

* Chp. 5 Eigen-stuff

Def: When $T: V \rightarrow V$ is a lin. trans.
and we find a specific vector
 $\vec{x} \in V$ such that $\vec{x} \neq \vec{0}$

and $T(\vec{x}) = c\vec{x}$ for some
constant c

then we call \vec{x} an eigenvector
with eigen value c (often use $c = \lambda$,
(λ can be 0, but $\vec{x} \neq \vec{0}$)

(if T is just multiplying every
vector by a constant, then every
vector in V is an eigenvector, with
that constant λ its eigenvalue.)

However, most lin. trans. $T: V \rightarrow V$ have only
certain eigenvectors and eigenvalues. Find them!

Steps:

1) We work with $A = [T]_{\mathcal{B}}$

2) Let $A\vec{x} = \lambda\vec{x}$ ($\vec{x} \neq \vec{0}$)
then $\Rightarrow A\vec{x} = (\lambda I)\vec{x}$ ($\lambda I = \begin{bmatrix} \lambda & 0 & 0 & \dots & 0 \\ 0 & \lambda & & & 0 \\ \vdots & & \ddots & & \vdots \\ 0 & 0 & 0 & \dots & \lambda \end{bmatrix}$)
 $\Rightarrow A\vec{x} - (\lambda I)\vec{x} = \vec{0}$
 $\Rightarrow (A - \lambda I)\vec{x} = \vec{0}$

So $\vec{x} \neq \vec{0}$ and $\vec{x} \in N(A - \lambda I)$

$\Rightarrow \det(A - \lambda I) = 0$

3) this gives us an algebraic equation
to solve for λ . Then plug back in to find \vec{x} .

ex) Let $T: p^2 \rightarrow p^2$

be given by $T(f(x)) = 2xf'(x) + 3xf''(x)$

Find the eigenvalues and their corresponding eigenvectors for T .

$\vec{e}_i \in \mathcal{E}$	$f'(x)$	$f''(x)$	$T(\vec{e}_i)$
1	0	0	0
x	1	0	$2x$
x^2	$2x$	2	$4x^2 + 6x$

$$1) \quad A = [T]_{\mathcal{E}}^{\mathcal{E}} = \begin{bmatrix} [0]_{\mathcal{E}} & [2x]_{\mathcal{E}} & [4x^2+6x]_{\mathcal{E}} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 2 & 6 \\ 0 & 0 & 4 \end{bmatrix}$$

$$2) \quad \det(A - \lambda I) = \det\left(\begin{bmatrix} 0 & 0 & 0 \\ 0 & 2 & 6 \\ 0 & 0 & 4 \end{bmatrix} - \begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix}\right) = 0$$

$$= \det\begin{pmatrix} -\lambda & 0 & 0 \\ 0 & 2-\lambda & 6 \\ 0 & 0 & 4-\lambda \end{pmatrix} = 0$$

$$= -\lambda(2-\lambda)(4-\lambda) = 0$$

$$\Rightarrow \boxed{\lambda = 0, 2, 4}$$

This is called the characteristic (polynomial) equation.

3) Solve $(A - \lambda I)\vec{x} = \vec{0}$

$$\boxed{\lambda = 0}$$

$$\begin{bmatrix} 0 & 0 & 0 & | & 0 \\ 0 & 2 & 6 & | & 0 \\ 0 & 0 & 4 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 0 & 0 & 0 & | & 0 \\ 0 & 1 & 0 & | & 0 \\ 0 & 0 & 1 & | & 0 \end{bmatrix}$$

$$\begin{cases} x_1 = x_1 \text{ free} \\ x_2 = 0 \\ x_3 = 0 \end{cases}$$

$$\vec{x} \in \text{Span}\left\{\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}\right\} \\ = \text{Span}\{1\}$$

$$\boxed{\lambda = 2}$$

$$\begin{bmatrix} -2 & 0 & 0 & | & 0 \\ 0 & 0 & 6 & | & 0 \\ 0 & 0 & 2 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & 1 & | & 0 \end{bmatrix}$$

$$\begin{cases} x_1 = 0 \\ x_2 = x_2 \\ x_3 = 0 \end{cases}$$

$$\vec{x} \in \text{Span}\left\{\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}\right\} \\ = \text{Span}\{x\}$$

$$\boxed{\lambda = 4}$$

$$\begin{bmatrix} -4 & 0 & 0 & | & 0 \\ 0 & -2 & 6 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & | & 0 \\ 0 & 1 & -3 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

$$\begin{cases} x_1 = 0 \\ x_2 = 3x_3 \\ x_3 = x_3 \end{cases}$$

$$\vec{x} \in \text{Span}\left\{\begin{pmatrix} 0 \\ 3 \\ 1 \end{pmatrix}\right\} \\ = \text{Span}\{3x + x^2\}$$

Note that the eigen vectors are found as spans. Indeed, for each eigen value λ_0 we get a subspace of $\text{dom}(T)$ called the eigenspace E_{λ_0} . We find a basis for E_{λ_0} , so $E_{\lambda_0} = \text{span} \{ \vec{x}_1, \vec{x}_2, \dots, \vec{x}_k \}$.

→ We define the geometric multiplicity of λ_0 as the dimension (number of basis vectors) k of E_{λ_0} .

→ There is also the algebraic multiplicity of λ_0 , which is the power p on the factor $(\lambda_0 - \lambda)^p$ in the characteristic polynomial $\det(A - \lambda I)$.

→ We can prove that for similar matrices A and B , $B = P^{-1}AP$,

the eigenvalues are the same for both.

→ That's true for $[T]_B^B$ and $[T]_C^C$, two

matrices for the same lin. trans. $T: V \rightarrow V$ using two different bases, B and C .

→ T is diagonalizable if there is a basis B such that $[T]_B^B$ is a diagonal matrix (any entry not on the main diagonal is zero).

→ Note that for a diagonal matrix, the eigenvalues are the diagonal entries.

Theorem: For $T: V \rightarrow V$

with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_j,$

the algebraic multiplicity of each λ_i is equal to the corresponding geometric multiplicity of that λ_i , and the sum of those multiplicities totals to n ,

iff T is diagonalizable, that is, there is a basis \mathcal{B} such that $[T]_{\mathcal{B}}^{\mathcal{B}}$ is diagonal.

Moreover, the diagonal entries of $[T]_{\mathcal{B}}^{\mathcal{B}}$ are the eigenvalues of T , with duplicates according to their algebraic multiplicities.

The basis \mathcal{B} is the set of eigenvectors found by listing all the bases of the eigenspaces E_{λ_i} together.

ex) $T(f(x)) = 2xf'(x) + 3xf''(x)$

$\lambda_1 = 0$, alg. mult. = 1 = geom. mult. ✓

$\lambda_2 = 2$, alg. mult. = 1 = geom. mult. ✓

$\lambda_3 = 4$, alg. mult. = 1 = geom. mult. ✓

diagonalizable!

$\mathcal{B} = \{1, x, 3x+x^2\}$, $[T]_{\mathcal{B}}^{\mathcal{B}} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix}$

Note : if $\lambda=0$ is an eigenvalue of T
then $N(T) \neq \vec{0}$, and T is not 1-1;
not onto, and $\det([T]_{\mathcal{B}}^{\mathcal{B}}) = 0$.

ex) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

given by $T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3x + y \\ 3y \end{pmatrix}$

diagonalizable?

$$A = [T]_{\mathcal{E}}^{\mathcal{E}} = \begin{bmatrix} 3(1)+0 & 3(0)+1 \\ 3(0) & 3(1) \end{bmatrix} = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix}$$

$$\det(A - \lambda I) = \det\left(\begin{bmatrix} 3-\lambda & 1 \\ 0 & 3-\lambda \end{bmatrix}\right) = 0$$

$$= (3-\lambda)(3-\lambda) = 0$$

$$= (3-\lambda)^2 = 0$$

$$\boxed{\lambda = 3}$$

power $p=2$

Find eigenspace for $\lambda=3$: Solve $(A - \lambda I)\vec{x} = \vec{0}$.

$$\left[\begin{array}{cc|c} 3-3 & 1 & 0 \\ 0 & 3-3 & 0 \end{array} \right] \sim \left[\begin{array}{cc|c} 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

$$\Rightarrow \begin{cases} x_1 = x, \text{ free} \\ x_2 = 0 \end{cases} \Rightarrow \vec{x} = x_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

That is $E_3 = \text{Span} \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$

one vector in basis

So alg. mult. of $\lambda=3$ is 2

geom mult. of $\lambda=3$ is 1

\Rightarrow Not diagonalizable.