#### **REPORT: ASSIGNMENT 7 FOUCAULT PENDULUM**

#### **GROUP: 2H**

### **Description of C-Code:**

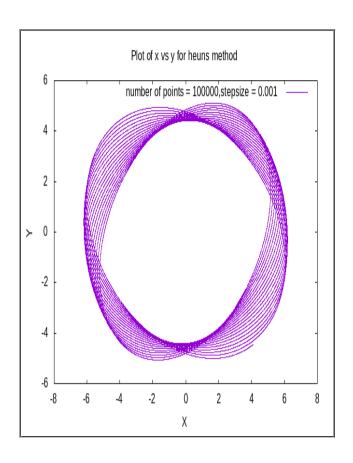
- The C code uses 4 different methods to solve ordinary differential equations i.e., euler, heuns,runge-kutta,rk45 methods.
- The second derivatives are taken as derivatives of 2 new variables and now 4 different first order differential equations can to solved to obtain the equations of foucault pendulum.
- Inputs are constants of the equations of foucault pendulum,intial coordinates and velocities, stepsize and number of points to be generated. And the method to solve differential equations.
- Output is the graph oh x vs y for a foucault pendulum.
- Compilation : cc foucault.c -lm

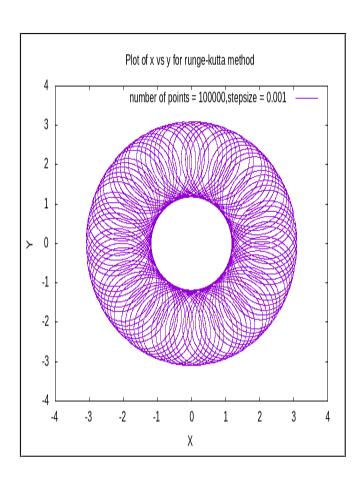
### **Learning outcomes:**

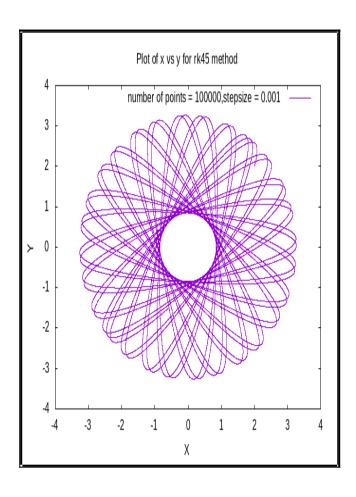
- Use of arrays
- Use of functions in a c code.
- Calling gnuplot from the c code.
- Use of switches.
- Methods to solve ordinary differential equations numerically
- Writing data into file.

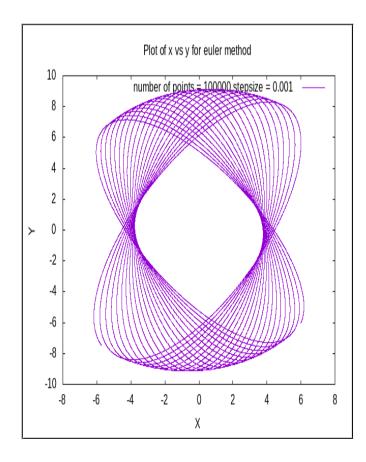
#### **Inferences:**

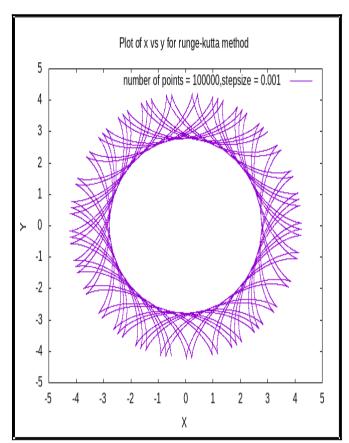
• The following lissago figures are obtained for various initial conditions.

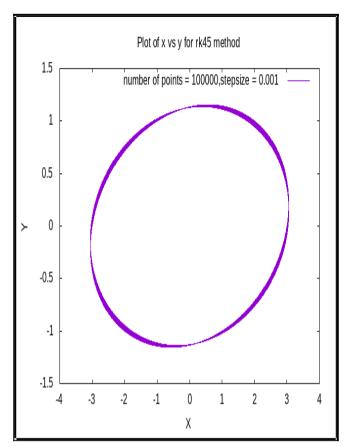




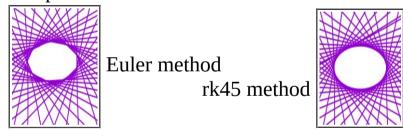




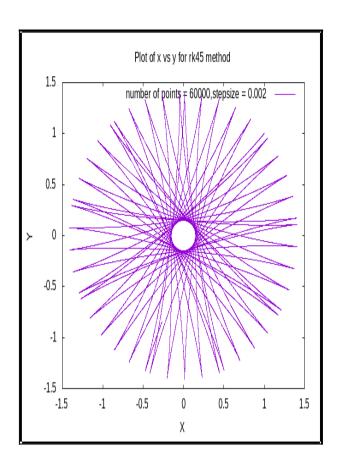


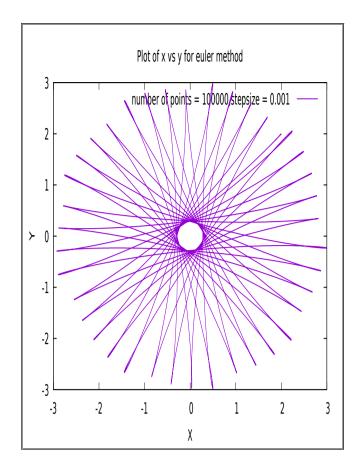


• For a given step size the graphs of rk45 method are smoother when compared to other methods.



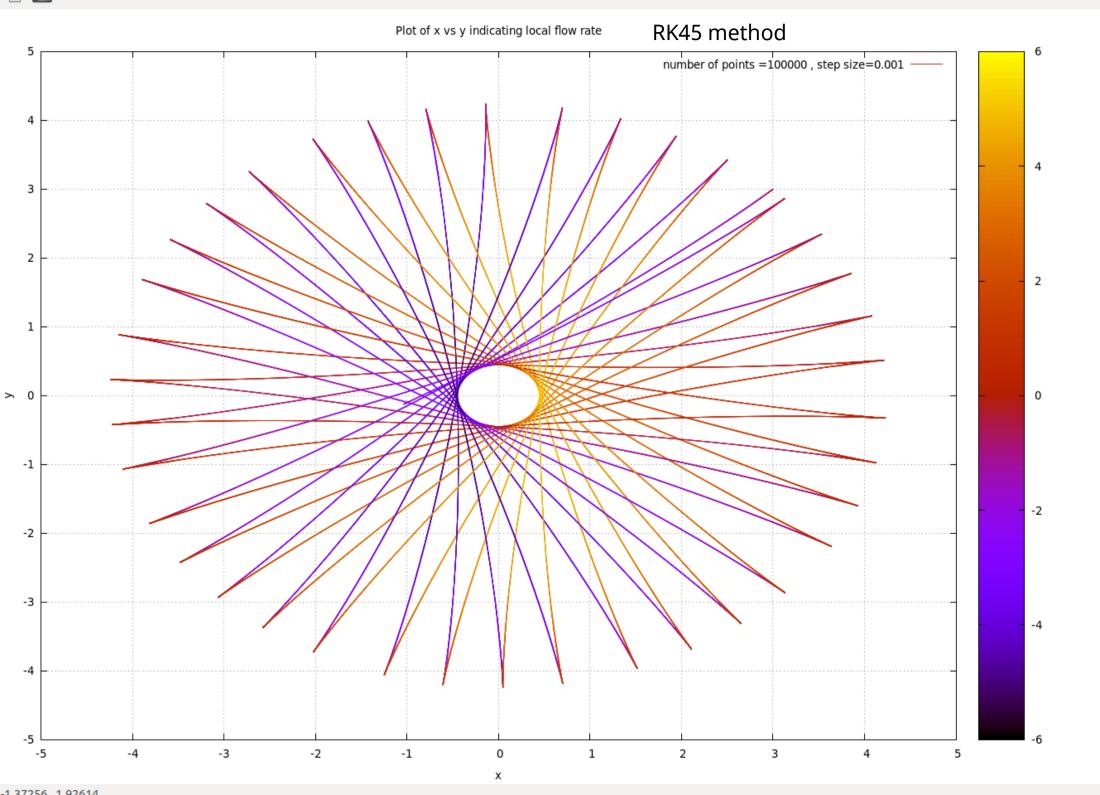
• For similar initial conditions, similar plots are obtained for lower step size, higher number of points for euler and higher step size and lower number points for rk45 method.



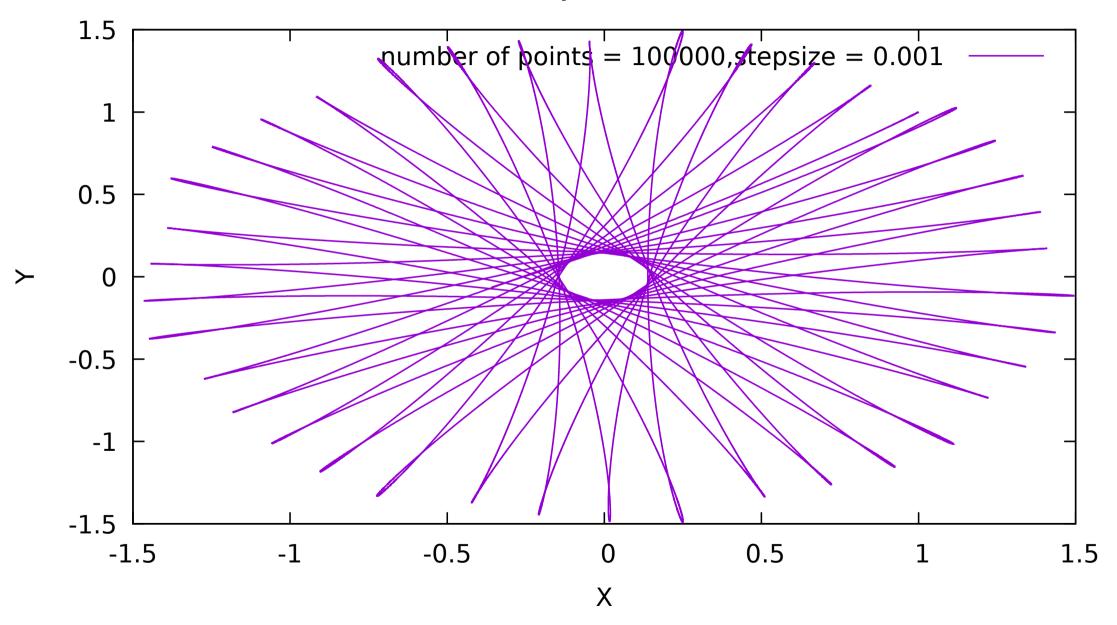


Various plots for several initial conditions are followed below.

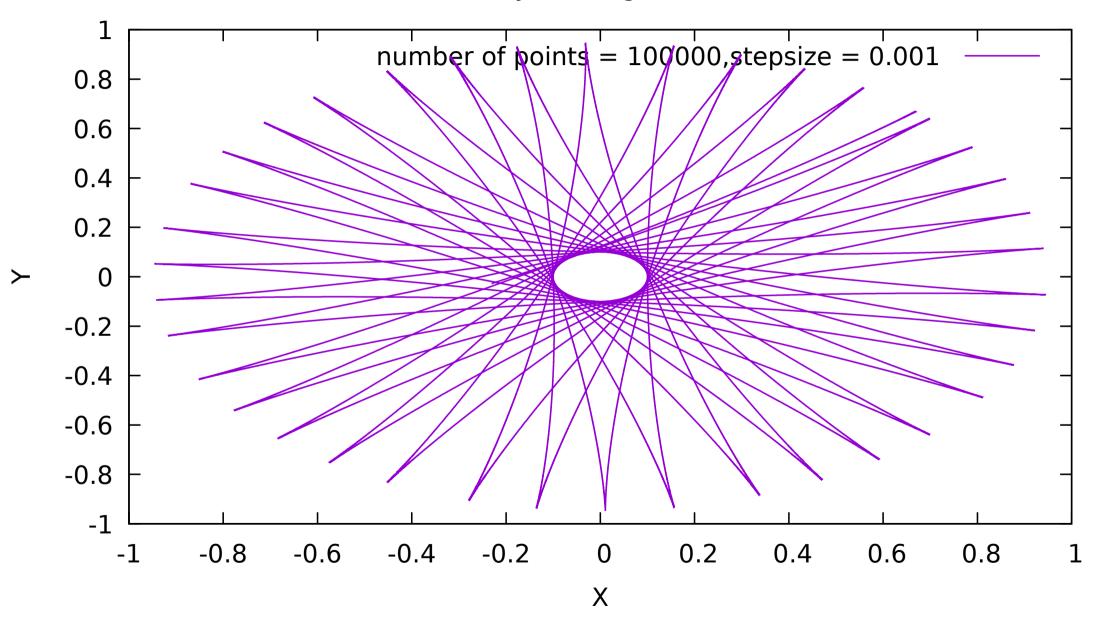
**Conclusion:** RK 45 is more closer to the actual values when compared to other methods



# Plot of x vs y for euler method



## Plot of x vs y for runge-kutta method



## Plot of x vs y for heuns method

