d6
// 4) if label[x] = label[x^1], then we have no solution -----//97
// 5) we have a solution. (and then? :0) -----//83
-----//9a
// if (x = a) then (y = b) -----//59
void add_implication(int x, bool a, int y, bool b, vvi &sat){
- x *= 2, y *= 2; -----//7c
- //nego se necessario -----//49
- if(!a) x ^= 1; -----//e6
- if(!b) y ^= 1; -----//db
- //aggiunge x -> y -----//22
- sat[x].push_back(y); -----//c0
- //aggiunge !y -> !x -----//65
- sat[y ^ 1].push_back(x ^ 1); -----//1b
} -----//f7
```

6. GEOM

6.1. Segment Point Distance.

```
// Magic formula to know point to line distance -----//fd
// Very accurate :P -----//15
-----//9b
// s.a.x <= s.b.x -----//53
double ps_distance(point &p, segment &s){ -----//91
- //magic dot product / square len ratio -----//8f
- vector<double> v{p.x - s.a.x, p.y - s.a.y}; -----//a2
- vector<double> u{s.b.x - s.a.x, s.b.y - s.a.y}; -----//31
- auto dot = v[0] * u[0] + v[1] * u[1]; -----//d2
- auto len = square(u[0]) + square(u[1]); -----//23
- if(len == 0) return p.distance(s.a); -----//df
- auto ratio = dot / len; -----//08
- //cout << dot << ' ' << len << " -> " << ratio << '\n'; -----//f4
- if(ratio <= 0) return p.distance(s.a); -----//e0
- if(ratio >= 1) return p.distance(s.b); -----//09
- point proj = {s.a.x + u[0] * ratio, s.a.y + u[1] * ratio};
```

```
- return p.distance(proj); -----//0c
} -----//21
```

6.2. Rotating Calipers.

```
/* -----//b6
- Rotating calipers: -----//5c
- A pair of parallel lines that can be rotated around the polygon and "holds" it as tight as possible -----//00
- I hope you won't need this. -----//3d
- But as you are here, let's see what we have: -----//8b
- (assuming we want farthest points) -----//19
- 1) find convex hull -----//59
- 2) pick any normal vector ? and find calipers -----//83
- that match this vector: -----//8a
- (I assume this means that you pick any two hull -----//3
- 3) Test the points facing the calipers -----//e7
- 4) find minimum angle to get next point -----//ea
- 5) rotate calipers by that angle -----//3f
- 6) if state is already visited, stop the calipers -----//a0
-----//8d
The above runs in O(N), assuming you can code it.
```

6.3. Graham Scan.

```
long long cross(P a, P b, P c){ -----//64
- return (b.x-a.x)*(c.y-a.y)-(b.y-a.y)*(c.x-a.x); -----//89
} -----//04
long long dist2(P a, P b){
- return (a.x-b.x)*(a.x-b.x)+(a.y-b.y)*(a.y-b.y); -----//44
} -----//78
vector<P> graham_scan(vector<P>& a){
- sort(a.begin()+1,a.end(), -----//87
- [&](P b, P c){ -----//34
- if(cross(a[0],b,c)==0) -----//87
- return dist2(a[0],b)<dist2(a[0],c); -----//34
- return cross(a[0],b,c)>0; -----//87
});
- vector<P> ch;
- ch.push_back(a[0]);
- ch.push_back(a[1]);
- for(auto &p:a){
- while(ch.size()>=2 && cross(ch[ch.size()-2],ch.back(),p)<0)
- ch.pop_back();
- ch.push_back(p);
- }
- return ch; -----//87
} -----//34
```

6.4. Geom Lib.

```
//Blaise1 geometry lib, in its shrinked version -----//50
-----//5c
using T = long double; T EPS = 1e-12; T INF = 1e18; -----//25
struct point { -----//bd
- T x, y; -----//01
- point(T x, T y) : x(x), y(y) { } -----//04
```

```
- bool operator==(point &o) { return (fabs(x-o.x)<=EPS) ? //99
-- ((fabs(y-o.y)<=EPS) ? true : false) : false; } -----//ee
- bool operator!=(point &o) { return !(*this == o); } -----//cd
- point operator+(point &o) { return {x+o.x,y+o.y}; } -----//ed
- point operator-() { return {-x,-y}; } -----//7b
- point operator-(point &o) { return *this+(-o); } -----//31
- point operator*(T &d) { return {x*d,y*d}; } -----//94
- point operator*(point &o) { return {x*o.x,y*o.y}; } -----//6d
- T operator%(point &o) { return (*this*o).magnitude(); } --//5f
- T operator*(point &o) { return x*o.y-y*o.x; } -----//db
- T distance(point &o) { -----//90
-- return hypotl(fabs(x - o.x), fabs(y - o.y)); } -----//d1
- T sq_distance(point &o) { -----//d7
-- return fabs(x-o.x)*fabs(x-o.x)+fabs(y-o.y)*fabs(y-o.y); }
- point normalized() { -----//5b
-- point tmp(x, y); tmp.normalize(); return tmp; } -----//46
- void normalize(){ T hy = hypotl(x, y); x /= hy; y /= hy; }
- T magnitude() { return x + y; } -----//bb
- point rotated_rad(T rad) { -----//44
-- point tmp(x, y); tmp.rotate_rad(rad); return tmp; } --//0f
- void rotate_rad(T rad){ -----//29
-- T cos = cosl(rad); T sin = sinl(rad); -----//45
-- cos = fabs(cos) < EPS ? 0 : cos; -----//41
-- sin = fabs(sin) < EPS ? 0 : sin; -----//c3
-- x = x * cos - y * sin; y = x * sin + y * cos; } -----//2b
- T angle(point& o) { -----//ef
-- point self = this->normalized(); -----//25
-- point oth = o.normalized(); -----//bf
-- if(self == oth) return 0; -----//a6
-- return fabs(acosl(self % oth)); } }; -----//b8
-----//7c
struct line { -----//ba
- point dir, perp; -----//7a
- T a,b,c; -----//79
- line(T a, T b, T c) : perp(a,b), dir(0,0) { -----//c5
-- assert(!(a == 0 && b == 0)); -----//18
-- perp.normalize(); dir = perp.rotated_rad(-M_PI/2); -----//05
-- this->c = c / hypotl(a,b); -----//82
-- this->a = perp.x; this->b = perp.y; } -----//f7
- line(point p1, point p2) : perp(0,0), dir(p2-p1) { -----//e2
-- assert(p1 != p2); -----//8f
-- dir.normalize(); perp = dir.rotated_rad(M_PI/2); -----//6a
-- a = perp.x; b = perp.y; c = -(perp % p1); } -----//55
- bool inLine(point &p) { -----//c5
-- return fabs(dir.x * p.x + dir.y * p.y + c) <= EPS; } --//fd
- bool operator==(line &o) { -----//a0
-- if(fabs(a - o.a) > EPS) return false; -----//cd
-- line inv(-o.a,-o.b,-o.c); -----//60
-- return fabs(a-inv.a)<=EPS && fabs(b-inv.b)<=EPS && -----//57
-- fabs(c-inv.c)<=EPS; } -----//4f
- T signed_distance(point &p) { return perp % p + c; } -----//c2
- point project(point &p) { -----//5c
-- return p - (perp * signed_distance(p)); } -----//91
- line parallel(point &p) { -----//a6
-- line res = *this; res.c -= signed_distance(p); -----//2d
-- return res; } -----//6a
```

```
- point intersect(line &s) { -----//22
-- line l = *this; T d = l.a * s.b - s.a * l.b; -----//55
-- if(fabs(d) <= EPS) return {-INF, -INF}; -----//61
-- return { (s.c*l.b-l.c*s.b)/d,(s.c*l.a-l.c*s.a)/(-d)}; } };
struct segment { -----//60
- point start, end; -----//6d
- segment(point p1, point p2) : start(p1), end(p2) { } -----//e9
- bool lies(point &a) { -----//f1
-- point b = start; point c = end; line l(b,c); -----//b9
-- T dist = l.signed_distance(a); -----//79
-- if(!(fabs(dist) <= EPS)) return false; -----//2c
-- point ba = a-b; point bc = c-b; -----//a6
-- point ca = a-c; point cb = b-c; -----//56
-- return !(ba % bc < 0 || ca % cb < 0); } -----//7e
- point intersect(segment &s2) { -----//58
-- segment s1 = *this; line l1(s1.start, s1.end); -----//1f
-- line l2(s2.start, s2.end); -----//94
-- point inter = l1.intersect(l2); point inf(-INF, -INF); //1c
-- if(inter == inf){ -----//7e
-- if(l1 == l2){ -----//ba
-- if(s1.lies(s2.start)) return s2.start; -----//3d
-- if(s1.lies(s2.end)) return s2.end; -----//f4
-- if(s2.lies(s1.start)) return s1.start; -----//b0
-- if(s2.lies(s1.end)) return s1.end; } -----//1e
-- return inf; } -----//1c
-- if(s1.lies(inter) && s2.lies(inter)) return inter; -----//9e
-- return inf; } -----//ed
- T sq_distance(point &p) { -----//1e
-- point v(p.x - start.x, p.y - start.y); -----//ff
-- point u(end.x - start.x, end.y - start.y); -----//9d
-- T dot = v % u; T len = (u * u).magnitude(); -----//29
-- if(fabs(len) <= EPS) return p.sq_distance(start); -----//26
-- T ratio = dot / len; -----//e1
-- if(ratio <= EPS) return p.sq_distance(start); -----//49
-- if(ratio >= 1 - EPS) return p.sq_distance(end); -----//a3
-- point proj = (u * ratio) + start; -----//a9
-- return p.sq_distance(proj); } -----//15
- T distance(point &p) { return sqrtl(sq_distance(p)); } };//e1

6.5. Closest Pair.
// Return the closest pair of points in O(NlogN) -----//20
using point = complex; -----//7b
struct cmpx { -----//64
- bool operator()(const point &a, const point &b) { -----//f7
-- return abs(real(a) - real(b)) > EPS ? -----//5e
-- real(a) < real(b) : imag(a) < imag(b); } }; -----//d1
-----//d2
struct cmpy { -----//86
- bool operator()(const point &a, const point &b) { -----//67
-- return abs(imag(a) - imag(b)) > EPS ? -----//64
-- imag(a) < imag(b) : real(a) < real(b); } }; -----//06
-----//a1
pair<point, point> closest_pair(vector<point> pts) { -----//ff
- pair<point, point> sol; -----//64
- sort(pts.begin(), pts.end(), cmpx()); -----//3b
- set<point, cmpy> cur; -----//ad
```

```
- set<point, cmpy>::const_iterator it, jt; -----//44
- double mn = INFINITY; -----//41
- for (int i = 0, l = 0; i < size(pts); i++) { -----//bb
-- while (real(pts[i]) - real(pts[l]) > mn) -----//eb
-- cur.erase(pts[l++]); -----//e2
-- it = cur.lower_bound(point(-INFINITY, imag(pts[i]) - mn));
-- jt = cur.upper_bound(point(INFINITY, imag(pts[i]) + mn));
-- while (it != jt) { -----//b4
-- double x = abs(*it - pts[i]); -----//2f
-- if(x < mn){ -----//66
-- mn = x; -----//c7
-- sol = {*it, pts[i]}; -----//f0
-- } -----//08
-- it++; -----//2e
-- cur.insert(pts[i]); } -----//b4
- return sol; } -----//eb

6.6. Andrew Mc.
// Convex Hull with Andrew Monotone chain algorithm -----//a1
// Also supports queries to check if point -----//76
// is contained in convex hull -----//2a
-----//44
struct point { -----//da
- int x, y; -----//bc
- bool operator==(point &other){ -----//a1
-- return x == other.x && y == other.y; -----//fa
- } -----//b6
- bool operator<(point &other){ -----//26
-- return tie(x, y) < tie(other.x, other.y); -----//0f
- } -----//94
}; -----//a4
-----//1b
// -1 ccw, 0 coll, 1 cw -----//b7
int orientation(point &a, point &b, point &c){ -----//8e
- ll val = (b.y - a.y) * (ll)(c.x - b.x) - -----//79
-- (b.x - a.x) * (ll)(c.y - b.y); -----//3a
- return val < 0 ? -1 : !!val; -----//5c
} -----//77
-----//c0
struct segment { -----//78
- point a, b; -----//61
- bool contains(point &p){ -----//a4
-- if(orientation(a, b, p) != 0) -----//9b
-- return 0; -----//7a
-- bool x = p.x >= a.x && p.x <= b.x; -----//0e
-- bool y = p.y >= min(a.y, b.y) && p.y <= max(a.y, b.y); //8d
-- return x && y; -----//9e
- } -----//84
- bool operator& (segment &s){ -----//f7
-- return intersect(s); -----//eb
- } -----//99
- bool intersect(segment &s){ -----//a3
-- ll o1 = orientation(a, b, s.a); -----//c7
-- ll o2 = orientation(a, b, s.b); -----//91
-- ll o3 = orientation(s.a, s.b, a); -----//9c
-- ll o4 = orientation(s.a, s.b, b); -----//24
```



```
--- if(o1 != o2 && o3 != o4) return 1; -----//95
--- return contains(s.a) || contains(s.b) || -----//75
--- s.contains(a) || s.contains(b); -----//88
- } -----//45
- segment(point p1, point p2) : a(p1), b(p2){ -----//a5
--- if(a.x > b.x) -----//68
--- swap(a, b); -----//99
- } -----//52
}; -----//a4
struct convex_hull : vector<point>{ -----//a2
- vector<point> &h = *this; -----//49
- vector<segment> bottom, top; -----//07
- convex_hull (vector<point> &v){ -----//0a
--- sort(v.begin(), v.end()); -----//c1
--- for(int i = 0; i < v.size(); i++){ -----//d6
--- while(h.size() >= 2 && -----//e7
----- orientation(h[h.size()-2], h.back(), v[i]) <= 0) -----//d0
----- h.pop_back(); -----//f8
----- h.push_back(v[i]); -----//d1
--- } -----//fd
--- int s = h.size() + 1, tops = h.size(); -----//da
--- for(int i = v.size() - 2; i >= 0; i--){ -----//dd
----- while(h.size() >= s && -----//02
----- orientation(h[h.size()-2], h.back(), v[i]) <= 0) -----//a3
----- h.pop_back(); -----//3b
----- h.push_back(v[i]); -----//87
--- } -----//f8
--- //reminder : we have an extra point! -----//92
--- // we build top/bottom segments -----//ac
--- top.reserve(tops - 1), bottom.reserve(h.size() - tops + 1);
--- for(int i = 0; i + 1 < tops; i++) -----//cb
--- top.push_back(segment(h[i], h[i+1])); -----//38
--- for(int i = h.size() - 1; i - 1 >= tops - 1; i--) -----//69
--- bottom.push_back(segment(h[i], h[i-1])); -----//89
- } -----//12
- //we also count point on the borders -----//c4
- bool contains(point &p){ -----//a2
--- //we create a line to the sky -----//4a
--- segment line(p, {p.x, INF}); -----//11
--- //if p lays in a segment, it's in -----//b9
--- //if line doesn't hit top, it's out -----//32
--- //if line hits bot, it's out -----//c3
--- //if none occurs, it's in -----//a4
----- -----//7f
--- //we search top hull -----//a3
--- //we find first segment with b.x >= p.x, -----//b9
--- //so that intersection is there or eventually -----//9c
--- int l = 0, r = top.size(); -----//33
--- while(l < r){ -----//91
----- int m = (l + r)/2; -----//df
----- if(top[m].b.x >= p.x) -----//eb
----- r = m; -----//25
----- else -----//82
----- l = m + 1; -----//64
--- } -----//fb
--- if(r == top.size()) return 0; -----//b4

--- segment &t = top[l]; -----//d7
--- if(t.contains(p)) return 1; -----//89
--- if(!t.intersect(line)) return 0; -----//14
--- //we repeat for bottom -----//25
--- l = 0, r = bottom.size(); -----//a1
--- while(l < r){ -----//aa
----- int m = (l + r)/2; -----//07
----- if(bottom[m].b.x >= p.x) r = m; -----//ed
----- else l = m+1; -----//4a
--- } -----//cf
--- //see above -----//22
--- if(r == bottom.size()) return 0; -----//57
--- segment &b = bottom[l]; -----//50
--- if(b.contains(p)) return 1; -----//cc
--- if(b.intersect(line)) return 0; -----//1d
--- //only 1 intersection so it's good -----//cb
--- return 1; -----//ee
- } -----//4c
}; -----//fb

7. Ds

7.1. Wavelet Tree.
// Wavelet tree data structure -----//5d
// can handle some 2D queries -----//95
// O(NlogA) preprocess -----//dd
// O(logA) queries -----//ad
// 1-indexed! -----//61
struct wavelet { -----//55
- int lo, hi; -----//64
- vi b; -----//0f
- wavelet *l = 0, *r = 0; -----//f9
- // begin, end, min val, max val -----//d8
- wavelet(vi::iterator pl, vi::iterator pr, -----//e9
- int x, int y) { -----//ab
- lo = x, hi = y; -----//eb
- if (lo == hi || pl >= pr) return; -----//37
- int mid = lo + (hi - lo) / 2; -----//37
- auto f = [mid](int x) { -----//12
- return x <= mid; }; -----//cc
- b.reserve(pr - pl + 1); -----//76
- b.push_back(0); -----//44
- for (auto it = pl; it != pr; it++) -----//9a
- b.push_back(b.back() + f(*it)); -----//07
- auto it = stable_partition(pl, pr, f); -----//5a
- l = new wavelet(pl, it, lo, mid); -----//a9
- r = new wavelet(it, pr, mid + 1, hi); -----//24
- } -----//c4
----- -----//83
- // retrieve the k_th minimal value in range [l, r] -----//c3
- int kth(int l, int r, int k) { -----//b3
- if (l > r) return 0; -----//de
- if (lo == hi) return lo; -----//3d
- int le = b[l - 1], ri = b[r]; -----//81
- if (ri - le >= k) -----//61
- return this->l->kth(le+1,ri,k); -----//b5

return this->r->kth(l-le,r-ri,k-(ri-le)); -----//4c
- } -----//cb
----- -----//7f
- // count values less than k in range [l, r] -----//99
- int clt(int l, int r, int k) { -----//d8
--- if (l > r || k <= lo) return 0; -----//05
--- if (k > hi) return r - l + 1; -----//f9
--- int le = b[l - 1], ri = b[r]; -----//26
--- return this->l->clt(le+1,ri,k) + -----//f2
--- this->r->clt(l-le, r-ri, k); -----//20
- } -----//2e
----- -----//30
- // count equal to k in range [l, r] -----//67
- int ce(int l, int r, int k) { -----//ba
--- if (k < lo || k > hi || l > r) -----//f8
--- return 0; -----//9b
--- if (lo == hi) return r - l + 1; -----//82
--- int le = b[l - 1], ri = b[r]; -----//75
--- return this->l->ce(le + 1, ri, k) + -----//6e
--- this->r->ce(l - le, r - ri, k); -----//3f
- } -----//30
}; -----//b5

7.2. Treap.
/* Implicit Treap (BBST) -----//23
- can be augmented or used as map/set -----//f3
- O(logN) expected queries */ -----//5d
----- -----//89
// srand(time(0)); -----//82
struct treap{ -----//39
private: -----//f7
- struct node{ -----//4a
--- int val; -----//10
--- int p = rand(); -----//0f
--- // int h = 1; -----//00
--- int size = 1; -----//4c
--- node *l = nullptr; -----//f3
--- node *r = nullptr; -----//fd
--- node (int a){ -----//ba
--- val = a; -----//6f
--- } -----//5d
--- void update(){ -----//34
----- // int lh = l != nullptr ? l->h : 0; -----//f7
----- // int rh = r != nullptr ? r->h : 0; -----//ae
----- // h = 1 + max(lh, rh); -----//a0
----- int ls = l != nullptr ? l->size : 0; -----//42
----- int rs = r != nullptr ? r->size : 0; -----//c0
----- size = 1 + ls + rs; -----//ae
--- } -----//96
- }; -----//31
- node *merge(node *a, node *b){ -----//28
--- if(a == nullptr) return b; -----//2a
--- if(b == nullptr) return a; -----//8c
--- if(a->p < b->p){ -----//51
--- a->r = merge(a->r, b); -----//92
--- a->update(); -----//02
```



```

return a; //0c
} else{ //0c
    b->l = merge(a, b->l);
    b->update(); //d2
    return b; //ff
} //4a
} //68
int pos(node *a){ //b7
    if(a->l == nullptr) return 0; //c0
    return a->l->size; //42
} //8b
pair<node*, node*> split(node *a, int k){ //7b
    if(a == nullptr) return {nullptr, nullptr}; //a4
    int p = pos(a); //1b
    // if a->key < k //f7
    if(p < k){ //ba
        auto x = split(a->r, k - (p + 1)); //2d
        a->r = x.first; //c6
        a->update(); //2a
        return {a, x.second}; //51
    } else{ //ec
        auto x = split(a->l, k); //50
        a->l = x.second; //20
        a->update(); //4d
        return {x.first, a}; //07
    } //c0
} //ae
node *insert(node* a, int index, int val){ //c7
    auto x = split(a, index); //f0
    return merge(x.first, merge(new node(val), x.second)); //b0
} //f0
node *erase(node *a, int k){ //57
    if(a == nullptr) return nullptr; //f4
    int p = pos(a); //f1
    // if a->key == k //e1
    if(p == k){ //96
        node* ans = merge(a->l, a->r); //89
        free(a); //b8
        return ans; //5c
    } //b3
    if(k < p) //6d
        a->l = erase(a->l, k); //c6
    else //8c
        a->r = erase(a->r, k - (p + 1)); //97
    a->update(); //8e
    return a; //8f
} //87
//0-based //26
int get_kth(node *a, int k){ //18
    int p = pos(a); //de
    if(p == k) //e3
        return a->val; //be
    if(k < p) //9d
        return get_kth(a->l, k); //d7
    else //c4
        return get_kth(a->r, k - (p + 1)); //25
} //69
node *root = nullptr; //25
public: //ce
    void insert(int i, int val){ //bf
        root = insert(root, i, val); //32
    } //ae
    void erase(int k){ //83
        root = erase(root, k); //55
    } //35
    // int height(){ //7a
    // return root != nullptr ? root->h : 0; //80
    // } //3b
    int operator[](int i){ //1d
        return get_kth(root, i); //15
    } //13
}; //f1

7.3. Sparse Table.
// Sparse Table //61
// O(NlogN) memory, O(1) RMQ //80
struct sparse_table { vvi m; //bf
    sparse_table(vi arr) { //f3
        m.push_back(arr); //8f
        for (int k = 0; (1<<(++k)) <= arr.size(); ) { //a1
            m.push_back(vi(arr.size()-(1<<k)+1)); //41
            for(int i = 0; i < arr.size() - (1<<k) + 1; i++) //2f
                m[k][i] = min(m[k-1][i], m[k-1][i+(1<<(k-1))]); } //54
        int query(int l, int r) { //01
            int k = 0; while (1<<(k+1) <= r-l+1) k++; //0e
            return min(m[k][l], m[k][r-(1<<k)+1]); } //dc
        }

7.4. Segment Tree.
/* SegmentTree for Range Sum Queries //9c
and lazy propagation //f2
O(N) mermory, O(logN) queries */ //ee
struct segtree { //b8
    vector<int> v, u; //46
    int n; //02
    const int NULL_VALUE = 0; //ce
    segtree(int num) { //f2
        v.resize((1 << (int)(ceil(log2(num))+1))-1, NULL_VALUE); //ea
        u.resize(v.size(), NULL_VALUE); //99
        n = v.size() / 2; //49
    } //05
    segtree(vector<int> &source) : segtree(source.size()) { //e6
        for (int i = 0; i < source.size(); i++) //0b
            v[i + n] = source[i]; //e3
        for (int i = n - 1; i >= 0; i--) //a3
            updateNode(i); //29
    } //db
    int left(int i) { return i*2+1; } //56
    int right(int i) { return i*2+2; } //32
    int parent(int i) { return (i - 1) / 2; } //ee
    int mergeValues(int v1, int v2) { //34
        return v1 + v2; //1c
    } //ff
    void updateNode(int i) { //a0
        v[i] = mergeValues(v[left(i)], v[right(i)]); //e9
    } //61
    void lazyUpdate(int i) { //cc
        if (u[i] != 0) { //d5
            v[i] += u[i]; //26
            if (i < v.size() / 2) { //05
                u[left(i)] += u[i] / 2; //b7
                u[right(i)] += u[i] / 2; } //21
            u[i] = 0; //32
        } //79
    } //72
    int rangeQuery(int i, int l, int r, int a, int b) { //5e
        lazyUpdate(i); //7f
        if (l >= a && r <= b) //84
            return v[i]; //59
        if (r < a || l > b) //b4
            return NULL_VALUE; //c6
        int m = (l + r) / 2; //d6
        return mergeValues(rangeQuery(left(i), l, m, a, b), //3d
            rangeQuery(right(i), m + 1, r, a, b)); //04
    } //3a
    void updateToRoot(int i) { //a9
        updateNode(i); //c4
        if (i != 0) updateToRoot(parent(i)); } //a3
    void rangeAdd(int i, int a, int b, int l, int r, int off) {
        lazyUpdate(i); //2c
        if (l >= a && r <= b) { //89
            u[i] += off * (r - l + 1); //3f
            lazyUpdate(i); //4d
        } else if (!(r < a || l > b)) { //d3
            int m = (l + r) / 2; //9b
            rangeAdd(left(i), a, b, l, m, off); //c0
            rangeAdd(right(i), a, b, m + 1, r, off); //91
            updateNode(i); //e3
        } //bd
    } //2b
    int rangeSum(int a, int b) { //cb
        return rangeQuery(0, 0, n, a, b); } //4b
    void update(int index, int value) { //ed
        int i = n + index; //09
        v[i] = value; //36
        updateToRoot(parent(i)); } //12
    void rangeUpdate(int a, int b, int offset) { //16
        rangeAdd(0, a, b, 0, n, offset); } //ed
    }; //50

7.5. Mergesort Tree.
/* //b6
MergeSort Tree //eb
O(NlogN) memory data structure //c2
for various 2D queries //58
```

```

- to build: mergetree mt(vector...); -----//8e
- v.resize((1<<(int)(ceil(log2(source.size()+1))))-1); --//26
- for(int i = source.size()*2 - 2; i >= 0; i--) -----//e7
- v[i].build(i, source, v); -----//26
- } -----//c0
- const int nullQuery = 0; -----//f5
- int qa, qb, qx; -----//dc
- int count(int i, int l, int r){ -----//9f
- if(l >= qa && r <= qb) -----//ce
- return v[i].count(qx); -----//a7
- if(l > qb || r < qa) -----//27
- return nullQuery; -----//08
- int m = (l+r)/2; -----//fd
- return count(left(i), l, m) + count(right(i), m+1, r); //c8
- } -----//fd
- // count value = x in [a, b] -----//0d
- int query(int a, int b, int x){ -----//8e
- qa = a, qb = b, qx = x; -----//e6
- int l = 0, r = v.size()/2; -----//83
- return count(0, l, r); -----//de
- } -----//02
- }; -----//a8

7.6. Max Queue.
// Queue with get_max() in O(1) -----//0b
- struct maxqueue{ -----//09
- deque<pair<ll,int>> q; -----//75
- int l = 0, r = 0; -----//4c
- int size(){ return r - l; } -----//79
- void push(ll val){ -----//5a
- while(q.size() && q.back().first <= val) -----//95
- q.pop_back(); -----//7a
- q.push_back({val, r++}); } -----//6d
- void pop(){ -----//62
- if(q.front().second == l) -----//b5
- q.pop_front(); -----//d5
- l++; } -----//e0
- ll get_max(){ -----//ec
- if(!size()) return -1; -----//90
- return q.front().first; } -----//11
- }; -----//b1
- }; -----//72

7.7. Kd Tree.
// k-D Tree -----//86
// Insert k dimensional points in ~O(log^k N) -----//10
// Closest Neighbour in ~O(log^k N) -----//cd
// CAREFUL - can degenerate to O(N) for -----//05
// pathological inputs -----//e0
#define INC(c) ((c) == K - 1 ? 0 : (c) + 1) -----//71
template<int K> struct kd_tree { -----//fc
- struct pt { -----//e2
- double coord[K]; -----//bd
- pt() {} -----//99
- pt(double c[K]) { rep(i,0,K) coord[i] = c[i]; } -----//2a
- double dist(const pt &other) const { -----//b5
- double sum = 0.0; -----//ff
- rep(i,0,K) sum += pow(coord[i] - other.coord[i], 2.0); -----//78
- return sqrt(sum); } }; -----//5f
- struct cmp { -----//7d
- int c; -----//5c
- cmp(int _c) : c(_c) {} -----//25
- bool operator()(const pt &a, const pt &b) { -----//db
- for (int i = 0, cc; i <= K; i++) { -----//3f
- cc = i == 0 ? c : i - 1; -----//4b
- if (abs(a.coord[cc] - b.coord[cc]) > EPS) -----//5d
- return a.coord[cc] < b.coord[cc]; -----//1e
- } -----//e0
- return false; } }; -----//be
- struct bb { -----//b5
- pt from, to; -----//8e
- bb(pt _from, pt _to) : from(_from), to(_to) {} -----//9f
- double dist(const pt &p) { -----//45
- double sum = 0.0; -----//3a
- rep(i,0,K) { -----//50
- if (p.coord[i] < from.coord[i]) -----//7e
- sum += pow(from.coord[i] - p.coord[i], 2.0); -----//17
- else if (p.coord[i] > to.coord[i]) -----//51
- sum += pow(p.coord[i] - to.coord[i], 2.0); -----//c7
- } -----//e9
- return sqrt(sum); } -----//5c
- bb bound(double l, int c, bool left) { -----//c2
- pt nf(from.coord), nt(to.coord); -----//1c
- if (left) nt.coord[c] = min(nt.coord[c], l); -----//9a
- else nf.coord[c] = max(nf.coord[c], l); -----//91
- return bb(nf, nt); } }; -----//41
- struct node { -----//8e
- pt p; node *l, *r; -----//bc
- node(pt _p, node *_l, node *_r) -----//1e
- : p(_p), l(_l), r(_r) { } }; -----//b0
- node *root; -----//db
- kd_tree(vector<pt> pts) { -----//d1
- root = construct(pts, 0, size(pts) - 1, 0); } -----//46
- node* construct(vector<pt> &pts, int from, int to, int c) { -----//7a
- if (from > to) return NULL; -----//7a
- int mid = from + (to - from) / 2; -----//89
- nth_element(pts.begin() + from, pts.begin() + mid, -----//25
- pts.begin() + to + 1, cmp(c)); -----//ab
- return new node(pts[mid], -----//89
- construct(pts, from, mid - 1, INC(c)), -----//dc
- construct(pts, mid + 1, to, INC(c))); } -----//d6
- bool contains(const pt &p) { return _con(p, root, 0); } -----//7b
- bool _con(const pt &p, node *n, int c) { -----//93
- if (!n) return false; -----//2c
- if (cmp(c)(p, n->p)) return _con(p, n->l, INC(c)); -----//8f
- if (cmp(c)(n->p, p)) return _con(p, n->r, INC(c)); -----//63
- return true; } -----//5c
- void insert(const pt &p) { _ins(p, root, 0); } -----//8d
- void _ins(const pt &p, node* &n, int c) { -----//1b
- if (!n) n = new node(p, NULL, NULL); -----//5b
- else if (cmp(c)(p, n->p)) _ins(p, n->l, INC(c)); -----//ec
- else if (cmp(c)(n->p, p)) _ins(p, n->r, INC(c)); } -----//a4
- void clear() { _clr(root); root = NULL; } -----//9e

```

```
void _clr(node *n) { -----//2f
-- if (n) _clr(n->l), _clr(n->r), delete n; } -----//e8
pair<pt, bool> nearest_neighbour(const pt &p, -----//7f
-- bool allow_same=true) { -----//e0
-- double mn = INFINITY, cs[K]; -----//73
-- rep(i,0,K) cs[i] = -INFINITY; -----//62
-- pt from(cs); -----//0b
-- rep(i,0,K) cs[i] = INFINITY; -----//a4
-- pt to(cs), resp; -----//d0
-- _nn(p, root, bb(from, to), mn, resp, 0, allow_same); -----//bd
-- return make_pair(resp, !std::isinf(mn)); } -----//40
void _nn(const pt &p, node *n, bb b, -----//09
-- double &mn, pt &resp, int c, bool same) { -----//e8
-- if (!n || b.dist(p) > mn) return; -----//23
-- bool l1 = true, l2 = false; -----//e7
-- if ((same || p.dist(n->p) > EPS) && p.dist(n->p) < mn) -----//ff
-- mn = p.dist(resp = n->p); -----//29
-- node *n1 = n->l, *n2 = n->r; -----//12
-- rep(i,0,2) { -----//95
-- if (i == 1 || cmp(c)(n->p, p)) swap(n1,n2),swap(l1,l2);
-- _nn(p, n1, b.bound(n->p.coord[c], c, l1), mn, -----//06
-- resp, INC(c), same); } } }; -----//7e
```

7.8. Fenwick Tree.

```
/* Fenwick Tree (up to 3D) -----//9e
- For each dimension: -----//77
-- O(N) memory -----//43
-- prefix query in O(logN) -----//69
-- point update in O(logN) -----//96
*/ -----//15
constexpr int lsb(int n){ -----//e1
- return n&(-n); -----//d7
} -----//3f
// 1-based !!! -----//80
struct fenwick{ -----//8b
- vi v; -----//16
- fenwick(int n) : v(n+1){} -----//62
- fenwick(vi &source) { -----//fd
-- v.resize(source.size() + 1); -----//ed
-- for(int i = 0; i < source.size(); i++){ -----//52
-- v[i+1] += source[i]; -----//7a
-- if(i+1 + lsb(i+1) < v.size()) -----//7e
-- v[i+1 + lsb(i+1)] += v[i+1]; -----//41
-- } -----//a2
- } -----//96
- int pf(int i){ -----//09
-- int ans = 0; -----//f6
-- for(; i; i-=lsb(i)) -----//7f
-- ans += v[i]; -----//8a
-- return ans; -----//89
- } -----//24
- int rsq(int l, int r){ -----//11
-- return pf(r) - pf(l-1); -----//b5
- } -----//76
- void update(int i, int k){ -----//da
-- for(; i < v.size(); i += lsb(i)) -----//9c
```

```
v[i] += k; -----//0a
- } -----//6b
}; -----//b6
struct fenwick2d{ -----//0c
- vector<fenwick> v; -----//15
- fenwick2d(int n, int m) : v(n+1, fenwick(m)){} -----//c5
- int pf(int r, int c){ -----//ba
-- int ans = 0; -----//d5
-- for(int i = r; i > 0; i -= lsb(i)) -----//3f
-- ans += v[i].pf(c); -----//46
-- return ans; -----//b2
- } -----//24
- int rsq(int r1, int c1, int r2, int c2){ -----//88
-- return pf(r2, c2) - pf(r1-1, c2) -----//09
-- - pf(r2, c1-1) + pf(c1-1, r1-1); -----//16
- } -----//28
- void update(int r, int c, int k){ -----//4a
-- for(int i = r; i < v.size(); i += lsb(i)) -----//65
-- v[i].update(c, k); -----//2c
- } -----//8c
}; -----//b9
struct fenwick3d{ -----//aa
- vector<fenwick2d> v; -----//a9
- fenwick3d(int x, int y, int z){ -----//8d
-- v.resize(x+1, fenwick2d(y, z)); -----//4b
- } -----//9c
- int pf(int x, int y, int z){ -----//86
-- int ans = 0; -----//79
-- for(int i = x; i > 0; i -= lsb(i)) -----//91
-- ans += v[i].pf(y, z); -----//33
-- return ans; -----//26
- } -----//63
- int rsq(int x1,int y1,int z1,int x2,int y2,int z2){ -----//2d
-- return pf(x2, y2, z2) - pf(x1-1, y2, z2) - -----//cb
-- pf(x2, y1-1, z2) - pf(x2, y2, z1-1) + -----//c8
-- pf(x2, y1-1, z1-1) + pf(x1-1, y2, z1-1) + -----//2c
-- pf(x1-1, y1-1, z2) - pf(x1-1, y1-1, z1-1); -----//da
- } -----//77
- void update(int x, int y, int z, int k){ -----//f5
-- for(int i = x; i < v.size(); i+=lsb(i)) -----//80
-- v[i].update(y, z, k); -----//25
- } -----//3d
}; -----//f2
```

7.9. Dsu.

```
// UnionFind Data structure -----//27
// can be used for Kruskal's MST -----//f6
struct union_find { -----//7a
- vi p; union_find(int n) : p(n, -1) { } -----//51
- int find(int x) { return p[x] < 0 ? x : p[x] = find(p[x]); }
- bool unite(int x, int y) { -----//bd
-- int xp = find(x), yp = find(y); -----//38
-- if (xp == yp) return false; -----//0f
-- if (p[xp] > p[yp]) swap(xp,yp); -----//18
-- p[xp] += p[yp], p[yp] = xp; -----//32
```

```
-- return true; } -----//14
- int size(int x) { return -p[find(x)]; } }; -----//d2
```

8. DP

8.1. Knuth Opt.

```
/* -----//b6
- Knuth's DP Optimization -----//fc
- Implementation example -----//c1
- Recurrence: -----//7c
-- dp[i][j] = min(i < k < j){dp[i][k] + dp[k][j]} + C[i][j]}
-- From O(n^3) to O(n^2) -----//bd
- Conditions: -----//36
-- opt[i][j-1] <= opt[i][j] <= opt[i+1][j], -----//da
-- where opt[i][j] is smallest optimal k for dp[i][j] -----//62
- What to do: -----//14
-- we solve smaller subproblems first -----//5f
-- then we use the fact that we don't need to try -----//a5
-- all k but that it's enough to try those between -----//9b
-- opt[i][j-1] and opt[i+1][j] -----//84
-- we magically drop a N in complexity :) -----//ca
*/ -----//67
/* input...*/ -----//fe
-----//5d
vi sum(n); -----//33
partial_sum(v.begin(), v.end(), sum.begin()); -----//87
-----//e9
vector<vector<ll>> dp(n, vector<ll>(n)); -----//4a
// smallest index of optimal solution for dp[l, r] -----//1a
vvi opt(n, vi(n)); -----//bb
for(int s = 1; s <= n; s++){ -----//b1
- for(int l = 0; l + s - 1 < n; l++){ -----//4c
-- int r = l + s - 1; -----//42
-- // base cases -----//a2
-- if(s <= 2){ -----//c7
-- dp[l][r] = s == 2 ? sum[r] - (1 ? sum[l-1] : 0) : 0; -----//52
-- opt[l][r] = 1; -----//85
-- } else{ -----//fc
-- int low = opt[l][r-1]; -----//ff
-- int hi = opt[l+1][r]; -----//52
-- int curr = sum[r] - (1 ? sum[l-1] : 0); -----//b0
-- dp[l][r] = LLINF; -----//2d
-- // solution must be in this range as\ -----//05
-- opt[l-1][r] <= opt[l][r] <= opt[l][r+1] -----//f9
-- for(int m = low; m <= hi; m++){ -----//b6
-- ll tmp = curr + dp[l][m] + dp[m+1][r]; -----//47
-- if(tmp < dp[l][r]){ -----//86
-- dp[l][r] = tmp; -----//7f
-- opt[l][r] = m; -----//58
-- } -----//f8
-- } // dp[l][r] is found -----//e7
-- } -----//96
- } -----//d4
} -----//02
```

8.2. Dc Opt.

```

/* -----//b6
- Divide and Conquer DP Optimization -----//ad
- Sadly, no implementation examples -----//1b
- Recurrence: -----//92
-- dp[i][j] = min[k < j]{dp[i-1][k] + C[k][j]} -----//f9
- From  $O(n^2k)$  to  $O(nk \log n)$  -----//c8
- Conditions: -----//75
--- opt[i][j] <= opt[i][j+1], -----//99
--- where opt[i][j] is smallest optimal k for dp[i][j] -----//3f
- What to do: -----//c0
--- we compute all dp[i] in [i][l, r] knowing that -----//4e
--- opt value is in k between [optL, optR] -----//0b
- solve(i, l, r, optL, optR) = -----//74
--- check l == r -----//77
--- m = (l+r) / 2; -----//bf
--- dp(i, m) -----//87
--- opt(i, m) -----//fc
--- // costs optR - optL -----//1a
--- // use newly found opt to solve the problem -----//65
--- solve(i, l, m-1, optL, opt[i][m]) -----//74
--- solve(i, m+1, r, opt[i][m], optR) -----//52
*/ -----//26

```

```

while(next(it)!=lines.end() && useless(next(it)))it=prev(lines.erase(next(it)));
while(it!=lines.begin() && useless(prev(it)))it=lines.erase(prev(it));
recalc(it); -----//cb
} -----//23
set<line>::iterator find(ll x){ -----//54
    line query = line{x,0,0,1}; -----//b4
    return lines.lower_bound(query); -----//42
} -----//26
ll at(ll x){ -----//73
    auto t = find(x); -----//77
    return (t->m)*x+t->q; -----//b2
} -----//83
}; -----//4e
-----//bb

```

### 8.3. Cht.

```

struct cht{ -----//3d
    struct line{ -----//4b
        mutable ll x1; -----//40
        ll m; -----//41
        ll q; -----//cd
        bool query; -----//23
        bool operator<(const line& o)const{ -----//97
            return (query||o.query)?x1<o.x1: -----//92
                m>o.m; //min cht -----//1b
                //m<o.m; //max cht -----//04
        } -----//ef
    }; -----//f2
    ll intersect(const line& a, const line& b){ -----//35
        if(a.m==b.m)return inf; -----//16
        return (a.q-b.q)/(b.m-a.m); -----//55
    } -----//78
    set<line> lines; -----//73
    bool useless(set<line>::iterator it){ -----//1d
        if(it==lines.begin()||next(it)==lines.end())return 0; ---//e2
        return (intersect(*prev(it),*it)>=intersect(*it,*next(it)));
    } -----//96
    void recalc(set<line>::iterator it){ -----//3a
        it->x1 = (next(it)==lines.end()?inf:intersect(*it,*next(it)));
        if(it!=lines.begin())prev(it)->x1 = intersect(*prev(it),*it);
    } -----//69
    void insert(ll m, ll q){ -----//96
        line nl = line{-1,m,q,0}; -----//75
        auto it = lines.insert(nl).first; -----//80
        if(useless(it)){ -----//3b
            lines.erase(it); -----//96
            return; -----//1f
        } -----//98
    }

```