

# PHYS2350: Forces

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# Quick Review:

## What is a force?

- A push or a pull (it is a *vector*)
- An *interaction* between *two things*

Force notation:

$$\vec{F}_{A,B}^{(\text{type})}$$

Only these forces make up the *net force* used in Newton's 2<sup>nd</sup> Law

Common “forces” that will never appear on a free-body diagram

- Centripetal Force:  $ma_{\perp}$
- Tangential Force:  $ma_{\parallel}$
- Centrifugal Force
- Tidal Force
- Coriolis Force

All of these are either ways of characterizing the **net force** or forces that are a result of being in a **non-inertial/accelerating reference frame**.

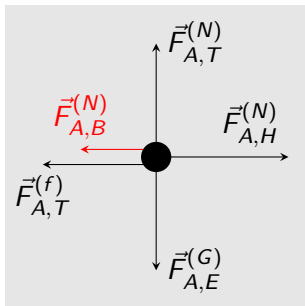
# Part I. Constant speed

## Newton's 2<sup>nd</sup> law

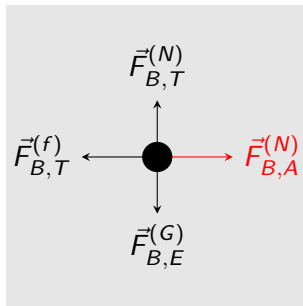
$$\vec{F}_{\text{net,system}} = m_{\text{system}} \vec{a}_{\text{system}}$$

If we have constant speed, and 1D motion, what is the acceleration?

System A

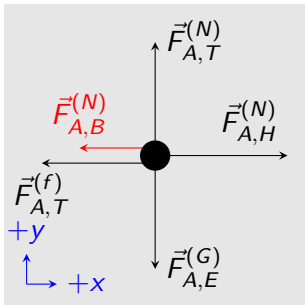


System B

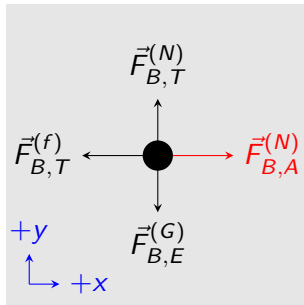


# Part I. Constant speed

System A



System B



Break into components . . . . . Considering magnitudes only

$$\begin{aligned} F_{A,H}^{(N)} - F_{A,B}^{(N)} - F_{A,T}^{(f)} &= 0 \\ F_{A,T}^{(N)} - F_{A,E}^{(G)} &= 0 \end{aligned}$$

$$\begin{aligned} F_{B,A}^{(N)} - F_{B,T}^{(f)} &= 0 \\ F_{B,T}^{(N)} - F_{B,E}^{(G)} &= 0 \end{aligned}$$

## Part I. Vertical forces, calculating weight

For the vertical forces, we have:

$$F_{A,T}^{(N)} = F_{A,E}^{(G)} \quad F_{B,T}^{(N)} = F_{B,E}^{(G)}$$

### Calculating weight on Earth

Suppose you have an object with a mass  $m = 7.0$  kg. We can calculate the weight (on Earth) by multiplying the mass of the object by the acceleration due to gravity  $g = 9.81 \text{ m/s}^2 \approx 10 \text{ m/s}^2$ . So the weight is:

$$F_{m,E}^{(G)} = mg = 7.0 \text{ kg} \times 10 \text{ m/s}^2 = 70 \text{ N}$$

You should be able to numerically determine all of the vertical force magnitudes given the information in part I.F.

## Part I. Horizontal forces, calculating friction

For the vertical forces, we have:

$$F_{A,H}^{(N)} = F_{A,B}^{(N)} + F_{A,T}^{(f)} \quad F_{B,A}^{(N)} = F_{B,T}^{(f)}$$

### Calculating kinetic friction

Remember, that friction is a contact force, and (when we deem it important) it will always correspond to a normal force between the same two interacting objects. It will depend on the coefficient of kinetic friction  $\mu_k$  (just a number, no units) and that normal force. So if a box is sliding along a table that has a normal force  $F_{B,T}^{(N)} = 20 \text{ N}$  and the coefficient of static friction between the box and table is  $\mu_k = 0.2$ , the frictional force has a magnitude:

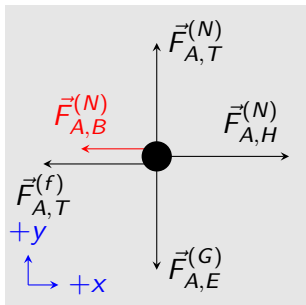
$$F_{B,T}^{(f)} = \mu_k F_{B,T}^{(N)} = 0.2 \times 20 \text{ N} = 4 \text{ N}$$

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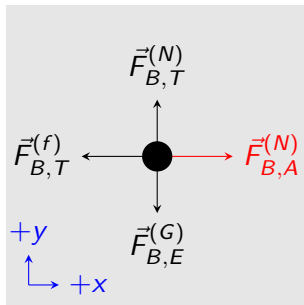
## Part II. Varying speed

Same as Part I, except  $\mu_k$  decreases. What forces change, and how?

System A



System B

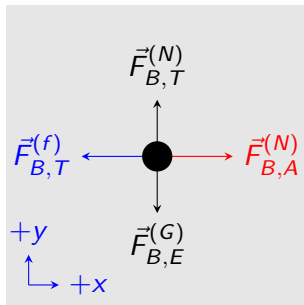
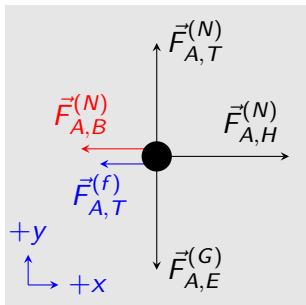


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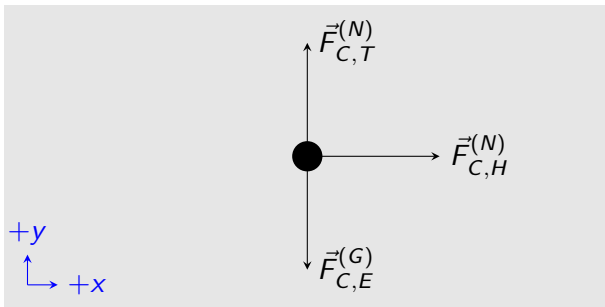


Only the **frictional forces** should decrease



## Part III. Dealing with systems

Same as Part II, acceleration is constant and *to the right*  
System C



Corresponding forces:

$$\vec{F}_{C,T}^{(N)} = \vec{F}_{A,T}^{(N)} + \vec{F}_{B,T}^{(N)}$$

$$\vec{F}_{C,T}^{(f)} = \vec{F}_{A,T}^{(f)} + \vec{F}_{B,T}^{(f)}$$

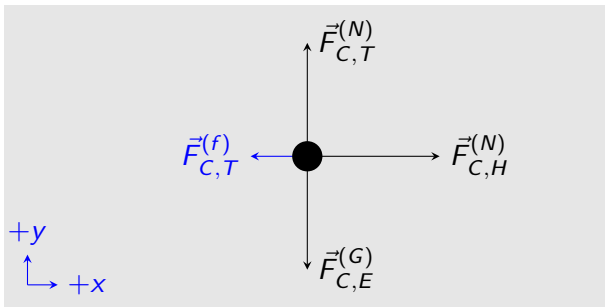
$$\vec{F}_{C,E}^{(G)} = \vec{F}_{A,E}^{(G)} + \vec{F}_{B,E}^{(G)}$$

Missing Forces:

- $\vec{F}_{A,B}^{(N)}$
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- These are *internal* to the system

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