Synchronization: Advanced

CSE4100: System Programming

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Review: Semaphores

■ **Semaphore:** non-negative global integer synchronization variable. Manipulated by **P** and **V** operations.

■ P(s)

- If s is nonzero, then decrement s by 1 and return immediately.
- If s is zero, then suspend thread until s becomes nonzero and the thread is restarted by a V operation.
- After restarting, the P operation decrements s and returns control to the caller.

■ *V(s)*:

- Increment s by 1.
- If there are any threads blocked in a P operation waiting for s to become non-zero, then restart exactly one of those threads, which then completes its P operation by decrementing s.
- Semaphore invariant: (s >= 0)

Review: Using semaphores to protect shared resources via mutual exclusion

Basic idea:

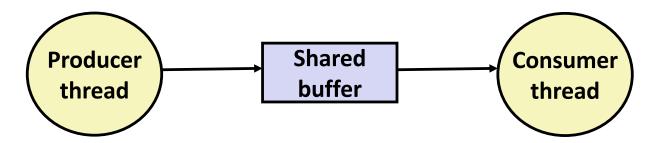
- Associate a unique semaphore mutex, initially 1, with each shared variable (or related set of shared variables)
- Surround each access to the shared variable(s) with P(mutex) and V(mutex) operations

```
mutex = 1
P(mutex)
cnt++
V(mutex)
```

Using Semaphores to Coordinate Access to Shared Resources

- Basic idea: Thread uses a semaphore operation to notify another thread that some condition has become true
 - Use counting semaphores to keep track of resource state and to notify other threads
 - Use mutex to protect access to resource
- Two classic examples:
 - The Producer-Consumer Problem
 - The Readers-Writers Problem

Producer-Consumer Problem



Common synchronization pattern:

- Producer waits for empty slot, inserts item in buffer, and notifies consumer
- Consumer waits for item, removes it from buffer, and notifies producer

Examples

- Multimedia processing:
 - Producer creates MPEG video frames, consumer renders them
- Event-driven graphical user interfaces
 - Producer detects mouse clicks, mouse movements, and keyboard hits and inserts corresponding events in buffer
 - Consumer retrieves events from buffer and paints the display

Producer-Consumer on an *n*-element Buffer

- Requires a mutex and two counting semaphores:
 - mutex: enforces mutually exclusive access to the buffer
 - slots: counts the available slots in the buffer
 - i tems: counts the available items in the buffer
- Implemented using a shared buffer package called sbuf.

sbuf Package - Declarations

```
#include "csapp.h"
typedef struct {
    int *buf; /* Buffer array */
           /* Maximum number of slots */
    int n;
    int front;  /* buf[(front+1)%n] is first item */
   int rear;  /* buf[rear%n] is last item */
sem_t mutex;  /* Protects accesses to buf */
    sem_t slots; /* Counts available slots */
    sem_t items; /* Counts available items */
} sbuf t;
void sbuf_init(sbuf_t *sp, int n);
void sbuf_deinit(sbuf_t *sp);
void sbuf_insert(sbuf_t *sp, int item);
int sbuf_remove(sbuf_t *sp);
                                                               sbuf.h
```

sbuf Package - Implementation

Initializing and deinitializing a shared buffer:

```
/* Create an empty, bounded, shared FIFO buffer with n slots */
void sbuf_init(sbuf_t *sp, int n)
   sp->buf = Calloc(n, sizeof(int));
                           /* Buffer holds max of n items */
   sp->n = n;
   sp->front = sp->rear = 0;  /* Empty buffer iff front == rear */
   Sem_init(&sp->mutex, 0, 1); /* Binary semaphore for locking */
   Sem_init(&sp->slots, 0, n); /* Initially, buf has n empty slots */
   Sem_init(&sp->items, 0, 0); /* Initially, buf has 0 items */
/* Clean up buffer sp */
void sbuf_deinit(sbuf_t *sp)
   Free(sp->buf);
                                                                  sbuf.c
```

sbuf Package - Implementation

Inserting an item into a shared buffer:

sbuf Package - Implementation

Removing an item from a shared buffer:

Readers-Writers Problem

Generalization of the mutual exclusion problem

Problem statement:

- Reader threads only read the object
- Writer threads modify the object
- Writers must have exclusive access to the object
- Unlimited number of readers can access the object

Occurs frequently in real systems, e.g.,

- Online airline reservation system
- Multithreaded caching Web proxy

Variants of Readers-Writers

- First readers-writers problem (favors readers)
 - No reader should be kept waiting unless a writer has already been granted permission to use the object
 - A reader that arrives after a waiting writer gets priority over the writer
- Second readers-writers problem (favors writers)
 - Once a writer is ready to write, it performs its write as soon as possible
 - A reader that arrives after a writer must wait, even if the writer is also waiting
- Starvation (where a thread waits indefinitely) is possible in both cases

Solution to First Readers-Writers Problem

Readers:

```
int readcnt; /* Initially = 0 */
sem_t mutex, w; /* Initially = 1 */
void reader(void)
{
   while (1) {
        P(&mutex):
        readcnt++;
        if (readcnt == 1) /* First in */
            P(&w);
        V(&mutex):
        /* Critical section */
        /* Reading happens */
        P(&mutex):
        readcnt--;
        if (readcnt == 0) /* Last out */
           V(&w);
        V(&mutex);
```

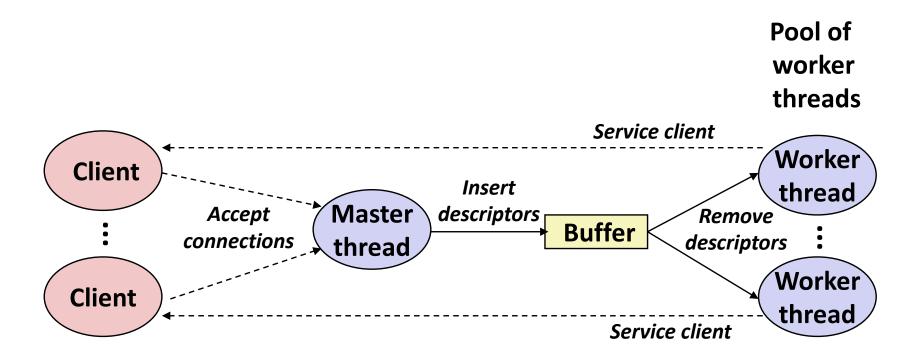
Writers:

```
void writer(void)
{
    while (1) {
        P(&w);

        /* Critical section */
        /* Writing happens */

        V(&w);
    }
}
rw1.c
```

Putting It All Together: Prethreaded Concurrent Server



```
sbuf_t sbuf; /* Shared buffer of connected descriptors */
int main(int argc, char **argv)
{
    int i, listenfd, connfd;
    socklen t clientlen;
    struct sockaddr_storage clientaddr;
    pthread t tid;
    listenfd = Open_listenfd(argv[1]);
    sbuf_init(&sbuf, SBUFSIZE);
    for (i = 0; i < NTHREADS; i++) /* Create worker threads */</pre>
       Pthread_create(&tid, NULL, thread, NULL);
    while (1) {
       clientlen = sizeof(struct sockaddr_storage);
       connfd = Accept(listenfd, (SA *) &clientaddr, &clientlen);
       sbuf_insert(&sbuf, connfd); /* Insert connfd in buffer */
                                                      echoservert pre.c
```

Worker thread routine:

```
void *thread(void *vargp)
{
    Pthread_detach(pthread_self());
    while (1) {
        int connfd = sbuf_remove(&sbuf); /* Remove connfd from buf */
        echo_cnt(connfd); /* Service client */
        Close(connfd);
    }
}
```

echo cnt initialization routine:

```
static int byte_cnt;  /* Byte counter */
static sem_t mutex;  /* and the mutex that protects it */

static void init_echo_cnt(void)
{
    Sem_init(&mutex, 0, 1);
    byte_cnt = 0;
}
    echo_cnt.c
```

Worker thread service routine:

```
void echo_cnt(int connfd)
{
    int n:
    char buf[MAXLINE];
    rio t rio:
    static pthread_once_t once = PTHREAD_ONCE_INIT;
    Pthread_once(&once, init_echo_cnt);
    Rio_readinitb(&rio, connfd);
    while((n = Rio_readlineb(&rio, buf, MAXLINE)) != 0) {
       P(&mutex):
       byte cnt += n;
       printf("thread %d received %d (%d total) bytes on fd %d\n",
               (int) pthread_self(), n, byte_cnt, connfd);
       V(&mutex):
       Rio_writen(connfd, buf, n);
                                                             echo_cnt.c
```

Crucial concept: Thread Safety

- Functions called from a thread must be thread-safe
- Def: A function is thread-safe iff it will always produce correct results when called repeatedly from multiple concurrent threads
- Classes of thread-unsafe functions:
 - Class 1: Functions that do not protect shared variables
 - Class 2: Functions that keep state across multiple invocations
 - Class 3: Functions that return a pointer to a static variable
 - Class 4: Functions that call thread-unsafe functions ©

Thread-Unsafe Functions (Class 1)

- Failing to protect shared variables
 - Fix: Use P and V semaphore operations
 - Example: goodcnt.c
 - Issue: Synchronization operations will slow down code

Thread-Unsafe Functions (Class 2)

- Relying on persistent state across multiple function invocations
 - Example: Random number generator that relies on static state

```
static unsigned int next = 1;

/* rand: return pseudo-random integer on 0..32767 */
int rand(void)
{
    next = next*1103515245 + 12345;
    return (unsigned int)(next/65536) % 32768;
}

/* srand: set seed for rand() */
void srand(unsigned int seed)
{
    next = seed;
}
```

Thread-Safe Random Number Generator

- Pass state as part of argument
 - and, thereby, eliminate global state

```
/* rand_r - return pseudo-random integer on 0..32767 */
int rand_r(int *nextp)
{
    *nextp = *nextp * 1103515245 + 12345;
    return (unsigned int)(*nextp/65536) % 32768;
}
```

Consequence: programmer using rand_r must maintain seed

Thread-Unsafe Functions (Class 3)

- Returning a pointer to a static variable
- Fix 1. Rewrite function so caller passes address of variable to store result
 - Requires changes in caller and callee
- Fix 2. Lock-and-copy
 - Requires simple changes in caller (and none in callee)
 - However, caller must free memory.

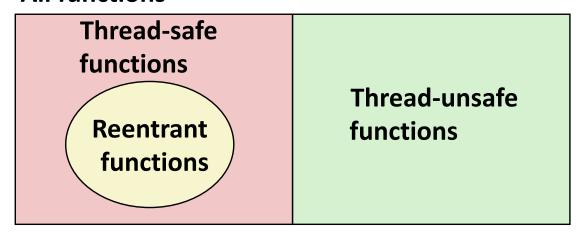
Thread-Unsafe Functions (Class 4)

- Calling thread-unsafe functions
 - Calling one thread-unsafe function makes the entire function that calls it thread-unsafe
 - Fix: Modify the function so it calls only thread-safe functions ©

Reentrant Functions

- Def: A function is reentrant iff it accesses no shared variables when called by multiple threads.
 - Important subset of thread-safe functions
 - Require no synchronization operations
 - Only way to make a Class 2 function thread-safe is to make it reetnrant (e.g., rand r)

All functions



Thread-Safe Library Functions

- All functions in the Standard C Library (at the back of your K&R text) are thread-safe
 - Examples: malloc, free, printf, scanf
- Most Unix system calls are thread-safe, with a few exceptions:

| Thread-unsafe function | Class | Reentrant version |
|------------------------|-------|-------------------|
| asctime | 3 | asctime_r |
| ctime | 3 | ctime_r |
| gethostbyaddr | 3 | gethostbyaddr_r |
| gethostbyname | 3 | gethostbyname_r |
| inet_ntoa | 3 | (none) |
| localtime | 3 | localtime r |
| rand | 2 | rand r |
| | | _ |

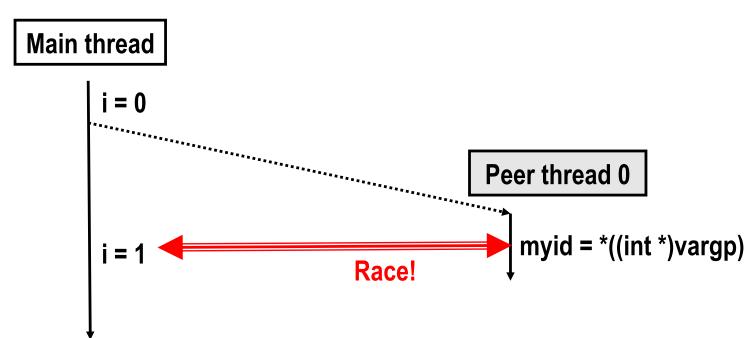
One worry: Races

A race occurs when correctness of the program depends on one thread reaching point x before another thread reaches point y

```
/* A threaded program with a race */
int main()
                                     N threads are sharing i
    pthread_t tid[N];
    int i: ←
    for (i = 0; i < N; i++)
        Pthread_create(&tid[i], NULL, thread, &i);
    for (i = 0; i < N; i++)
        Pthread_join(tid[i], NULL);
    exit(0):
/* Thread routine */
void *thread(void *vargp)
    int myid = *((int *)vargp);
    printf("Hello from thread %d\n", myid);
    return NULL:
                                               race.c
```

Race Illustration

```
for (i = 0; i < N; i++)
Pthread_create(&tid[i], NULL, thread, &i);</pre>
```



- Race between increment of i in main thread and deref of varge in peer thread:
 - If deref happens while i = 0, then OK
 - Otherwise, peer thread gets wrong id value

Could this race really occur?

Main thread

Peer thread

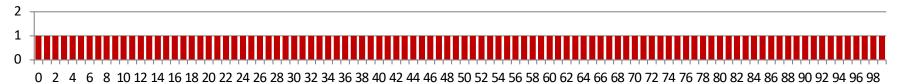
```
void *thread(void *vargp) {
    Pthread_detach(pthread_self());
    int i = *((int *)vargp);
    save_value(i);
    return NULL;
}
```

Race Test

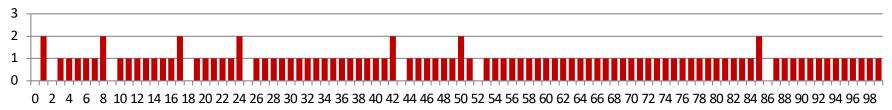
- If no race, then each thread would get different value of i
- Set of saved values would consist of one copy each of 0 through 99

Experimental Results

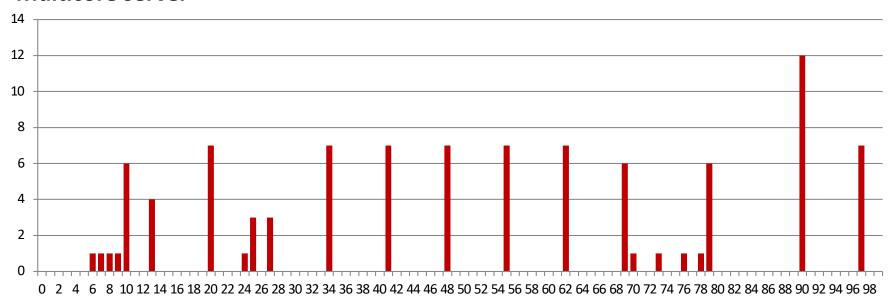
No Race



Single core laptop



Multicore server



The race can really happen!

Race Elimination

```
/* Threaded program without the race */
int main()
                                 Avoid unintended sharing of
{
    pthread_t tid[N];
                                    state
    int i, *ptr;
    for (i = 0; i < N; i++) {
        ptr = Malloc(sizeof(int));
        *ptr = i;
        Pthread_create(&tid[i], NULL, thread, ptr);
    for (i = 0; i < N; i++)
        Pthread_join(tid[i], NULL);
    exit(0):
}
/* Thread routine */
void *thread(void *vargp)
{
    int myid = *((int *)vargp);
    Free(vargp);
    printf("Hello from thread %d\n", myid);
    return NULL;
                                              norace.c
```

Another worry: Deadlock

Def: A process is deadlocked iff it is waiting for a condition that will never be true

Typical Scenario

- Processes 1 and 2 needs two resources (A and B) to proceed
- Process 1 acquires A, waits for B
- Process 2 acquires B, waits for A
- Both will wait forever!

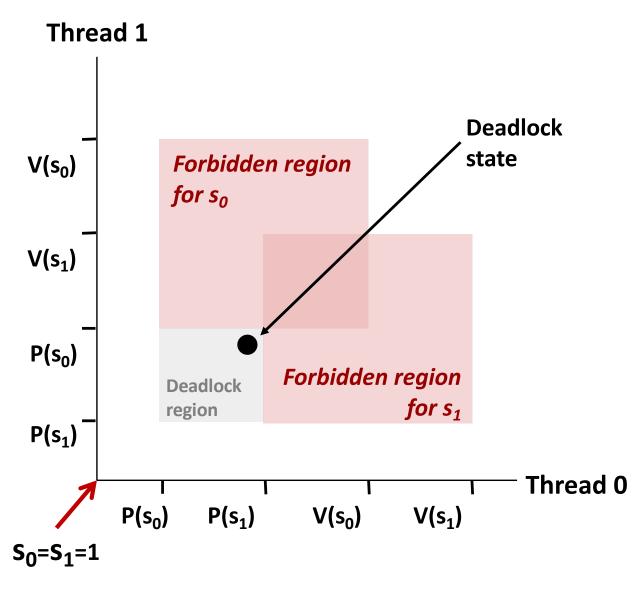
Deadlocking With Semaphores

```
int main()
{
    pthread_t tid[2];
    Sem_init(&mutex[0], 0, 1); /* mutex[0] = 1 */
    Sem_init(&mutex[1], 0, 1); /* mutex[1] = 1 */
    Pthread_create(&tid[0], NULL, count, (void*) 0);
    Pthread_create(&tid[1], NULL, count, (void*) 1);
    Pthread_join(tid[0], NULL);
    Pthread_join(tid[1], NULL);
    printf("cnt=%d\n", cnt);
    exit(0);
}
```

```
void *count(void *vargp)
{
    int i;
    int id = (int) vargp;
    for (i = 0; i < NITERS; i++) {
        P(&mutex[id]); P(&mutex[1-id]);
        cnt++;
        V(&mutex[id]); V(&mutex[1-id]);
    }
    return NULL;
}</pre>
```

```
Tid[0]: Tid[1]: P(s<sub>0</sub>); P(s<sub>1</sub>); P(s<sub>0</sub>); cnt++; V(s<sub>0</sub>); V(s<sub>1</sub>); V(s<sub>0</sub>);
```

Deadlock Visualized in Progress Graph



Locking introduces the potential for *deadlock:* waiting for a condition that will never be true

Any trajectory that enters the *deadlock region* will eventually reach the *deadlock state*, waiting for either S₀ or S₁ to become nonzero

Other trajectories luck out and skirt the deadlock region

Unfortunate fact: deadlock is often nondeterministic (race)

Avoiding Deadlock

Acquire shared resources in same order

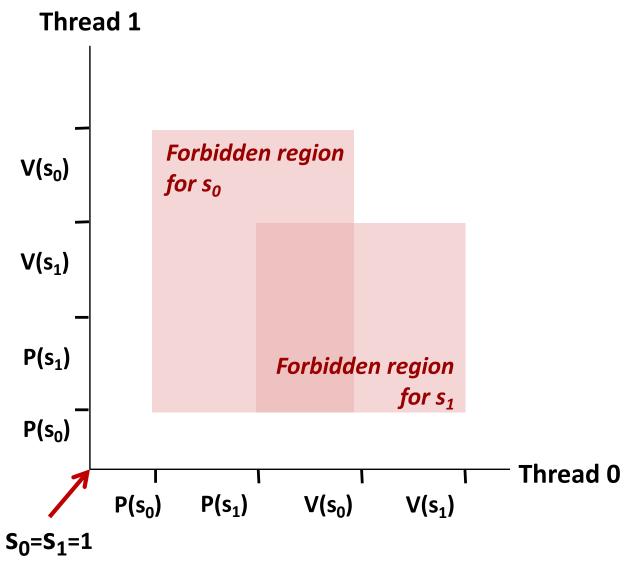
```
int main()
{
    pthread_t tid[2];
    Sem_init(&mutex[0], 0, 1); /* mutex[0] = 1 */
    Sem_init(&mutex[1], 0, 1); /* mutex[1] = 1 */
    Pthread_create(&tid[0], NULL, count, (void*) 0);
    Pthread_create(&tid[1], NULL, count, (void*) 1);
    Pthread_join(tid[0], NULL);
    Pthread_join(tid[1], NULL);
    printf("cnt=%d\n", cnt);
    exit(0);
}
```

```
void *count(void *vargp)
{
    int i;
    int id = (int) vargp;
    for (i = 0; i < NITERS; i++) {
        P(&mutex[0]); P(&mutex[1]);
        cnt++;
        V(&mutex[id]); V(&mutex[1-id]);
    }
    return NULL;
}</pre>
```

Brva

```
Tid[0]: Tid[1]: P(s0); P(s1); P(s1); cnt++; V(s0); V(s1); V(s0);
```

Avoided Deadlock in Progress Graph



No way for trajectory to get stuck

Processes acquire locks in same order

Order in which locks released immaterial