Concurrent Programming

CSE4100: System Programming

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Concurrent Programming is Hard!

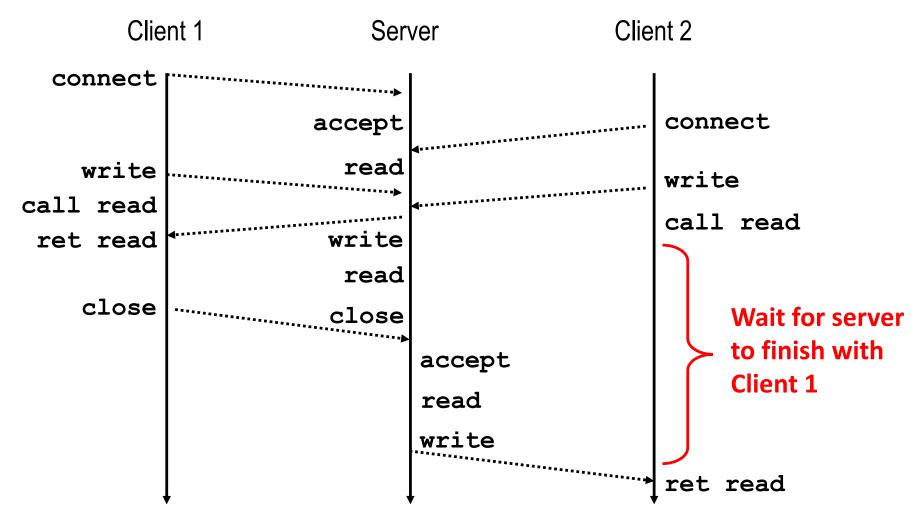
- The human mind tends to be sequential
- The notion of time is often misleading
- Thinking about all possible sequences of events in a computer system is at least error prone and frequently impossible

Concurrent Programming is Hard!

- Classical problem classes of concurrent programs:
 - Races: outcome depends on arbitrary scheduling decisions elsewhere in the system
 - Example: who gets the last seat on the airplane?
 - Deadlock: improper resource allocation prevents forward progress
 - Example: traffic gridlock
 - Livelock / Starvation / Fairness: external events and/or system scheduling decisions can prevent sub-task progress
 - Example: people always jump in front of you in line
- Many aspects of concurrent programming are beyond the scope of our course..
 - but, not all [©]
 - We'll cover some of these aspects in the next few lectures.

Iterative Servers

Iterative servers process one request at a time



Where Does Second Client Block?

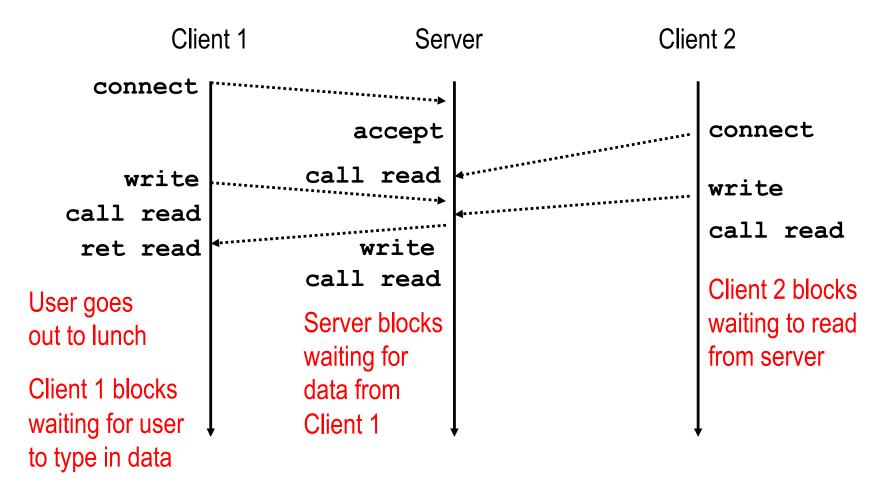
Second client attempts to connect to iterative server

Client socket open clientfd Connection request connect rio writen rio readlineb

Call to connect returns

- Even though connection not yet accepted
- Server side TCP manager queues request
- Feature known as "TCP listen backlog"
- Call to rio_writen returns
 - Server side TCP manager buffers input data
- Call to rio_readlineb blocks
 - Server hasn't written anything for it to read yet.

Fundamental Flaw of Iterative Servers



Solution: use concurrent servers instead

 Concurrent servers use multiple concurrent flows to serve multiple clients at the same time

Approaches for Writing Concurrent Servers

Allow server to handle multiple clients concurrently

1. Process-based

- Kernel automatically interleaves multiple logical flows
- Each flow has its own private address space

2. Event-based

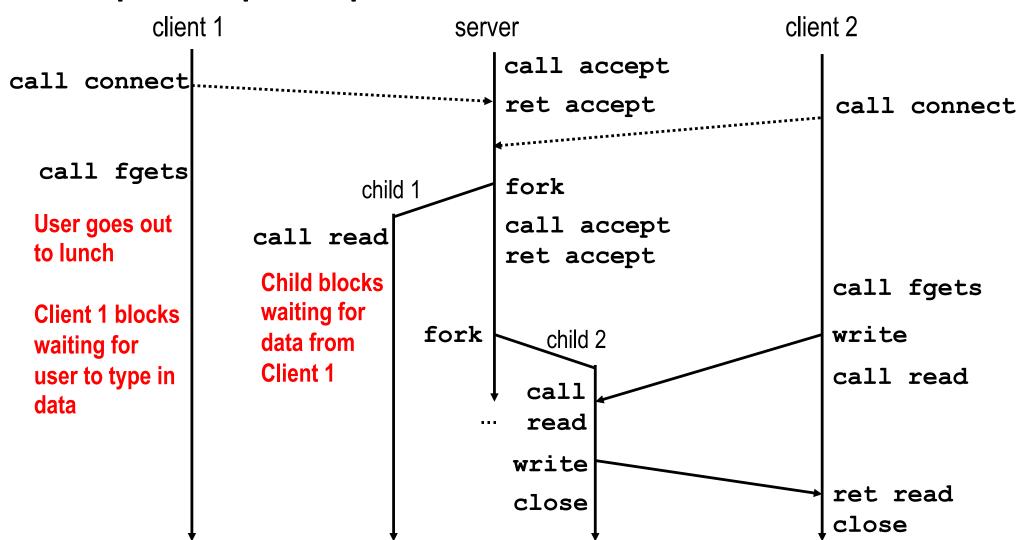
- Programmer manually interleaves multiple logical flows
- All flows share the same address space
- Uses technique called I/O multiplexing.

3. Thread-based

- Kernel automatically interleaves multiple logical flows
- Each flow shares the same address space
- Hybrid of of process-based and event-based.

Approach #1: Process-based Servers

Spawn separate process for each client



Process-Based Concurrent Echo Server

```
int main(int argc, char **argv)
{
   int listenfd, connfd;
   socklen t clientlen;
   struct sockaddr_storage clientaddr;
   Signal(SIGCHLD, sigchld_handler);
   listenfd = Open_listenfd(argv[1]);
   while (1) {
       clientlen = sizeof(struct sockaddr_storage);
       connfd = Accept(listenfd, (SA *) &clientaddr, &clientlen);
       if (Fork() == 0) {
           Close(listenfd); /* Child closes its listening socket */
           echo(connfd); /* Child services client */
           Close(connfd); /* Child closes connection with client */
           exit(0); /* Child exits */
       Close(connfd); /* Parent closes connected socket (important!) */
                                                              echoserverp.c
```

Process-Based Concurrent Echo Server (cont)

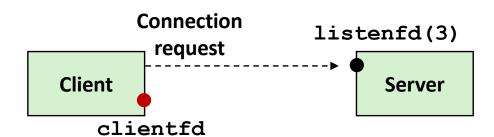
Reap all zombie children

```
void sigchld_handler(int sig)
{
    while (waitpid(-1, 0, WNOHANG) > 0)
    ;
    return;
}
```

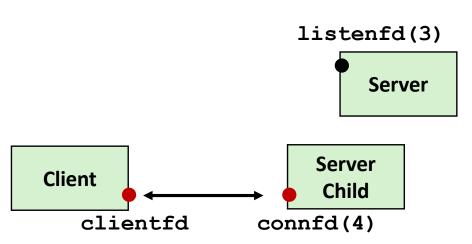
Concurrent Server: accept Illustrated



1. Server blocks in accept, waiting for connection request on listening descriptor listenfd

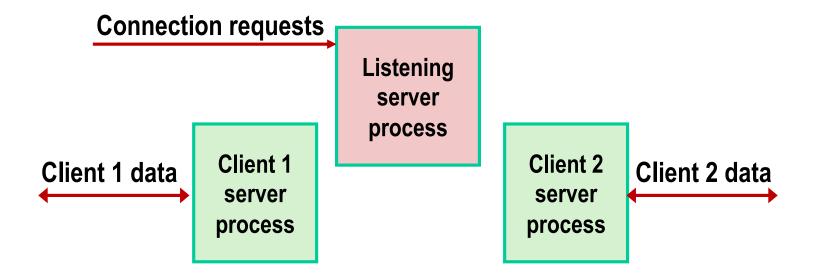


2. Client makes connection request by calling connect



3. Server returns connfd from accept. Forks child to handle client. Connection is now established between clientfd and connfd

Process-based Server Execution Model



- Each client handled by independent child process
- No shared state between them
- Both parent & child have copies of listenfd and connfd
 - Parent must close connfd
 - Child should close listenfd

Issues with Process-based Servers

- Listening server process must reap zombie children
 - to avoid fatal memory leak
- Parent process must close its copy of connfd
 - Kernel keeps reference count for each socket/open file
 - After fork, refcnt (connfd) = 2
 - Connection will not be closed until refcnt (connfd) =
 0

Pros and Cons of Process-based Servers

- + Handle multiple connections concurrently
- + Clean sharing model
 - descriptors (no)
 - file tables (yes)
 - global variables (no)
- + Simple and straightforward
- Additional overhead for process control
- Nontrivial to share data between processes
 - Requires IPC (interprocess communication) mechanisms
 - FIFO's (named pipes), System V shared memory and semaphores

Approach #2: Event-based Servers

- Server maintains set of active connections
 - Array of connfd's

Repeat:

- Determine which descriptors (connfd's or listenfd) have pending inputs
 - e.g., using select or epoll functions
 - arrival of pending input is an event
- If listenfd has input, then accept connection
 - and add new connfd to array
- Service all connfd's with pending inputs

Details for select-based server in book

I/O Multiplexed Event Processing

Read and service **Active Descriptors Pending Inputs** listenfd = 3 listenfd = 3 connfd's connfd's 10 0 10 **Active** 4 3 -1 -1 **Inactive** 4 -1 -1 5 12 12 **Active** 6 5 5 -1 -1 8 -1 -1 9 **Never Used** -1

Pros and Cons of Event-based Servers

- + One logical control flow and address space.
- + Can single-step with a debugger.
- + No process or thread control overhead.
 - Design of choice for high-performance Web servers and search engines. e.g., Node.js, nginx, Tornado
- Significantly more complex to code than process- or thread-based designs.
- Hard to provide fine-grained concurrency
 - E.g., how to deal with partial HTTP request headers
- Cannot take advantage of multi-core
 - Single thread of control

Approach #3: Thread-based Servers

- Very similar to approach #1 (process-based)
 - ...but using threads instead of processes

Traditional View of a Process

Process = process context + code, data, and stack

Process context

Program context:

Data registers

Condition codes

Stack pointer (SP)

Program counter (PC)

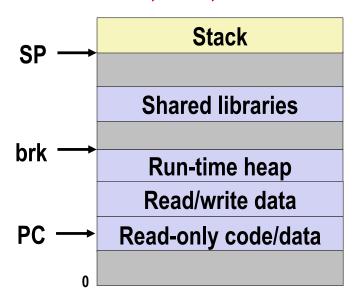
Kernel context:

VM structures

Descriptor table

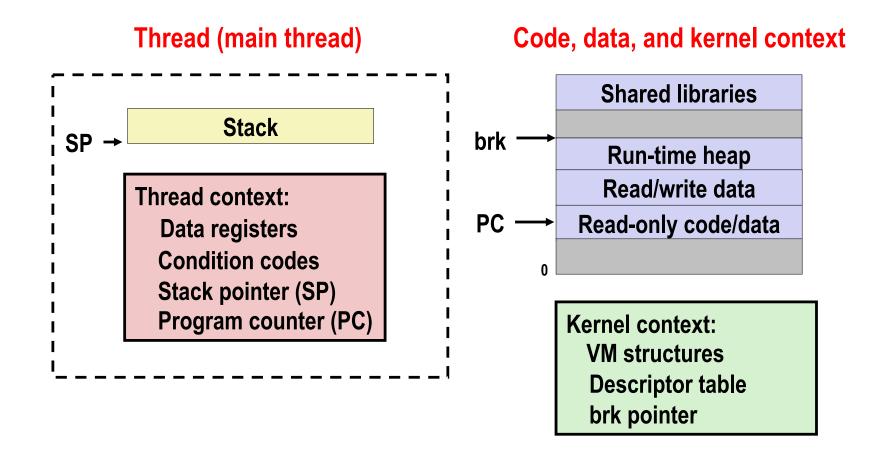
brk pointer

Code, data, and stack



Alternate View of a Process

Process = thread + code, data, and kernel context



A Process With Multiple Threads

- Multiple threads can be associated with a process
 - Each thread has its own logical control flow
 - Each thread shares the same code, data, and kernel context
 - Each thread has its own stack for local variables.
 - but not protected from other threads
 - Each thread has its own thread id (TID)

Thread 1 (main thread) Thread 2 (peer thread)

stack 1

Thread 1 context:

Data registers

Condition codes

SP1

PC1

stack 2

Thread 2 context:

Data registers

Condition codes

SP2

PC2

Shared code and data

shared libraries

run-time heap read/write data

read-only code/data

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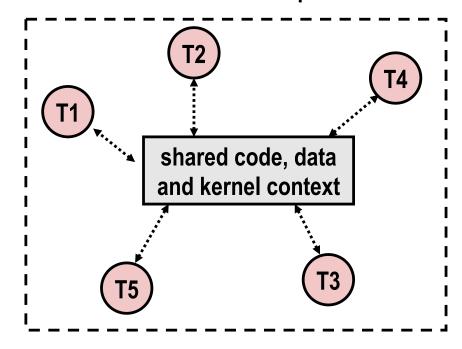
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Kernel context:
VM structures
Descriptor table
brk pointer

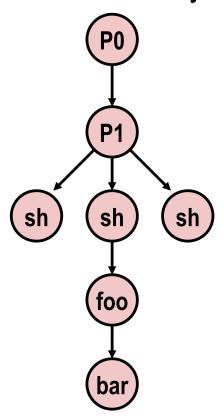
Logical View of Threads

- Threads associated with process form a pool of peers
 - Unlike processes which form a tree hierarchy

Threads associated with process foo



Process hierarchy



Concurrent Threads

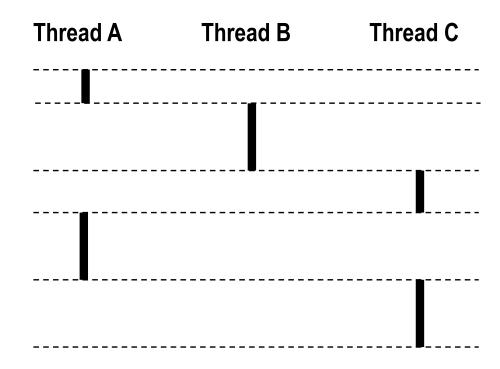
- Two threads are concurrent if their flows overlap in time
- Otherwise, they are sequential

Examples:

Concurrent: A & B, A&C

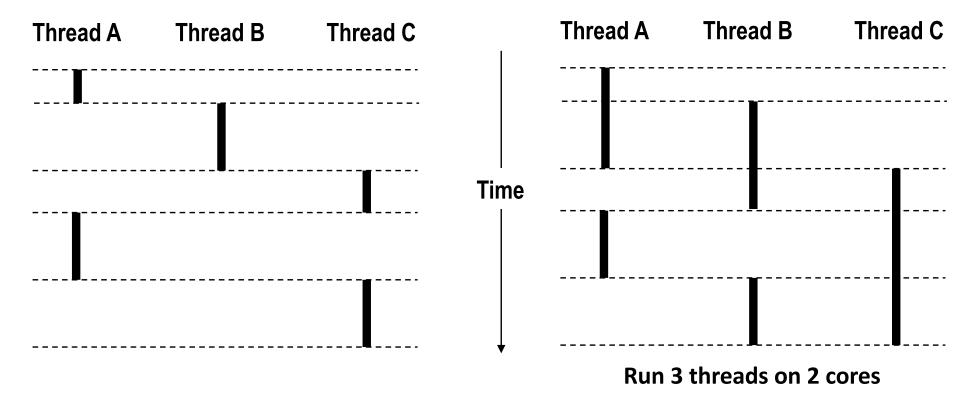
Sequential: B & C

Time



Concurrent Thread Execution

- Single Core Processor
 - Simulate parallelism by time slicing
- Multi-Core Processor
 - Can have true parallelism



Threads vs. Processes

How threads and processes are similar

- Each has its own logical control flow
- Each can run concurrently with others (possibly on different cores)
- Each is context switched

How threads and processes are different

- Threads share all code and data (except local stacks)
 - Processes (typically) do not
- Threads are somewhat less expensive than processes
 - Process control (creating and reaping) twice as expensive as thread control
 - Linux numbers:
 - ~20K cycles to create and reap a process
 - ~10K cycles (or less) to create and reap a thread

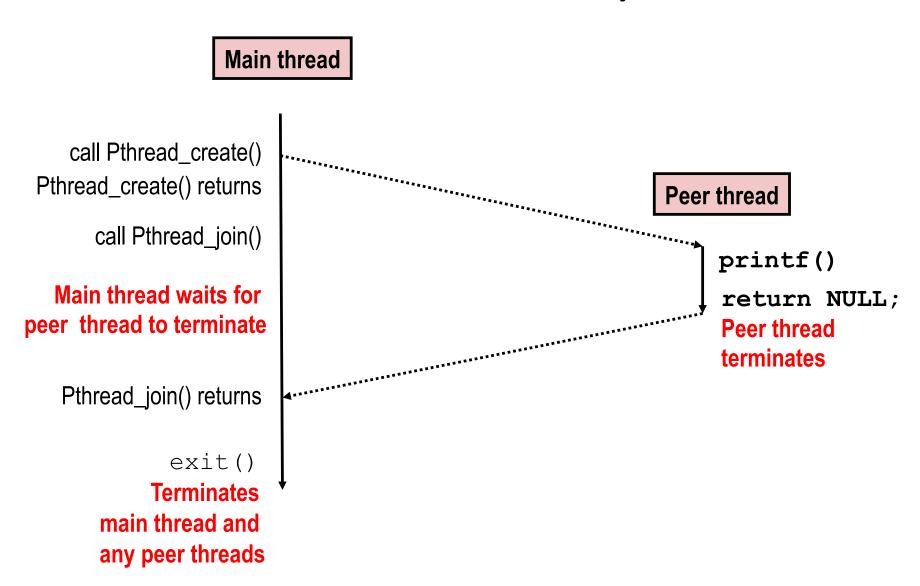
Posix Threads (Pthreads) Interface

- Pthreads: Standard interface for ~60 functions that manipulate threads from C programs
 - Creating and reaping threads
 - pthread create()
 - pthread join()
 - Determining your thread ID
 - pthread_self()
 - Terminating threads
 - pthread cancel()
 - pthread exit()
 - exit() [terminates all threads]
 - Synchronizing access to shared variables
 - pthread_mutex_init
 - pthread_mutex_[un]lock

The Pthreads "hello, world" Program

```
/*
 * hello.c - Pthreads "hello, world" program
                                                         Thread attributes
                                       Thread ID
#include "csapp.h"
                                                          (usually NULL)
void *thread(void *vargp);
int main()
                                                          Thread routine
    pthread_t tid;
    Pthread_create(&tid, NULL, thread, NULL);
    Pthread_join(tid, NULL);
                                                        Thread arguments
    exit(0);
                                                            (void *p)
                                            hello.c
                                                       Return value
                                                         (void **p)
void *thread(void *vargp) /* thread routine */
    printf("Hello, world!\n");
    return NULL;
                                                  hello.c
```

Execution of Threaded "hello, world"



Thread-Based Concurrent Echo Server

```
int main(int argc, char **argv)
{
    int listenfd, *connfdp;
    socklen_t clientlen;
    struct sockaddr_storage clientaddr;
    pthread t tid;
    listenfd = Open_listenfd(argv[1]);
    while (1) {
       clientlen=sizeof(struct sockaddr_storage);
       connfdp = Malloc(sizeof(int));
       *connfdp = Accept(listenfd,
                 (SA *) &clientaddr, &clientlen);
       Pthread_create(&tid, NULL, thread, connfdp);
    }
}
                                           echoservert.c
```

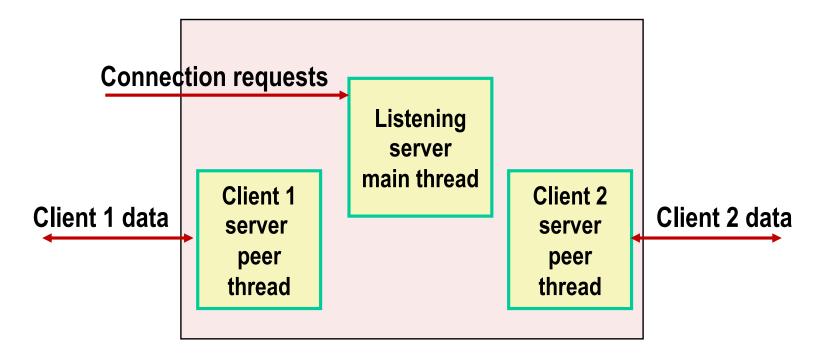
malloc of connected descriptor necessary to avoid deadly race (later)

Thread-Based Concurrent Server (cont)

```
/* Thread routine */
void *thread(void *vargp)
{
    int connfd = *((int *)vargp);
    Pthread_detach(pthread_self());
    Free(vargp);
    echo(connfd);
    Close(connfd);
    return NULL;
}
```

- Run thread in "detached" mode.
 - Runs independently of other threads
 - Reaped automatically (by kernel) when it terminates
- Free storage allocated to hold connfd.
- Close connfd (important!)

Thread-based Server Execution Model



- Each client handled by individual peer thread
- Threads share all process state except TID
- Each thread has a separate stack for local variables

Issues With Thread-Based Servers

- Must run "detached" to avoid memory leak
 - At any point in time, a thread is either joinable or detached
 - Joinable thread can be reaped and killed by other threads
 - must be reaped (with pthread join) to free memory resources
 - Detached thread cannot be reaped or killed by other threads
 - resources are automatically reaped on termination
 - Default state is joinable
 - use pthread_detach (pthread_self()) to make detached
- Must be careful to avoid unintended sharing
 - For example, passing pointer to main thread's stack
 - Pthread create(&tid, NULL, thread, (void *)&connfd);
- All functions called by a thread must be thread-safe
 - (next lecture)

Pros and Cons of Thread-Based Designs

- + Easy to share data structures between threads
 - e.g., logging information, file cache
- + Threads are more efficient than processes
- Unintentional sharing can introduce subtle and hard-to-reproduce errors!
 - The ease with which data can be shared is both the greatest strength and the greatest weakness of threads
 - Hard to know which data shared & which private
 - Hard to detect by testing
 - Probability of bad race outcome very low
 - But nonzero!
 - Future lectures

Summary: Approaches to Concurrency

Process-based

- Hard to share resources: Easy to avoid unintended sharing
- High overhead in adding/removing clients

Event-based

- Tedious and low level
- Total control over scheduling
- Very low overhead
- Cannot create as fine grained a level of concurrency
- Does not make use of multi-core

Thread-based

- Easy to share resources: Perhaps too easy
- Medium overhead
- Not much control over scheduling policies
- Difficult to debug
 - Event orderings not repeatable