

# Sagnik Ghatak

Ingolstadt, Deutschland

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🌐 linkedin

🐙 Github

## EXPERIENCE

**Schanzer Racing Elektrik**.....  
Team Member - Driverless Mar 2024 - Jul 2024, Ingolstadt

### Localization and planning of an autonomous vehicle

- Designed a dual Extended Kalman Filter (EKF) system for robust sensor fusion, integrating steering angle sensors, wheel odometry, and GPS data to enhance vehicle state estimation.
- Designed a path planning algorithm for autonomous driving in dynamic environments to generate optimized paths for acceleration and maneuvering, ensuring precise and adaptive navigation.

**Cognizant Technology Solution**.....  
Programmer Analyst Oct 2021 - Sept 2023, Kolkata

### Data engineering for insurance services

- Led the development of an ETL pipeline for insurance services
- Automated tasks with UNIX and Python scripts that reduce manual intervention by 60 %
- Reduction of project implementation time by 15 % through agile collaboration and cross-functional teamwork

## PROJECTS

**Tower of Hanoi**.....  
Python, PyTorch, Reinforcement Learning, Pygame, Seaborn, Numpy

### Github

- Development of Tower of Hanoi, an environment to train a reinforcement learning agent.
- Analysis of Markov Decision Process and implementation of a Q-Learning Agent using Q-Learning Algorithm
- Development of a Deep Q Network(DQN) agent to tackle the dynamic aspect of the Tower of Hanoi environment

**Local Planning And Evaluation Of Evasive Maneuvers For Automated Vehicles**.....  
Python, Matplotlib

### Github

- Design and implementation of a Local Trajectory Planner (LTP) to facilitate evasive maneuvers in automated vehicles.
- Develop vehicle model and controller algorithms to track the trajectory planned by the LTP accurately.

**Echo-bot**.....  
C++, Python, CMAKE, ROS2, SLAM, GAZEBO

### Github

- Development of an echo robot with URDF and simulation in Gazebo. Control of the robot with the ROS 2 control package.
- Implementation of SLAM for real-time mapping and localization. Robust navigation with NAV2, which enables autonomous path planning and obstacle.

## SKILLS

- **Programming Languages:** C/C++, Python, MATLAB, SQL
- **Software Development:** OOP, Agile, CI/CD
- **Frameworks/Libraries:** Tensorflow, Sci-kit Learn, PyTorch, NumPy, Pandas, Matplotlib, Pygame, ROS2
- **Simulators:** Gazebo, CARLA, Simulink, CoppeliaSim
- **Tools:** Azure DevOps, Docker, JIRA, Git, Linux

## ACADEMICS

**Technische Hochschule Ingolstadt**  
**Master of Engineering**  
AI Engg. of Autonomous Systems  
Ingolstadt, Deutschland

**St. Thomas' College of Engineering and Technology**  
**Bachelor of Technology**  
Electrical Engineering  
Kolkata, India

## ACHIEVEMENTS

- **Cognizant Cheers (Cognizant)**  
Recognized for an invaluable contribution to project implementation

## LANGUAGES

- Bengali (Mothertongue)
- Hindi (Business Fluent)
- English (Business Fluent)
- German (Beginner)

## INTERESTS

- Football
- Hiking
- Cooking