

Assumptions:

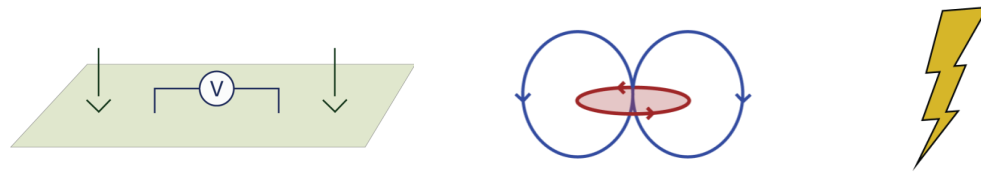
This course is for 3rd/4th year students in geoscience.

Basic background of physics are not preferred, but not required.

Apps developed by Jupyter Notebooks, Python and SimPEG are used, but strong software background is not required.



The Physics of Geophysical Prospecting Methods: Resistivity and Controlled Source vs Natural EM methods



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Stanford University

Learning goals

Understand electrical resistivity and its linkage to geologic units.

Understand physical principles of Electromagnetic (EM) methods

- Charge build-up (or current channeling, galvanic currents)
- EM induction

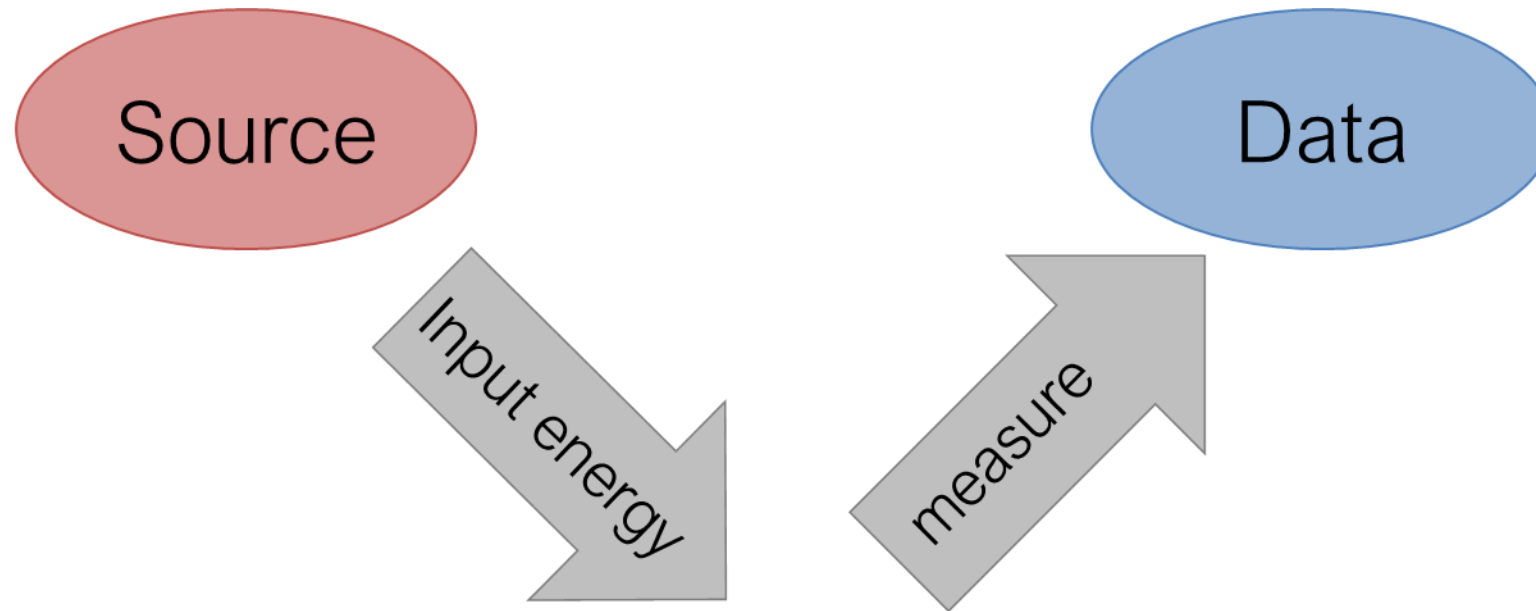
Identify difference between controlled-source EM and magnetotellurics (MT)

Identify all EM methods are governed by the same physical principles

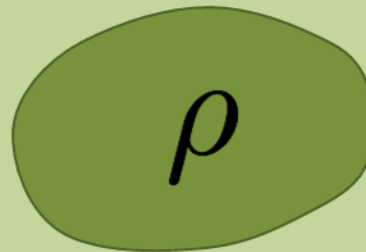
Understand survey setup of EM methods and data

Understand sensitivity of EM methods to conductors & resistors

Electromagnetic (EM) survey



10s of m to 100s of km

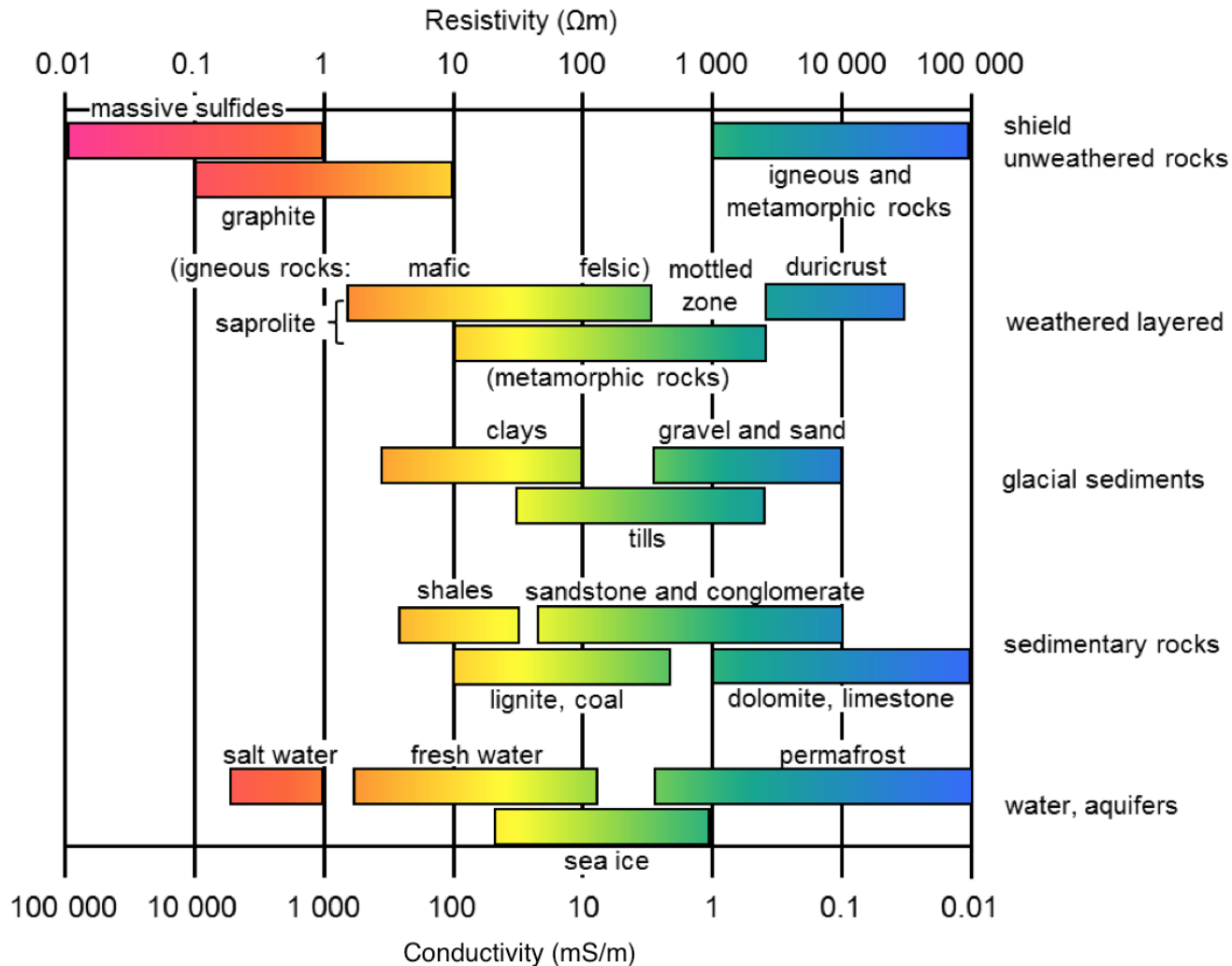


$$\rho = 1/\sigma$$

ρ : resistivity

σ : electrical conductivity

Electrical resistivity (or conductivity)



DC resistivity is sensitive to:

- σ : Conductivity [S/m]
- ρ : Resistivity [Ωm]
- $\sigma = 1/\rho$

Varies over many orders of magnitude

Depends on many factors:

- Rock type
- Porosity
- Connectivity of pores
- Nature of the fluid
- Metallic content of the solid matrix

Electrical resistivity can be a diagnostic physical property for ...



minerals



contaminants



water



geothermal



geotechnical



slope stability

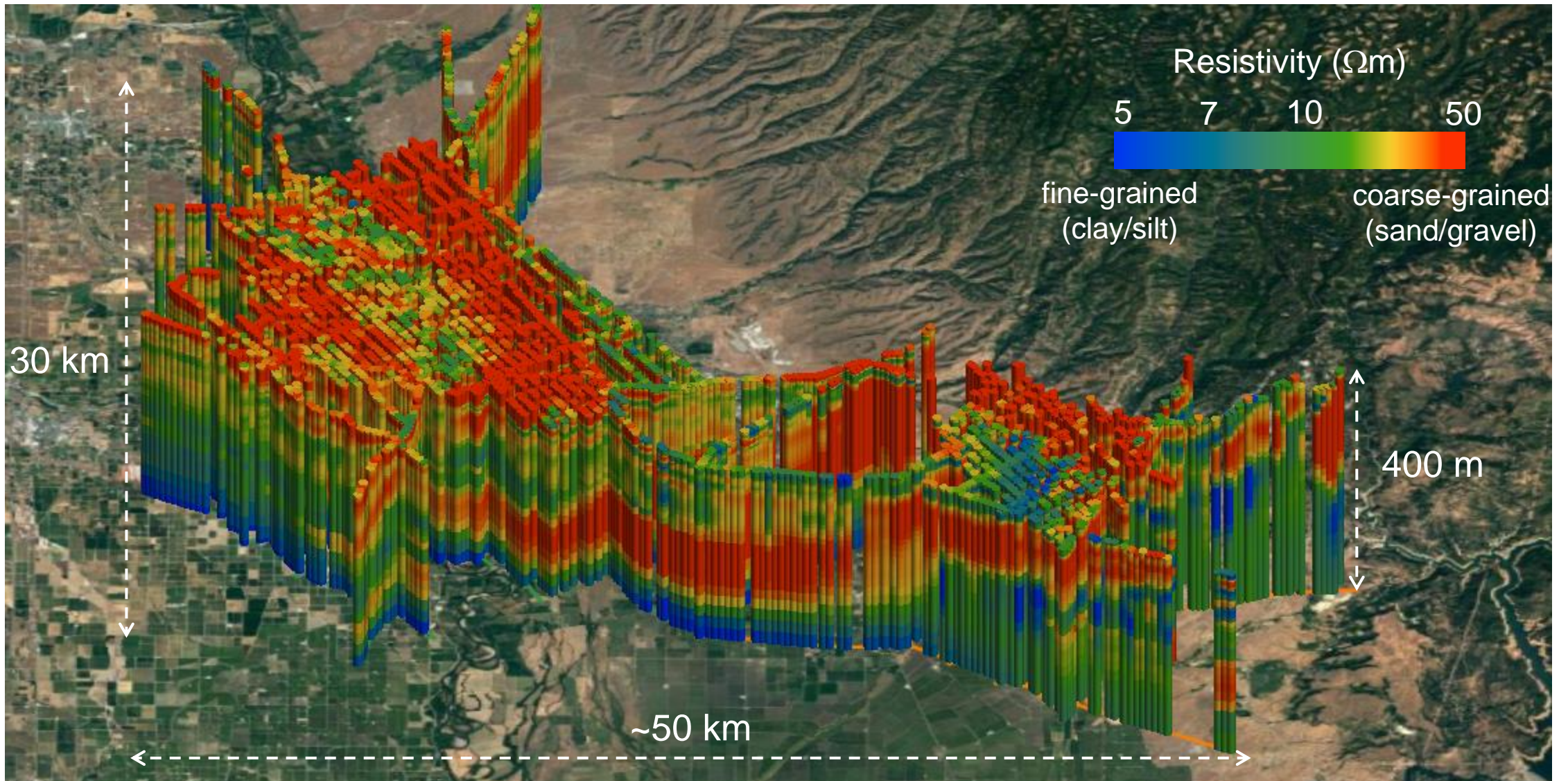


hydrocarbons

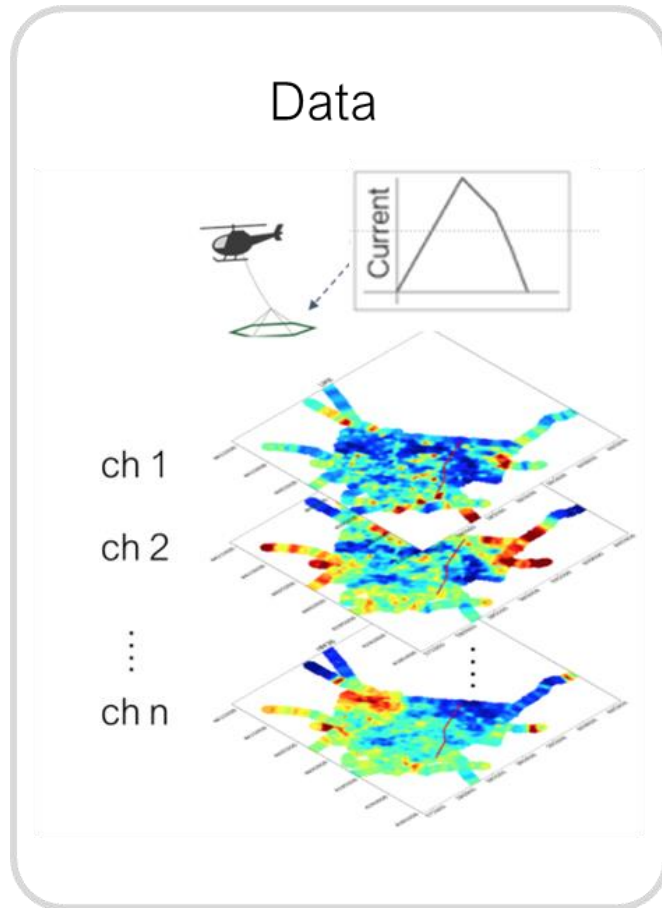


unexploded ordnance

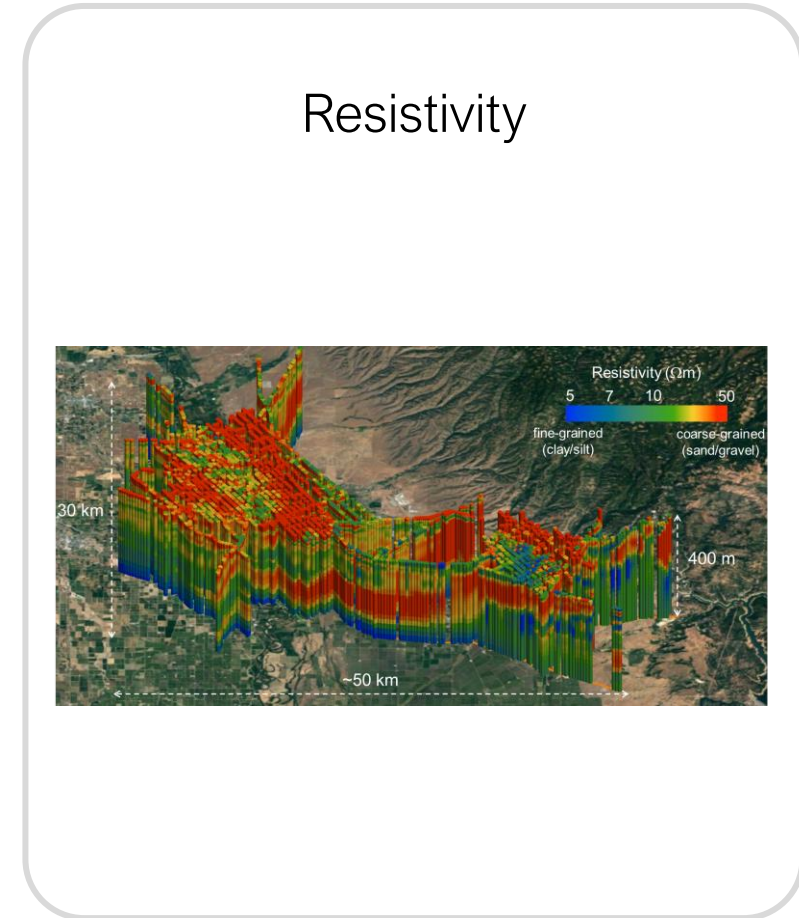
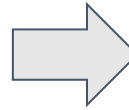
3D resistivity model from an airborne EM survey



EM imaging – inverse problem



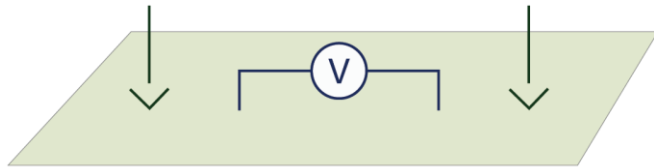
Inversion



There are many models that can fit the data – non-uniqueness
CRITICAL to understand underlying physics

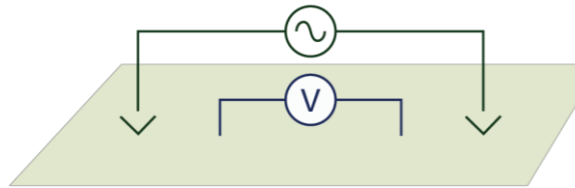
Resistivity, Controlled-source EM, and Magnetotellurics

Direct Current resistivity

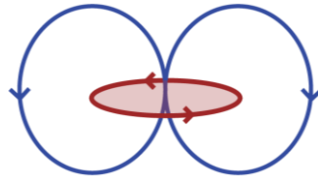


Controlled-source EM

Grounded source



Inductive source



Magnetotellurics



Depth range

meters

hundreds of km

Electromagnetics: basic equations (quasi-static)

	Time	Frequency
Faraday's Law	$\nabla \times \vec{e} = -\frac{\partial \vec{b}}{\partial t}$	$\nabla \times \vec{E} = -i\omega \vec{B}$
Ampere's Law	$\nabla \times \vec{h} = \vec{j} + \frac{\partial \vec{d}}{\partial t}$	$\nabla \times \vec{H} = \vec{J} + i\omega \vec{D}$
No Magnetic Monopoles	$\nabla \cdot \vec{b} = 0$	$\nabla \cdot \vec{B} = 0$
Constitutive Relationships (non-dispersive)	$\vec{j} = \sigma \vec{e}$ $\vec{b} = \mu \vec{h}$ $\vec{d} = \epsilon \vec{e}$	$\vec{J} = \sigma \vec{E}$ $\vec{B} = \mu \vec{H}$ $\vec{D} = \epsilon \vec{E}$

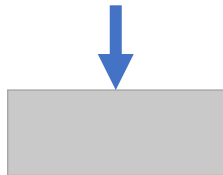
Steady-state Maxwell's equations – DC resistivity method

	Full	Steady State
Faraday	$\nabla \times \vec{e} = -\frac{\partial \vec{b}}{\partial t}$	$\nabla \times \vec{e} = 0 \quad \vec{e} = -\nabla V$
Ampere	$\nabla \times \vec{h} = \vec{j} + \frac{\partial \vec{d}}{\partial t} + \vec{j}_s$	$\nabla \cdot \vec{j} = -\nabla \cdot \vec{j}_s$
Ohm's Law	$\vec{j} = \sigma \vec{e}$	

Put it together

$$\nabla \cdot \sigma \nabla V = I \delta(r)$$

Potential in a
homogeneous halfspace



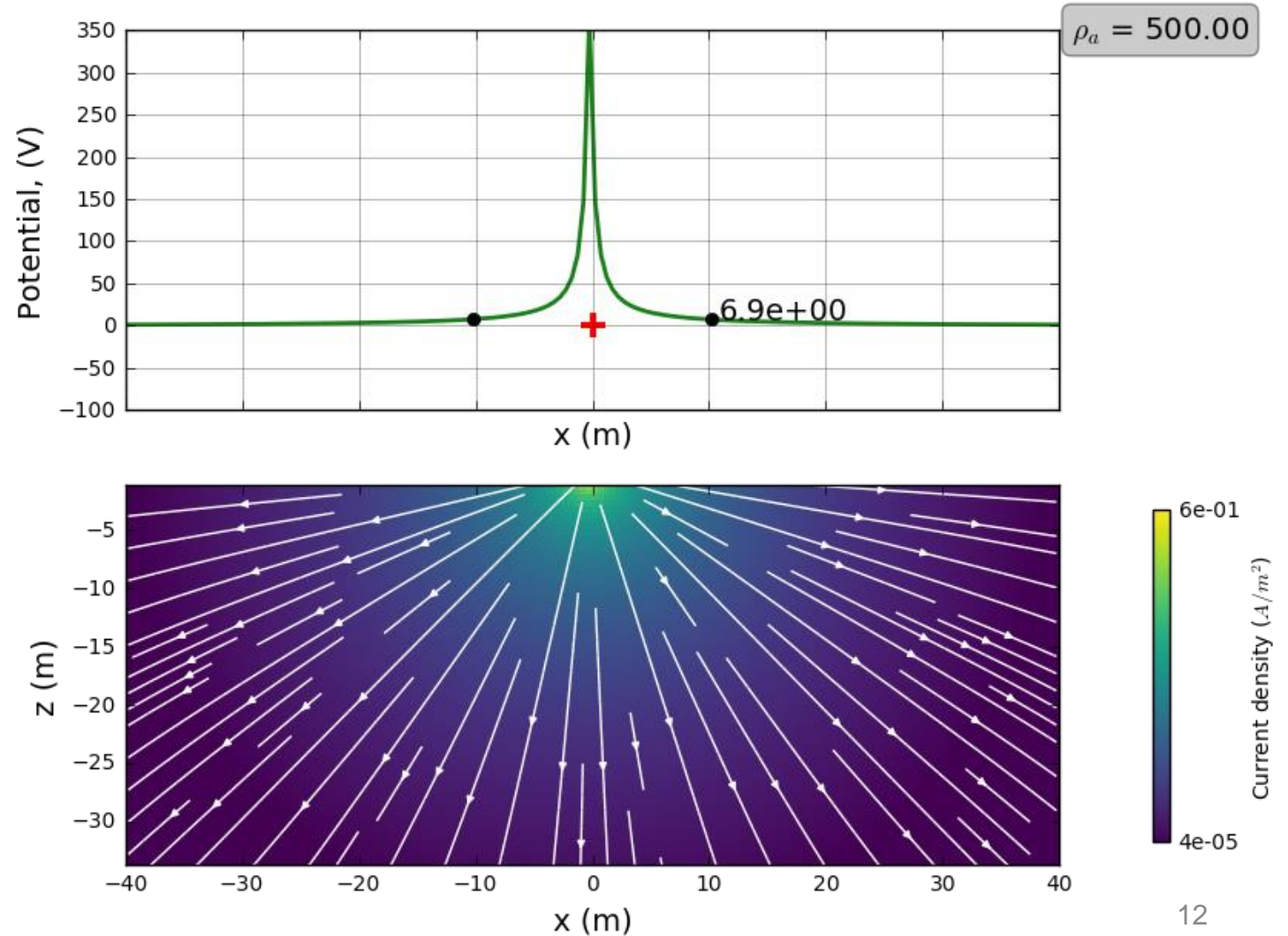
$$V = \frac{I}{2\pi\sigma} \frac{1}{r}$$

$$V = \frac{\rho I}{2\pi r}$$

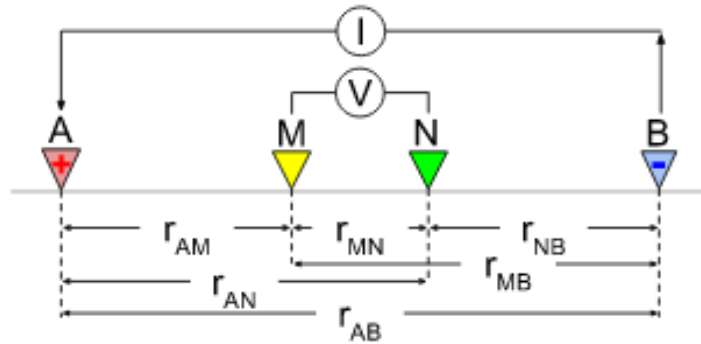
Currents and potentials: halfspace

$$V = \frac{\rho I}{2\pi r}$$

$$\rho = \frac{2\pi r V}{I}$$



Currents and potentials: 4-electrode array



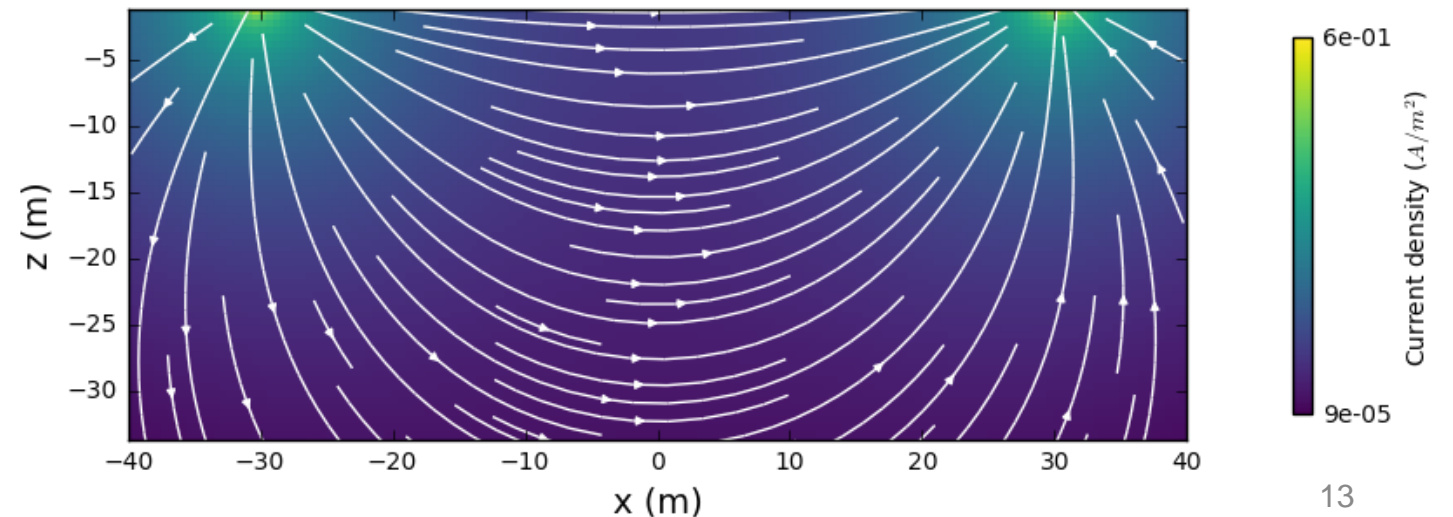
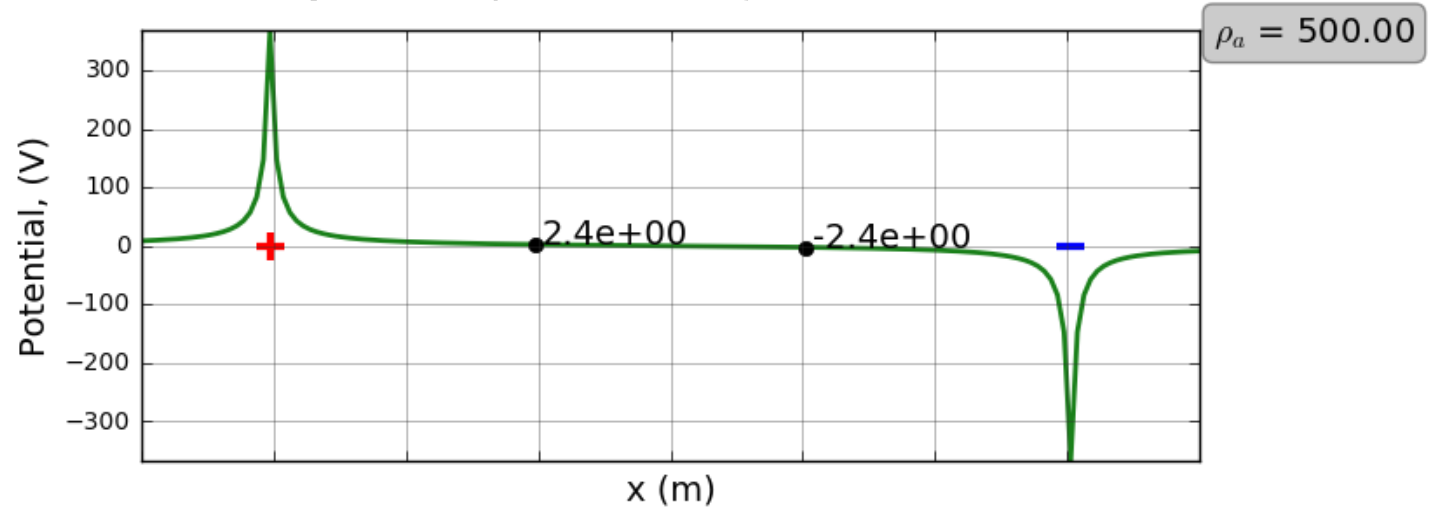
$$\Delta V_{MN} = \rho I \underbrace{\frac{1}{2\pi} \left[\frac{1}{AM} - \frac{1}{MB} - \frac{1}{AN} + \frac{1}{NB} \right]}_G$$

Resistivity

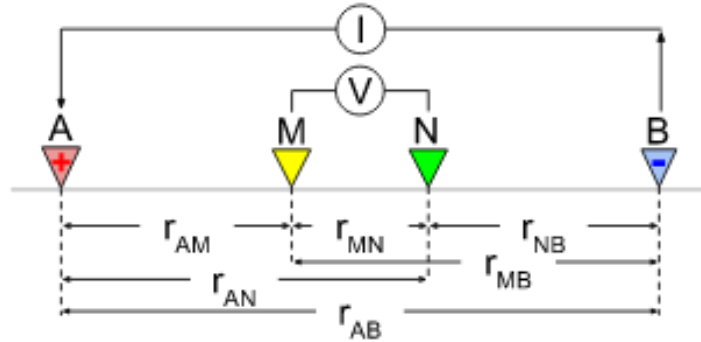
$$\rho = \frac{\Delta V_{MN}}{IG}$$

G: geometric factor

Halfspace ($500 \Omega m$)



Currents and Apparent resistivity



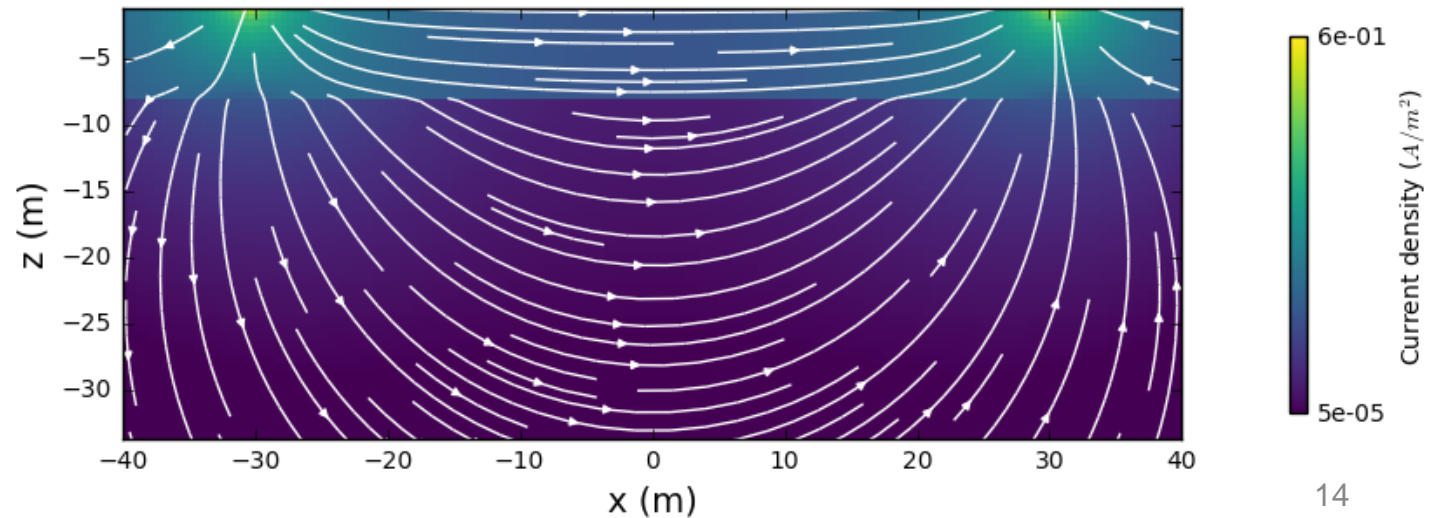
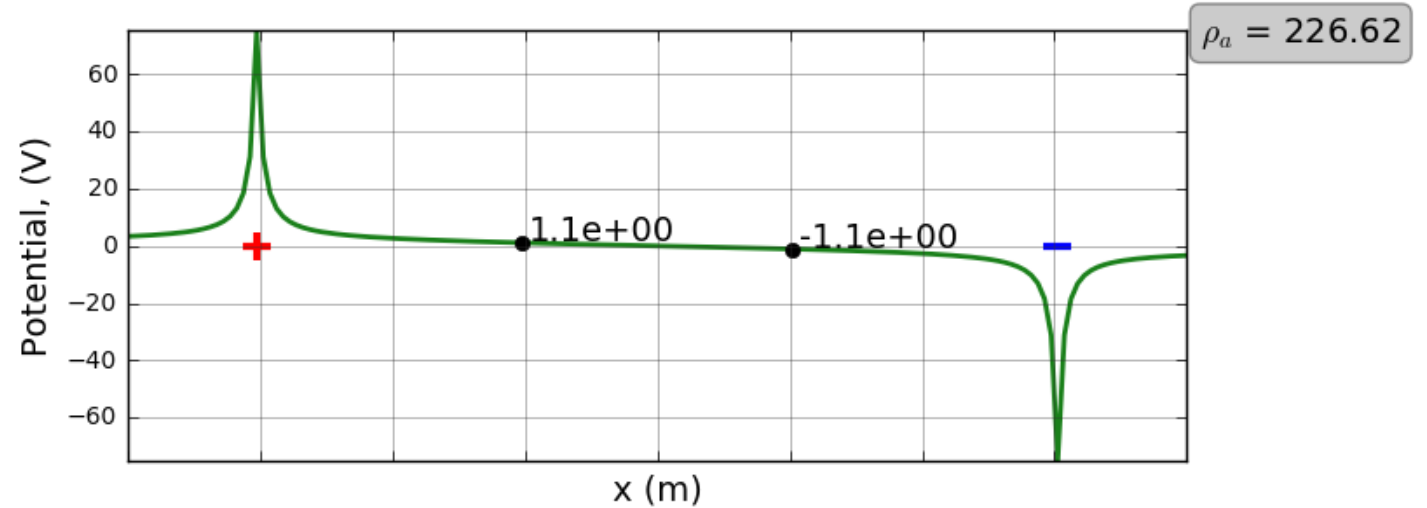
$$\Delta V_{MN} = \rho I \underbrace{\frac{1}{2\pi} \left[\frac{1}{AM} - \frac{1}{MB} - \frac{1}{AN} + \frac{1}{NB} \right]}_G$$

Apparent resistivity

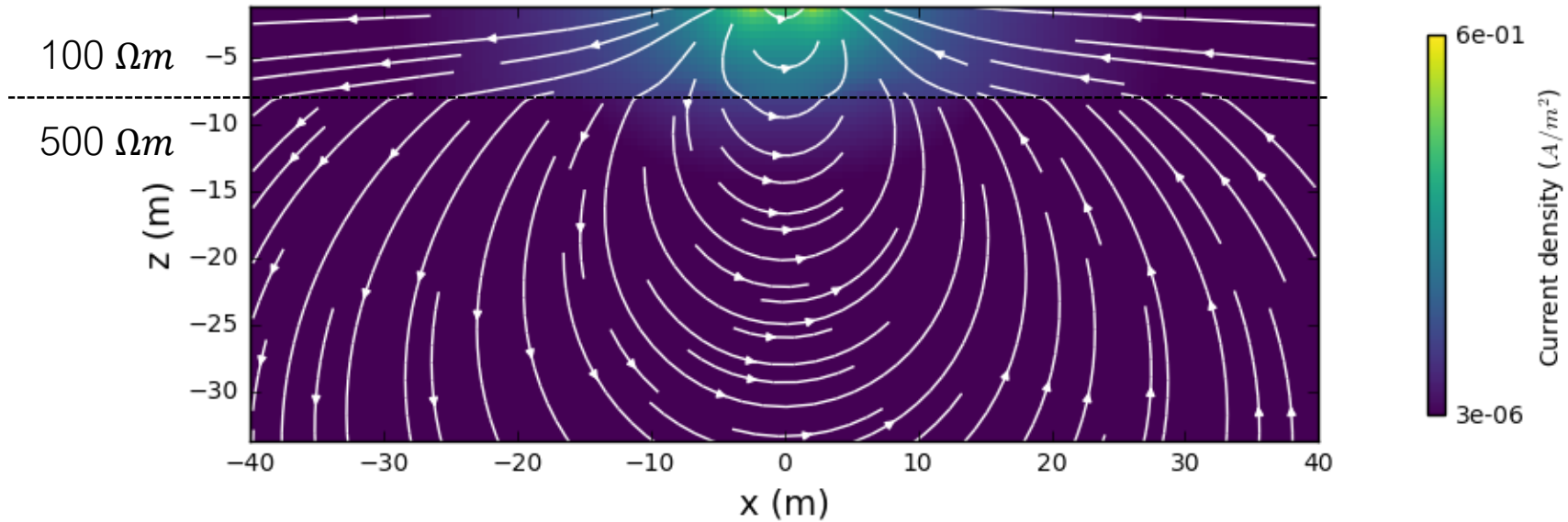
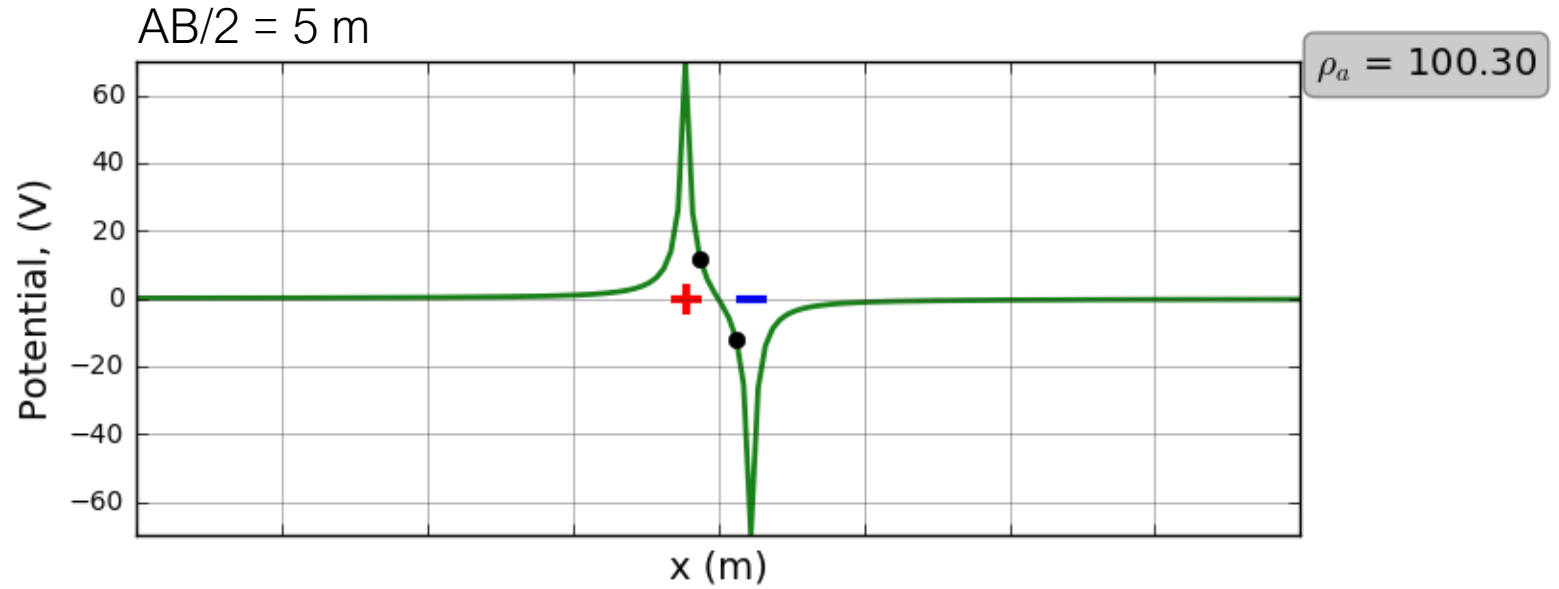
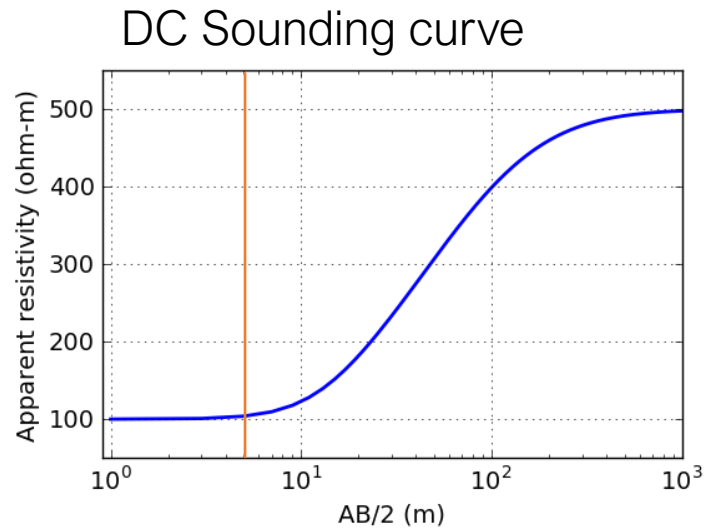
$$\rho_a = \frac{\Delta V_{MN}}{IG}$$

G: geometric factor

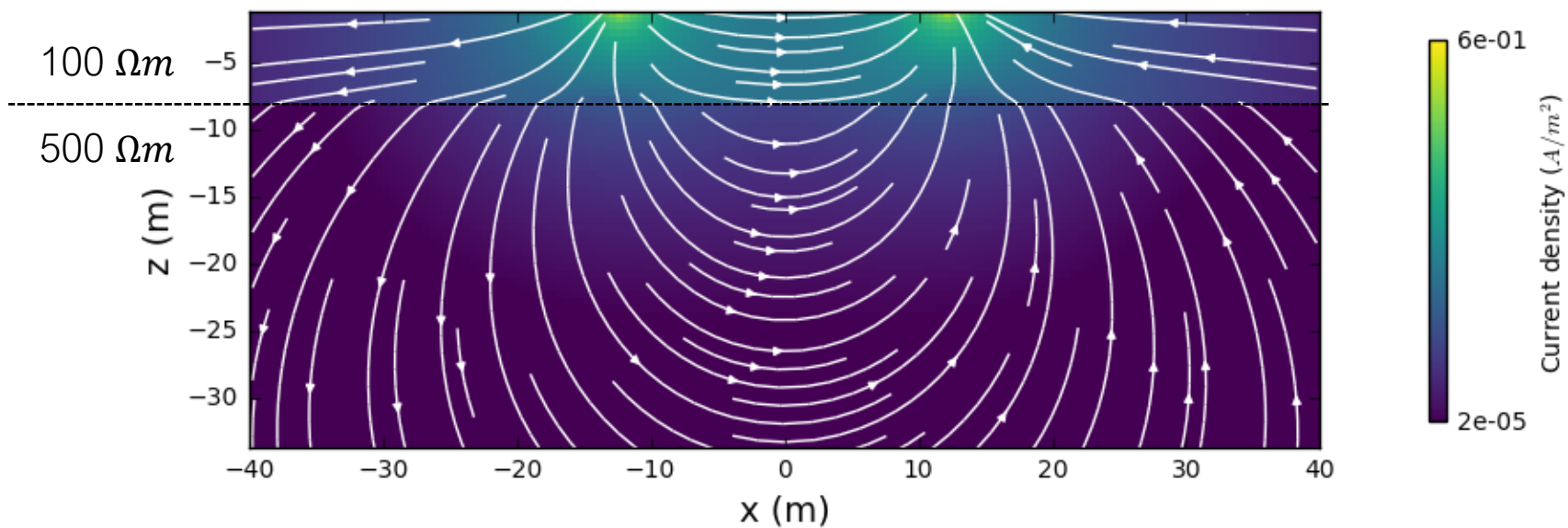
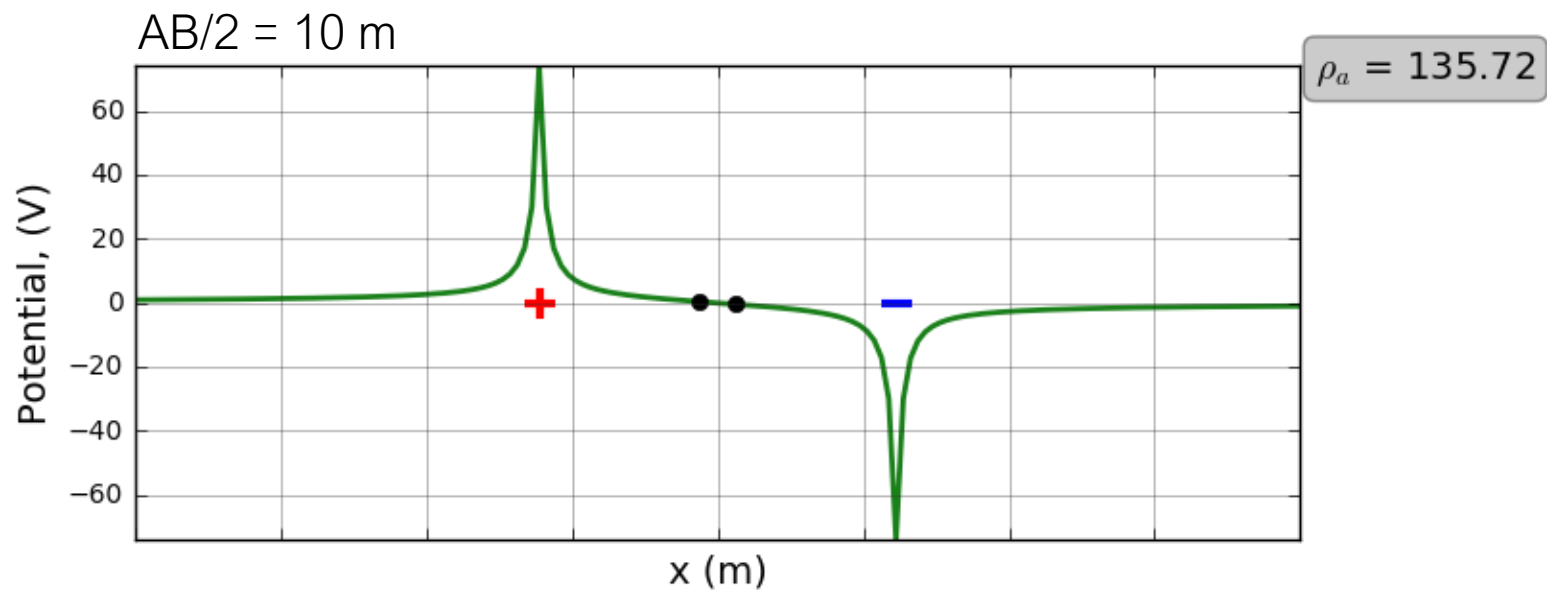
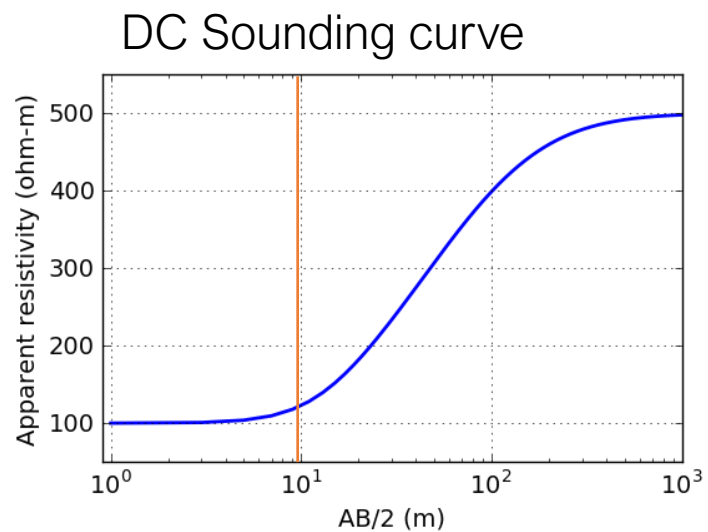
Conductive overburden ($100 \Omega m$)



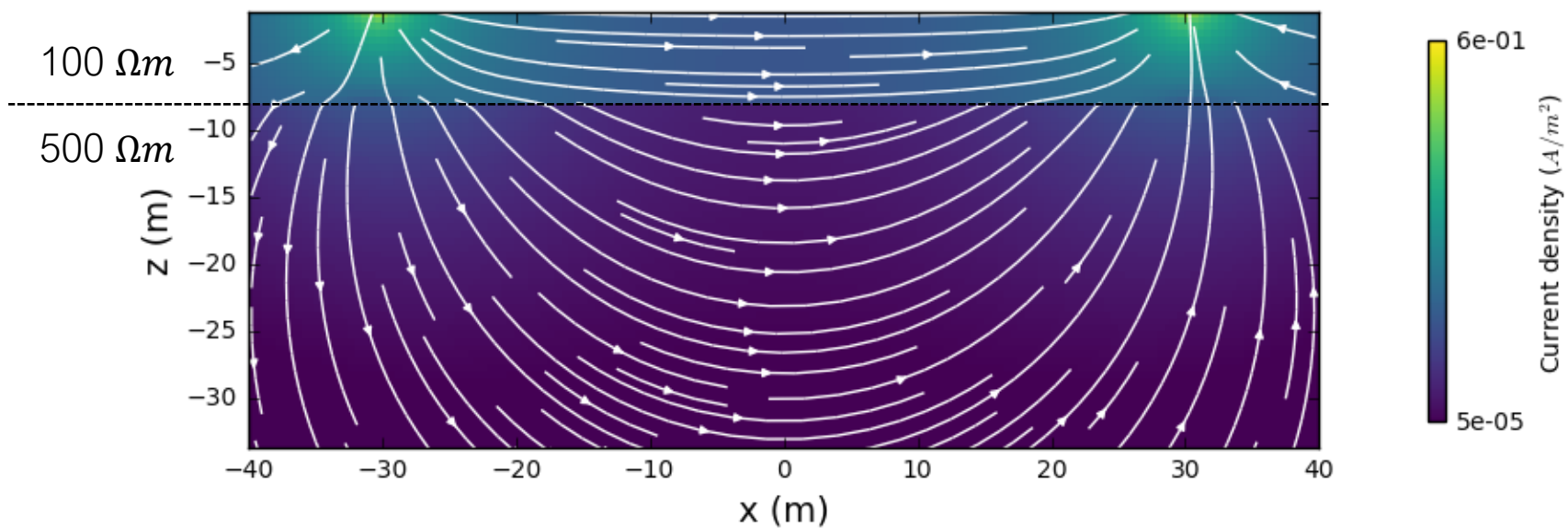
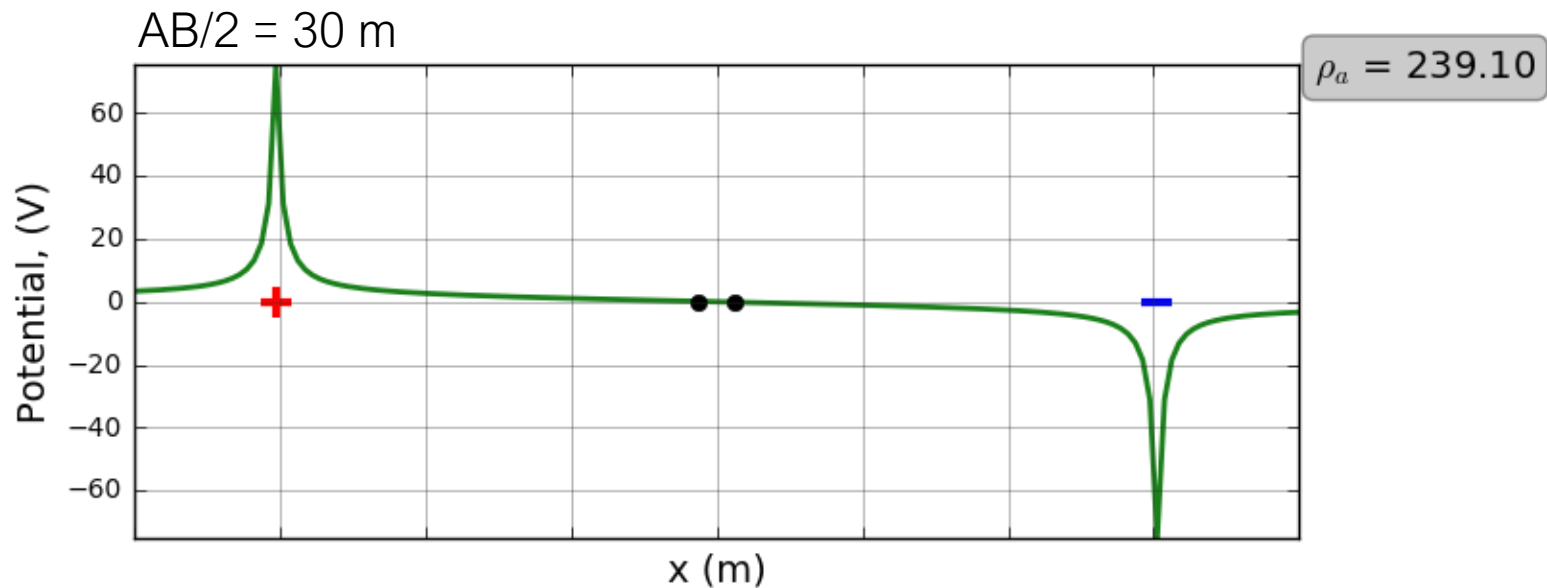
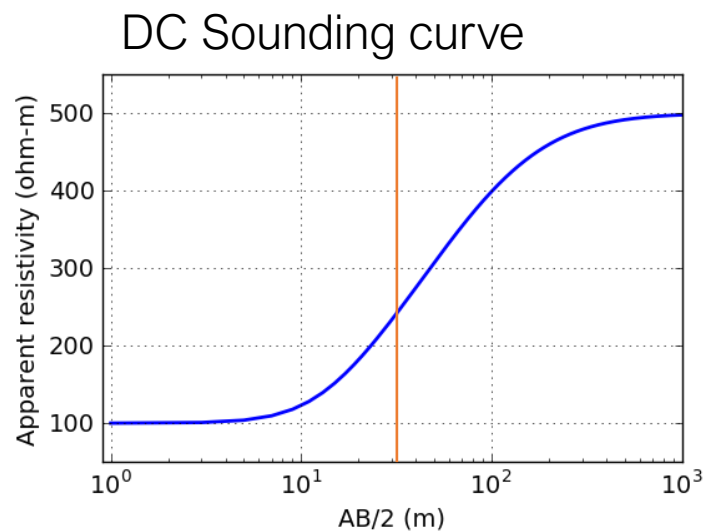
Geometric sounding



Geometric sounding



Geometric sounding



Concept of charges

Normal component of current density is continuous

$$J_{1n} = J_{2n}$$
$$\sigma_1 E_{1n} = \sigma_2 E_{2n}$$

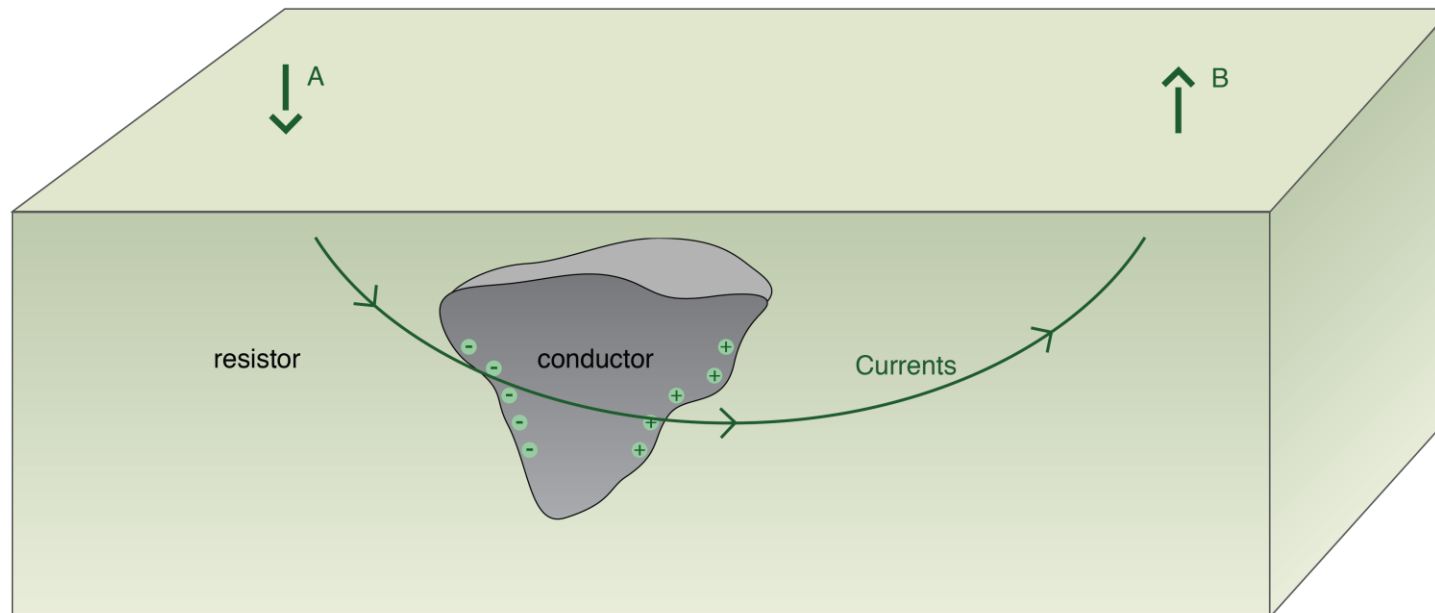
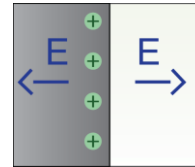
Conductivity contrast

$$\sigma_1 \neq \sigma_2$$

Electric field discontinuous

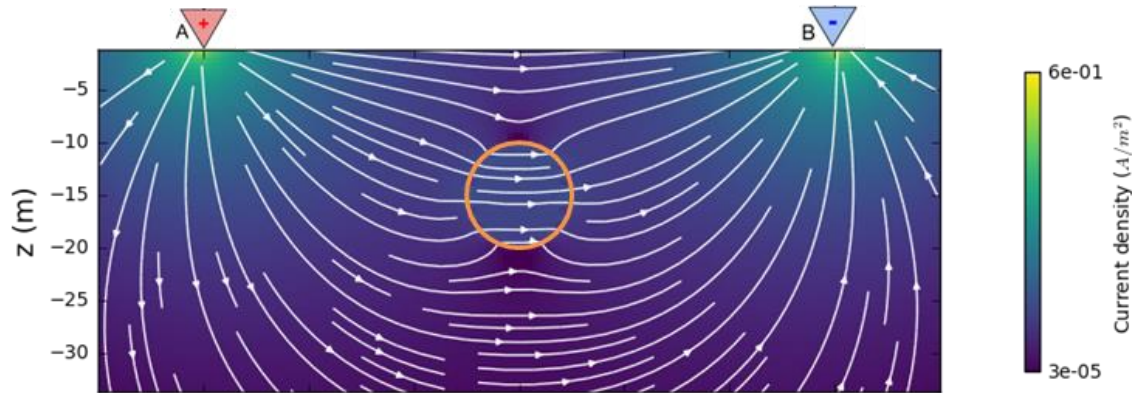
Charge build-up

$$\mathbf{E} = \frac{Q}{4\pi\epsilon_0|\mathbf{r} - \mathbf{r}'|^2}\hat{\mathbf{r}}$$

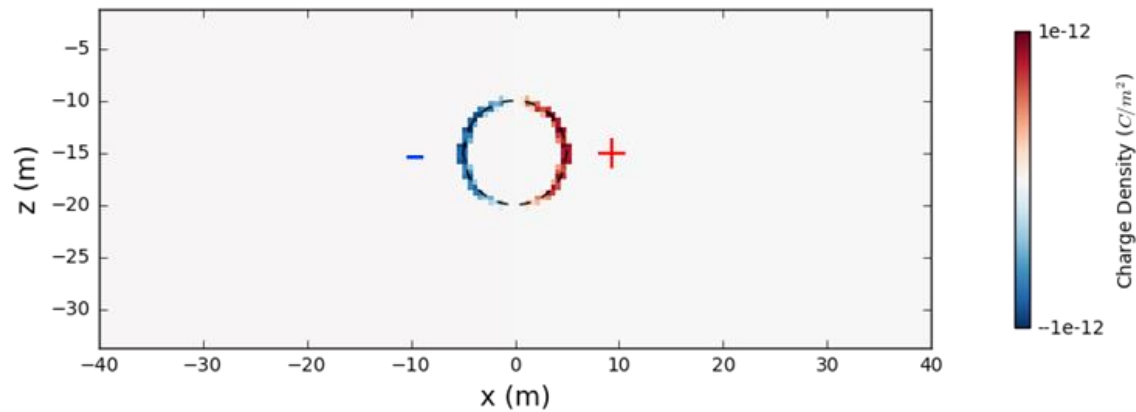
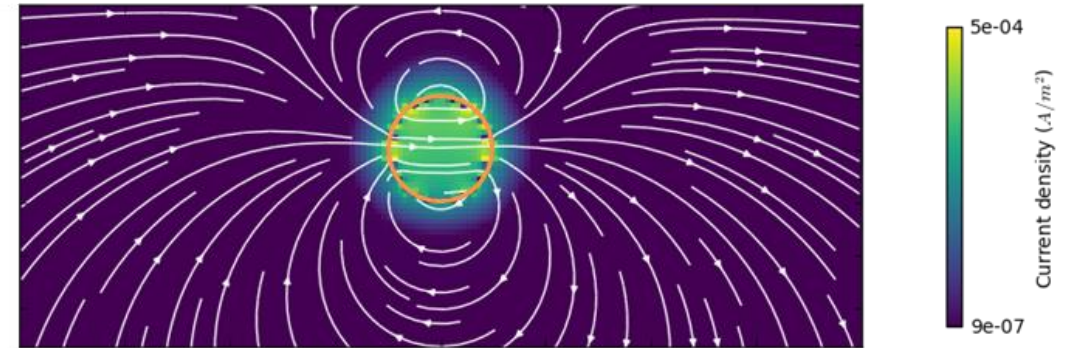


Currents, charges, and potentials

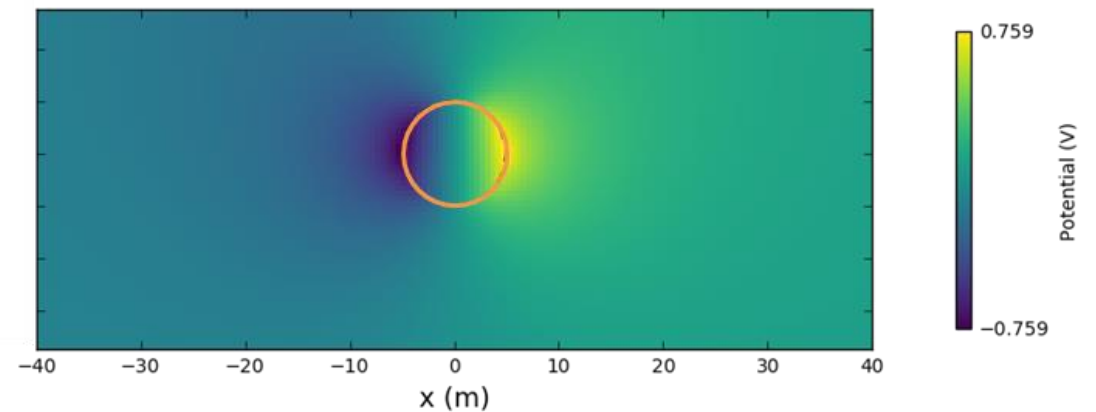
Total currents: J



Secondary currents: J_s

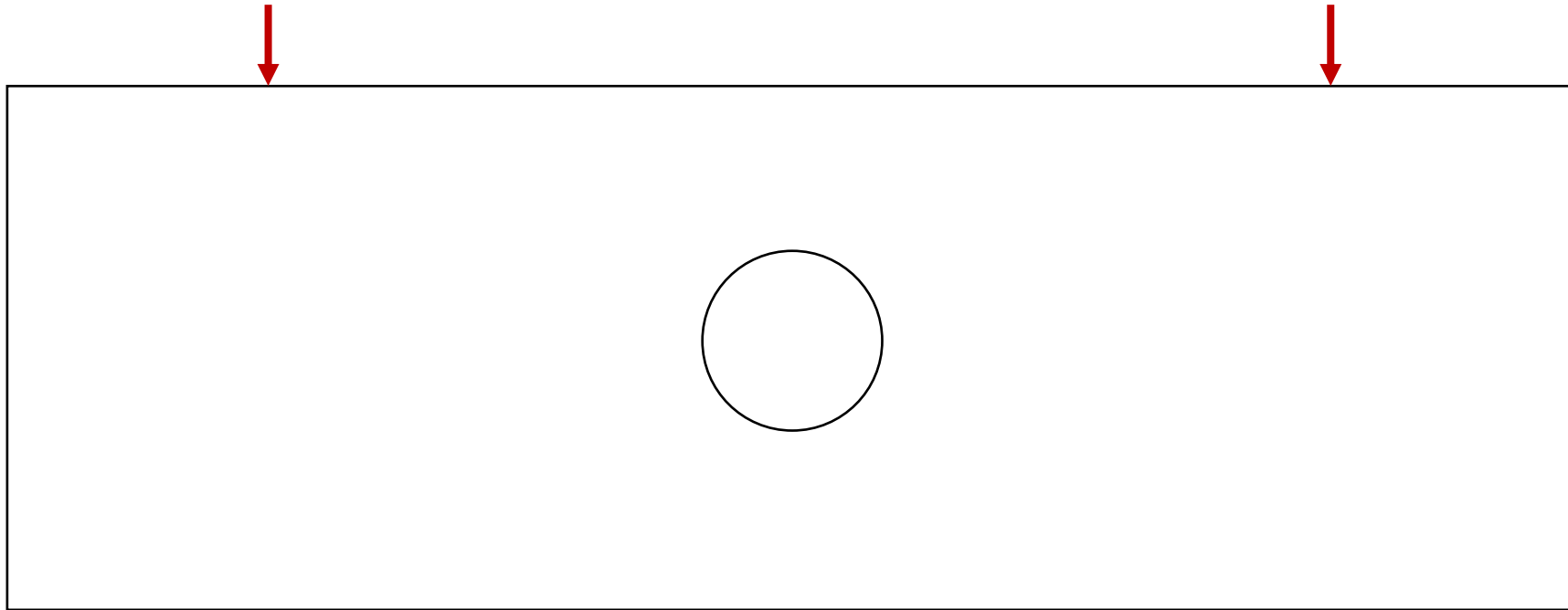


Secondary charges: Q_s



Secondary potential: ϕ_s

What would happen if there was a resistor



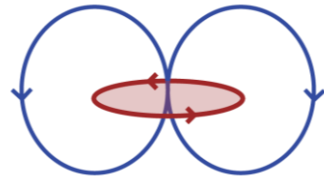
DC resistivity \rightarrow EM; EM fields are varying with time or frequency

	Time	Frequency
Faraday's Law	$\nabla \times \vec{e} = -\frac{\partial \vec{b}}{\partial t}$	$\nabla \times \vec{E} = -i\omega \vec{B}$
Ampere's Law	$\nabla \times \vec{h} = \vec{j} + \frac{\partial \vec{d}}{\partial t}$	$\nabla \times \vec{H} = \vec{J} + i\omega \vec{D}$
No Magnetic Monopoles	$\nabla \cdot \vec{b} = 0$	$\nabla \cdot \vec{B} = 0$
Constitutive Relationships (non-dispersive)	$\vec{j} = \sigma \vec{e}$ $\vec{b} = \mu \vec{h}$ $\vec{d} = \epsilon \vec{e}$	$\vec{J} = \sigma \vec{E}$ $\vec{B} = \mu \vec{H}$ $\vec{D} = \epsilon \vec{E}$

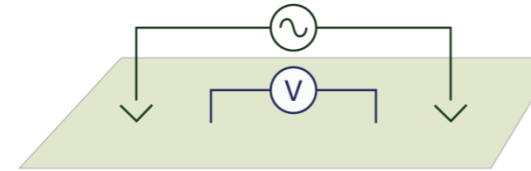
Controlled-source EM methods

Types of EM source

Inductive source



Grounded source

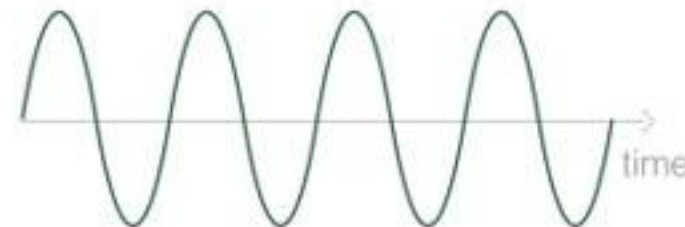


Types of current waveform

Time-domain; Transient

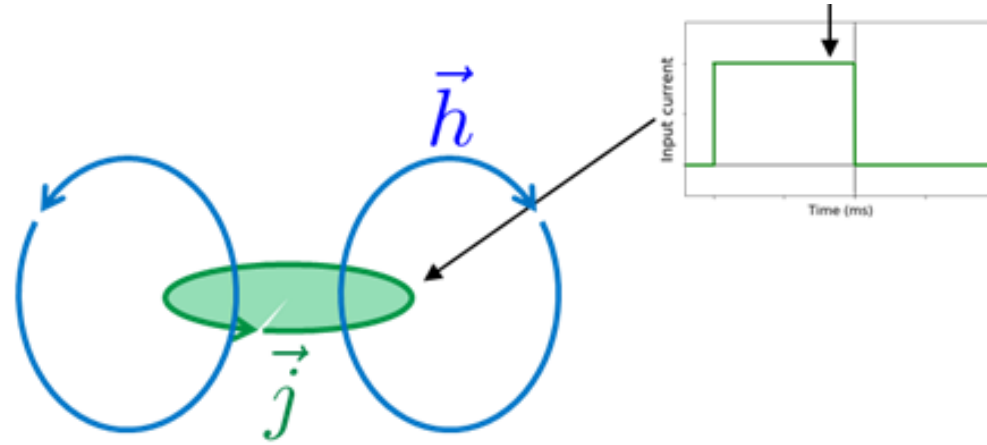


Frequency-domain; Harmonic



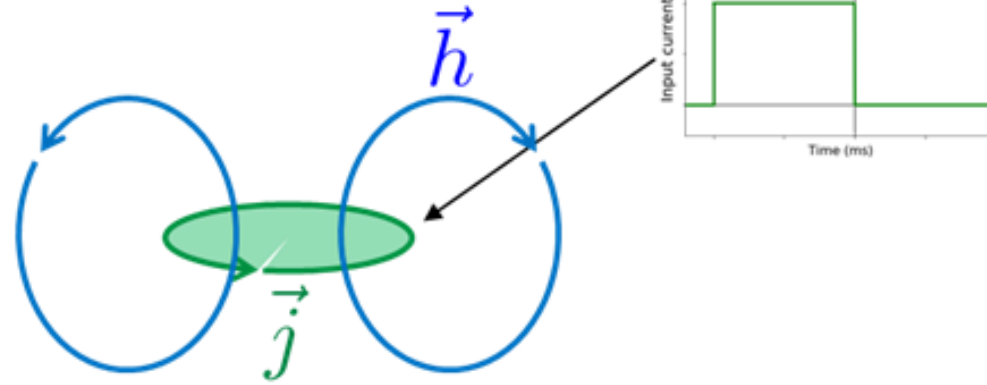
EM induction

Ampere's Law: $\vec{\nabla} \times \vec{h} = \vec{j}$

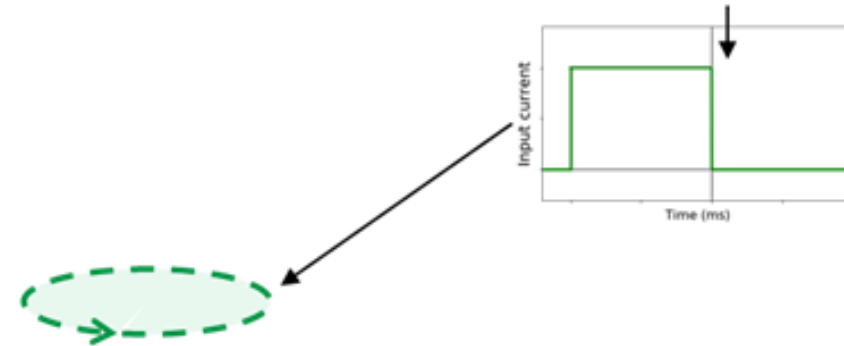


EM induction

Ampere's Law: $\vec{\nabla} \times \vec{h} = \vec{j}$

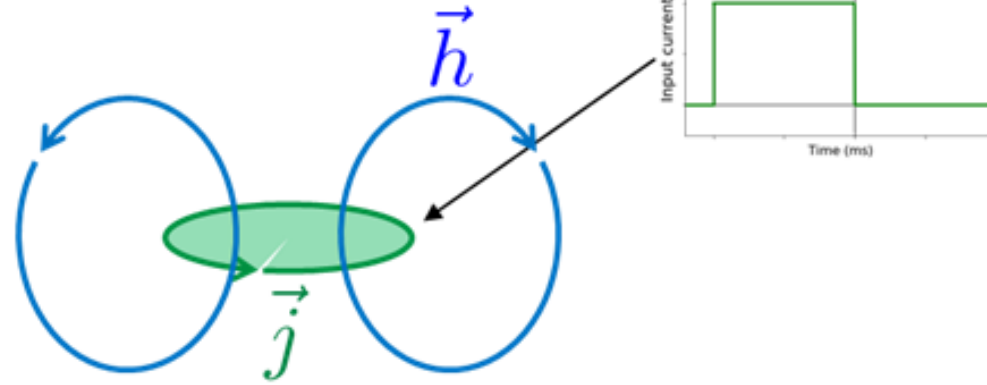


Faraday's Law: $\vec{\nabla} \times \vec{e} = -\mu_0 \frac{\partial \vec{h}}{\partial t}$



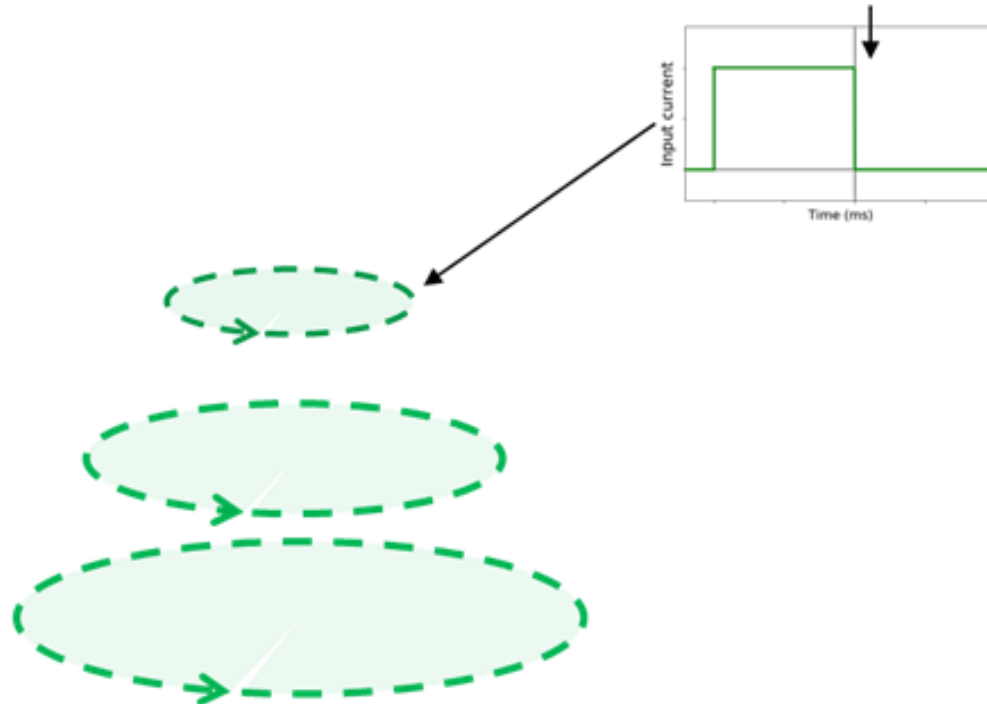
EM induction

Ampere's Law: $\vec{\nabla} \times \vec{h} = \vec{j}$



Faraday's Law: $\vec{\nabla} \times \vec{e} = -\mu_0 \frac{\partial \vec{h}}{\partial t}$

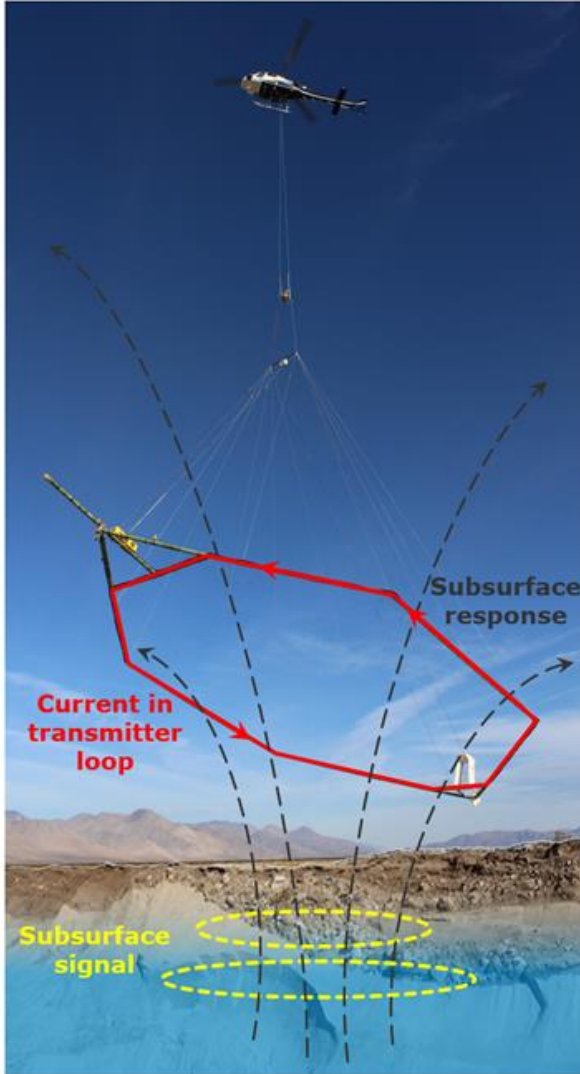
Ohm's Law: $\vec{j} = \sigma \vec{e}$



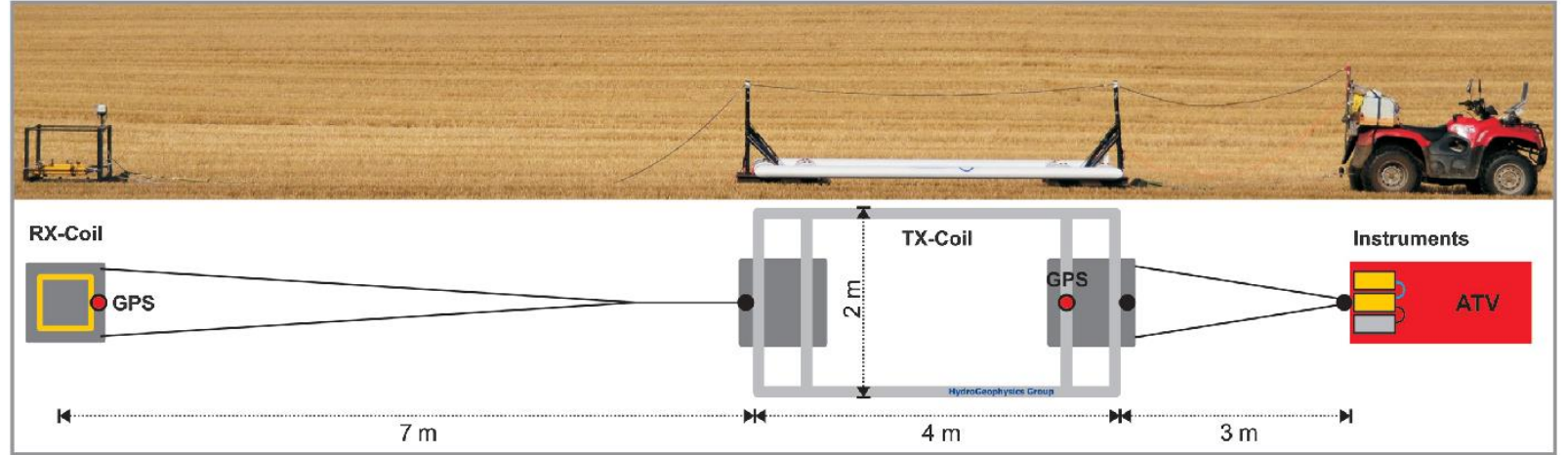
Currents diffuse away (EM induction)

EM induction methods (no need to “contact”)

Airborne EM



Towed time-domain EM



EM-31

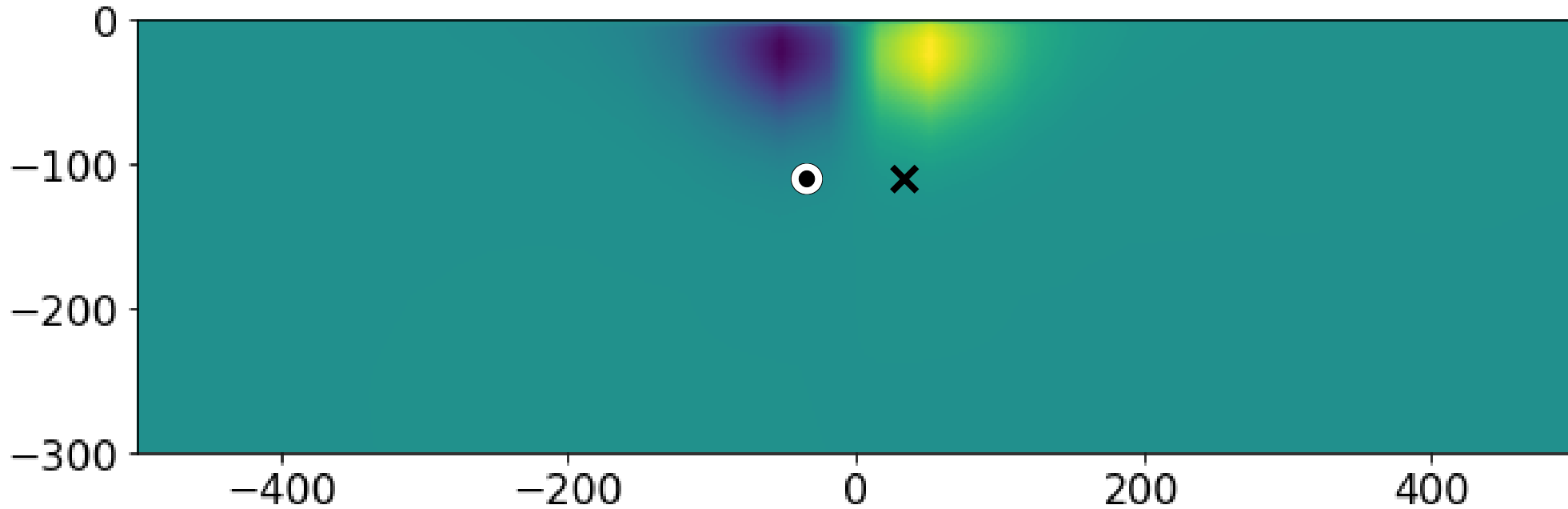
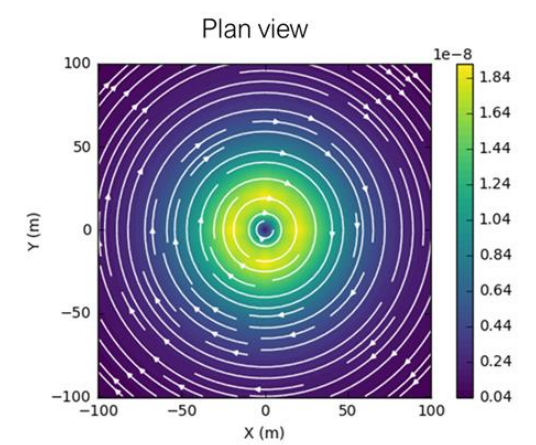


DualEM



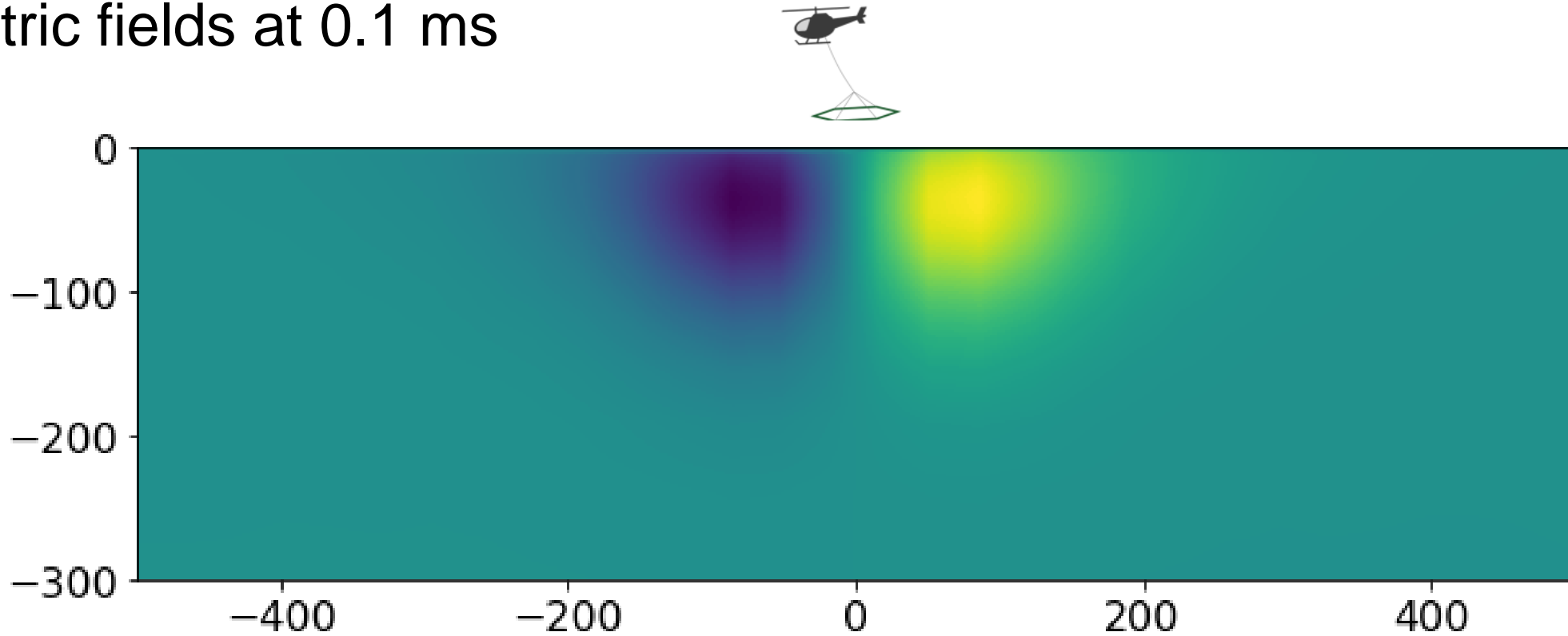
Diffusive EM wave

Electric fields at 0.06 ms



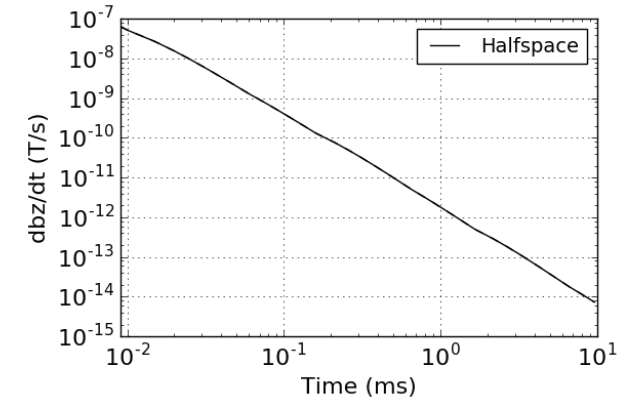
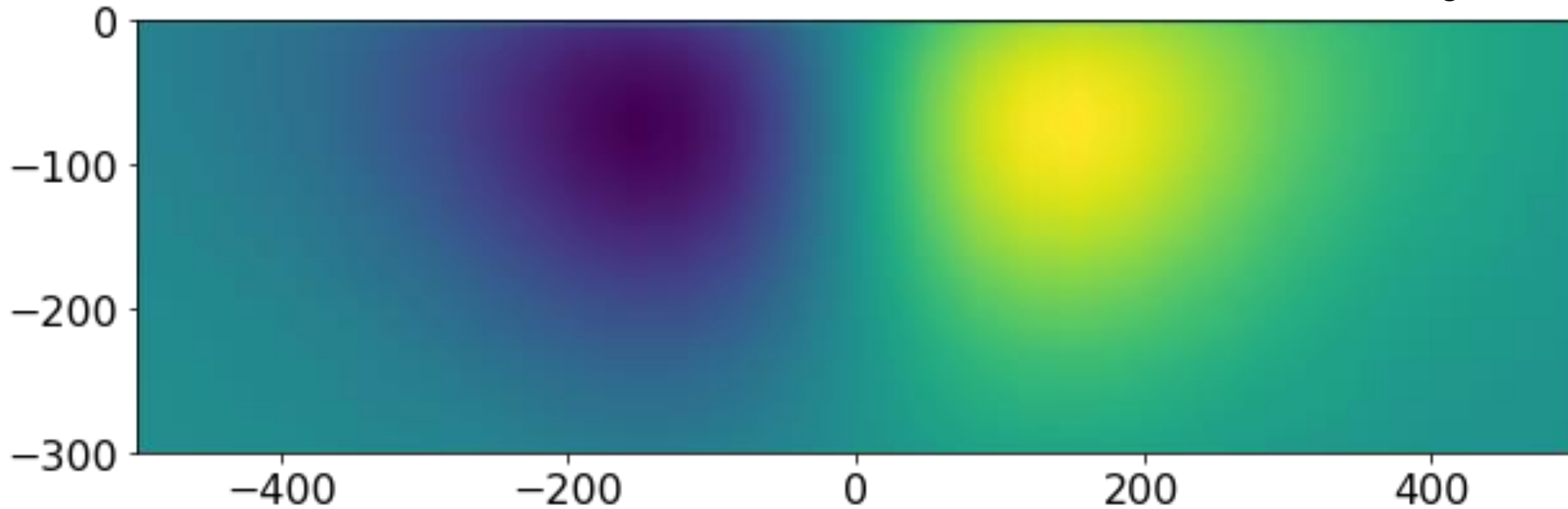
Diffusive EM wave

Electric fields at 0.1 ms



Diffusive EM wave

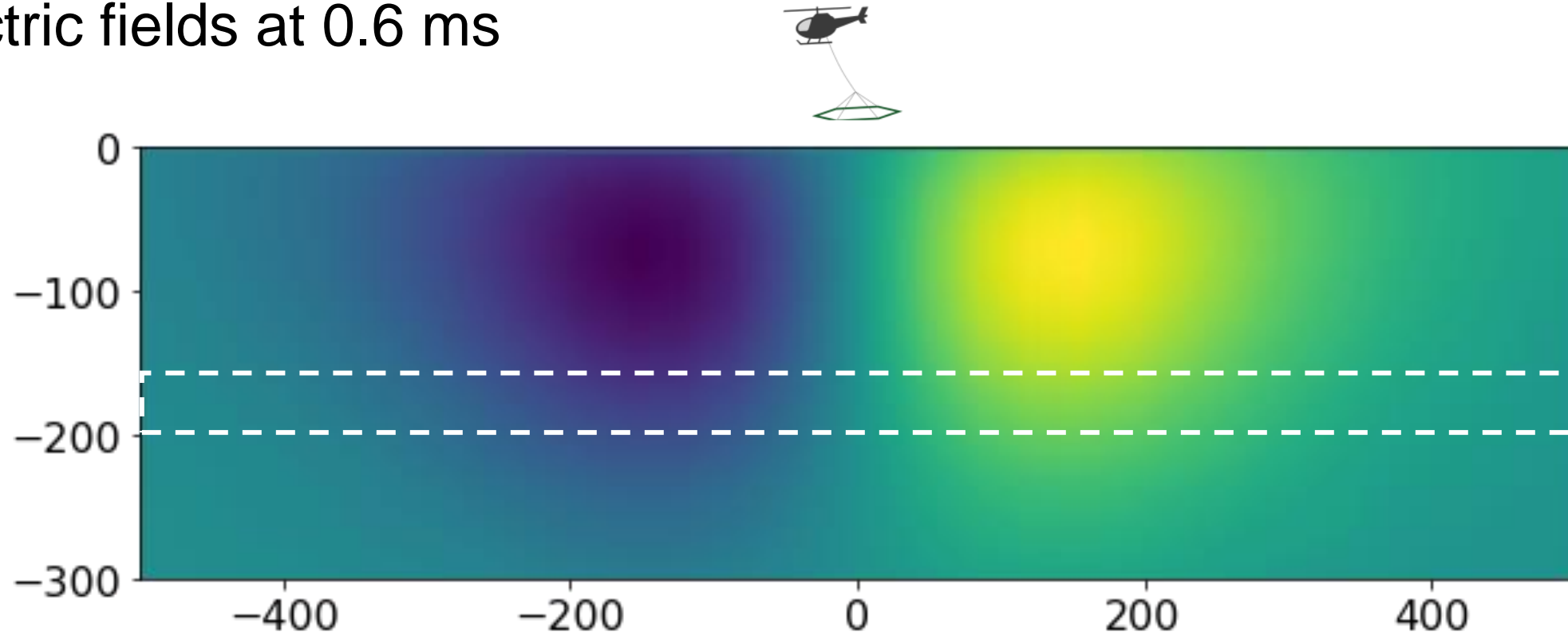
Electric fields at 0.6 ms



Time sounding for depth resolution

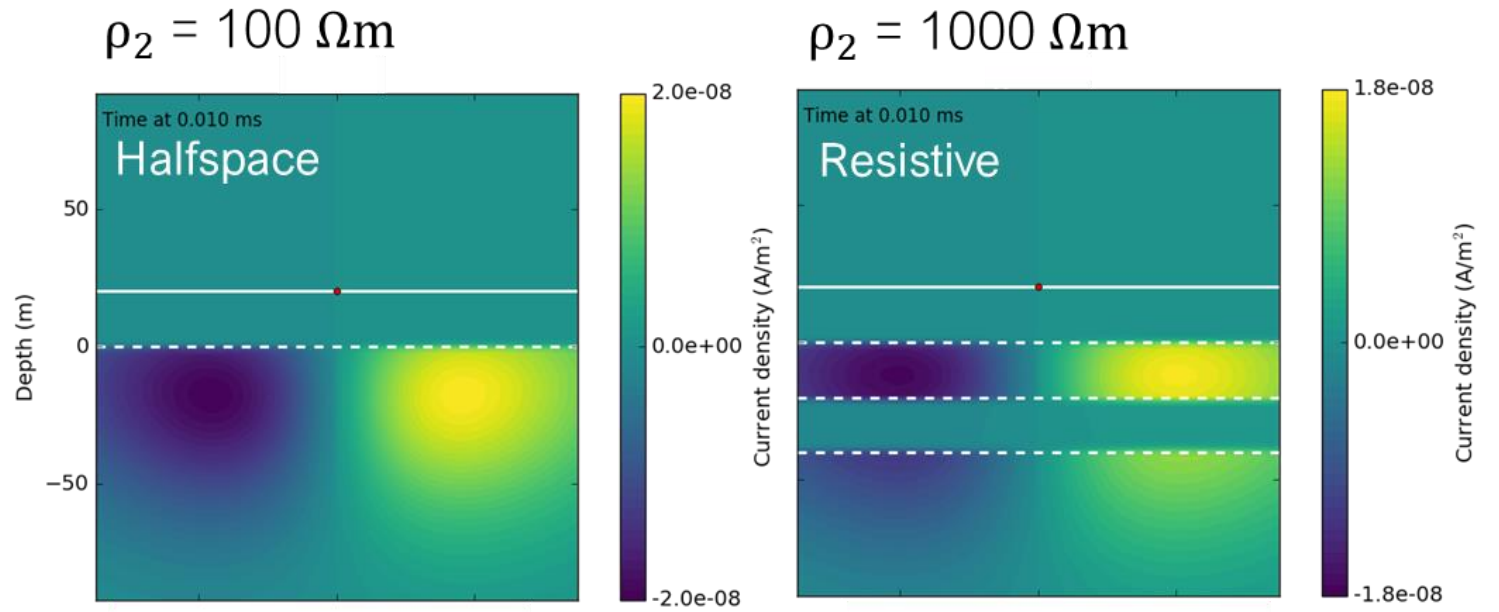
Electrical fields are parallel to the layered structure

Electric fields at 0.6 ms



Layered structure

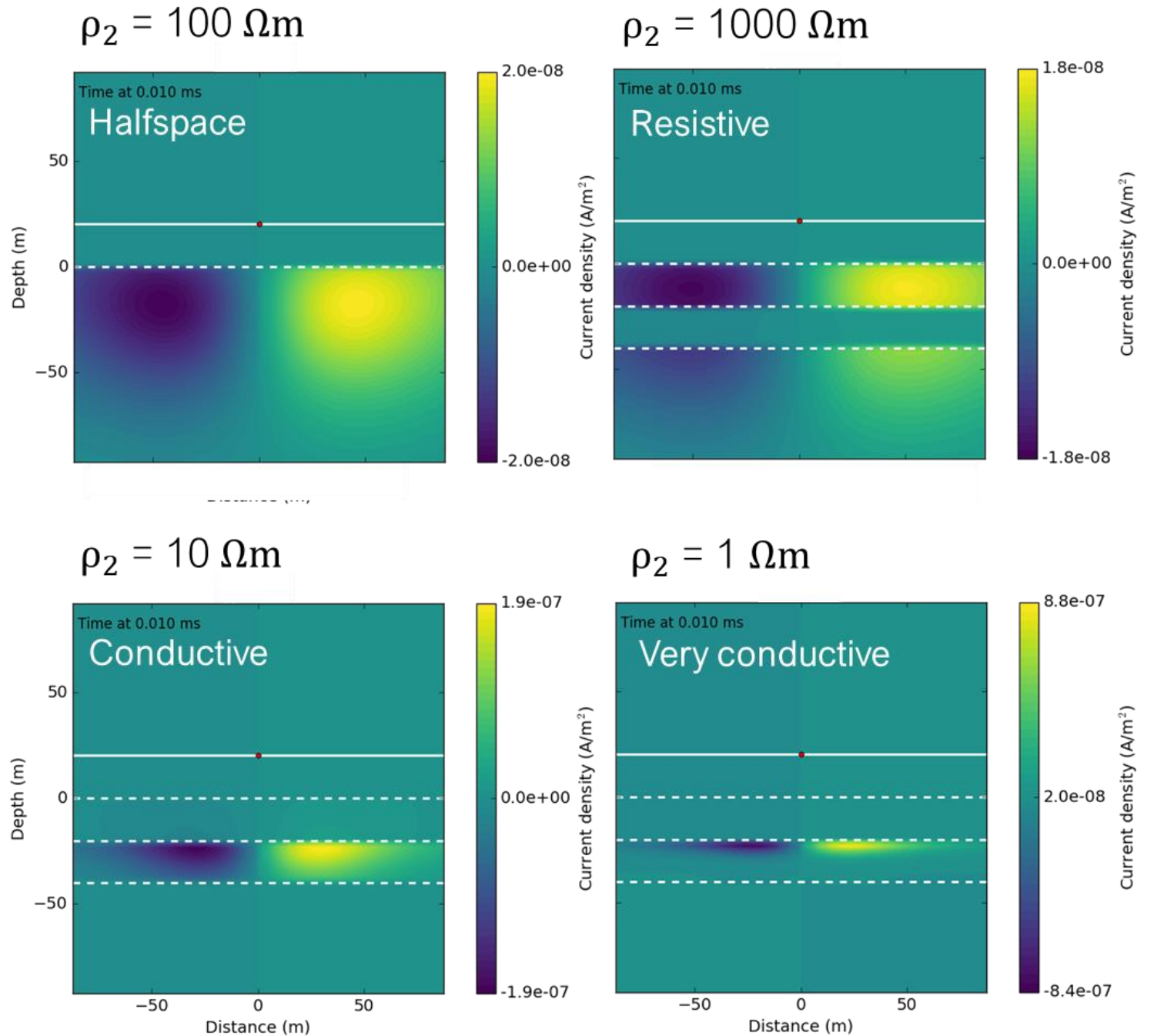
$\rho_1 = 100 \, \Omega\text{m}$
ρ_2
ρ_1



Layered structure

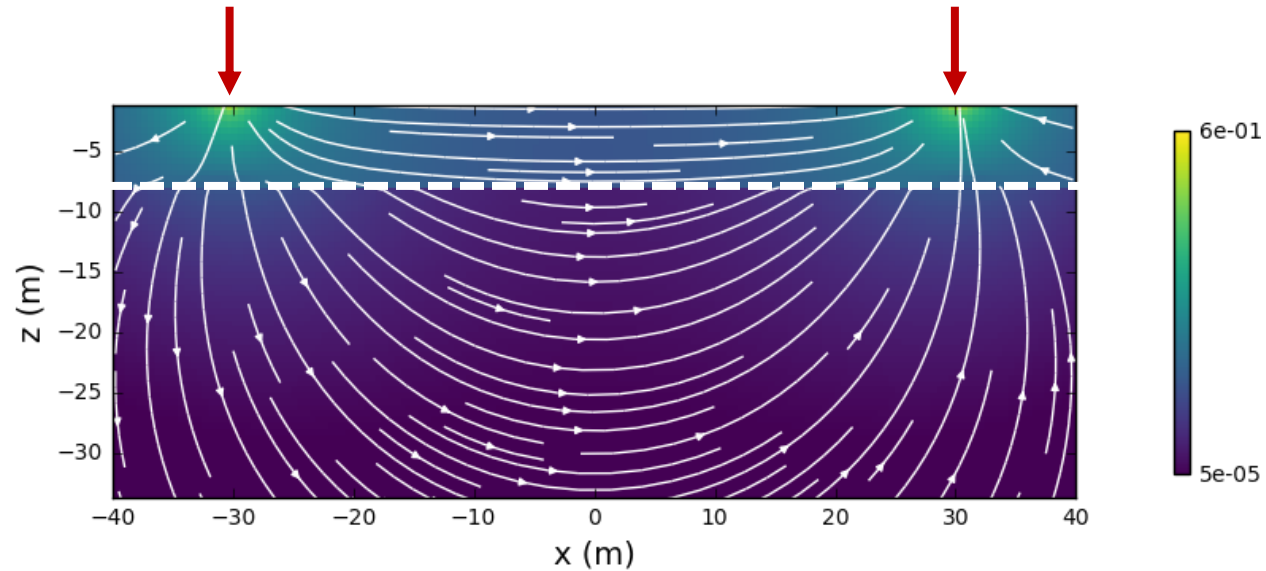
$\rho_1 = 100 \Omega\text{m}$
ρ_2
ρ_1

Biased sensitivity towards
a conductor

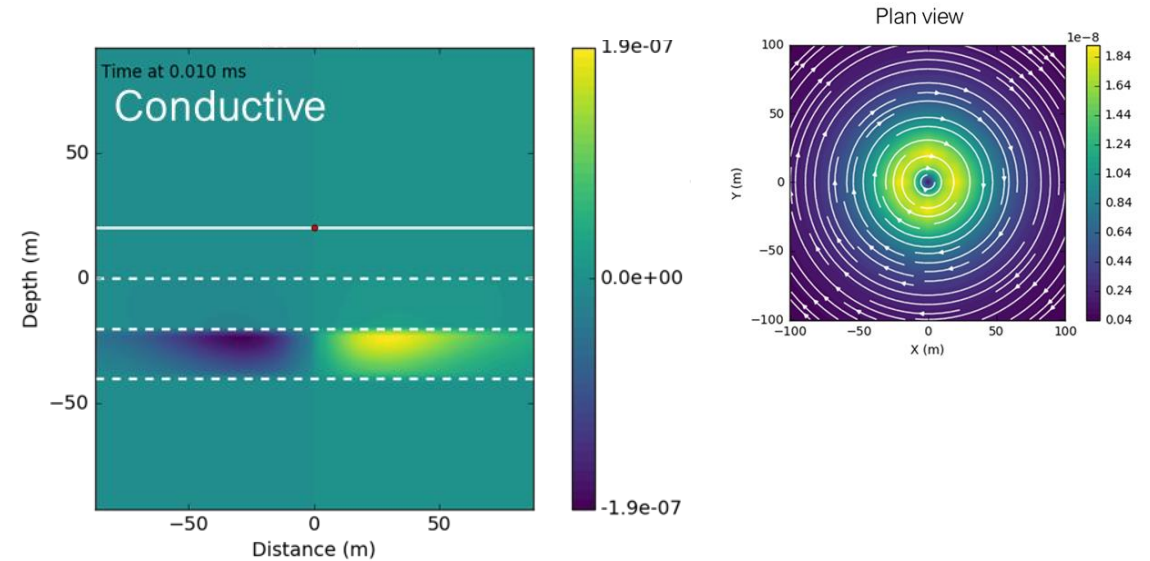


DC resistivity vs. Inductive source EM

E-fields crosses the layer boundary
(charge build-up; galvanic currents; current channeling)

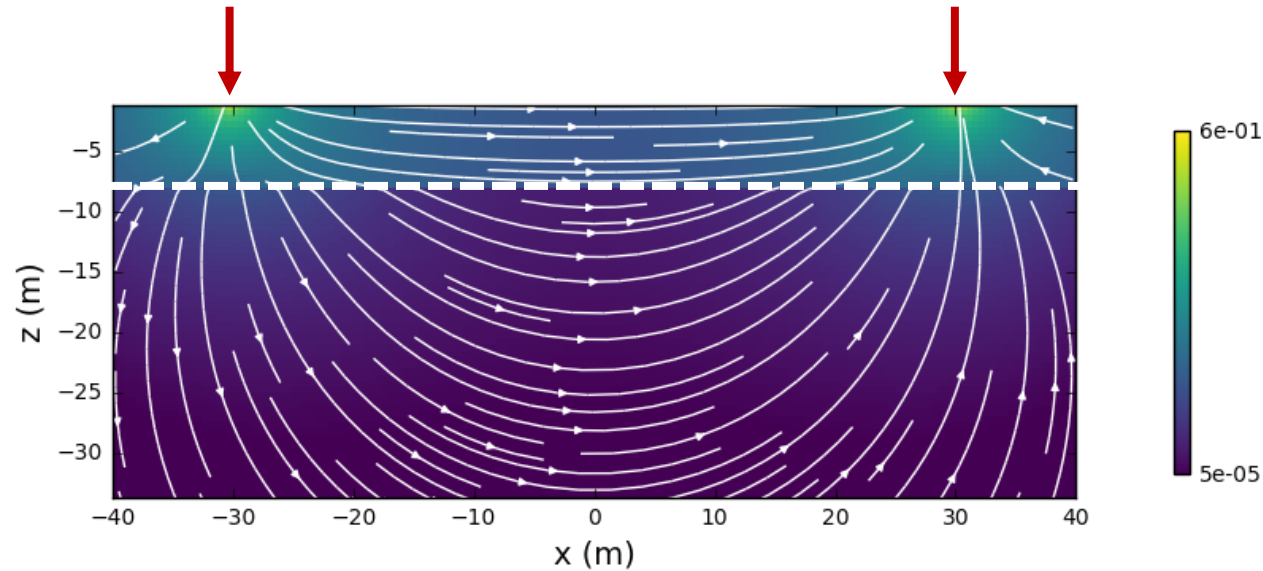


E-fields parallel to the layer boundary
(EM induction)

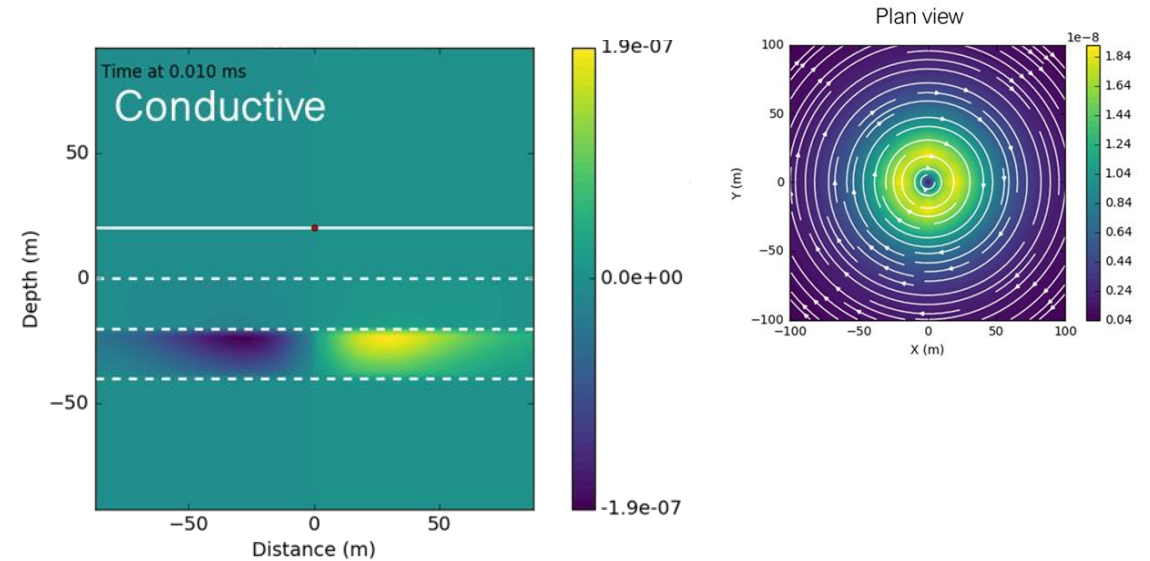


DC resistivity vs. Inductive source EM

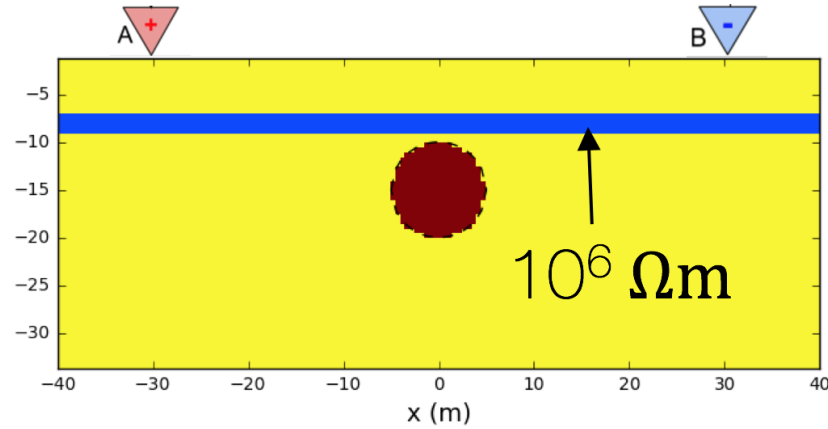
E-fields crosses the layer boundary
(charge build-up; galvanic currents; current channeling)



E-fields parallel to the layer boundary
(EM induction)

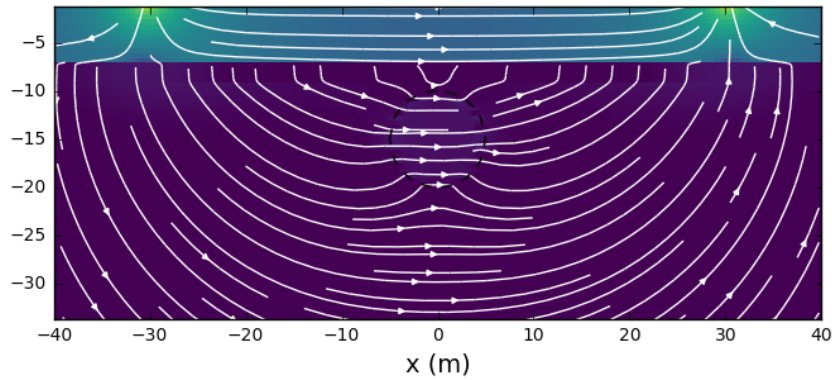


Shielding problem



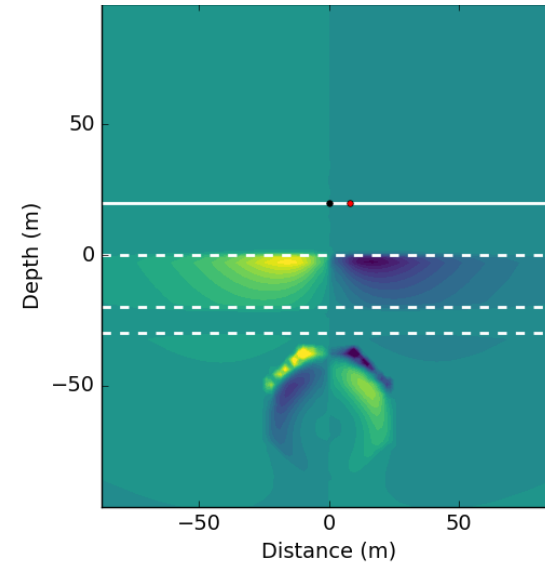
DC resistivity

Hard to see below the insulator



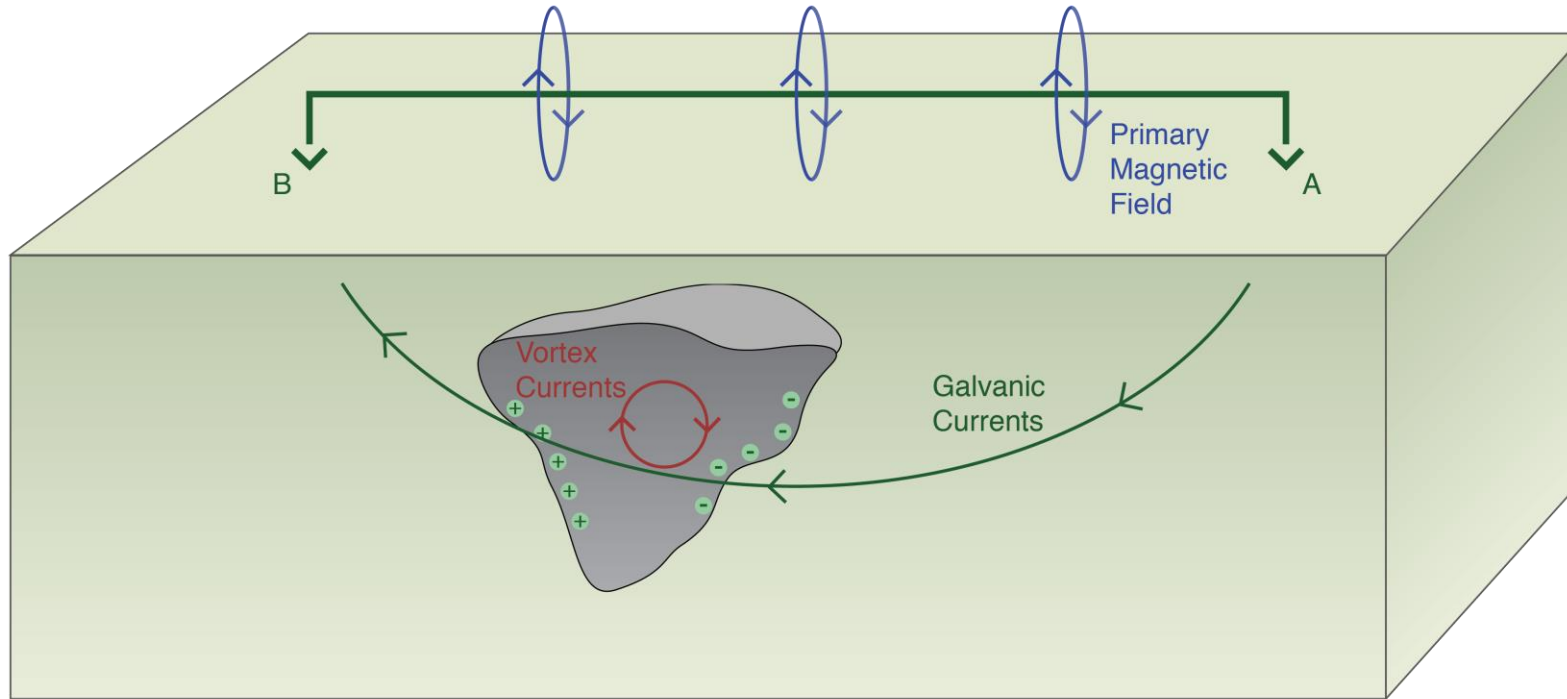
Inductive source EM

Easy to see below the insulator



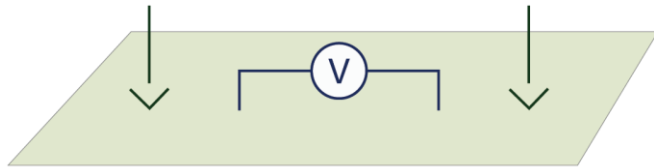
Grounded source EM

Current channeling + EM induction



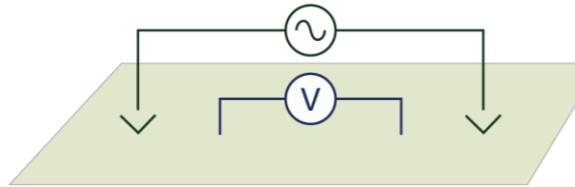
For deeper imaging (a few km to 100s of km)

Direct Current resistivity

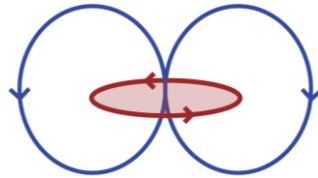


Controlled-source EM

Grounded source



Inductive source



Magnetotellurics



Depth range

meters

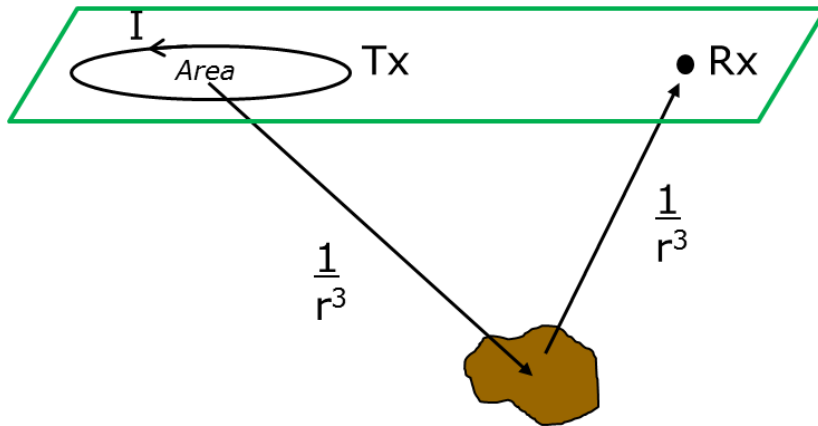
hundreds of km

What is required to see deeper?

Penetration depth depends upon system power

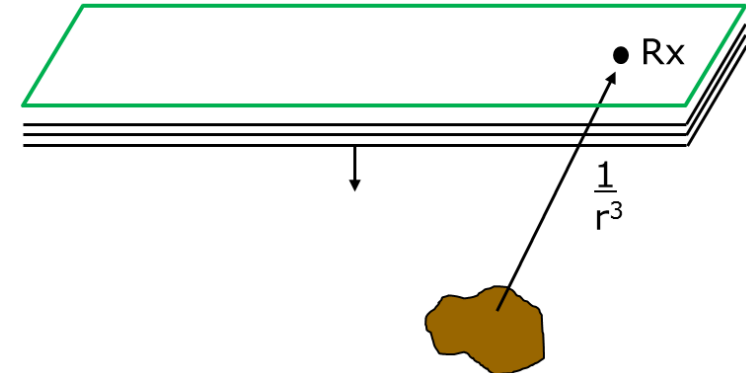
Controlled source:

- Using a small loop
- Magnetic moment
 $m = IA$
- Total geometric decay
 $\sim \frac{1}{r^6}$



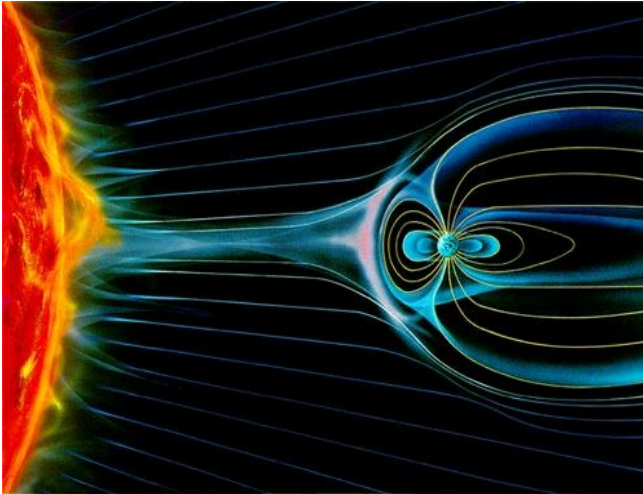
Infinitely large loop source

- Sheet currents generate plane waves
- Total geometric decay
 $\sim \frac{1}{r^3}$



Natural EM sources

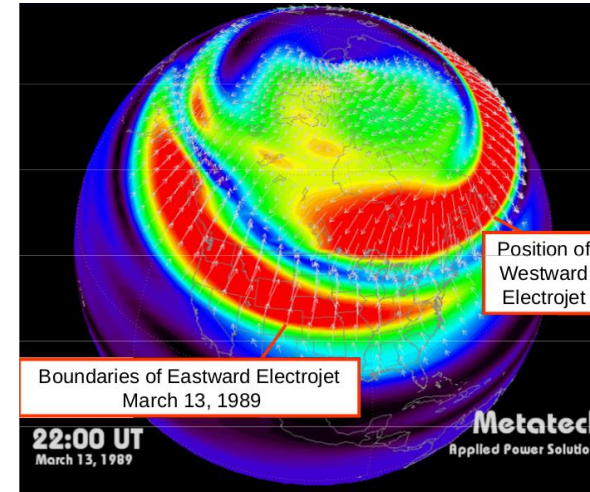
Sun and magnetosphere,
solar storms



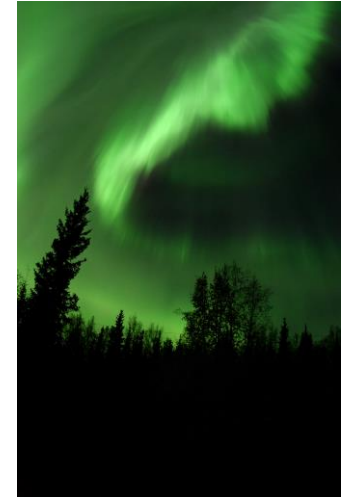
Lightning



Auroral electrojet



Aurora



Refraction of waves

Snell's law

$$k_i \sin \theta_i = k_t \sin \theta_t$$

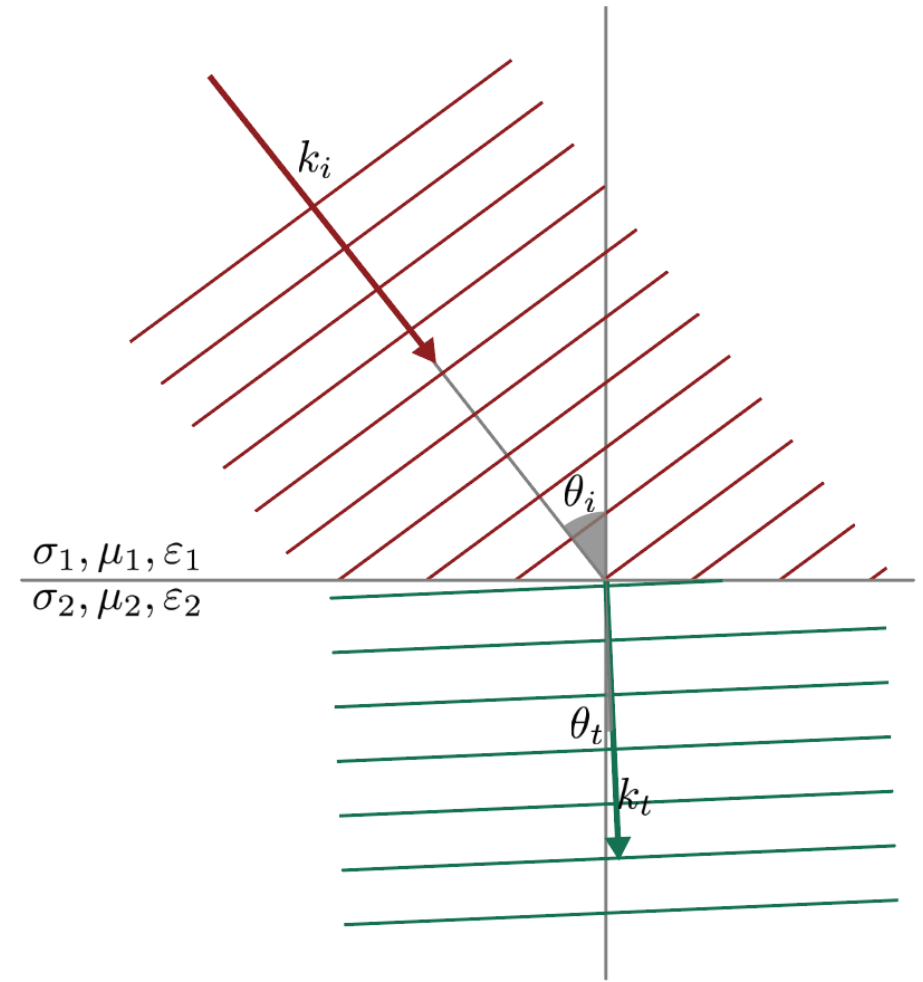
k is complex wave number

$$k^2 = \omega^2 \mu \epsilon - i \omega \mu \sigma$$

Quasi-static: $\frac{\omega \epsilon_0}{\sigma} \ll 1$

$$\sin \theta_t = \sqrt{\frac{2 \omega \epsilon_0}{\sigma}} \sin \theta_i$$

Angle of refraction is $\theta_t = 0^\circ$ in almost every instance



Example for 10,000 Hz

$$\sigma = 10^{-3} \text{ S/m}$$

$$\theta_i = 89^\circ$$

$$\text{Then } \theta_t = 1.35^\circ$$

Plane waves and skin depth

Skin depth (meters)

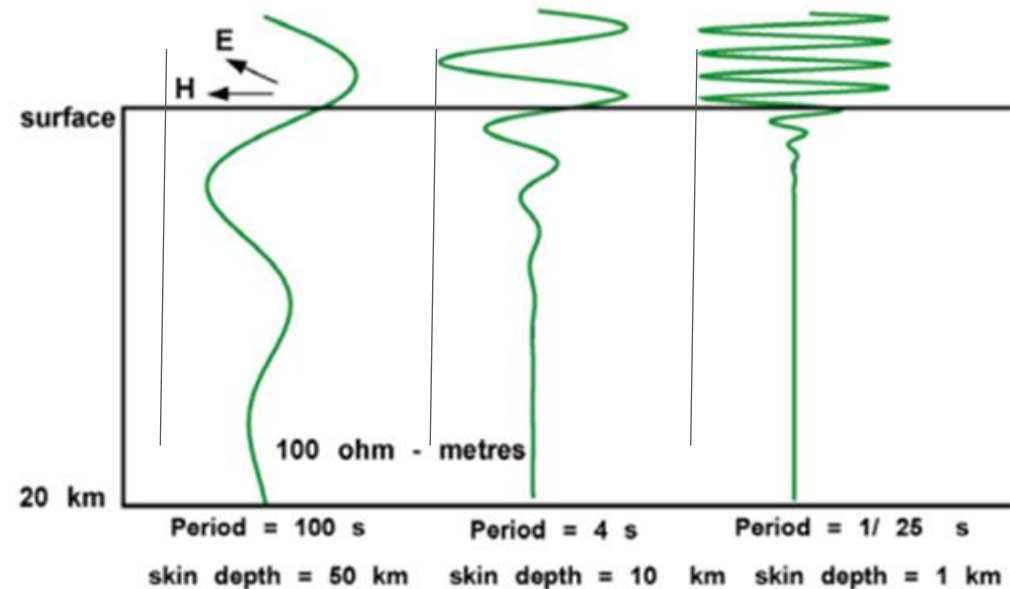
$$\delta = \sqrt{\frac{2}{\omega\mu\sigma}} = 503\sqrt{\frac{1}{\sigma f}}$$

Low frequency waves propagate further

Frequency sounding

Depth of propagation

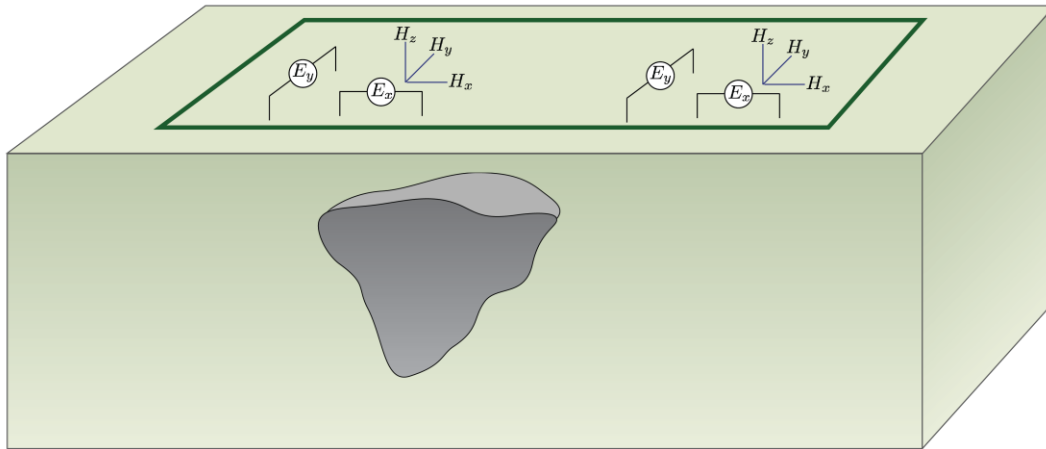
- A few skin depths
- Only a portion of a wavelength



Controlled-source vs. Natural source

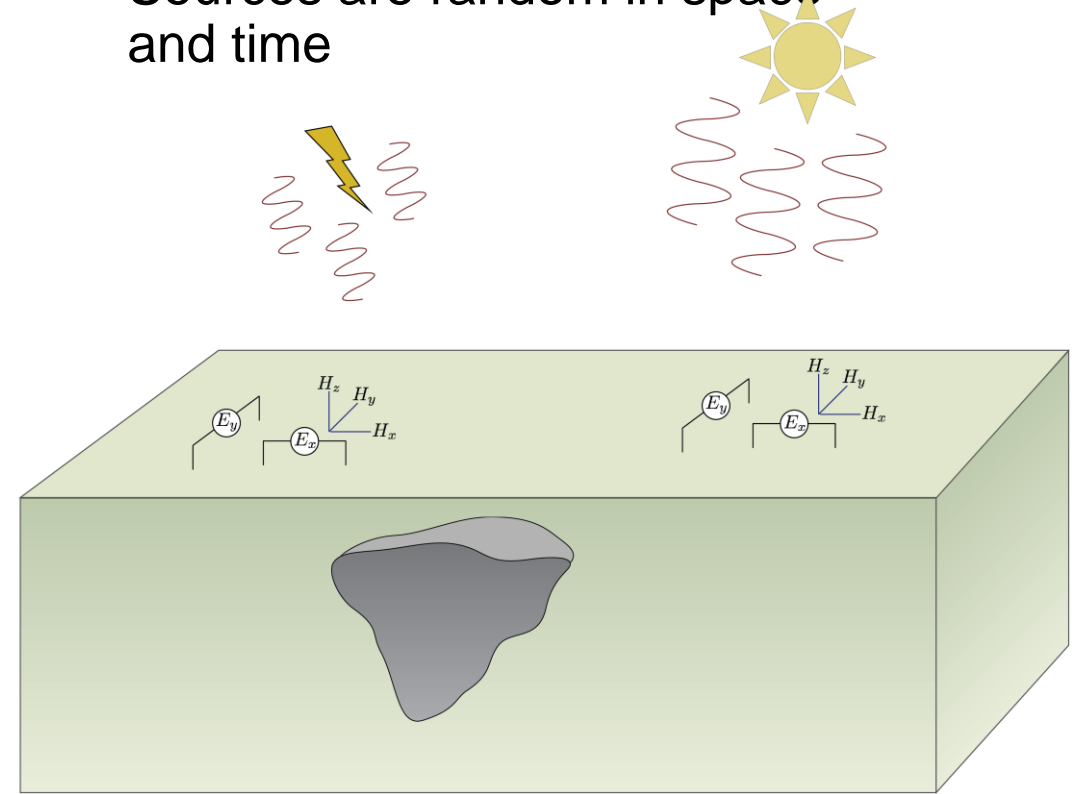
Controlled-source

Well-defined location,
geometry, and amplitude



Natural sources

Sources are random in space
and time



MT Station

Maxwell's equations:

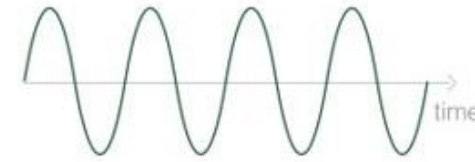
- Linear in J_s
- E and H affected in the same way

Effects of unknown source removed by taking ratio

Transfer function $\mathbf{E} = \mathbf{ZH}$

↑
impedance (matrix)

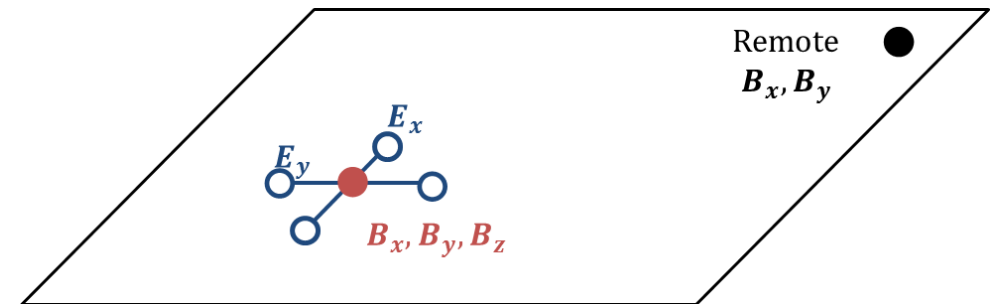
$$\begin{pmatrix} E_x \\ E_y \end{pmatrix} = \begin{pmatrix} Z_{xx} & Z_{xy} \\ Z_{yx} & Z_{yy} \end{pmatrix} \begin{pmatrix} H_x \\ H_y \end{pmatrix}$$



Frequency-domain

$$\nabla \times \mathbf{E} + i\omega\mu\mathbf{H} = 0$$

$$\nabla \times \mathbf{H} - \sigma\mathbf{E} = \mathbf{J}_s$$

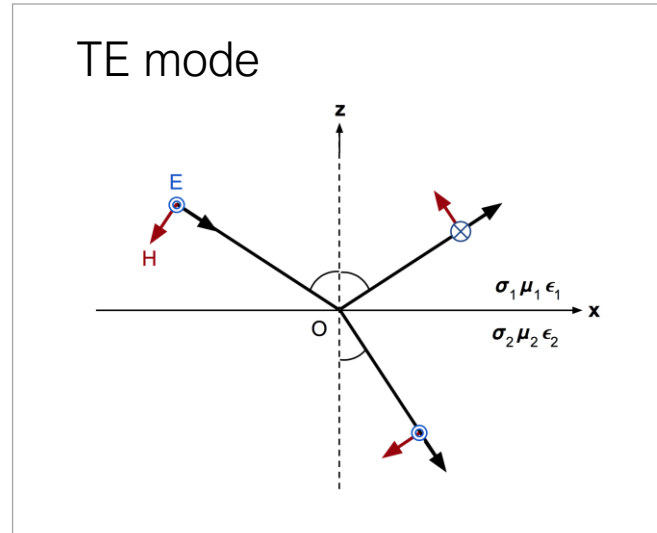


Impedance and resistivity

Plane wave in homogenous media:

- E and H fields are perpendicular

E-field parallel to the
boundary
(EM induction)



Homogeneous half space

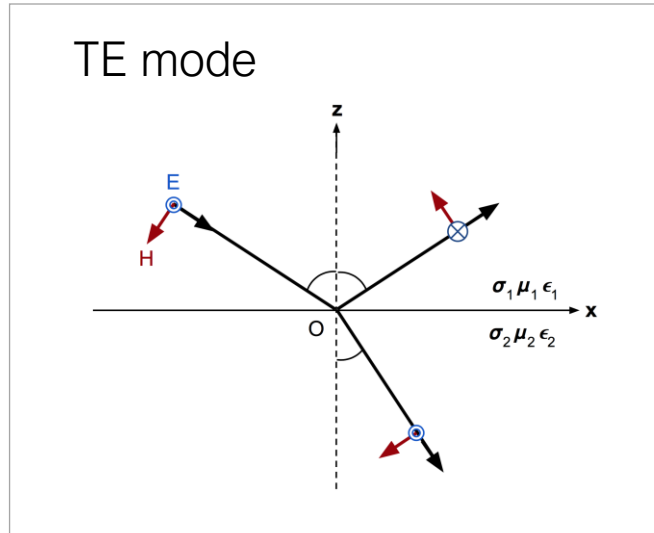
Impedance	Resistivity	Phase
$Z_{xy} = \frac{E_x}{H_y}$	$\rho = \frac{1}{\omega\mu} Z_{xy} ^2$	$\Phi = \tan^{-1} \left(\frac{\text{Im}(Z_{xy})}{\text{Re}(Z_{xy})} \right) = \frac{\pi}{4}$

Impedance and resistivity

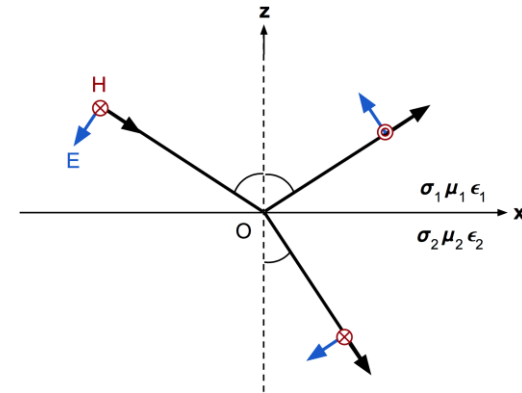
Plane wave in homogenous media:

- E and H fields are perpendicular

E-field parallel to the boundary
(EM induction)



TM mode



E-field crosses the boundary
(Current channeling)

Homogeneous half space

Impedance

$$Z_{xy} = \frac{E_x}{H_y}$$

Resistivity

$$\rho = \frac{1}{\omega \mu} |Z_{xy}|^2$$

Phase

$$\Phi = \tan^{-1} \left(\frac{\text{Im}(Z_{xy})}{\text{Re}(Z_{xy})} \right) = \frac{\pi}{4}$$

MT soundings in 1D

- In general:

$$Z = \begin{pmatrix} Z_{xx} & Z_{xy} \\ Z_{yx} & Z_{yy} \end{pmatrix}$$

- Apparent resistivity:

$$\rho_a = \frac{1}{\omega \mu_0} |Z_{xy}|^2$$

- Phase:

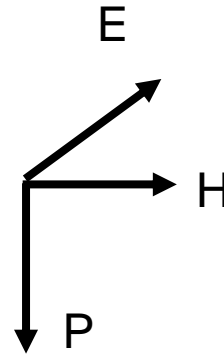
$$\Phi = \tan^{-1} \left(\frac{\text{Im}(Z_{xy})}{\text{Re}(Z_{xy})} \right)$$

- In 1D:

$$Z = \begin{pmatrix} 0 & Z_{xy} \\ Z_{yx} & 0 \end{pmatrix}$$

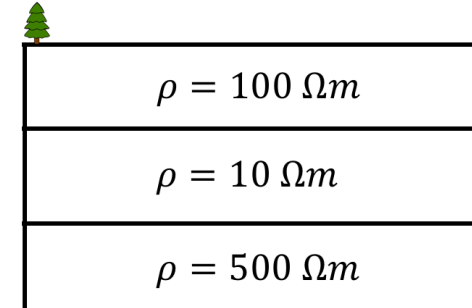
$$Z_{xy} = \frac{E_x}{H_y}$$

$$Z_{xy} = -Z_{yx}$$

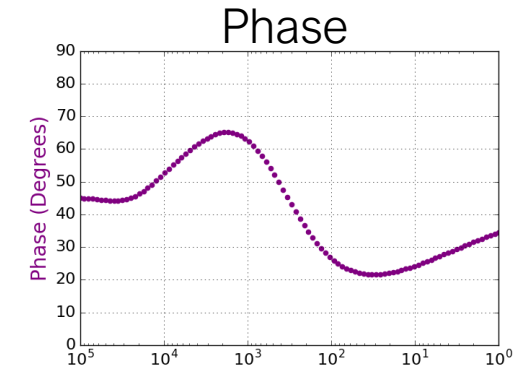
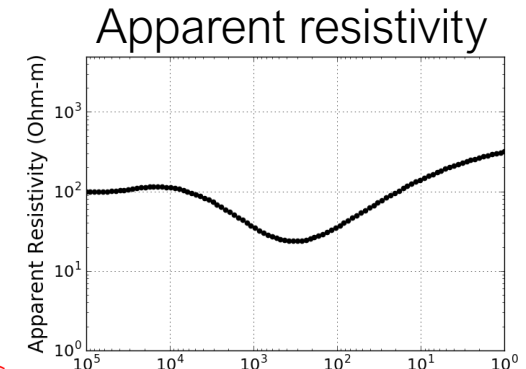
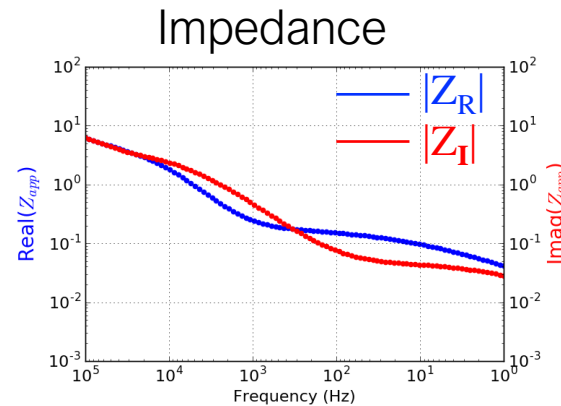


$E \times H = P$
P: pointing vector

Very similar to inductive source EM
(E-fields parallel to the boundary)



Frequency sounding
for depth resolution



MT soundings in 2D

- In general:

$$Z = \begin{pmatrix} Z_{xx} & Z_{xy} \\ Z_{yx} & Z_{yy} \end{pmatrix}$$

- In 2D:

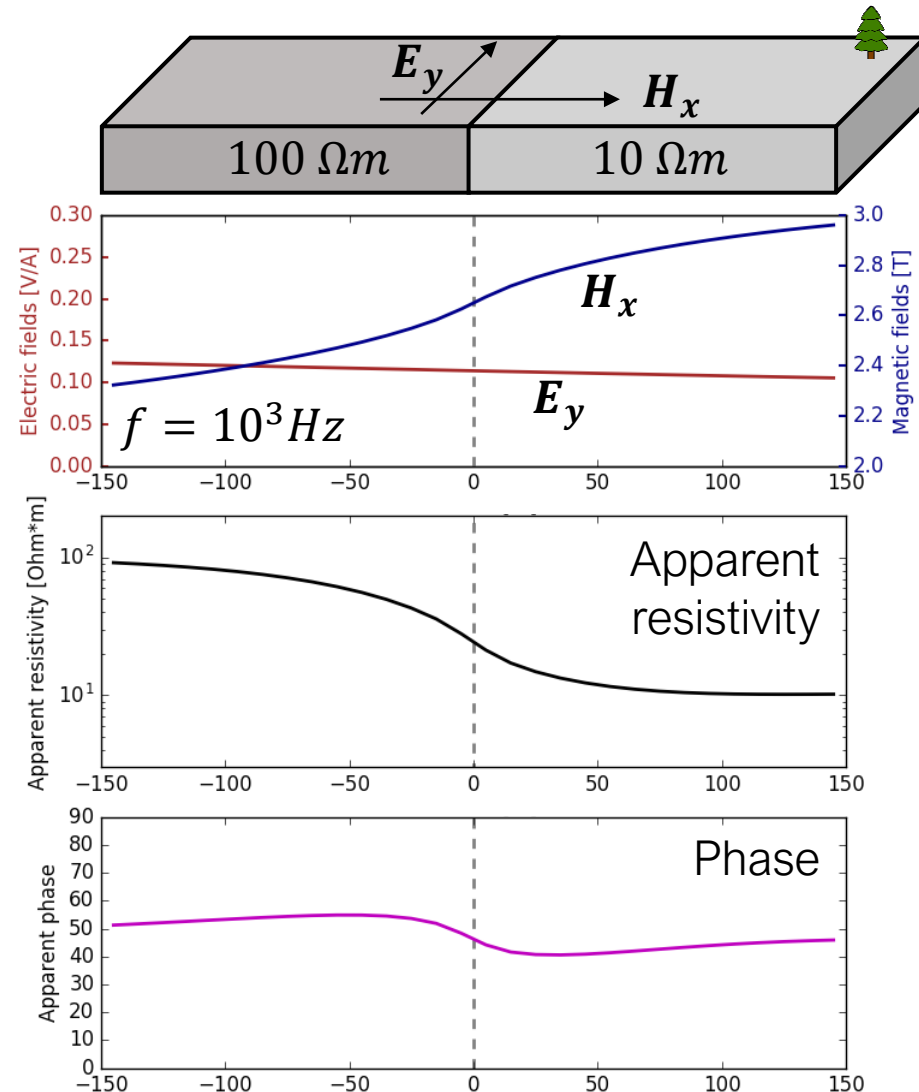
$$Z = \begin{pmatrix} 0 & Z_{xy} \\ Z_{yx} & 0 \end{pmatrix}$$

$$Z_{xy} \neq Z_{yx}$$

- TE mode
 - E-field parallel to structure

$$Z_{yx} = \frac{E_y}{H_x}$$

E-field parallel to the boundary
(EM induction; biased sensitivity towards a conductor)



MT soundings in 2D

- In general:

$$Z = \begin{pmatrix} Z_{xx} & Z_{xy} \\ Z_{yx} & Z_{yy} \end{pmatrix}$$

- In 2D:

$$Z = \begin{pmatrix} 0 & Z_{xy} \\ Z_{yx} & 0 \end{pmatrix}$$

$$Z_{xy} \neq Z_{yx}$$

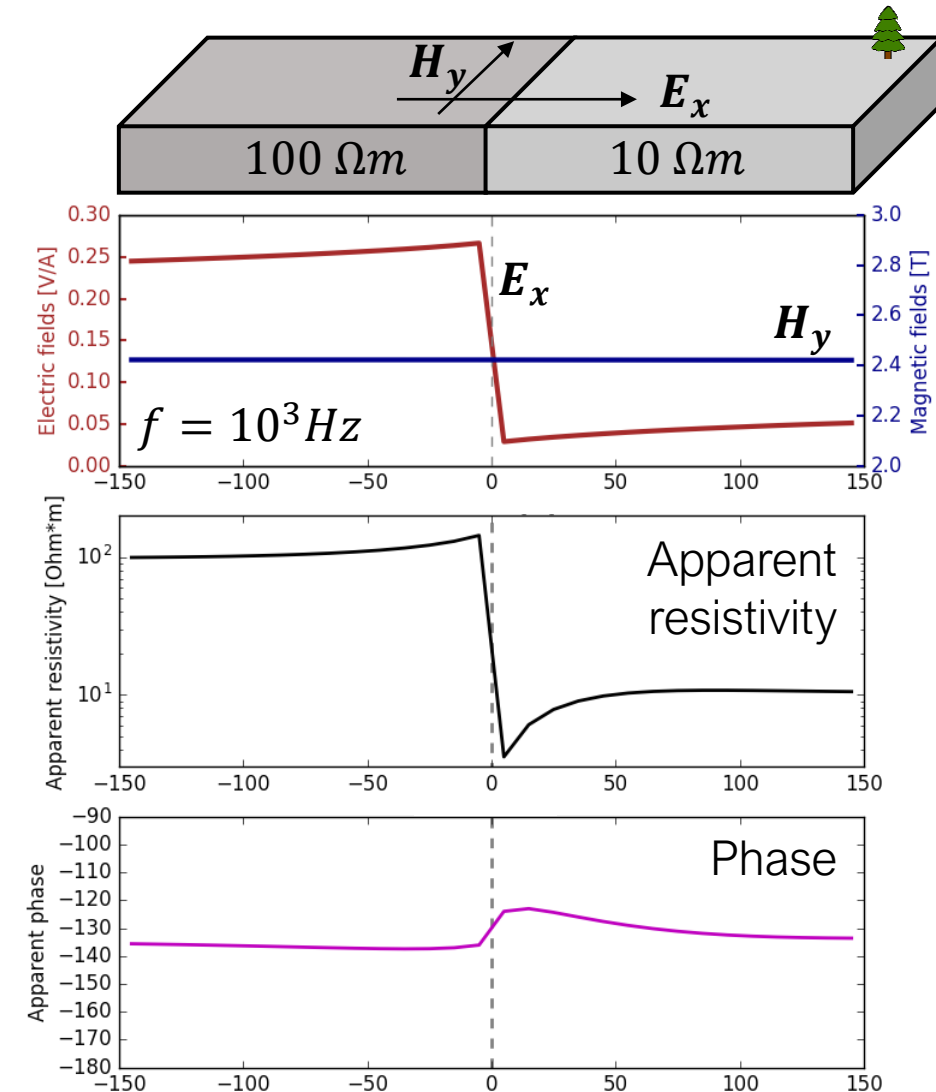
- TM mode

- H-field parallel to structure
- E_x discontinuous

$$Z_{xy} = \frac{E_x}{H_y}$$

E-field crosses the boundary

(Current channeling; sensitive to both conductor & resistor)



MT soundings in 3D

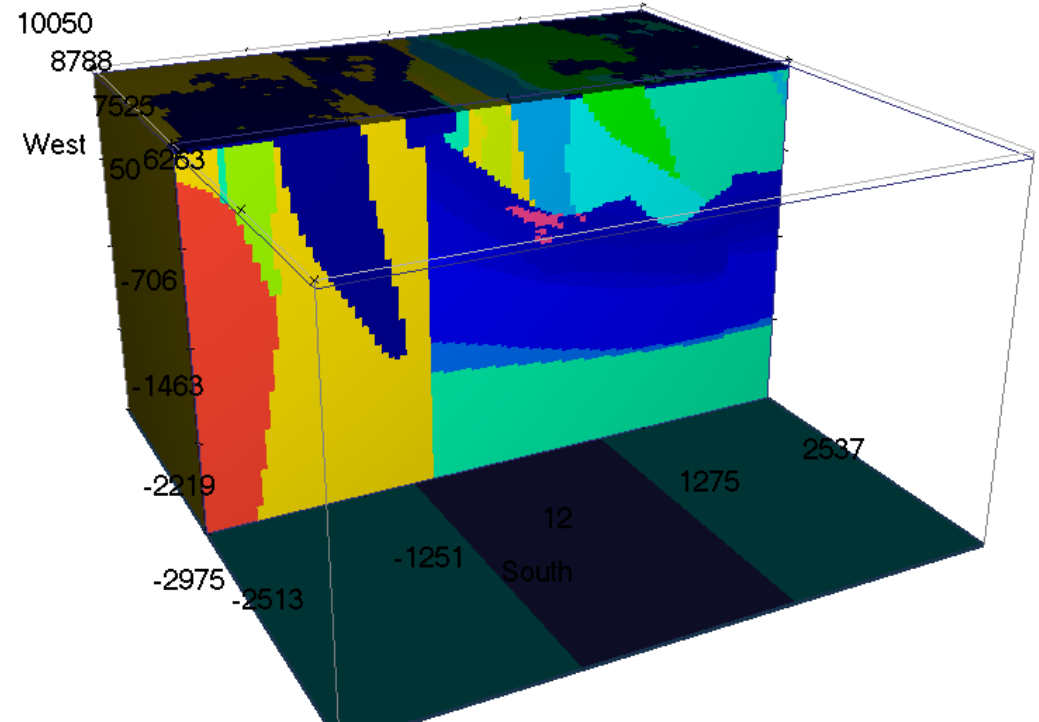
- In general:

$$Z = \begin{pmatrix} Z_{xx} & Z_{xy} \\ Z_{yx} & Z_{yy} \end{pmatrix}$$

- In 3D:

$$Z = \begin{pmatrix} Z_{xx} & Z_{xy} \\ Z_{yx} & Z_{yy} \end{pmatrix}$$

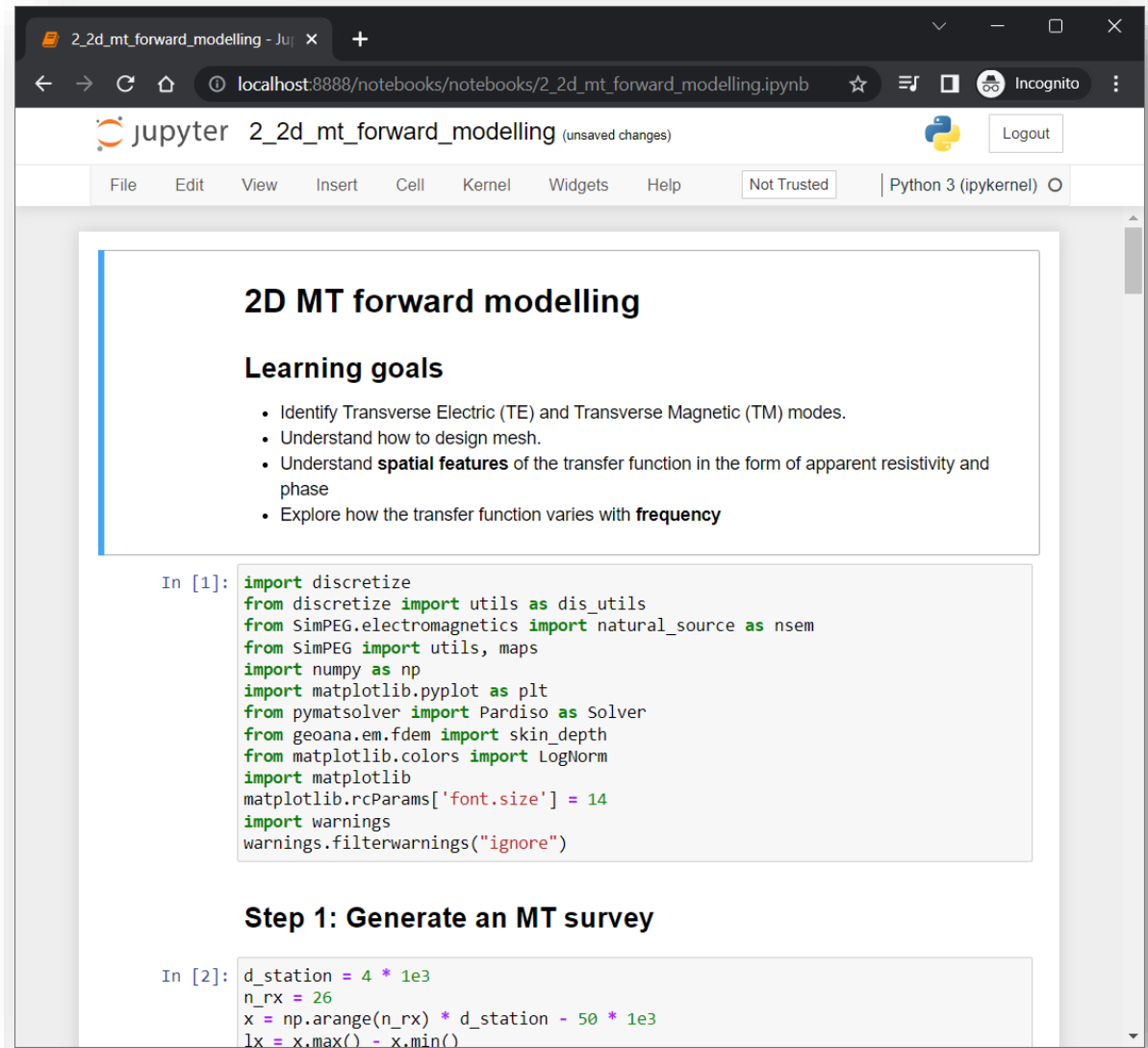
- No symmetry or special conditions



Demo: 2D MT forward modelling app

Why interactive apps?

- Visualization aids understanding
- Learn through interaction
ask questions and investigate
- Open source:
Free to use
Welcome contributions!



The screenshot shows a web browser window displaying a Jupyter Notebook titled "2_2d_mt_forward_modelling". The browser address bar shows "localhost:8888/notebooks/notebooks/2_2d_mt_forward_modelling.ipynb". The Jupyter interface includes a menu bar with options like File, Edit, View, Insert, Cell, Kernel, Widgets, and Help. Below the menu bar, there's a status bar indicating "Not Trusted" and "Python 3 (ipykernel)". The notebook content is displayed in a light blue box with the following structure:

2D MT forward modelling

Learning goals

- Identify Transverse Electric (TE) and Transverse Magnetic (TM) modes.
- Understand how to design mesh.
- Understand **spatial features** of the transfer function in the form of apparent resistivity and phase
- Explore how the transfer function varies with **frequency**

```
In [1]: import discretize
from discretize import utils as dis_utils
from SimPEG.electromagnetics import natural_source as nsem
from SimPEG import utils, maps
import numpy as np
import matplotlib.pyplot as plt
from pymatsolver import Pardiso as Solver
from geoana.em.fdem import skin_depth
from matplotlib.colors import LogNorm
import matplotlib
matplotlib.rcParams['font.size'] = 14
import warnings
warnings.filterwarnings("ignore")
```

Step 1: Generate an MT survey

```
In [2]: d_station = 4 * 1e3
n_rx = 26
x = np.arange(n_rx) * d_station - 50 * 1e3
lx = x.max() - x.min()
```

Learning goals

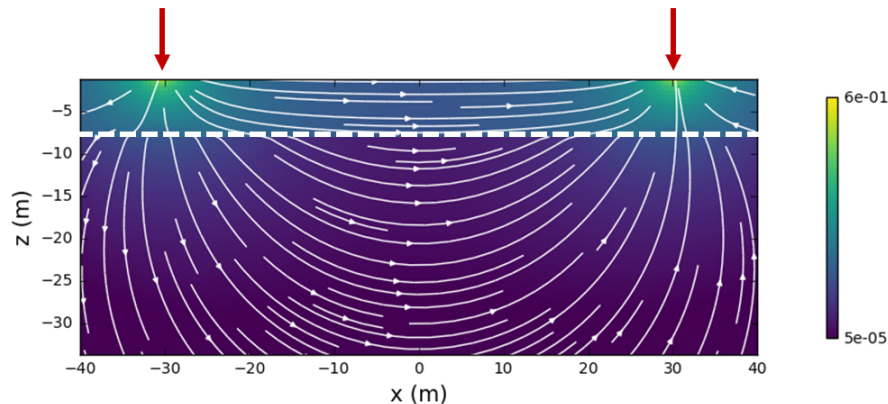
Understand electrical resistivity and its linkage to geologic units.

Understand physical principles of Electromagnetic (EM) methods

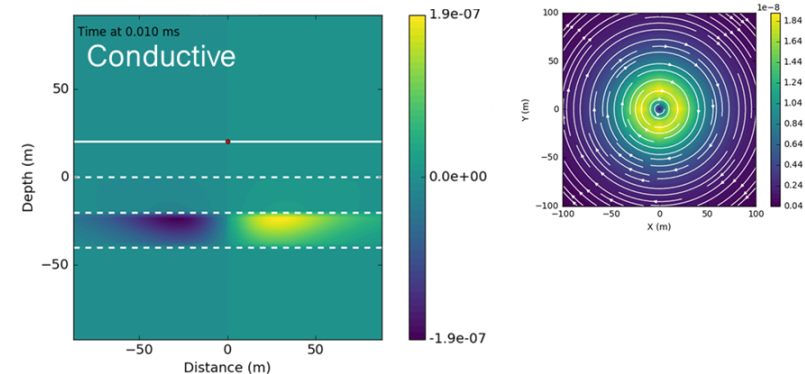
- Charge build-up (or current channeling, galvanic currents)
- EM induction

DC resistivity vs. Inductive source EM

E-fields crosses the layer boundary
(charge build-up; galvanic currents; current channeling)

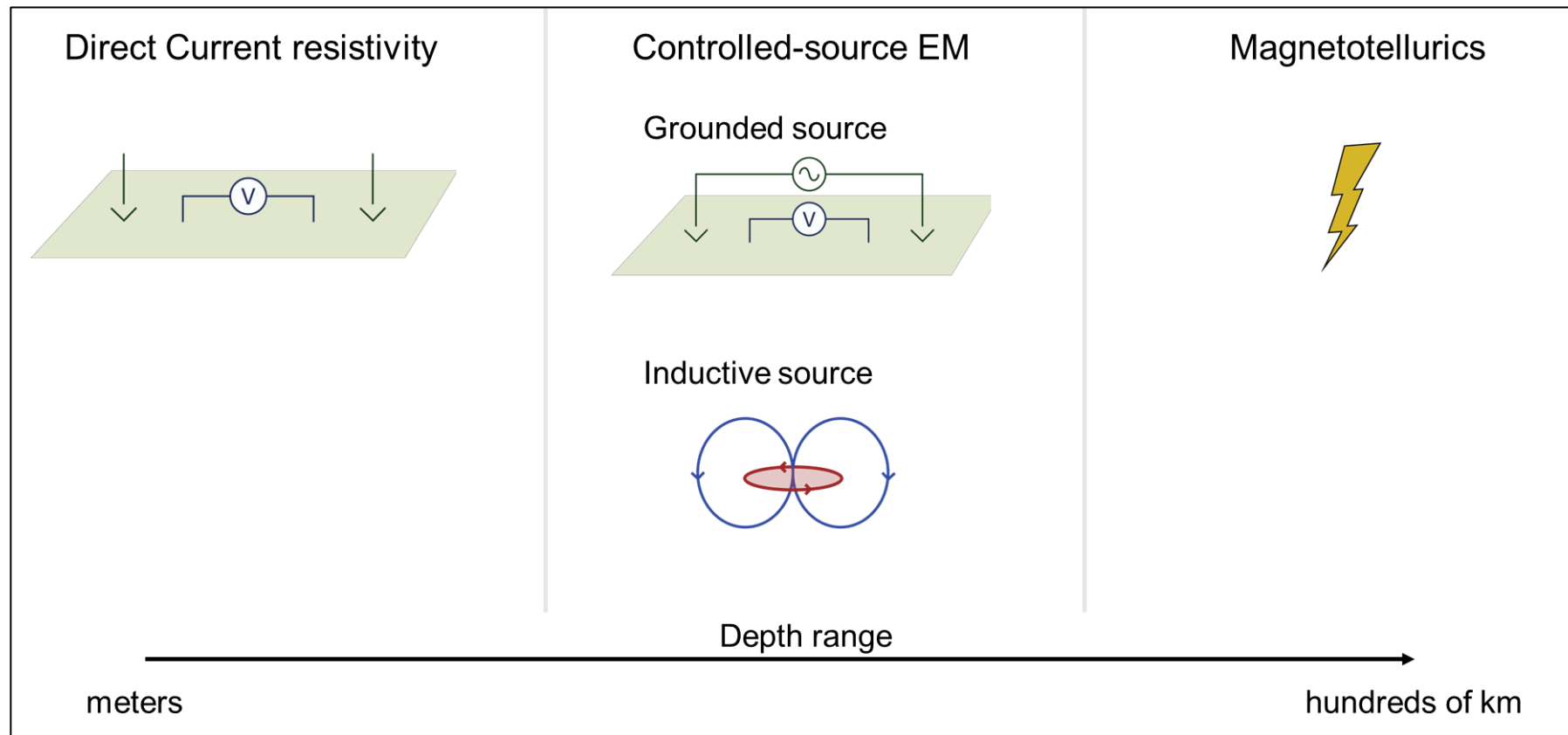


E-fields parallel to the layer boundary
(EM induction)



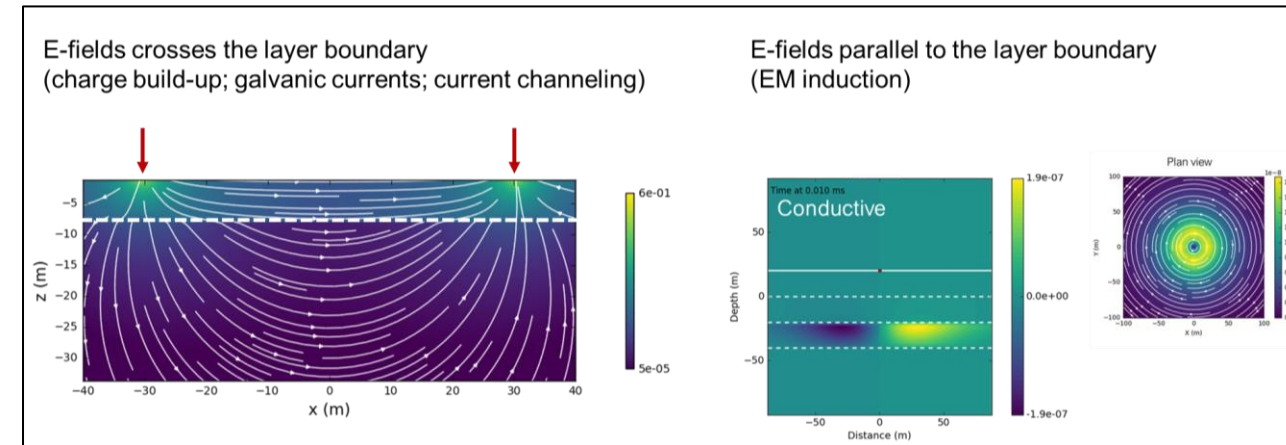
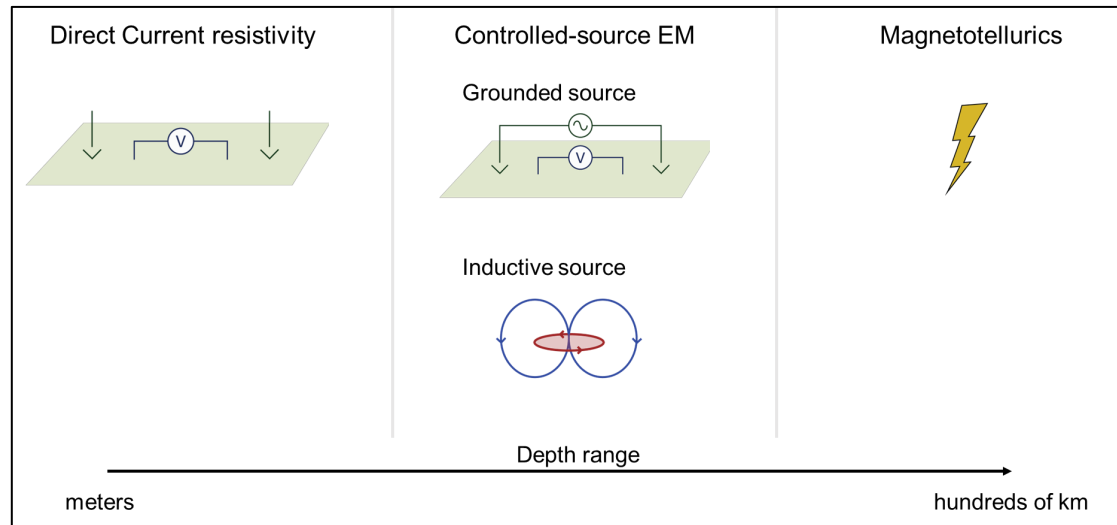
Learning goals

Identify difference between controlled-source EM and magnetotellurics (MT)



Learning goals

Identify all EM methods are governed by the same physical principles



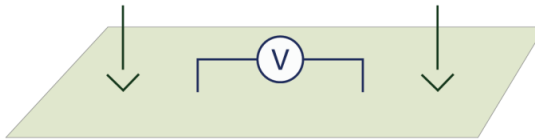
Current channeling
EM induction

Learning goals

Understand survey setup of EM methods and data

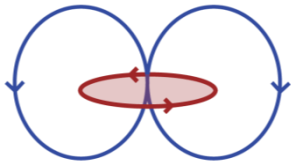
Understand sensitivity of EM methods to conductors & resistors

DC resistivity



Current channeling
Sensitive to both conductors and resistors

Inductive source EM



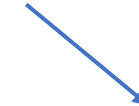
EM induction
Biased sensitivity towards conductors



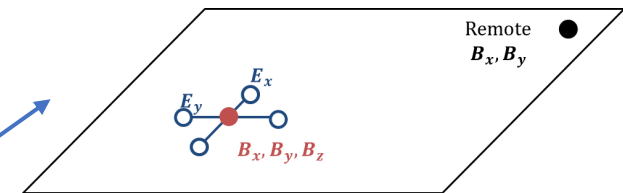
Magnetotellurics



TM mode

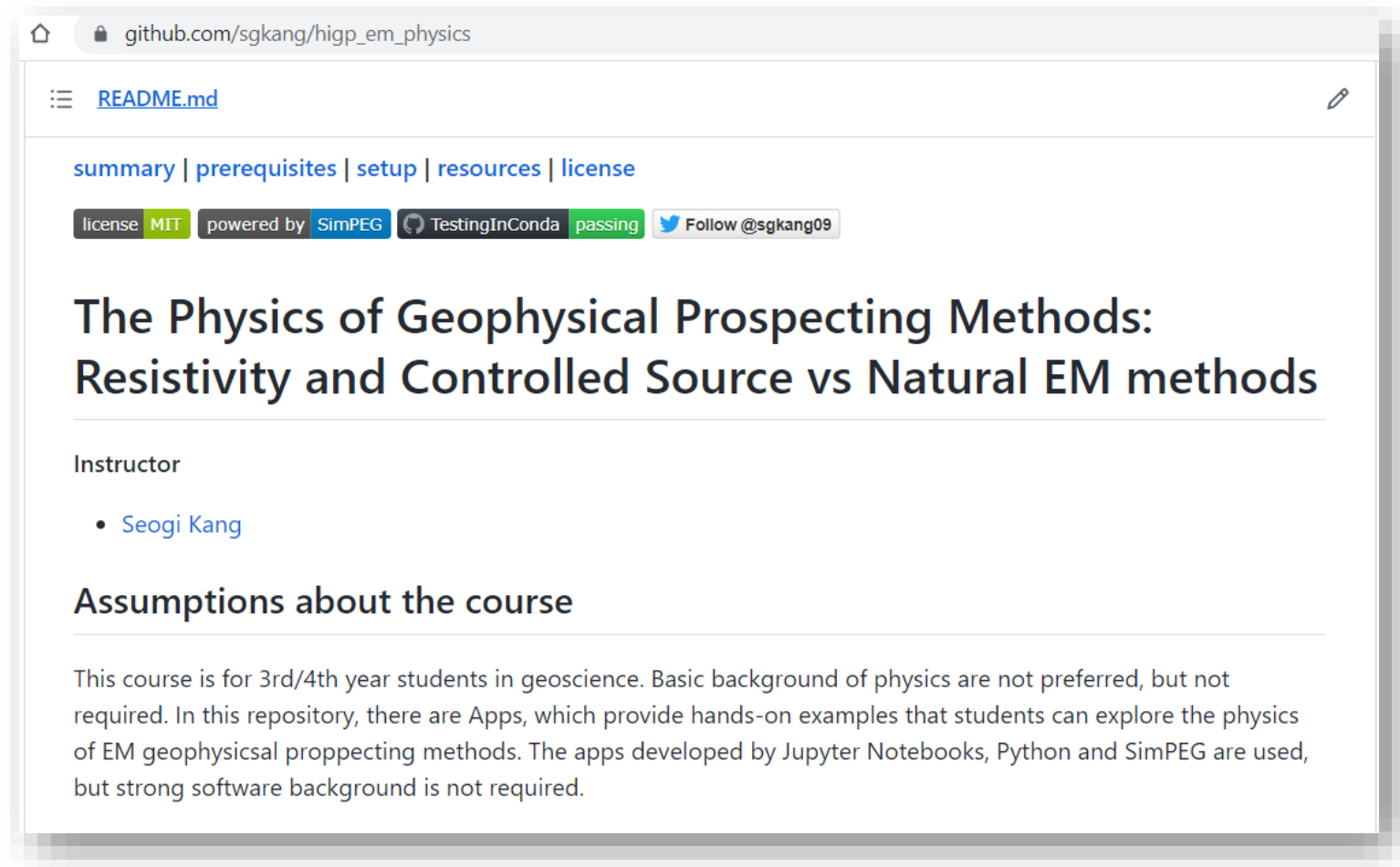


TE mode



Resources:

https://github.com/sgkang/higp_em_physics



The end