



# Pico and I2C Using MicroPython

Steven F. LeBrun

October 8, 2022

Roanoke Robotics & Makers Club  
of Southwest Virginia

# Overview

- Raspberry Pi Pico
- I2C Protocol
- Raspberry Pi Pico and I2C
- Programming I2C Devices for Pico
- SSD1306 oLED Display
- LCD Display
- ADXL345 Accelerometer
- References

# Raspberry Pi Pico

- The Pico is a microcontroller board – not a computer
- Based on the RP2040 chip – Dual core ARM processor
- Powered by 5V USB cable
- GPIO Pins
  - High -- 3.3V
  - Low -- 0V or Ground
- Supports I2C, SPI, UART communication protocols
- 3 available ADC pins

# I2C Protocol

- I2C, a.k.a. I<sup>2</sup>C, IIC, is formally called **Inter-Integrated Circuit**
- Two-Wire Serial communications between low speed devices
  - SDA – Serial Data
  - SCL – Serial Clock
- Multiple devices can be connected to the same SDA & SCL lines
- One device is a master and the other devices are slaves
- Each slave device identified with a unique 7 bit address

# I2C Protocol

- Transmission starts with the Master Device generating a Start Condition of SDA low and SCL high
- First byte written by Master
  - Contains Slave Address and the I/O bit
- The I/O bit is bit 0 determines I/O direction
  - High – Slave writes next bytes and Master reads them
  - Low -- Master writes next bytes and Slave reads them
- Transmission ends with Master Device generating a Stop Condition of SDA high and SCL high

# I2C Protocol

- Each [slave] I2C Device has its own protocol that is on top of I2C.
- Device datasheets explain what those protocols are
- Commonly, the first byte is a register or memory location on the slave device.
- The next n bytes are the data read or written to and from the slave device.
- The format of those bytes are defined in the device datasheet

# Pico – I2C GPIO Pins

- The Pico, like the Raspberry Pi, has two I2C buses.
  - Labeled I2C0 for I2C Bus 0, and I2C1 for I2C Bus 1
- On the Raspberry Pi, the command “i2cdetect 0” and “i2cdetect 1” are used to scan the I2C Bus 0 and Bus 1, respectively.
  - Use the command “sudo apt-get install i2c-tools” to install i2cdetect
- There is no such program is available for the Pico
  - Can use method I2C.scan() to obtain the same information on the Pico
  - My program, I2C-scan.py, will perform the scan operation and list the I2C addresses that are active on the two buses.

# I2C Scan Program

```
## I2C-scan.py

from machine import I2C, Pin

def print_devices( i2c, devices ):
    print("In Print I2C Device Addresses")
    print("I2C ID = ", i2c)
    if ( devices ):
        for dev in devices:
            print(hex(dev))

i2c0 = I2C(0, sda=Pin(8), scl=Pin(9), freq=400000)
i2c1 = I2C(1, sda=Pin(6), scl=Pin(7), freq=400000)

devices0 = i2c0.scan()
print_devices( i2c0, devices0 )

devices1 = i2c1.scan()
print_devices( i2c1, devices1 )
```



# Output from I2C-scan.py

In Print I2C Device Addresses

I2C ID = I2C(0, freq=399361, scl=9, sda=8)

0x1d

0x27

0x3c

In Print I2C Device Addresses

I2C ID = I2C(1, freq=399361, scl=7, sda=6)

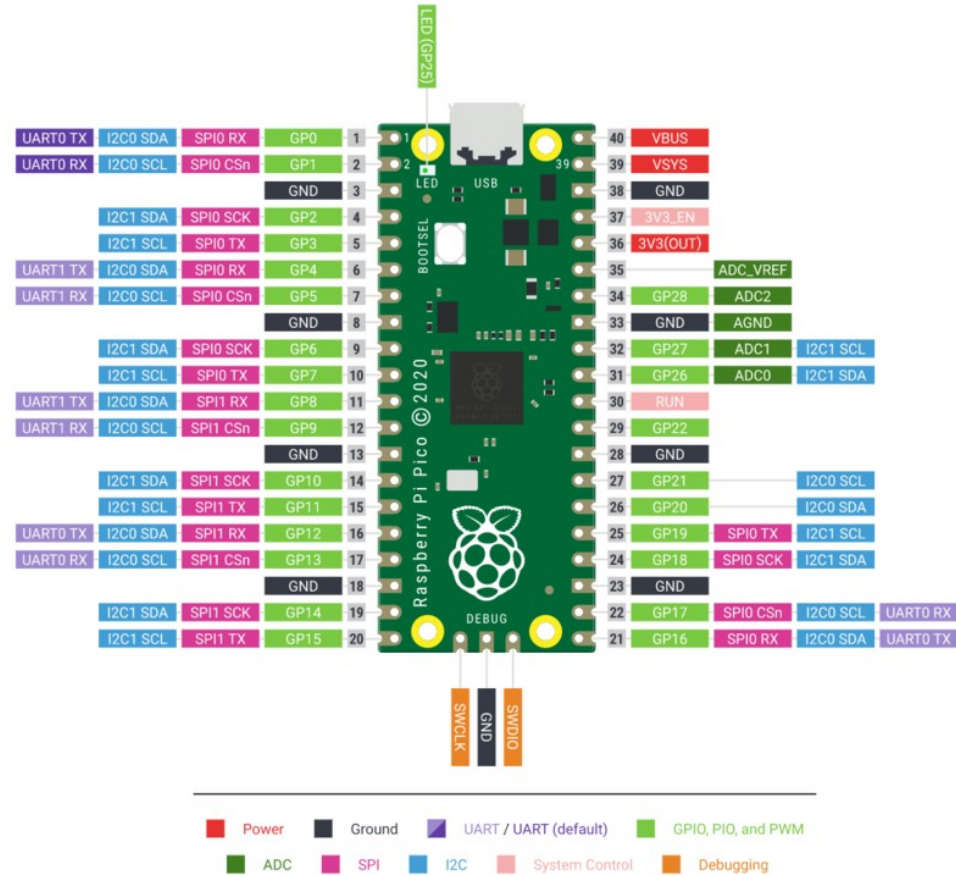
# Pico – I2C GPIO Pins

- Different sets of GPIO Pins on the Pico can be used for I2C communications
- See a Raspberry Pi Pico Pinout to determine which GPIO Pins are configured for I2C I/O
- I2C GPIO Pins can be used for other purposes.
- The following table lists the pairs of SDA and SCL GPIO Pins.

# Pico – I2C GPIO Pins

I2C Bus 0			I2C Bus 1	
SDA	SCL		SDA	SCL
0	1	1	2	3
4	5	2	6	7
8	9	3	10	11
12	13	4	14	15
16	17	5	18	19
20	21	6	26	27

# Pico Pinout



# Programming I2C Device for Pico

- Select a module that supports I2C
  - Examples SSD1306 oLED display, ADXL345 Accelerometer, BME280 Combined Temperature/Humidity/Pressure sensor
- Information needed before writing code:
  - Datasheet
  - MicroPython Library/Package – If any exists
  - Example Programs – If any exist

# Programming I2C Device for Pico – Datasheets

- The datasheet provides the following information
  - Pins and how to connect them to Pico
  - Protocol that rides on top of I2C
  - Commands and Data for controlling device
- Control Flow for the device
  - How to initialize
  - How to change modes or behavior
  - How to read and write data

# Programming I2C Device for Pico – Libraries

- Performs the low level work needed to control the device
  - Performs the I2C byte-level communication
- Provides API for basic commands
  - Such as display text, read data, initialize device
- Make sure Library is for the programming language you are using
  - MicroPython vs CircuitPython
- Use Thonny or Google to find libraries

# Programming I2C Device for Pico – Libraries

- ADXL345 Accelerometer
  - `Hass-python-adxl34x` library
- BME280 Combined Temperature/Humidity/Pressure Sensor
  - `micropython-bme280`
- LCD 20x4 Display
  - RPI-PICO-I2C-LCD by T-622 on GitHub
- SSD1306 oLED Display
  - `micropython-ssd1306`



# Programming I2C Device for Pico – Examples

- Example Programs
  - Provide source code for controlling the device.
    - Make sure example uses the same or similar library
  - Provide insight on how to use the device
    - What steps are needed to prepare the device for use
    - What steps are needed to obtain data from device
    - For display devices, how to get text, images, pixels to actually be displayed

# Programming I2C Device for Pico

- If no library can be found
  - You will need to write your own low-level library
  - Use the datasheet to:
    - Determine how to write to and read from the device using I2C
    - What methods are needed based on the command set for the device
- Command sets are usually mapped to registers or memory locations
  - Registers are normally represented by a one byte hexadecimal value
  - Registers usually have one byte data values that can be RO, WO, RW

# SSD1306 OLED Display

- OLED or oLED == Organic Light Emitting Diodes
- OLED are bitmap displays
- Common SSD1306 module is a 0.96" monochrome display
  - With 128 x 64 pixels
  - The foreground color is blue. Sometimes the first 15-20 rows of pixels may be a different color such as red or yellow
- Multiple libraries are available to handle the low level work of running the display.
  - My choice was micropython-ssd1306

# SSD1306 OLED Display

- The `ssd1306` defines three classes
  - `SSD1306` – Base class derived from `frame.FrameBuffer` class
    - This is an abstract class used by the following two classes
  - `SSD1306_I2C` – Class that uses I2C to communicate with display
    - This is the class we will use.
  - `SSD1306_SPI` – Class that uses SPI to communicate with display
    - SPI is another serial communication protocol that uses two shared wires for Data and Clock, plus a third dedicated wire instead of addresses.

# SSD1306 OLED Display

- The underlying **FrameBuffer** class contains methods for managing a bitmap display, such as the SSD1306
- A set of primitive methods control pixels:
  - They are *fill()*, *pixel()*, *hline()*, *vline()*, *line()*, *rect()*, *ellipse()*, *poly()*
- They are *text()* places text strings into the bit map
- Extra methods for more complex operations:
  - They are *scroll()*, *blit()*
- Most important, ***SSD1306.show()***, which causes changes to be sent to the display.

# Simple OLED Program

```
## oled-demo.py
from machine import Pin, I2C
from ssd1306 import SSD1306_I2C

#i2c = I2C(0, sda=Pin(8), scl=Pin(9), freq=400000 )
i2c = I2C(1, sda=Pin(6), scl=Pin(7), freq=400000 )
display = SSD1306_I2C( 128, 64, i2c, addr=0x3C )

display.text("Hello World!", 0,0,1)
display.hline(0, 10, 128, 1)
display.vline(100, 0, 64, 1)
display.show()
```

# LCD Displays

- LCD Displays are character based displays
- Two common sizes are 16x2 characters and 20x4 characters
  - 16 and 20 are the number characters in a row
  - 2 and 4 are the number of rows
- LCD Displays normally use a lot of GPIO pins
- LCD Displays with I2C interfaces uses 2 GPIO pins plus a Vcc and Ground connection

# LCD Displays

- MicroPython libraries for LCD Displays are not as common as the libraries for the SSD1306
- The micropython-lcd library on pypi.org is a dummy library.
  - No content or code
  - PyPi is where Thonny searches for packages
- Libraries are available on GitHub
  - I use <https://github.com/T-622/RPI-PICO-I2C-LCD.git>
  - By Tyler Peppy -- T-622



# ADXL345 Accelerometer

- The ADXL345 measures acceleration
  - In X, Y, and Z axes
  - Measures dynamic and static acceleration
    - Dynamic acceleration of movement
    - Static acceleration of gravity
- Uses either SPI or I2C communication protocols
  - Communication protocol selected by CS Pin
  - For this presentation, we will only be using I2C

# ADXL345 Accelerometer

- Has an 8 pin interface
  - 4 pins for I2C and SPI communications
  - CS pin to select protocol
    - High for I2C and Low for SPI
  - SDO – Serial Data Output
    - If CS is Low, SDO is for SPI as Serial Data Output
    - If CS is High, I2C Address – High for 0x1D and Low for 0x53
  - 2 pins to generate interrupts

# References – This Presentation

- GitHub – Repository Robot-Maker for “Pico and I2C Talk”
  - <https://github.com/sflebrun/Robot-Maker>
- Directory containing Source Code and Presentation Documents
  - <https://github.com/sflebrun/Robot-Maker/tree/main/Pico%20and%20I2C%20Talk>

# References – ADXL345

- Datasheet
  - <https://www.analog.com/media/en/technical-documentation/data-sheets/adxl345.pdf>
- ADXL345 and Pico using MicroPython
  - <https://www.digikey.com/en/maker/projects/raspberry-pi-pico-rp2040-i2c-example-with-micropython-and-cc/47d0c922b79342779cdbc4b37b7eb7e2>

# References – I2C

- I2C Bus, Interface, and Protocol
  - <https://i2c.info/>
- I2C Bus Specification
  - <https://i2c.info/i2c-bus-specification>
- UM10204 – I2C Bus Specification and User Manual
  - <https://www.nxp.com/docs/en/user-guide/UM10204.pdf>

# References – LCD Display

- Library used in GitHub
  - <https://github.com/T-622/RPI-PICO-I2C-LCD.git>
- Library contains two files that need to be copied to Pico
  - `lcd_api.py`
    - Abstract base class `LcdApi` for operating LCD Displays
    - Imported indirectly `pico_i2c_lcd`
  - `pico_i2c_lcd.py`
    - Class `I2cLcd`, derived from `LcdApi`
    - Adds I2C functionality to LCD communication

# References – MicroPython

- Overview – MicroPython 1.19.1 Documentation
  - <https://docs.micropython.org/en/latest/index.html>
- Class I2C – a two-wire serial protocol
  - <https://docs.micropython.org/en/latest/library/machine.I2C.html?highlight=t=i2c#machine.I2C>
- Class FrameBuffer – for creating and manipulating bitmaps
  - <https://docs.micropython.org/en/latest/library/framebuf.html>
- Class Pin – Control GPIO Pins
  - <https://docs.micropython.org/en/latest/library/machine.Pin.html>

# References – Pico

- **Raspberry Pi Pico [W] Pinout**
  - <https://datasheets.raspberrypi.com/picow/PicoW-A4-Pinout.pdf>
- **Raspberry Pi Pico SDK Documentation V1.4.0**
  - <https://raspberrypi.github.io/pico-sdk-doxxygen/index.html>
- **Class machine.I2C for Pico**
  - <https://docs.micropython.org/en/latest/library/machine.I2C.html>
  - [https://wiki.sipeed.com/soft/maixpy/en/api\\_reference/machine/i2c.html](https://wiki.sipeed.com/soft/maixpy/en/api_reference/machine/i2c.html)



# References – SSD1306

- Datasheet
  - <https://www.elecrow.com/download/SSD1306%20Datasheet.pdf>
- OLED 4 Pin 128 x 64 Display Module 0.96”
  - <https://www.rajguruelectronics.com/Product/1145/OLED%204%20Pin%20128x64%20Display%20module%200.96%20inch%20blue%20color.pdf>
- SSD1306 Demo V3
  - <https://www.instructables.com/SSD1306-With-Raspberry-Pi-Pico/?fbclid=IwAR0Eg8xfaiJfQH-qZjBUu31SCgZRet8Qgi7HSJ0NvJ9zgLF8q60sfZ62Hp0>