

New terms:  $T: V \rightarrow W$ ,  $\dim V = n$ ,  $\dim W = m$

$$\rightarrow \boxed{\text{rank}(T)} = \text{rank}(A) = \dim(R(T))$$

$$\rightarrow \boxed{\text{nullity}(T)} = \text{nullity}(A) = \dim(N(T))$$

$\rightarrow$  So  $\text{rank}(T) + \text{nullity}(T) = \dim(\text{dom}(T)) = n$   
where  $n$  is also the number of columns of  $A$

$$\begin{aligned} \rightarrow \text{rank}(A) &= \text{number of pivot columns of } A \\ &= \text{number of (lin. indep.) vectors in any basis of } \text{col}(A) = R(T) \end{aligned}$$

$$\begin{aligned} \rightarrow \text{nullity}(A) &= \text{number of free variables in } A\vec{x} = \vec{0} \text{ solution} \\ &= \text{number of (lin. indep.) vectors in any basis of } N(T). \end{aligned}$$

$\rightarrow$  Note: if  $N(T) = \{\vec{0}\}$  it has only one vector in it. The dimension is  $\text{nullity}(T) = 0$ , since  $\{\vec{0}\}$  is not lin. indep.

$$\begin{aligned} \rightarrow N(T) = \{\vec{0}\} &\Leftrightarrow \text{nullity}(T) = 0 \\ &\Leftrightarrow T \text{ is 1-1} \\ &\Leftrightarrow \text{rank}(T) = \dim(\text{dom}(T)) = n \\ &\Leftrightarrow \text{columns of } A \text{ are lin. indep.} \end{aligned}$$

$$\begin{aligned} \rightarrow R(T) = \text{codom}(T) &\Leftrightarrow T \text{ is onto} \\ &\Leftrightarrow \text{rank}(T) = \dim(\text{codom}(T)) = m \\ &\Leftrightarrow \text{rows of } A \text{ are lin. indep.} \end{aligned}$$



Also, if  $T: V \rightarrow V$  is  
 1-1 and onto (bijective) so, an  
 isomorphism, then  $T$  is invertible  
 and  $[T^{-1}]_B^B = A^{-1}$

where  $A = [T]_B^B$ .

So for square matrix  $A$ ,  $n \times n$ :

$$\begin{aligned}
 \det(A) \neq 0 &\Leftrightarrow A \text{ is invertible} \\
 &\Leftrightarrow T \text{ is 1-1} \quad (A = [T]_B^B) \\
 &\Leftrightarrow T \text{ is onto} \\
 &\Leftrightarrow \text{nullity}(T) = 0 \\
 &\Leftrightarrow \text{rank}(T) = n \\
 &\Leftrightarrow \text{rows of } A \text{ lin. indep.} \\
 &\Leftrightarrow \text{columns of } A \text{ lin. indep.} \\
 &\Leftrightarrow R(T) = W \\
 &\Leftrightarrow N(T) = \{0\} \\
 &\Leftrightarrow A\vec{x} = \vec{0} \text{ has one solution } \vec{0} \\
 &\Leftrightarrow T \text{ is an isomorphism}
 \end{aligned}$$

ex)  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  given by  $T(\vec{x}) = 5\vec{x}$ .

$$\begin{aligned}
 A = [T]_{\mathcal{E}}^{\mathcal{E}} &= \left[ \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix}_{\mathcal{E}} \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix}_{\mathcal{E}} \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix}_{\mathcal{E}} \right] \\
 &= \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix} \quad \text{and } \det(A) = 125 \\
 &= 5I \quad \Rightarrow \text{isomorphism}
 \end{aligned}$$



Recall our first example  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$

given by  $T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x+y \\ 2x \\ -y \end{pmatrix}$

Find  $[T]_{\mathcal{E}}^{\mathcal{E}} = A$ , find rank, nullity,  $N(T)$ ,  $R(T)$ .

$$[T]_{\mathcal{E}}^{\mathcal{E}} = \left[ [T\begin{pmatrix} 1 \\ 0 \end{pmatrix}]_{\mathcal{E}} \quad [T\begin{pmatrix} 0 \\ 1 \end{pmatrix}]_{\mathcal{E}} \right]$$

$$= \begin{bmatrix} 1 & 1 \\ 2 & 0 \\ 0 & -2 \end{bmatrix} = A_{3 \times 2} \quad m=3, n=2$$

Notice: this is just the matrix of coeffs  
of the system  $\begin{cases} x+y = - \\ 2x = - \\ -y = - \end{cases}$  no constant yet.

A linear transformation just gives all the  
outputs of a system of linear functions.

r.r.e.f.  $\left[ \begin{array}{cc|c} 1 & 1 & 0 \\ 2 & 0 & 0 \\ 0 & -2 & 0 \end{array} \right] \sim \left[ \begin{array}{cc|c} 1 & 1 & 0 \\ 0 & -2 & 0 \\ 0 & -2 & 0 \end{array} \right]$

$$\sim \left[ \begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 0 \end{array} \right] \sim \left[ \begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

↑ ↑ both pivots

so  $\text{rank}(T) = 2 = n < m = 3$

nullity  $(T) = 0$

$N(T) = \{ \vec{0} \} = \left\{ \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right\}$

$R(T) = \text{span} \left\{ \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ -2 \end{pmatrix} \right\}$

• one solution to  $A\vec{x} = \vec{0}$

•  $T$  is 1-1

•  $T$  is not onto

•  $R(T) \neq \mathbb{R}^3$

• rows are lin. dep.

• columns are lin. indep.



Two square matrices  $A, B$  both  $n \times n$  are similar when there exists a third matrix  $P$  which is square & invertible and

$$B = P^{-1}AP$$

Ex: for a lin. trans.  $T: V \rightarrow V$  and two bases  $B, C$  of  $V$

$$[T]_B^B = [I]_C^B [T]_C^C [I]_B^C$$

matrix rep. using basis  $B$  for input and output.      takes answer in  $C$  and switches to  $B$ .      matrix rep. using  $C$       c. of b., or transition takes input in  $B$  and switches to  $C$

here  $P = [I]_B^C$ ,  $P^{-1} = [I]_C^B$

and similarity means "really the same transformation."

So, similar matrices have all the same:  
rank, nullity, 1-1, onto, eigen values.\*

Also same determinants:  $\det(P^{-1}AP) = \det(A)$ .