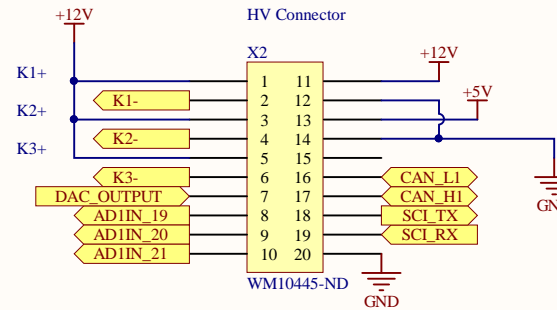
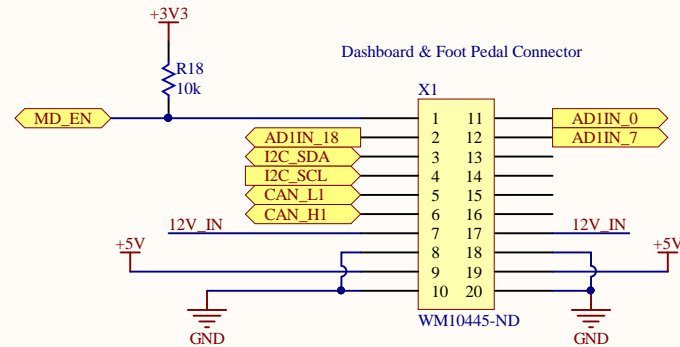
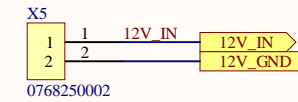


# CONNECTORS



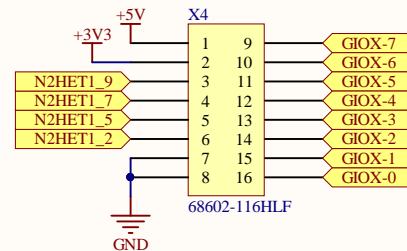
## DESIGN NOTE:

Breaking out rails to power external components (Voltage Transducer, Current Transducer, LCDs, Enable Switches)

GPIO PIN MUX : -----			
PORT A :			
(INPUT)	0 :	MD_EN	
(INPUT)	1 :	MD_RUN	
(OUTPUT)	2 :	MTR_EN	
(OUTPUT)	5 :	(Pre_Charge)	
(OUTPUT)	6 :	(High_Voltage)	
(OUTPUT)	7 :	(Ground)	
PORT B :			
(INPUT)	0 :	Limit Switch	
(INPUT)	1 :	S_BMS	
(INPUT)	2 :		
(INPUT)	3 :		
ADC : -----			
ADC 1 Group 1 :			
PIN 0 : Throttle Input from Foot Pedal			
PIN 7 : Voltage Transducer Analog Signal			
PIN 18: Current Transducer Low Signal			
PIN 19: Current Transducer High Signal			
PIN 20:			

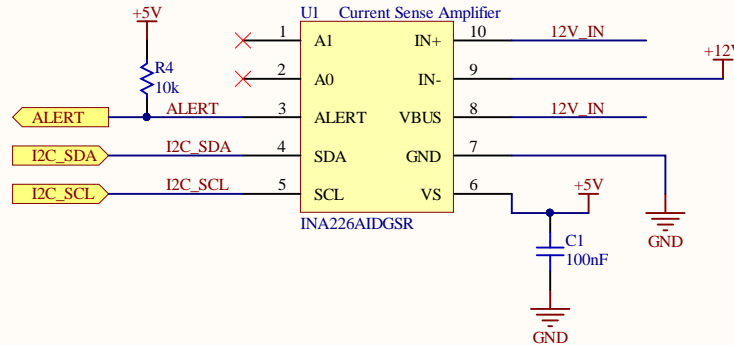
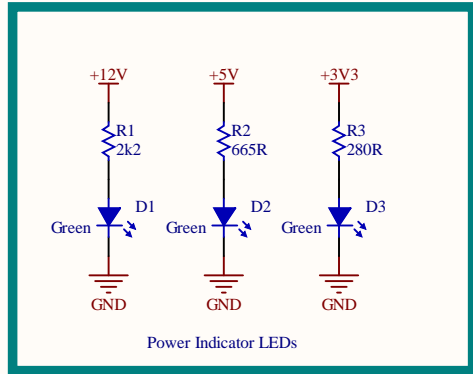
## Extra Broken Out Signals

Add more analog inputs here



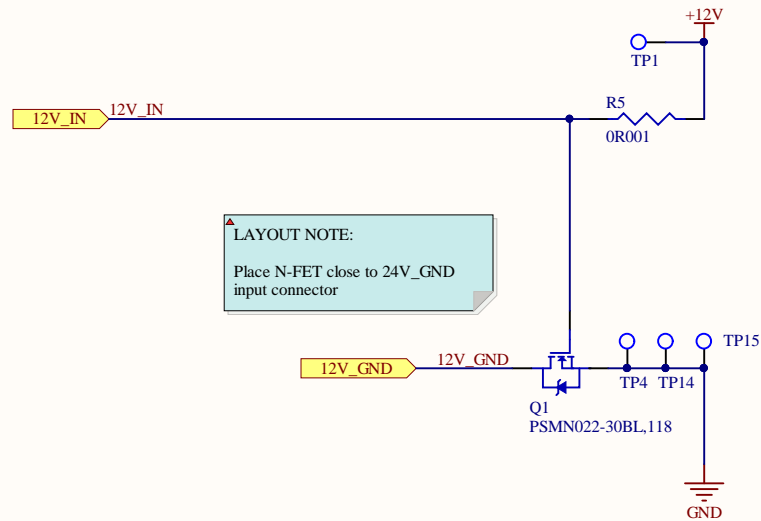
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# POWER & CURRENT SENSING



**LAYOUT NOTE:**  
Place sensing wires (IN+, IN-) in a Kelvin connection to the shunt resistor  
Route sensing wires as a differential pair

**DESIGN NOTE:**  
Add overvoltage protection on 5V, 3.3, and 1.2



**LAYOUT NOTE:**  
Place N-FET close to 24V\_GND input connector

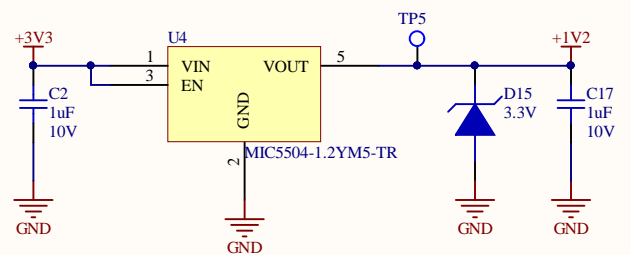
**DESIGN NOTE:**  
N-FET placed for reverse polarity protection. Will conduct at correct 24V input polarity, will not conduct when polarity reversed.

**LAYOUT NOTE:**  
Place output filter (inductor and capacitor) close to output of 3V3 DCDC

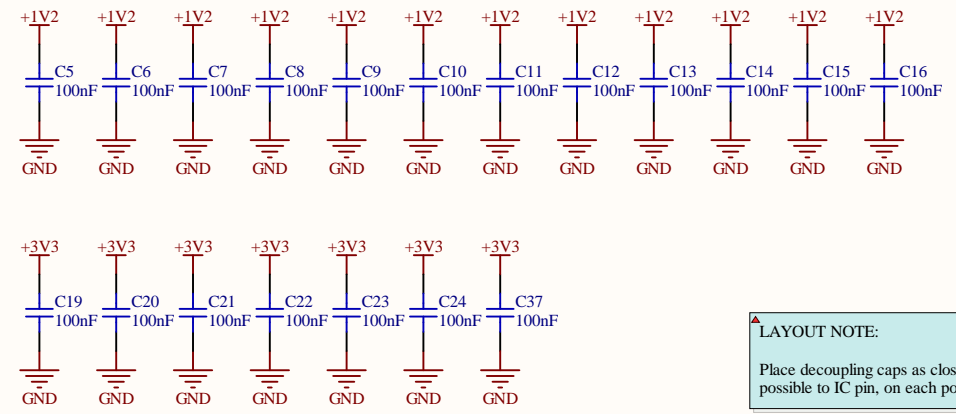
**DESIGN NOTE:**  
Output resistor for minimum load requirement. DCDC needs min. 10% load otherwise voltage output isn't 3.3V

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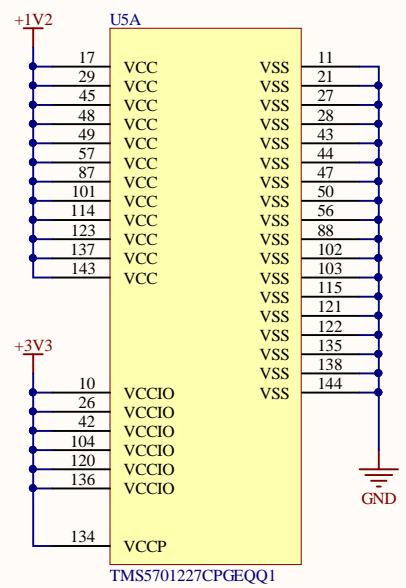
# TMS570 POWER



**DESIGN NOTE:**  
Decoupling capacitors help reduce the transients seen by the MCU on the power input pins



**LAYOUT NOTE:**  
Place decoupling caps as close as possible to IC pin, on each power



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## 1

Overvoltage protection in case foot pedal pot shorts to 24V

Place decoupling caps as close as possible to IC pin

2

AD1IN_0	AD1IN_0	6
AD1IN_7	AD1IN_7	6
AD1IN_18	AD1IN_18	6
AD1IN_19	AD1IN_19	6
AD1IN_20	AD1IN_20	6
AD1IN_21	AD1IN_21	6

AD1IN[16]/AD2IN[0]
AD1IN[17]/AD2IN[1]
AD1IN[0]
AD1IN[7]
AD1IN[18]/AD2IN[2]
AD1IN[19]/AD2IN[3]
AD1IN[20]/AD2IN[4]
AD1IN[21]/AD2IN[5]

4	MIBSPI3NCS[2]/I2C_SDA/N2HET1[27]/NTZ2
3	MIBSPI3NCS[3]/I2C_SCL/N2HET1[29]/NTZ1

MIBSP11SOMI[0]	
MIBSP11SIMO[0]	MIBSP13SIMO[0]
MIBSP11CLK	MIBSP13CLK
MIBSP11NCS[0]/MIBSP11SOMI[1]	MIBSP13SOMI[0]
MIBSP11NCS[1]/N2HET1[17]	MIBSP13NCS[0]
MIBSP11NCS[2]/N2HET1[19]	MIBSP13NCS[1]

4

30	N2HET1_2	N2HET1_2
31	N2HET1_5	N2HET1_5
33	N2HET1_7	N2HET1_7
35	N2HET1_9	N2HET1_9
36		

IOB[2] is only capable of input, it is meant to read interrupts from the system

**8-GPIO EXPANDER**

The diagram shows the following components and connections:

- Power Supply:** A 5V supply is connected to the expander's VDD pin (A0) through a 40Ω resistor (R40). A 100nF capacitor (C59) is connected between the 5V supply and ground. A 3V3 supply is connected to the expander's VSS pin (P4) through a 10kΩ resistor (R41).
- IO Power:** The IO\_POWER pin (1) is connected to the 5V supply. The IO\_RST pin (3) is connected to the 3V3 supply through a 10kΩ resistor (R42).
- GPIO Pins:** The 8 GPIO pins (GIOX-0 to GIOX-7) are connected to the expander's A0-P4 pins. The expander is labeled U8 and PCA9538APWJ.
- I2C Pins:** The expander's I2C pins (SDA, SCL, DRDY) are connected to the Raspberry Pi's I2C pins. The expander's I2C pins are labeled 15 (I2C SDA), 14 (I2C SCL), and 13 (IO\_DRDY).

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Place output filter cap near connector

Unstuffing the 0 ohm resistors can also allow for current to be measured using a DMM

0 ohm resistors allow IC's to be unpowered and unused if needed. (i.e. don't need them or they draw too much power)  
They also provide a footprint for a resistor, in case an RC filter is needed

1

2

3

4

1

2

3

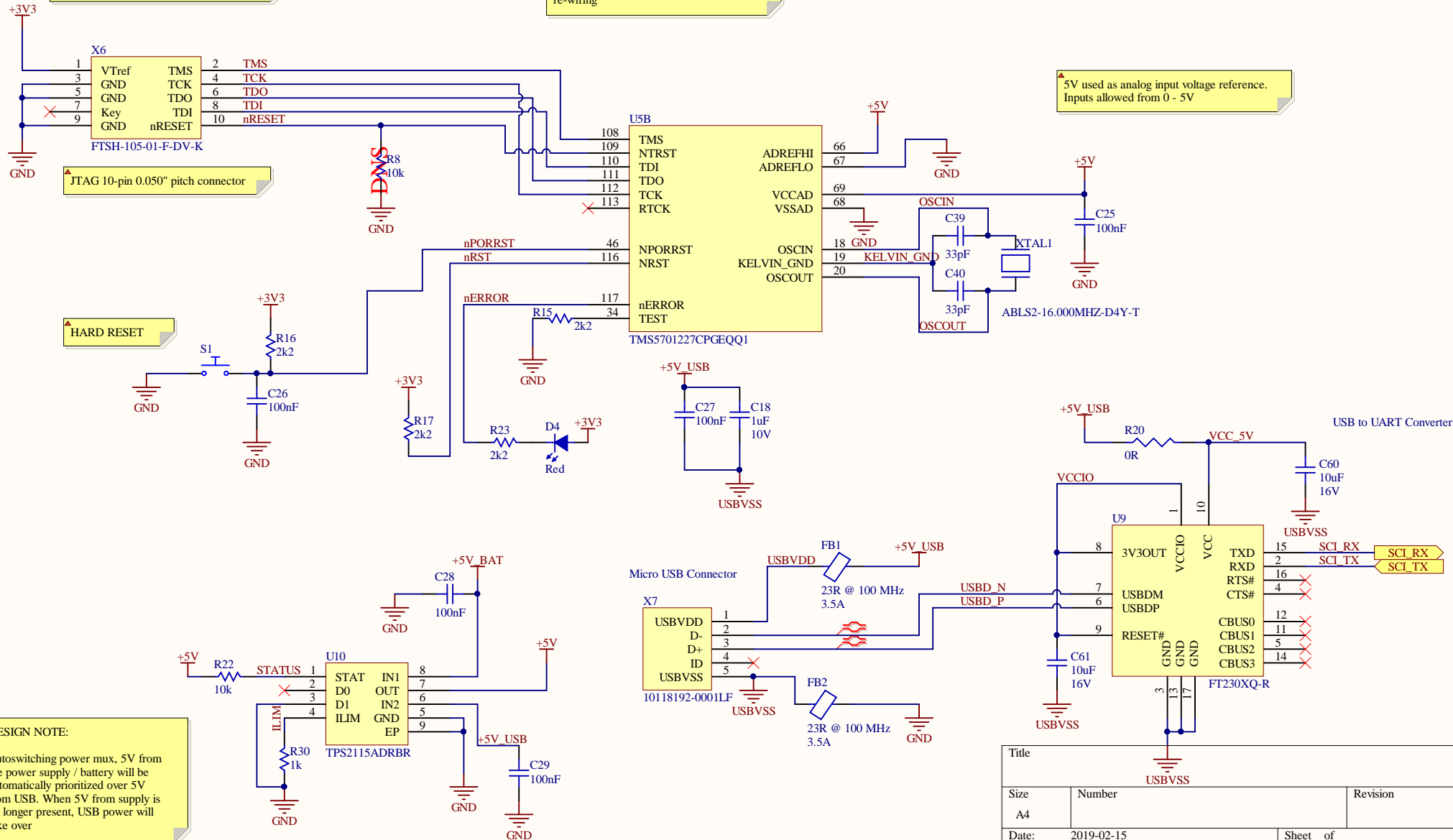
4

## DESIGN NOTE:

JTAG connection allows programming & debugging the MCU, which needs external power to turn on

## DESIGN NOTE:

0 ohm resistors and unstuffed resistors allow for pull-ups/downs if needed or re-wiring



## DESIGN NOTE:

Autoswitching power mux, 5V from the power supply / battery will be automatically prioritized over 5V from USB. When 5V from supply is no longer present, USB power will take over

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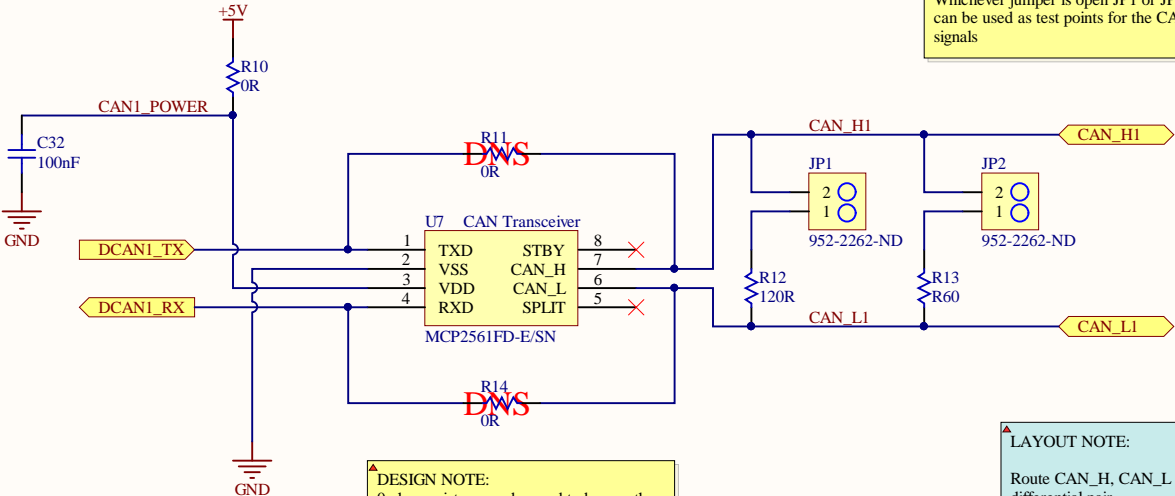
1

2

3

4

# CAN TRANSCEIVER



DESIGN NOTE:

Whichever jumper is open JP1 or JP2, can be used as test points for the CAN signals

DESIGN NOTE:

0 ohm resistors allow IC's to be unpowered and unused if needed. (i.e. don't need them or they draw too much power)

### LAYOUT NOTE

Place decoupling caps as close as possible to IC pin

DESIGN NOTE:

0 ohm resistors can be used to bypass the CAN transceivers if needed. (i.e. using external CAN transceivers). Depopulated by default

**LAYOUT NOTE:**

Route CAN\_H, CAN\_L signals as differential pair

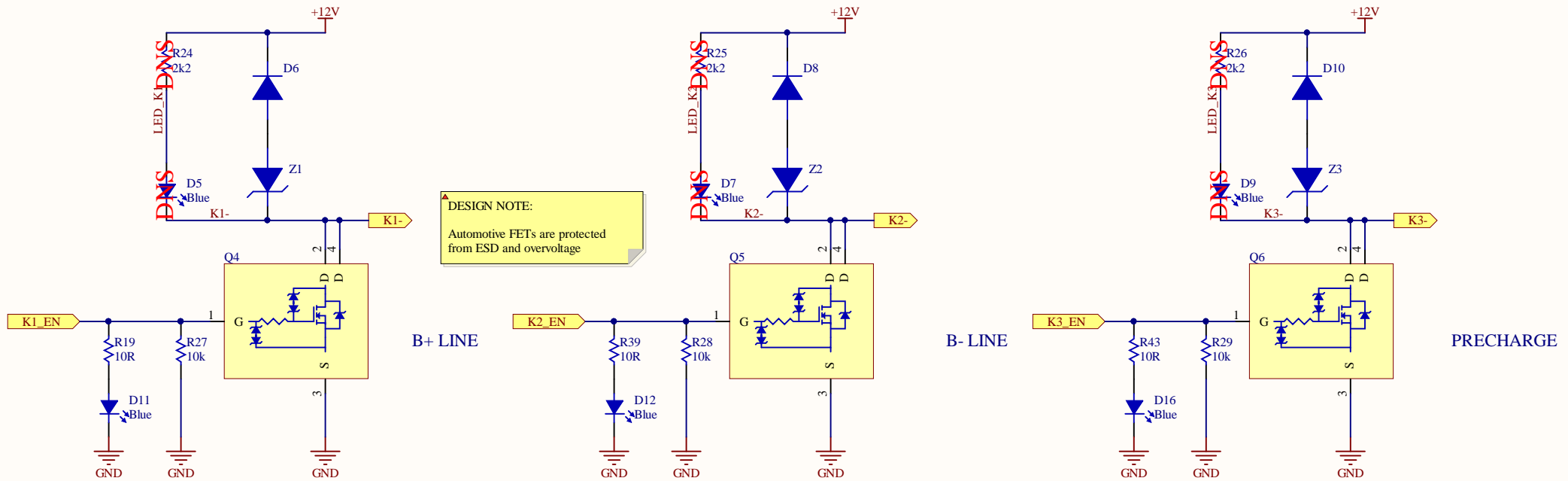
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# LOW SIDE CONTACTOR SWITCHING

DESIGN NOTE:  
Diode-Zener snubber acts as a good way to dissipate inductive voltage kicks when the contactor opens

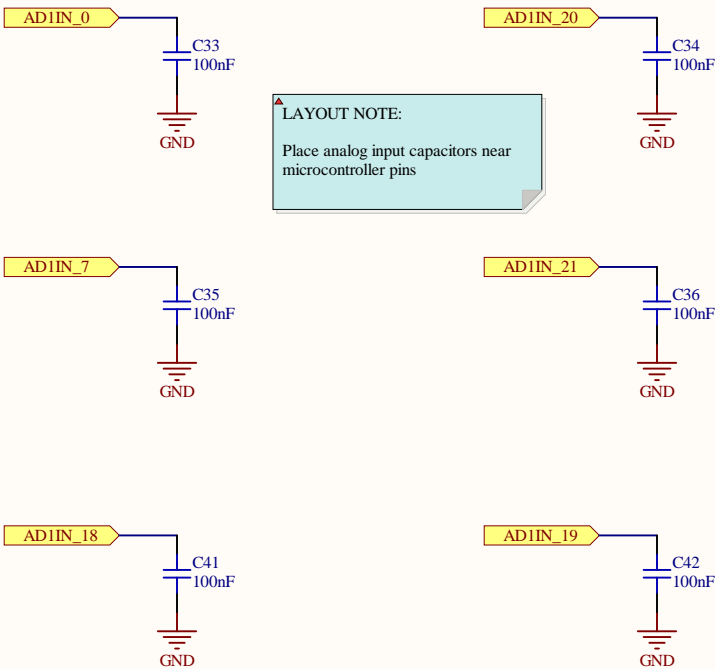
DESIGN NOTE:  
These low-side switches go out to the rest of the shutdown circuit. The snubber circuit and LED remain for backwards compatibility with the go kart, where the contactors connect directly to the VCU.

DESIGN NOTE:  
Automotive FETs are protected from ESD and overvoltage



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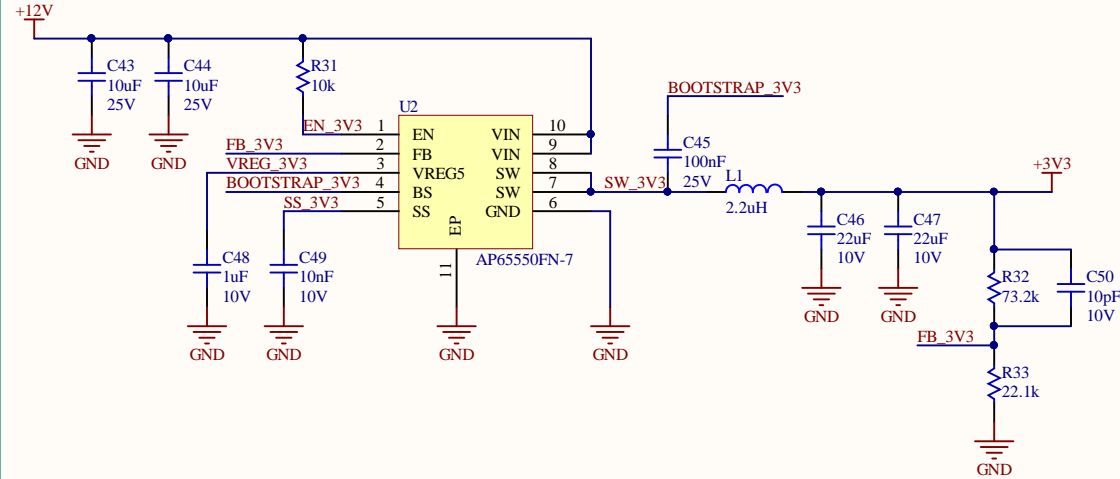
# ADC DECOUPLING



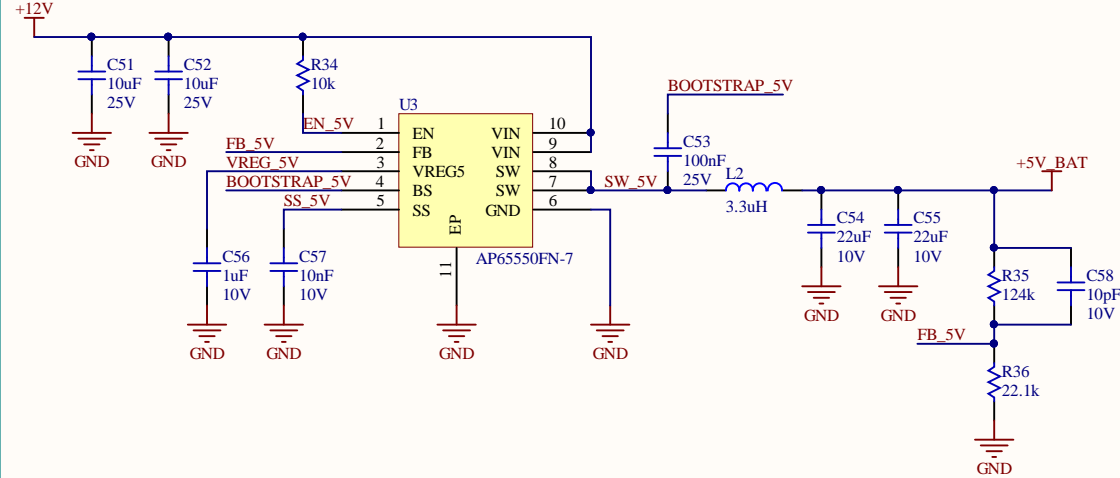
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File:	C:\Users\...\ADC_Decoupling.SchDoc	Drawn By:



### 3V3 5A BUCK REGULATOR



### 5V 5A BUCK REGULATOR



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