#### ein physikalisches Multi-Agenten-System zur Modellierung interaktiver Aktive Brownsche Teilchen: Strukturbildung

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#### Gliederung

- 1. Multi-Agenten-Systeme
- 2. Modell Aktiver Brownscher Teilchen
- 3. Aktive Brownsche Teilchen mit Energiedepot
- 4. Strukturbildung mit Aktiven Brownschen Teilchen (1) Biologische Aggregation
- (2) Simulation von Wegenetzen von Ameisen

5. Zusammenfassung

### Complex Systems

 $computer\ simulations."$ nonlinear models, out-of equilibrium descriptions and requires the development, or the use of, new scientific tools, entities, processes, or agents, the understanding of which  $(usually\ large)\ number\ of\ (usually\ strongly)\ interacting$ "By complex system, it is meant a system comprised of a

Journal "Advances in Complex Systems"

the behavior of the components. components whose behavior cannot be simply inferred from "Complex systems are systems with multiple interacting

ecosystems, and human social and economic structures." including biological macromolecules, biological organisms, fields to the universe. Among the most complex systems with The study of complex systems spans all scales, from particle which we are familiar are biological and social systems –

New England Complex Systems Institute

# Multi-Agent Systems (MAS)

#### agent:

- subunit with "intermediate" complexity
- ⇒ may represent local processes, individuals, species agglomerates, components, ...

### multi-agent system:

- ullet large number / different types of agents
- interactions between agents:

- on different spatial and temporal scales
   local / direct interaction
   global / indirect interactions (coupling via resources)
- $\Rightarrow$  self-organization, *emergence* of system properties "bottom-up approach": no universal equations
- external influences (boundary conditions, in/outflux)
- ⇒ coevolution, circular causality

### minimalistic agent:

- $\bullet$  possibly simplest set of rules  $\Rightarrow$  "sufficient" complexity
- no deliberative actions, no specialization, no internal memory
- cooperative interaction instead of autonomous action

## Active Brownian Particles

signal-response behavior." and to convert internal energy to perform different activities, such as metabolism, motion, change of the environment, or energy from the environment, to store it in an internal depot internal degrees of freedom. They have the ability to take up "Active Brownian particles are Brownian particles with

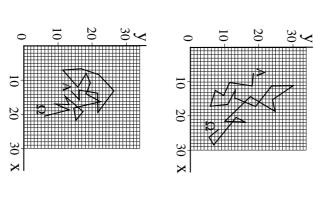
# internal degrees of freedom:

- 1. internal energy depot:  $e_i(t)$
- take-up, storage, conversion of internal energy
- $\rightarrow$ pumped Brownian particles, Brownian motors
- 2. discrete internal states:  $\theta_i(t)$
- generation of different components of a self-consistent field
- sensitivity to different field components
- $\rightarrow$  non-linear feedback  $\Rightarrow$  interactive structure formation on the macroscopic level

#### advantages:

- particle-based approach to structure formation
- complete stochastic dynamics, based on Langevin equations
- consideration of energetic aspects
- interaction between particles via multicomponent field
- $\bullet$  external eigendynamics of the field

# Observation of Brownian Motion



The position of the Brownian particle (radius 0.4  $\mu m)$  is documented on a millimeter grid in time intervals  $t_0=30$  seconds.

# **Equations for Brownian Particles**

 $\bullet$  stochastic approach  $\Rightarrow$  Langevin equation:

$$\frac{d\mathbf{r}_i}{dt} = \mathbf{v}_i$$
 ;  $m\frac{d\mathbf{v}_i}{dt} = -\gamma_0 \mathbf{v}_i + \mathcal{F}^{stoch}$ 

 $\gamma_0$ : friction coefficient of motion

 $\mathcal{F}^{stoch}$ : stochastic force

$$\langle \mathcal{F}^{stoch}(t) \rangle = 0$$
;  $\langle \mathcal{F}^{stoch}(t) \mathcal{F}^{stoch}(t') \rangle = 2S \, \delta(t - t')$ 

fluctuation-dissipation theorem:  $S = k_B T \gamma_0$ 

rdamped limit: 
$$d{m v}_i/dt=0$$
, or  $\gamma_0 o \infty$   $d{m r}_i ext{ } \frac{k_B T}{2} ext{ } arepsilon$ 

• overdamped limit:  $d\mathbf{v}_i/dt = 0$ , or  $\gamma_0 \to \infty$ 

$$\frac{d \boldsymbol{r}_i}{dt} = \sqrt{2 \, D_n} \, \boldsymbol{\xi}(t) \; \; ; \; D_n = \frac{k_B T}{\gamma_0} = \frac{\varepsilon}{\gamma_0}$$

 $D_n$ : spatial diffusion coefficient of the particles

$$\boldsymbol{\xi}(t)$$
: white noise,  $\left\langle \boldsymbol{\xi}_{i}(t) \, \boldsymbol{\xi}_{j}(t') \right\rangle = \delta_{ij} \, \delta(t-t')$ .

# Brownian Particle with Internal Energy Depot

Depot  $e(t) \Rightarrow$  internal storage of energy

$$\frac{d}{dt}e(t) = q(\boldsymbol{r}) - c\; e(t) - d(\boldsymbol{v})\; e(t)$$

 $q(\mathbf{r})$ :  $gain \Rightarrow$  space-dependent take-up of energy

 $c: loss \Rightarrow internal dissipation$ 

 $d(\mathbf{v})$ : conversion of internal into kinetic energy simple ansatz:  $d(\mathbf{v}) = d_2 v^2$ ;  $d_2 > 0$ 

Stochastic equation for Brownian particles with energy depot

$$m\dot{\boldsymbol{v}} + \gamma_0 \boldsymbol{v} + \nabla U(\boldsymbol{r}) = d_2 e(t) \boldsymbol{v} + \mathcal{F}(t)$$

# Non-linear Friction Function

equations of motion:

$$\dot{\boldsymbol{v}} + \gamma_0 \boldsymbol{v} + \nabla U(\boldsymbol{r}) = d_2 e(t) \boldsymbol{v} + \mathcal{F}(t)$$

$$\frac{d}{dt} e(t) = q(\boldsymbol{r}) - c e(t) - d(\boldsymbol{v}) e(t)$$

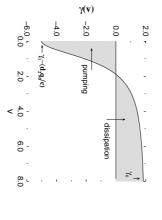
$$\gamma(\boldsymbol{v}) = \gamma_0 - d_2 e(t)$$

assumptions: 
$$q(\mathbf{r}) \equiv q_0$$
;  $d(\mathbf{v}) = d_2 v^2$ ;  $\dot{e}(t) = 0$ 

$$e_0 = \frac{q_0}{c + d_2 v^2}$$

$$\gamma(v) = \gamma_0 - \frac{q_0 d_2}{c + d_2 v^2}$$
 zero:  $v_0^2 = \frac{q_0}{\gamma_0} - \frac{c}{d_2}$ 

 $\Downarrow$ 

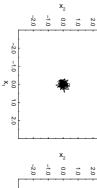


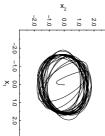
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## Critical Supply of Energy

assumption: motion in two dimensions

$$q(x_1, x_2) = q_0$$
  $U(x_1, x_2) = \frac{a}{2}(x_1^2 + x_2^2)$ 





 $q_0 = 1.0$ : motion on a stochastic limit cycle  $q_0 = 0.0$ : simple Brownian motion;

# Brownian particle as micro-motor:

efficiency ratio:

$$\sigma = \frac{dE_{out}/dt}{dE_{in}/dt} = \frac{d_2 e v^2}{q_0}$$

- $\bullet$ energy depot in quasi-stationary equilibrium:  $e = \frac{q_0}{c + d_2 v^2}$
- ullet v approximated by the stationary velocity:

$$v_0^2 = \left(v_1^2 + v_2^2\right) = \frac{q_0}{\gamma_0} - \frac{c}{d_2}$$

$$\sigma = 1 - \frac{c \gamma_0}{d_2 q_0} \qquad \sigma > 0 \quad \text{onl}$$

 $\Downarrow$ 

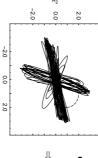
$$\sigma > 0$$
 only if:  $q_0 > q_0^{crit} = \frac{\gamma_0 c}{d_2}$ 

#### Slide 9

## Localized Energy Sources

- parabolic potential:  $U(x_1,x_2) = \frac{a}{2}(x_1^2 + x_2^2)$  take-up of energy in a restricted area:

$$q(x_1, x_2) = \begin{cases} q_0 & \text{if } [(x_1 - b_1)^2 + (x_2 - b_2)^2] \le R^2 \\ 0 & \text{else} \end{cases}$$



- $\Rightarrow$  oscillatory movement motion into the energy area becomes accelerated
- 2.0 with fixed direction
- intermittent type of motion
- new cycles start with a burst of energy

X<sub>2</sub>

4.0 3.0 2.0

• increase in  $d_2$  abridges to become Brownian the cycle  $\Rightarrow$  directed motion more susceptible

100

300

motion

# Active Brownian Particles Responding to a Field

### active particles:

- characterized by an internal degree of freedom:  $\theta_i(t)$ , which can be changed:  $w(\theta_i'|\theta_i)$
- Langevin equation:

$$\frac{d\mathbf{r}_{i}}{dt} = \mathbf{v}_{i} ; \frac{d\mathbf{v}_{i}}{dt} = -\gamma \mathbf{v}_{i} + \alpha_{i} \frac{\partial h^{\varepsilon}(\mathbf{r}, t)}{\partial \mathbf{r}} \Big|_{\mathbf{r}_{i}} + \sqrt{2 \varepsilon_{i} \gamma} \, \boldsymbol{\xi}_{i}(t)$$

overdamped limit:

$$\frac{d\mathbf{r}_{i}}{dt} = \frac{\alpha_{i}}{\gamma} \frac{\partial h^{e}(\mathbf{r}, t)}{\partial \mathbf{r}} \Big|_{\mathbf{r}_{i}} + \sqrt{\frac{2\varepsilon_{i}}{\gamma}} \boldsymbol{\xi}_{i}(t)$$

 $\bullet$  "individual" parameters (may depend on  $\theta_i)$  :  $h^e(\boldsymbol{r},t)$ : effective field

 $\alpha_i$ : individual response to the field

– attraction:  $\alpha_i > 0$ , or repulsion:  $\alpha_i < 0$ 

- threshold  $h_0$ :  $\alpha_i = \Theta[h^e(\mathbf{r}, t) - h_0], \, \Theta[y] = 1$ , if y > 0

– internal value  $\theta$ :  $\alpha_i = \delta(\theta_i - \theta)$ 

 $\varepsilon_i$ : individual intensity of noise

- measure of the sensitivity  $s_i$  of the particle:  $s_i \propto 1/\varepsilon_i$ .

### Effective Field

- $\bullet$  Langevin eq.: particles respond to the gradient of  $h^e(\boldsymbol{r},t)$
- effective field: a specific function of the different field components  $h_{\theta}(\mathbf{r}, t)$ :

$$oldsymbol{
abla} h^e(oldsymbol{r},t) = oldsymbol{
abla} h^e(\ldots,h_{ heta}(oldsymbol{r},t),h_{ heta'}(oldsymbol{r},t),\ldots)$$

 $\bullet$  particles with internal parameter  $\theta$  generate a field  $h_{\theta}(\boldsymbol{r},t)$ which obeys a reaction-diffusion equation:

$$\begin{split} \frac{dh_{\theta}(\boldsymbol{r},t)}{dt} &= -k_{\theta} \, h_{\theta}(\boldsymbol{r},t) + D_{\theta} \, \boldsymbol{\Delta} h_{\theta}(\boldsymbol{r},t) \\ &+ \sum\limits_{i=1}^{N} q_{i}(\theta_{i},t) \, \delta(\theta - \theta_{i}(t)) \, \delta(\boldsymbol{r} - \boldsymbol{r}_{i}(t)) \end{split}$$

spatio-temporal evolution of the field,  $h_{\theta}(\boldsymbol{r},t)$ :

- (i) decay with rate  $k_{\theta}$
- (ii) diffusion (coefficient  $D_{\theta}$ )
- (iii) production with individual rate  $q_i(\theta_i, t)$

# Complete Dynamics for N Active Particles

 $\bullet$  N active Brownian particles:

canonical N-particle distribution function: internal parameters  $\theta_1, ..., \theta_N$ ; positions  $\boldsymbol{r}_1, ...., \boldsymbol{r}_N$ 

$$P(\underline{r}, \underline{\theta}, t) = P(\boldsymbol{r}_1, \theta_1, \dots, \boldsymbol{r}_N, \theta_N, t)$$

(i) movement:  $r_i \to r_i'$ (ii) transition:  $\theta_i \to \theta_i'$  with probability  $w(\theta_i'|\theta_i)$ 

• multivariate master equation:

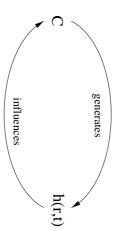
limit of strong damping:  $\gamma_0 \to \infty$ , and  $\alpha_i = \alpha$ ,  $\varepsilon_i = \varepsilon$ :

 $\frac{\partial}{\partial t}P(\underline{r},\underline{\theta},t) \; = \; -\sum_{i=1}^{N} \left\{ \boldsymbol{\nabla}_{i} \; \left( (\alpha/\gamma_{0}) \, \boldsymbol{\nabla}_{i}h^{e}(\boldsymbol{r},t) \, P(\underline{\theta},\underline{r},t) \right) \right.$  $-D_n \Delta_i P(\underline{r},\underline{\theta},t) \}$ 

 $+ \sum_{i=1}^{N} \sum_{\theta_i' \neq \theta_i} \left\{ w(\theta_i | \theta_i') P(\theta_i', \underline{\theta}^{\star}, \underline{r}, t) \right\}$  $-w(\theta_i'|\theta_i)P(\theta_i,\underline{\theta}^{\star},\underline{r},t)\}$ 

ullet dynamics of the effective field  $h^e({m r},t)$ 

# **Examples of Circular Causation**



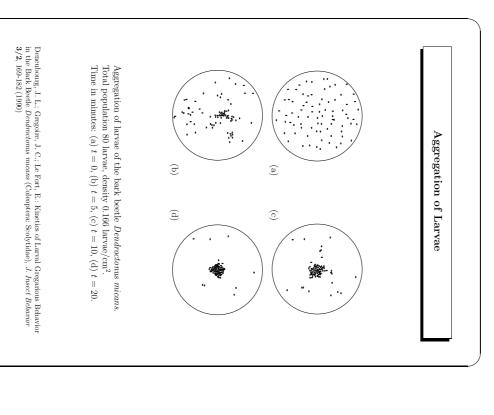
- $\bullet$  active particles are identical  $\Rightarrow$  no transitions  $\alpha_i = \alpha > 0, \ \varepsilon_i = \varepsilon, \ \theta_i = 0, \ q_i(\theta_i, t) = q_0 = \text{const.}$
- one-component field:

$$egin{aligned} oldsymbol{
abla}_i h^e(oldsymbol{r},t) &= oldsymbol{
abla}_i h(oldsymbol{r},t) \\ rac{dh(oldsymbol{r},t)}{dt} &= -k_0 \, h(oldsymbol{r},t) + D_0 \, oldsymbol{\Delta} h_{ heta}(oldsymbol{r},t) + q_0 \, \sum\limits_{i=1}^N \, \delta(oldsymbol{r} - oldsymbol{r}_i(t)) \end{aligned}$$

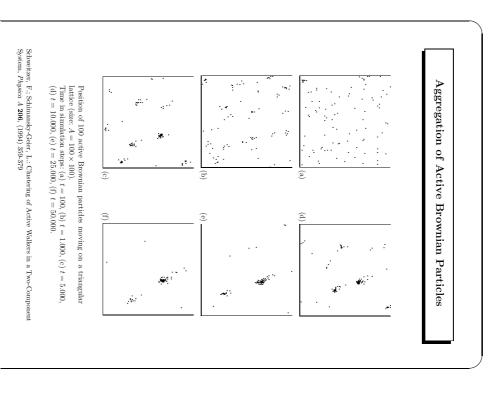
### applications:

- biological aggregation:
- cells, slime mold amoebae, myxobacteria generate a chemical field to communicate
- track formation:

by other individuals (ususally  $D_0 = 0$ ) bacteria, pedestrians mark their track, which can be reinforced

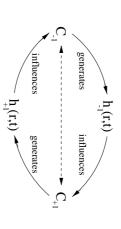


Slide 15



# Evolution of the Self-Consistent Field (a) (d) (e) (e) (f) (e) (f) (e) t = 1.000, (fight side) Competition regime: (a) t = 10, (b) t = 5.000, (fight side) Competition regime: (d) t = 1.000, (e) t = 5.000, (f) t = 5.000, (The same as Fig. (c).

# **Examples of Circular Causation**



- $\bullet$  active particles with two different states  $\theta \in \{-1,+1\},$  transitions possible
- $\bullet$  state dependent production rate

$$q_i(\theta_i,t) = \frac{\theta_i}{2}[(1+\theta_i)\,q_i(+1,t)\,-\,(1-\theta_i)\,q_i(-1,t)\!-\!1]$$

• two-component field

$$\begin{split} \boldsymbol{\nabla}_{i}h^{e}(\boldsymbol{r},t) \; &= \; \frac{\theta_{i}}{2}[(1+\theta_{i})\,\boldsymbol{\nabla}_{i}h_{-1}(\boldsymbol{r},t) \; - \; (1-\theta_{i})\,\boldsymbol{\nabla}_{i}h_{+1}(\boldsymbol{r},t)] \\ \frac{dh_{\theta}(\boldsymbol{r},t)}{dt} \; &= \; -k_{\theta}\,h_{\theta}(\boldsymbol{r},t) + \sum_{i=1}^{N}q_{i}(\theta_{i},t)\,\delta(\theta-\theta_{i}(t))\,\delta(\boldsymbol{r}-\boldsymbol{r}_{i}(t)) \end{split}$$

### applications:

- exploitation of food sources:
- ants mark trails from food sources to the nest with additional chemicals to guide nestmates to resources
- self-assembling of networks:
- particles responding to two different fields, link nodes with opposite potential

Schweitzer, F.; Schimansky-Geier, L.: Clustering of Active Walkers in a Two-Component System, *Physica A* **206**, (1994) 359-379

# Foraging Route of Ants (Pheidole milicida) Branches Branches

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Slide 19

Hölldobler, B. and Möglich, M.: The foraging system of Pheidole militicida (Hymenoptera: Formicidae), Insectes Sociaux 27/3 (1980) 237-264

Schematic representation of the complete foraging route of *Phei-dole milicida*, a harvesting ant of the southwestern U.S. deserts. Each day tens of thousands of workers move out to the dendritic trail system, disperse singly, and forage for food.

Schweitzer, F.; Lao, K.; Family, F.: Active Random Walkers Simulate Trunk Trail Formation by Ants, BioSystems 41 (1997) 153-166

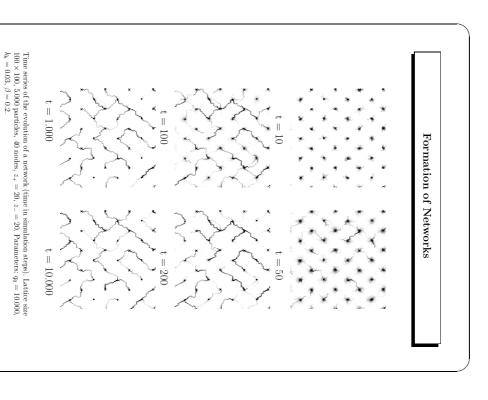
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Schweitzer, F.; Lao, K.; Family, F.: Active Random Walkers Simulate Trunk Trail Formation by Ants,  $BioSystems~\bf 41~(1997)~153-166$ 

Slide 21

Slide 22

time steps, respectively.



#### Conclusions

- 1. Model of Active Brownian Particles:
- particle-based model for interactive structure formation
- relation to biology:
- (a) energy consumption for metabolism and motion
- (b) interaction with the environment due to a self-consistent multicomponent field  $\Rightarrow$  non-linear feedback
- 2. Conversion of Brownian Motion into Directed Motion:
- (a) quasiperiodic movement of the particles between energy sources and "home"
- (c) chemotactic response to a self-consistent chemical field (b) directed movement in a asymetric periodic potential two-component field  $\Rightarrow$  directed forward / backward motion  $\Rightarrow$  direction depends on conversion parameter  $d_2$  and noise D
- 3. Advantage of the Active Brownian Particles Model:
- stochastic approach to directed movement and structure formation
- efficient and stable simulation algorithm: instead of integrating  $\text{PDE} \Rightarrow \text{simulation of the Langevin equation}$
- govern the system dynamics

• applicable to systems where only small particle numbers

### Self-Organization

achieve, through their cooperative interactions, states properties of their constitutive parts. Self-organization is the process by which individual subunits characterized by new, emergent properties transcending the

Physico-Chemical and Life Sciences, EU Report 16546 (1995) Biebricher, C. K.; Nicolis, G.; Schuster, P.: Self-Organization in the

equilibrium as a result of the influx of unspecific energy, forming in non-linear dynamic systems by way of feedback evolution and differentiation of complex order structures Self-organization is defined as spontaneous formation, matter or information. these systems have passed a critical distance from the statical mechanisms involving the elements of the systems, when

SFB 230 "Natural Constructions", Stuttgart, 1984 - 1995