



# INTEGER MULTIPLICATION

By: Tamal Chakraborty

# Multiplication of 2 n bit numbers

- Let  $x$  and  $y$  be represented as  $n$ -digit strings in some base  $B$ . For any positive integer  $m$  less than  $n$ , one can split the two given numbers as follows

$$x = x_1 \cdot B^m + x_0, x_0 < B^m$$

$$y = y_1 \cdot B^m + y_0, y_0 < B^m$$

- The product  $xy$ , can be then represented as:

$$\begin{aligned} xy &= (x_1 \cdot B^m + x_0) \cdot (y_1 \cdot B^m + y_0) \\ &= z_2 \cdot B^{2m} + z_1 \cdot B^m + z_0 \end{aligned}$$

- Where,

$$z_2 = x_1 y_1, z_1 = x_1 y_0 + x_0 y_1, z_0 = x_0 y_0$$

# Performance Analysis

- Without loss of generality, let us assume that  $x_1, y_1, x_0, y_0$  are  $n/2$  digit numbers, for if the number of digit in any of them is less than  $n/2$ , then we can add zeros to the left-hand side to make them  $n/2$  digit long.
- Now, clearly the multiplication of 2  $n$  digit numbers,  $xy$ , involves 4 multiplications of  $n/2$  digit numbers and three additions of  $n/2$  digit numbers.
- Let  $T(n)$  be the time needed to multiply 2  $n$  digit numbers. Then,
- $T(n) = 4T(n/2) + 3n$ , since addition is  $O(n)$  operation
- Solving, the above recurrence by Master Method, we get
- $T(n) = \Theta(n^2)$

# Karatsuba Technique

- Karatsuba observed that  $xy$  can be computed in only 3 multiplications, such that:
  - $z_2 = x_1y_1$
  - $z_0 = x_0y_0$
  - $z_1 = (x_1 + x_2) \cdot (y_1 + y_2) - z_2 - z_0$
  - In this case,  $T(n)$  would be given by:
  - $T(n) = 3T(n/2) + O(n)$
  - Thus,  $T(n) = \theta(n^{\log_2 3}) < \theta(n^2)$

# Example

- To compute the product of 1234 and 5678, choose  $B = 10$  and  $m = 2$ . Then
- $12\ 34 = 12 \times 10^2 + 34$
- $56\ 78 = 56 \times 10^2 + 78$
- $z_2 = 12 \times 56 = 672$
- $z_0 = 34 \times 78 = 2652$
- $z_1 = (12 + 34)(56 + 78) - z_2 - z_0$   
 $= 46 \times 134 - 672 - 2652 = 2840$
- $\text{result} = z_2 \times 10^{2 \times 2} + z_1 \times 10^2 + z_0$   
 $= 672 \times 10000 + 2840 \times 100 + 2652 = \mathbf{7006652}$

The background of the slide features a close-up, warm-toned photograph of mathematical tools. A large protractor is positioned at the top, with its curved edge and degree markings visible. Below it, a ruler with numerical markings lies diagonally. In the foreground, a red pencil is angled across the lower left. The entire scene is set against a background of graph paper with a grid pattern.

# MULTIPLICATION OF TWO MATRICES

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# Matrix Multiplication

- Suppose we wish to compute the matrix product  $C = AB$ , where  $A$  &  $B$  are  $n \times n$  matrices.
- Without loss of generality we can assume that  $n$  is an exact power of 2, since if it is not an exact power of 2, we can add zeros in the rows and columns of  $A$  &  $B$  to make it a power of 2.
- Assuming  $n$  to be an exact power of 2, we divide  $A$ ,  $B$  &  $C$  into 4  $n/2 \times n/2$  matrices, then the equation  $C = AB$  can be rewritten as follows:

$$\begin{pmatrix} r & s \\ t & u \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} e & g \\ f & h \end{pmatrix}$$

# Matrix Multiplications

- The matrix product equation corresponds to four equations:

$$r = ae + bf$$

$$s = ag + bh$$

$$t = ce + df$$

$$u = cg + dh$$

- Each of these equations gives rise to two multiplications of  $n/2 \times n/2$  matrices, in addition to 1 matrix addition (which is  $\Theta(n^2)$  operation.)
- Thus the recurrence relation for matrix multiplication is:  
$$T(n) = 8T(n/2) + \Theta(n^2)$$
- Solving by master method, we get  $T(n) = \Theta(n^3)$



# Strassen's Algorithm

- In Strassen's matrix multiplication algorithm 7 ( $n/2 \times n/2$ ) matrix multiplications are used, instead of 8, to reduce the time.
- We need to compute  $r, s, t, u$  such that
$$\begin{aligned}r &= ae + bf \\s &= ag + bh \\t &= ce + df \\u &= cg + dh\end{aligned}$$
- Let  $P1 = a(g - h) = ag - ah$
- $P2 = (a + b)h = ah + bh$
- Then  $s = P1 + P2$

# Strassen's Algorithm

- Let  $P3 = (c + d)e = ce + de$
- $P4 = d(f - e) = df - de$
- Thus  $t = P3 + P4$
- Now we have calculated  $s, t$  of the result matrix, we need to compute  $r = ae + bf$  &  $u = cg + dh$
- Let us look at the terms  $ae$  &  $dh$  first
- Let  $P5 = (a + d)(e + h) = ae + ah + de + dh$
- We are getting two terms  $ah$  &  $de$  in  $P5$ , which are not essential

# Strassen's Algorithm

- To cancel  $ah$  &  $de$ , we can use  $P4$  &  $P2$ , since  $P5 - P4 + P2 = ae + dh + df - bh$ . But two other inessential terms appear.
- Let  $P6 = (b - d)(f + h)$
- Then  $r = P5 - P4 + P2 + P6$
- Similarly, if we cancel the inessential terms in  $P5$  by using  $P1$  &  $P3$ , such that  $P5 + P1 - P3 = ae + ag - ce + dh$ , we get two other inessential terms.
- Let  $P7 = (a - c)(e + g)$
- Then  $u = P5 + P1 - P3 - P7$
- Since we are using 7 matrix products, Strassen's algorithm runs in  $\theta(n^{\log_2 7})$  time.

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# MULTIPLICATION OF A CHAIN OF MATRICES

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# Matrix Chain Multiplication

- Let us suppose that we are given a chain of  $n$  matrices  $A_1, A_2, \dots, A_n$  and we have to calculate the matrix product  $P$ , such that  $P = A_1 A_2 \dots A_n$
- We know that multiplication of 2  $(n \times n)$  matrices takes  $\Theta(n^3)$  time.
- Thus if two matrices  $A$  &  $B$  of dimensions  $(p \times q)$  and  $(q \times r)$  would require  $p \cdot q \cdot r$  scalar multiplications.
- Our intension is to multiply  $n$  matrices  $A_1, A_2, \dots, A_n$  to find their product  $P$ , such that the number of scalar multiplications are minimum.

# Matrix Multiplication is Associative

- Suppose A, B & C are 3 matrices, then their product P can be calculated as  $P = (A.B).C = A.(B.C)$
- That is, multiplying A with B first and then multiplying their product with C gives the same result as multiplying B with C first and then multiplying their product with A.
- But the way we parenthesize this operation has a big impact on the number of scalar multiplications required to compute the product.

# Calculating the number of scalar multiplications

- Suppose the dimensions of A, B & C are given as  $(1 \times 2)$ ,  $(2 \times 5)$  &  $(5 \times 1)$  respectively.
- If we find their product as  $(A.B).C$  then the number of scalar multiplications needed are  $1.2.5 + 1.5.1 = 15$
- If we find their product as  $A.(B.C)$  then the number of scalar multiplications needed are  $2.5.1 + 1.2.1 = 12$
- Thus we observe that parenthesizing the matrices as  $A.(B.C)$  evaluates their product with less scalar multiplications.



# Problem Statement

- The matrix chain multiplication problem can be restated as follows:
- Given  $n$  matrices  $A_1, A_2, \dots, A_n$  of dimensions  $(p_0 \times p_1), (p_1 \times p_2), \dots, (p_{n-1} \times p_n)$  respectively, we have to fully parenthesize the product  $P = A_1 A_2 \dots A_n$  in such a way that it minimizes the number of scalar multiplications.

# The structure of optimal solution

- Let  $A_{i,j}$  denote the matrix product  $A_i A_{i+1} \dots A_j$
- Let us suppose that there is an integer  $k$ , such that if we parenthesize the product  $A_{i,j}$  as  $(A_i A_{i+1} \dots A_k) \cdot (A_{k+1} \dots A_j)$  the number of scalar multiplications are minimum.
- Clearly to compute  $A_{i,j}$  one has to compute the product matrices  $A_{i,k} = (A_i A_{i+1} \dots A_k)$  and  $A_{k+1,j} = (A_{k+1} \dots A_j)$  and then multiply them.
- Since the dimension of  $A_i$  is  $(p_{i-1} \times p_i)$  the dimensions of  $A_{i,k}$  &  $A_{k+1,j}$  would be  $(p_{i-1} \times p_k)$  and  $(p_k \times p_j)$  respectively.
- Hence multiplication of  $A_{i,k}$  &  $A_{k+1,j}$  would require  $p_{i-1} p_k p_j$  scalar multiplications.

# A recursive solution

- Let  $m(i, j)$  be the optimal cost for multiplying matrices  $A_i A_{i+1} \dots A_j$  i.e. computing  $A_{i,j}$
- Since computation of  $A_{i,j}$  requires computation of  $A_{i,k}$  &  $A_{k+1,j}$  and then  $p_{i-1} p_k p_j$  scalar multiplications for evaluating their product, we have:
- $m(i, j) = m(i, k) + m(k + 1, j) + p_{i-1} p_k p_j$
- Clearly  $m(i, i) = 0$  &  $m(i, i + 1) = p_{i-1} p_i p_{i+1}$
- The above recurrence relation assumes that we know the value of  $k$ , which we do not, hence we need to check it for all possible values of  $k$ , where  $i \leq k < j$

# Example

- Find the least number of scalar multiplications to compute the product of the following chain of matrices:  $A_{(1 \times 2)}$ ,  $B_{(2 \times 5)}$ ,  $C_{(5 \times 10)}$ ,  $D_{(10 \times 1)}$

- Solution:

We need to compute  $m(1, 4)$ , which is given by:

$$m(1, 4) = \min \left\{ \begin{array}{l} m(1, 1) + m(2, 4) + 1.2.1 \\ m(1, 2) + m(3, 4) + 1.5.1 \\ m(1, 3) + m(4, 4) + 1.10.1 \end{array} \right\}$$

$$m(1, 1) = m(4, 4) = 0$$

$$m(1, 2) = 1.2.5 = 10 \text{ \& } m(3, 4) = 5.10.1 = 50$$

# Example

$$\begin{aligned} m(1, 3) &= \min \begin{Bmatrix} m(1, 1) + m(2, 3) + 1.2.10 \\ m(1, 2) + m(3, 3) + 1.5.10 \end{Bmatrix} \\ &= \min \begin{Bmatrix} 0 + 2.5.10 + 1.2.10 \\ 1.2.5 + 0 + 1.5.10 \end{Bmatrix} = 60 \end{aligned}$$

$$\begin{aligned} m(2, 4) &= \min \begin{Bmatrix} m(2, 2) + m(3, 4) + 2.5.1 \\ m(2, 3) + m(3, 4) + 2.10.1 \end{Bmatrix} \\ &= \min \begin{Bmatrix} 0 + 5.10.1 + 2.5.1 \\ 1.2.10 + 0 + 2.10.1 \end{Bmatrix} = 40 \end{aligned}$$

$$\text{Thus } m(1, 4) = \min \begin{Bmatrix} 0 + 40 + 2 \\ 10 + 50 + 5 \\ 60 + 0 + 10 \end{Bmatrix} = 42$$

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# Polynomial Multiplication Techniques

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# Polynomials

- A *polynomial in the variable  $x$  over an algebraic field  $F$*  is a representation of  $A(x)$  as a formal sum:

$$A(x) = \sum_{j=0}^{n-1} a_j x^j$$

- We call the values  $a_0, a_1, \dots, a_{n-1}$  the *coefficients* of the polynomial.



# Polynomials

- A polynomial  $A(x)$  is said to have **degree**  $k$  if its highest non-zero coefficient is  $a_k$
- For example: degree of  $2x^3 + 3x + 5$  is 3
- Any integer strictly greater than the degree of a polynomial is a **degree-bound** of that polynomial.
- For example: degree bound of  $2x^3 + 3x + 5$  is 4

# Polynomial Operations: Addition

- if  $A(x)$  and  $B(x)$  are polynomials of degree-bound  $n$ , we say that their **sum** is a polynomial  $C(x)$ , also of degree-bound  $n$ , such that  $C(x) = A(x) + B(x)$  for all  $x$  in the underlying field. That is:  
if  $A(x) = \sum_{j=0}^{n-1} a_j x^j$  and  $B(x) = \sum_{j=0}^{n-1} b_j x^j$  then  $C(x) = \sum_{j=0}^{n-1} c_j x^j$
- where  $c_j = a_j + b_j$  for  $j = 0, 1, \dots, n - 1$ .
- For example, if we have the polynomials
- $A(x) = 6x^3 + 7x^2 - 10x + 9$  and
- $B(x) = -2x^3 + 4x - 5$ , then
- $C(x) = 4x^3 + 7x^2 - 6x + 4$ .

# Polynomial Operations: Multiplication

- *if  $A(x)$  and  $B(x)$  are polynomials of degree-bound  $n$ , we say that their product  $C(x)$  is a polynomial of degree-bound  $2n - 1$  such that  $C(x) = A(x) B(x)$  for all  $x$  in the underlying field.*
- *We can multiply polynomials by multiplying each term in  $A(x)$  by each term in  $B(x)$  and combining terms with equal powers.*

# Polynomial Operations: Multiplication

- *For example, we can multiply*
- $A(x) = 6x^3 + 7x^2 - 10x + 9$  and
- $B(x) = -2x^3 + 4x - 5$
- *as follows:*

$$\begin{array}{r} 6x^3 + 7x^2 - 10x + 9 \\ - 2x^3 \qquad \qquad + 4x - 5 \\ \hline - 30x^3 - 35x^2 + 50x - 45 \\ 24x^4 + 28x^3 - 40x^2 + 36x \\ - 12x^6 - 14x^5 + 20x^4 - 18x^3 \\ \hline - 12x^6 - 14x^5 + 44x^4 - 20x^3 - 75x^2 + 86x - 45 \end{array}$$

We have,  $C(x) = \sum_{j=0}^{2n-2} c_j x^j$  where  $c_j = \sum_{k=0}^j a_k b_{j-k}$

# Polynomial Representation

- Coefficient Representation

- *A **coefficient representation** of a polynomial  $A(x)$  of degree-bound  $n$  is a vector of coefficients  $a = (a_0, a_1, \dots, a_{n-1})$ .*
- *For example: if  $A(x) = 2x^2 + 3x + 4$  then  $(4, 3, 2)$  is a coefficient representation of  $A(x)$*
- *the operation of **evaluating** the polynomial  $A(x)$  at a given point  $x_0$  consists of computing the value of  $A(x_0)$ . **Evaluation** takes time  $\Theta(n)$  using Horner's rule:*
- $$A(x_0) = a_0 + x_0(a_1 + x_0(a_2 + \dots + x_0(a_{n-2} + x_0(a_{n-1}))) \dots)$$
- *For example: evaluation of  $A(x)$  at  $x = 5$  is given by*
- $$A(5) = 4 + 5(3 + 5(2)) = 69$$

# Polynomial Representation

- Point-value Representation

- *A point-value representation of a polynomial  $A(x)$  of degree-bound  $n$  is a set of  $n$  point-value pairs  $\{(x_0, y_0), (x_1, y_1), \dots, (x_{n-1}, y_{n-1})\}$ , such that all the  $x_k$  are distinct and  $y_k = A(x_k)$*
- *For example: if  $A(x) = 2x^2 + 3x + 4$  then  $\{(0, 4), (1, 9), (2, 18)\}$  is a point-value representation of  $A(x)$ .*
- *Given a coefficient form of a polynomial the point-value form can be computed using Horner's method, by evaluating  $A(x_k)$  for  $k = 0, 1, \dots, n-1$ . This  $n$ -point evaluation takes  $\Theta(n^2)$  time*
- *The process of determining the coefficient form of a polynomial, given the point-value representation is called **interpolation**.*

# Lagrange's Interpolation Formula

- Given  $n$  points  $(x_k, y_k)$ , the coefficients of the unique polynomial is obtained using Lagrange's formula:

$$A(x) = \sum_{k=0}^{n-1} y_k \frac{\prod_{j \neq k} (x - x_j)}{\prod_{j \neq k} (x_k - x_j)}$$

- For example: if  $\{(0, 4), (1, 9), (2, 18)\}$  is the input:

$$A(x) = \frac{(x-1)(x-2)}{(0-1)(0-2)} 4 + \frac{(x-0)(x-2)}{(1-0)(1-2)} 9 + \frac{(x-0)(x-1)}{(2-0)(2-1)} 18$$

$$\text{or, } A(x) = 2(x^2 - 3x + 2) - 9(x^2 - 2x) + 9(x^2 - x)$$

$$\text{or, } A(x) = 2x^2 + 3x + 4$$



# Lagrange's Interpolation Formula

- Exercise:
- *Find the coefficient form of the polynomial given the point-value form  $\{(0,5), (1, 10), (2, 21)\}$*
- Note:
- *Given the point-value form we can get the coefficient form of the polynomial in  $\Theta(n^2)$  time, where  $n$  is the degree bound of the polynomial.*

# Polynomial Multiplication

- *Let  $A(x)$  and  $B(x)$  be two polynomials represented in coefficient form. Computing their product  $C(x)$  takes  $\Theta(n^2)$  time, since the computation involves multiplication of each coefficient  $a$  of  $A$  with each coefficient  $b$  of  $B$ .*
- *Let  $A(x) = \{(x_0, y_0), (x_1, y_1), \dots, (x_{2n-1}, y_{2n-1})\}$  and  $B(x) = \{(x_0, \acute{y}_0), (x_1, \acute{y}_1), \dots, (x_{2n-1}, \acute{y}_{2n-1})\}$  be two polynomials represented in point-value form. Computing their product  $C(x)$  takes  $\Theta(n)$  time, where  $C(x) = \{(x_0, y_0 \acute{y}_0), (x_1, y_1 \acute{y}_1), \dots, (x_{2n-1}, y_{2n-1} \acute{y}_{2n-1})\}$*

# Polynomial Multiplication



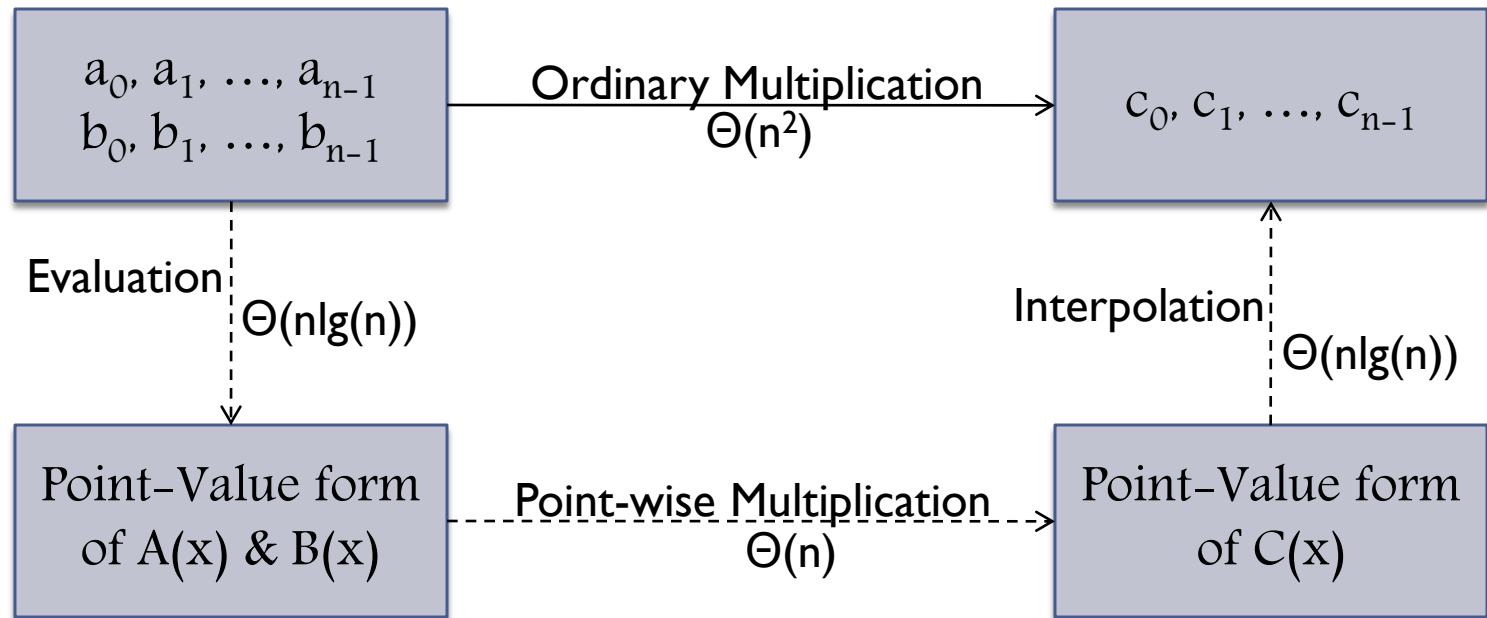
*Can we use the linear-time multiplication method for polynomials in point-value form to expedite polynomial multiplication in coefficient form?*

*The answer hinges on our ability to convert a polynomial quickly from coefficient form to point-value form (evaluate) and vice-versa (interpolate).*



# Polynomial Multiplication

- While converting from coefficient to point-value form we can use any points we want as evaluation points, but by choosing the evaluation points *wisely*, we can convert between representations in only  $\Theta(n \lg(n))$  time.



# Complex Roots of Unity

- *We will show that if we use the complex roots of unity, then we can evaluate and interpolate polynomials in  $\Theta(n \lg(n))$  time.*
- *A complex  $n$ th root of unity is a complex number  $\omega$  such that:  $\omega^n = 1$*
- *There are exactly  $n$  complex  $n$ th roots of unity, given by  $e^{2\pi i k/n}$  for  $k = 0, 1, \dots, n-1$ , where  $i = \sqrt{-1}$*
- *$\omega_n = e^{2\pi i/n}$  is the principal  $n$ th root of unity.*
- *The other complex  $n$ th roots of unity are powers of  $\omega_n$ , given by  $\omega_n^0, \omega_n^1, \dots, \omega_n^{n-1}$*

# Properties of Complex Roots of Unity

1.  $(\omega_n^k)^2 = \omega_{n/2}^k$

•  $\omega_{n/2}^k = e^{2\pi i k / (n/2)} = e^{4\pi i k / n} = (\omega_n^k)^2$

2.  $(\omega_n^k)^2 = (\omega_n^{k+n/2})^2$

•  $(\omega_n^{k+n/2})^2 = \omega_n^{2k+n} = \omega_n^{2k} \omega_n^n = \omega_n^{2k} = (\omega_n^k)^2$

3. *Summation Property:*  $\sum_{j=0}^{n-1} (\omega_n^k)^j = 0$

We know  $\sum_{k=0}^n x^k = 1 + x + x^2 + \dots + x^n$

is a geometric series and has the value:  $\sum_{k=0}^n x^k = \frac{x^{n+1} - 1}{x - 1}$

Thus,  $\sum_{j=0}^{n-1} (\omega_n^k)^j = \frac{(\omega_n^k)^n - 1}{\omega_n^k - 1} = \frac{(\omega_n^n)^k - 1}{\omega_n^k - 1} = \frac{(1)^k - 1}{\omega_n^k - 1} = 0$

# The DFT

- We wish to evaluate a polynomial  $A(x) = a_0 + a_1x + a_2x^2 + \dots + a_{n-1}x^{n-1}$  of degree-bound  $n$  at  $\omega_n^0, \omega_n^1, \dots, \omega_n^{n-1}$
- Without loss of generality we assume that  $n$  is a power of 2, since a given degree bound can always be raised by adding new high order zero coefficients as necessary.
- Let  $A$  be given in coefficient form  $a = (a_0, a_1, \dots, a_{n-1})$ .
- Let  $y_k$  be the results at  $k = 0, 1, \dots, n-1$ , i.e.

$$y_k = A(\omega_n^k) = \sum_{j=0}^{n-1} a_j \omega_n^{kj}$$

- The vector  $y = (y_0, y_1, \dots, y_{n-1})$  is called the **Discrete Fourier Transform (DFT)** of the coefficient vector  $a = (a_0, a_1, \dots, a_{n-1})$ . We write  $y = \text{DFT}_n(a)$



# The FFT

- *By using a method called the **Fast Fourier Transform (FFT)**, which takes advantage of the special properties of the complex roots of unity, we can compute  $DFT_n(a)$  in  $\Theta(n \lg(n))$  time.*
- *The FFT employs a divide & conquer strategy, using the even-index and odd-index coefficients of  $A(x)$  separately to define two new  $n/2$  degree-bound polynomials  $A^0(x)$  and  $A^1(x)$ .*
- $A^0(x) = a_0 + a_2x + a_4x^2 + \dots + a_{n-2}x^{n/2-1}$
- $A^1(x) = a_1 + a_3x + a_5x^2 + \dots + a_{n-1}x^{n/2-1}$
- *Thus  $A(x) = A^0(x^2) + x A^1(x^2)$*

# The FFT

- *So, the problem of evaluating  $A(x)$  at  $\omega_n^0, \omega_n^1, \dots, \omega_n^{n-1}$  now reduces to:*
  1. *Evaluating the  $n/2$  degree bound polynomials  $A^0(x)$  and  $A^1(x)$  at points  $(\omega_n^0)^2, (\omega_n^1)^2, \dots, (\omega_n^{n-1})^2$*
  2. *Then combining the results according to the equation  $A(x) = A^0(x^2) + x A^1(x^2)$*
- *Using the properties of complex roots of unity the list of values in step 1 consists not of  $n$ -distinct values but only of  $n/2$  complex  $(n/2)^{\text{th}}$  roots of unity.*

# The FFT

- Let us illustrate with an example that we need to evaluate  $A^0(x)$  and  $A^1(x)$  only at  $n/2$  points instead of  $n$  points.
  1. Say,  $n = 4$ , So we need to compute the polynomials at points  $(\omega_{40})^2, (\omega_{41})^2, (\omega_{42})^2, (\omega_{43})^2$
  2. As per the rule:  $(\omega_{nk})^2 = \omega_{n/2k}$ , we have  $(\omega_{40})^2 = (\omega_{20})$  and  $(\omega_{41})^2 = (\omega_{21})$
  3. As per the rule:  $(\omega_{nk})^2 = (\omega_{nk + n/2})^2$ , we have  $(\omega_{42})^2 = (\omega_{40+2})^2 = (\omega_{40})^2$  (here  $k = 0$ ) and  $(\omega_{43})^2 = (\omega_{41+2})^2 = (\omega_{41})^2$  (here  $k = 1$ )
  4. But as shown in step 2,  $(\omega_{40})^2 = (\omega_{20})$  and  $(\omega_{41})^2 = (\omega_{21})$
  5. Hence we need to evaluate  $A^0(x)$  and  $A^1(x)$  only at 2 points  $(\omega_{20})$  and  $(\omega_{21})$

# The FFT

- Let  $T(n)$  be the total time taken by the algorithm for evaluating the degree-bound  $n$  polynomial  $A(x)$  at  $n$  distinct points.
- Then as per our divide & conquer strategy we need to evaluate two degree-bound  $n/2$  polynomials  $A^0(x)$  and  $A^1(x)$  only at  $n/2$  points, each of which will take  $T(n/2)$  time.
- Then we have to combine the result using equation  $A(x) = A^0(x^2) + x A^1(x^2)$ , which requires polynomial addition and hence takes  $\Theta(n)$  time.
- So, we get a recurrence relation of the form:
- $T(n) = 2T(n/2) + \Theta(n)$
- Solving this using the master method we see that the time taken to evaluate the polynomial is  $\Theta(n \lg(n))$ .

# The FFT

- *So far, we have evaluated a polynomial using the  $n$  complex roots of unity as points of evaluation in  $\Theta(n \lg(n))$  time.*
- *Now we need to interpolate the complex roots of unity by a polynomial.*
- *If a polynomial  $A(x) = a_0 + a_1x + a_2x^2 + \dots + a_{n-1}x^{n-1}$  has the point value form  $\{(x_0, y_0), (x_1, y_1), \dots, (x_{n-1}, y_{n-1})\}$  then we can represent it in the matrix equation:*

$$\begin{pmatrix} 1 & x_0 & x_0^2 & \dots & x_0^{n-1} \\ 1 & x_1 & x_1^2 & \dots & x_1^{n-1} \\ \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots \\ 1 & x_{n-1} & x_{n-1}^2 & \dots & x_{n-1}^{n-1} \end{pmatrix} \begin{pmatrix} a_0 \\ a_1 \\ \dots \\ \dots \\ a_{n-1} \end{pmatrix} = \begin{pmatrix} y_0 \\ y_1 \\ \dots \\ \dots \\ y_{n-1} \end{pmatrix}$$

# The FFT

- In this case we have evaluated the polynomial  $A(x) = a_0 + a_1x + a_2x^2 + \dots + a_{n-1}x^{n-1}$  at points  $\omega_n^0, \omega_n^1, \dots, \omega_n^{n-1}$  so the point value form is  $\{(x_0, \omega_n^0), (x_1, \omega_n^1), \dots, (x_{n-1}, \omega_n^{n-1})\}$ , their relationship can be represented by the following matrix equation:

$$\begin{pmatrix} 1 & \omega_n^0 & (\omega_n^0)^2 & \dots & (\omega_n^0)^{n-1} \\ 1 & \omega_n^1 & (\omega_n^1)^2 & \dots & (\omega_n^1)^{n-1} \\ 1 & \omega_n^2 & (\omega_n^2)^2 & \dots & (\omega_n^2)^{n-1} \\ \dots & \dots & \dots & \dots & \dots \\ 1 & \omega_n^{n-1} & (\omega_n^{n-1})^2 & \dots & (\omega_n^{n-1})^{n-1} \end{pmatrix} \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ \dots \\ a_{n-1} \end{pmatrix} = \begin{pmatrix} y_0 \\ y_1 \\ y_2 \\ \dots \\ y_{n-1} \end{pmatrix}$$

- i.e.  $\mathbf{y} = V_n \mathbf{a}$ , where  $V_n$  is called the Vandermonde matrix containing the appropriate powers of  $\omega_n$
- The  $(k, j)$ th entry in  $V_n$  is  $\omega_n^{kj}$  for  $j, k = 0, 1, \dots, n-1$
- The coefficient vector  $\mathbf{a}$  can be obtained by  $\mathbf{a} = V_n^{-1} \mathbf{y}$

# The FFT

- *Theorem:*

- for  $j, k = 0, 1, \dots, n-1$  the  $(j, k)$  entry of  $V_n^{-1}$  is  $\omega_n^{-kj} / n$

- *Proof:*

- We will prove the theorem by showing that  $V_n^{-1} V_n = I_n$
- Where  $I_n$  is the  $n \times n$  identity matrix
- The  $(j, l)$  entry of  $V_n^{-1} V_n$  is given by:

$$[V_n^{-1} V_n]_{j,l} = \sum_{k=0}^{n-1} (\omega_n^{-kj} / n) (\omega_n^{kl}) = \sum_{k=0}^{n-1} \omega_n^{k(l-j)} / n$$

- The summation equals 1 if  $j = l$  and it is 0 otherwise by the summation property of  $\omega_n$  (refer to slide 15 for proof)
- Hence  $V_n^{-1} V_n = I_n$

# The FFT

- Given the inverse matrix  $V_n^{-1}$ ,  $a = DFT_n^{-1}(y)$  is given by:

$$a_j = \frac{1}{n} \sum_{k=0}^{n-1} y_k \omega_n^{-kj}$$

- Comparing this with the equation  $y = DFT_n(a)$ , i.e.

$$y_k = \sum_{j=0}^{n-1} a_j \omega_n^{kj}$$

- We see that by modifying the FFT algorithm to switch the roles of  $a$  and  $y$ , replacing  $\omega_n$  by  $\omega_n^{-1}$  and dividing each element of result by  $n$ , we can compute the inverse of DFT.
- Thus  $DFT_n^{-1}$  can be computed in  $\Theta(n \lg(n))$  time as well.



# The FFT

- *So, two polynomials  $A(x)$  and  $B(x)$  in coefficient form can be multiplied by:*
  1. *Evaluating them at  $n$  distinct points  $\omega_n^0, \omega_n^1, \dots, \omega_n^{n-1}$  in  $\Theta(\text{nlg}(n))$  time, where  $\omega_n$  is the principal complex  $n^{\text{th}}$  root of unity.*
  2. *Multiplying the results of step 1 (in point-value form) in  $\Theta(n)$  time, to get the product.*
  3. *Interpolating the product polynomial of step 2 to its coefficient form to get the desired output  $C(x) = A(x).B(x)$  in  $\Theta(\text{nlg}(n))$  time.*
- *Hence total time taken by the polynomial multiplication algorithm is  $\Theta(\text{nlg}(n)) + \Theta(n) + \Theta(\text{nlg}(n))$*
- *Which is  $\Theta(\text{nlg}(n))$ .*



*Thank You!!!*