

CSE331

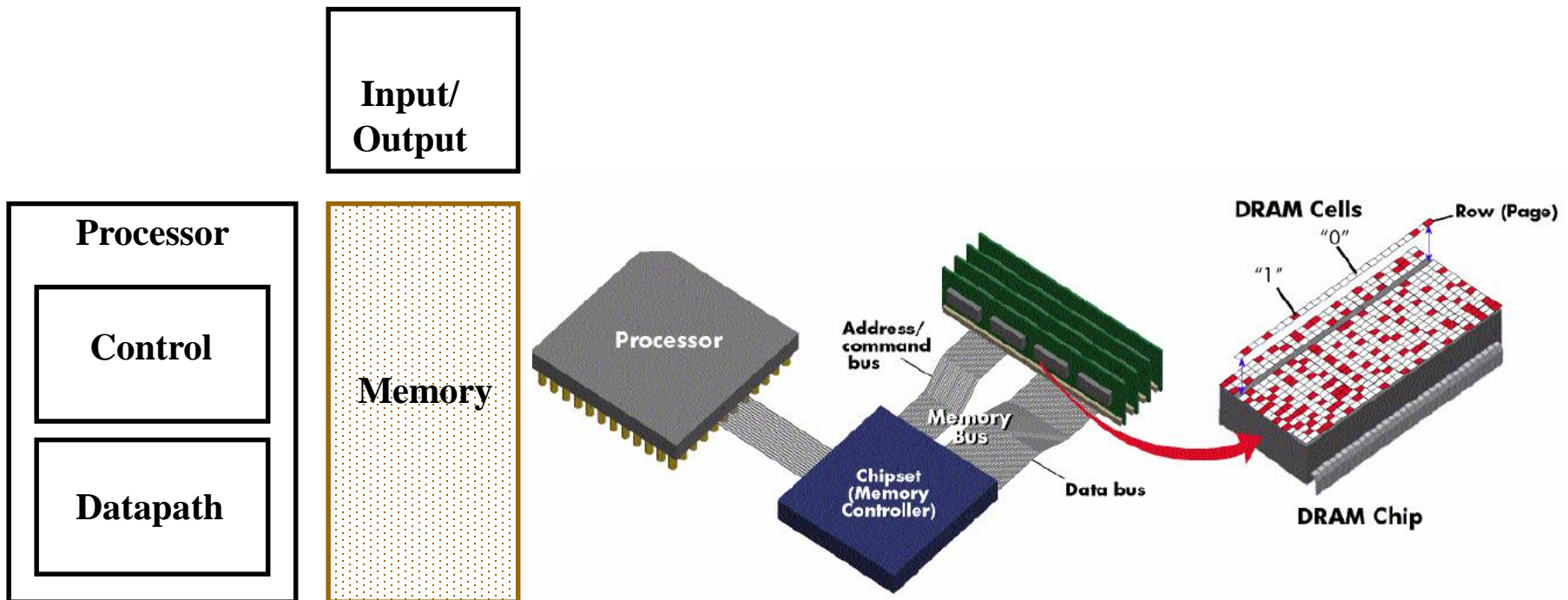
Computer Organization

Memory Hierarchy and Cache Design

Lecture 12

The Big Picture: Where are We Now?

- The Five Classic Components of a Computer
- Memory is usually implemented as:
 - ❑ Dynamic Random Access Memory (DRAM) - for main memory
 - ❑ Static Random Access Memory (SRAM) - for cache



Technology Trends

	Capacity	Speed (latency)
Logic:	2x in 3 years	2x in 3 years
DRAM:	4x in 3 years	2x in 10 years
Disk:	4x in 3 years	2x in 10 years

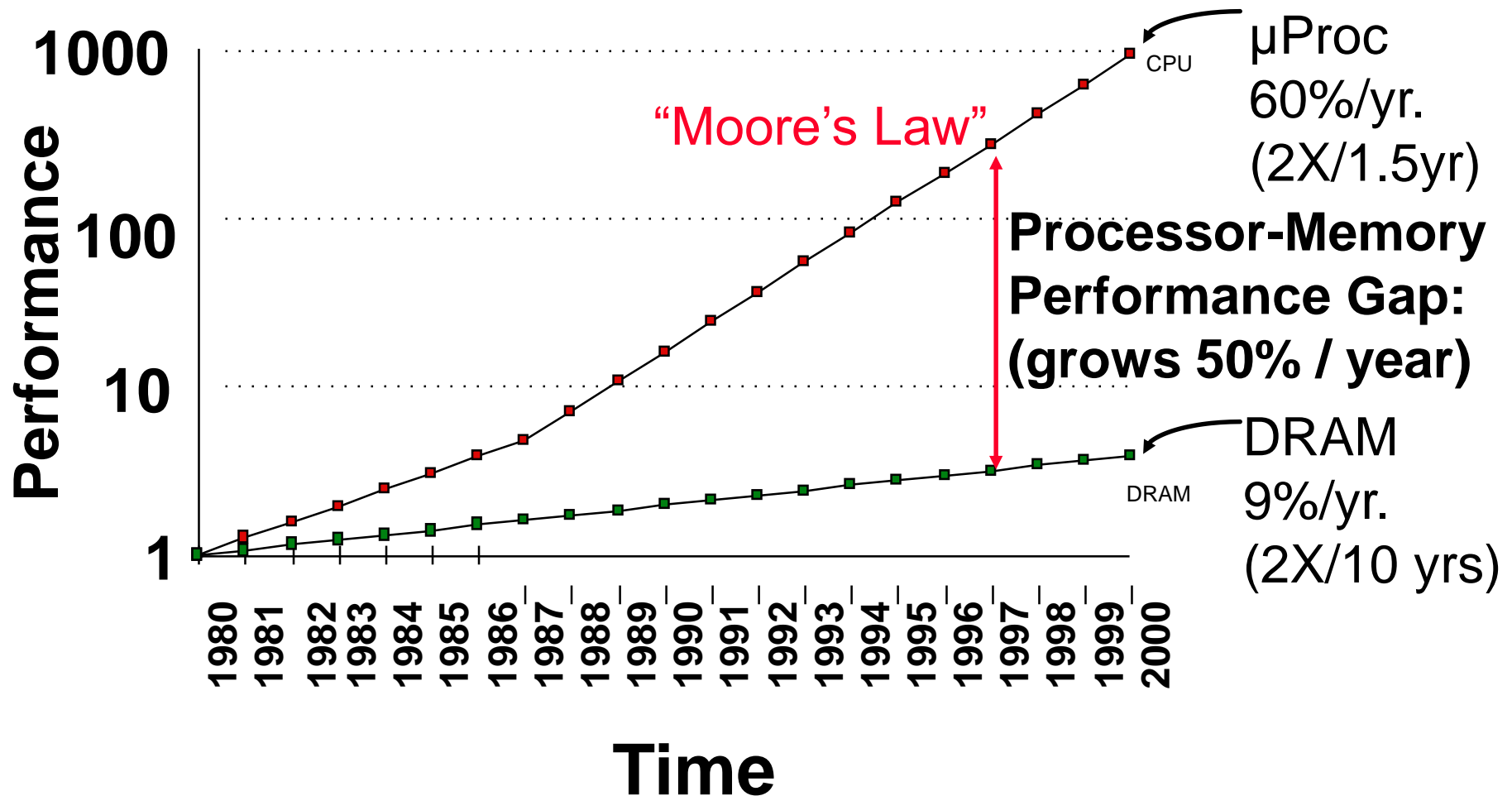
DRAM		
Year	Size	Cycle Time
1980	64 Kb	250 ns
1983	256 Kb	220 ns
1986	1 Mb	190 ns
1989	4 Mb	165 ns
1992	16 Mb	145 ns
1995	64 Mb	120 ns
1998	256 Mb	100 ns
2001	1 Gb	80 ns

1000:1!

2:1!

Who Cares About Memory?

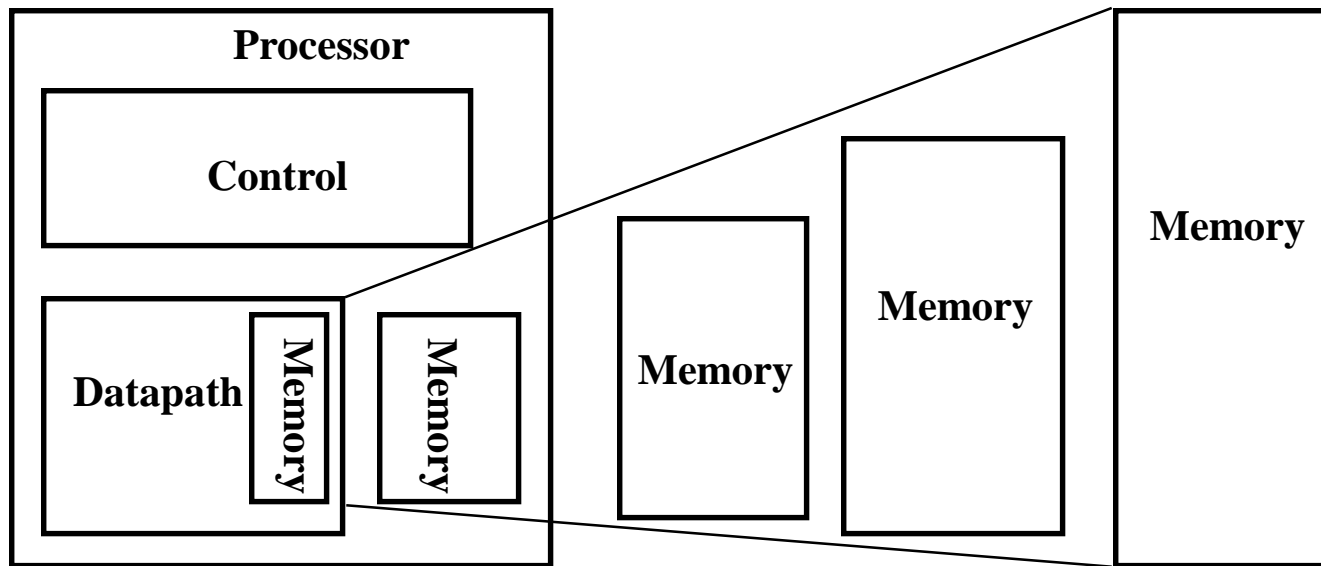
Processor-DRAM Memory Gap (latency)



Today's Situation: Microprocessors

- Rely on caches to bridge gap
- Cache is a high-speed memory between the processor and main memory
- 1980: no cache in μ proc;
1997 2-level cache, on Alpha 21164 μ proc

An Expanded View of the Memory System



Speed: Fastest
Size: Smallest
Cost: Highest

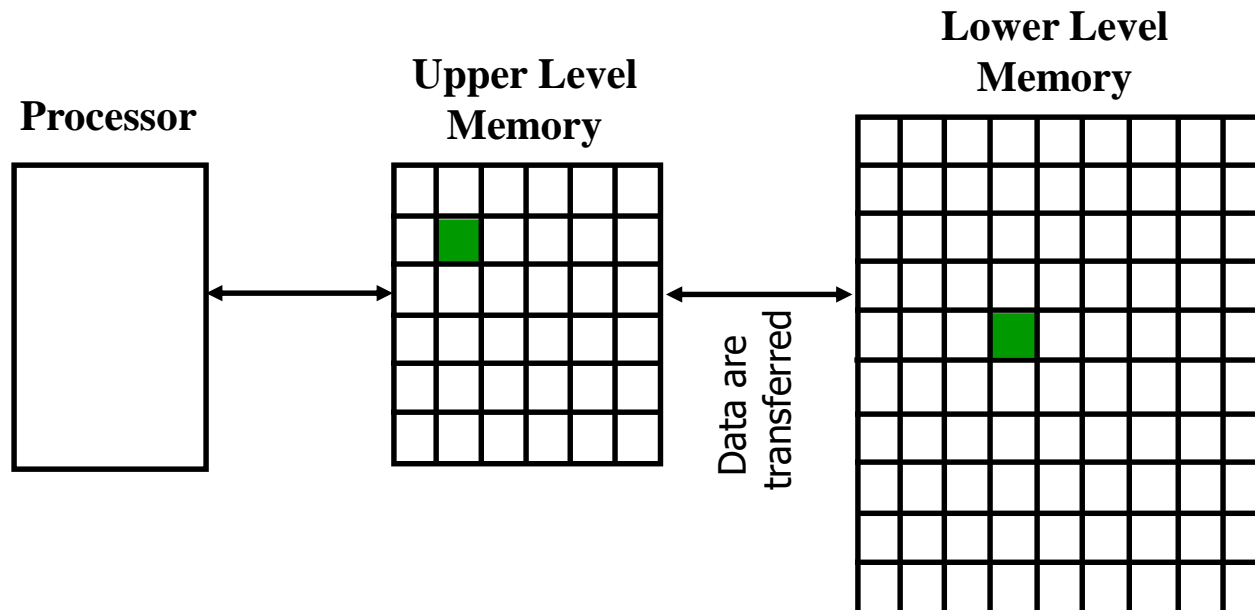
Slowest
Biggest
Lowest

Taking Advantage of Locality

- Memory hierarchy
- Store everything on disk
- Copy recently accessed (and nearby) items from disk to smaller DRAM memory
 - Main memory
- Copy more recently accessed (and nearby) items from DRAM to smaller SRAM memory
 - Cache memory attached to CPU

Memory Hierarchy: How Does it Work?

- **Temporal Locality** (Locality in Time):
 - => Keep most recently accessed data items closer to the processor
- **Spatial Locality** (Locality in Space):
 - => Move blocks consists of contiguous words to the upper levels



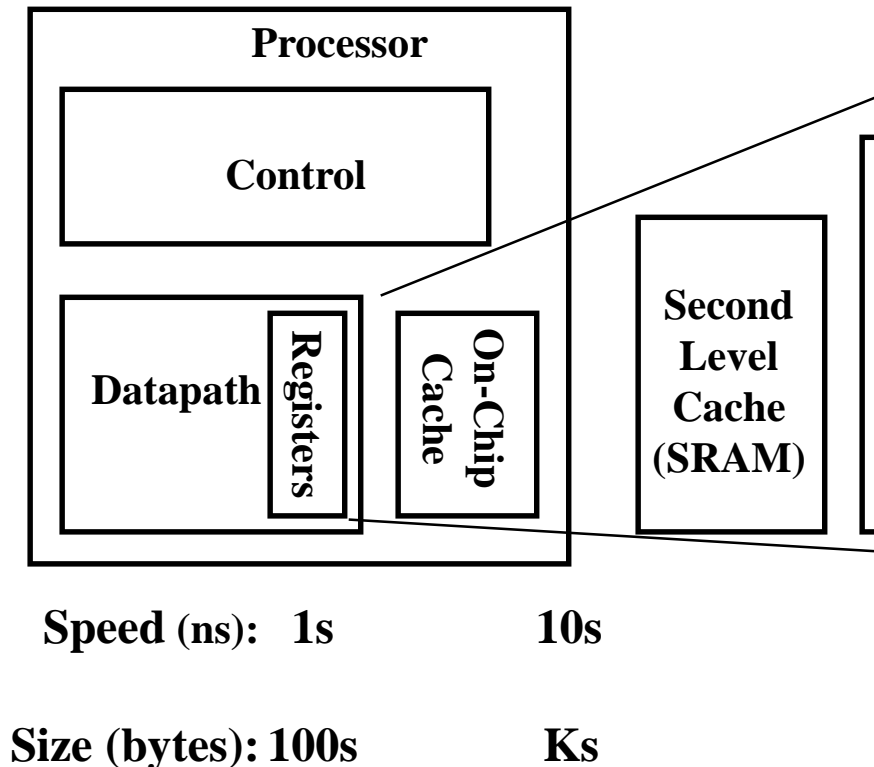
Memory Hierarchy: Terminology

- **Hit**: If the data requested by a processor appears in some block in the upper level.
 - **Hit Time**: Time to access the upper level which consists of RAM access time + Time to determine hit/miss
 - **Hit Rate**: The fraction of memory access found in the upper level
- **Miss**: If the data is not found in the upper level.
 - **Miss Rate** = $1 - (\text{Hit Rate})$
 - **Miss Penalty**: Time to replace a block in the upper level + Time to deliver the block the processor
- **Hit Time** \ll **Miss Penalty**

Memory Hierarchy of a Modern Computer System

- By taking advantage of the principle of locality:

- Present the user with as much cheapest technology.
- Provide access at the speed of



How is the hierarchy managed?

- Registers <-> Memory
 - by compiler (programmer?)
- cache <-> memory
 - by the hardware
- memory <-> disks
 - by the hardware and operating system (virtual memory)
 - by the programmer (files)

Memory Hierarchy Technology

- Random Access:
 - “Random” is good: access time is the same for all locations
 - **DRAM**: Dynamic Random Access Memory
 - High density, low power, cheap, slow
 - Dynamic: need to be “refreshed” regularly
 - **SRAM**: Static Random Access Memory
 - Low density, high power, expensive, fast
 - Static: content will last “forever” (until lose power)
- “Non-so-random” Access Technology:
 - Access time varies from location to location and from time to time
 - Examples: Disk, CDROM
- Sequential Access Technology: access time linear in location (e.g., Tape)

General Principles of Memory

■ Locality

- *Temporal Locality* : referenced memory is likely to be referenced again soon (e.g. code within a loop)
- *Spatial Locality* : memory close to referenced memory is likely to be referenced soon (e.g., data in a sequentially access array)

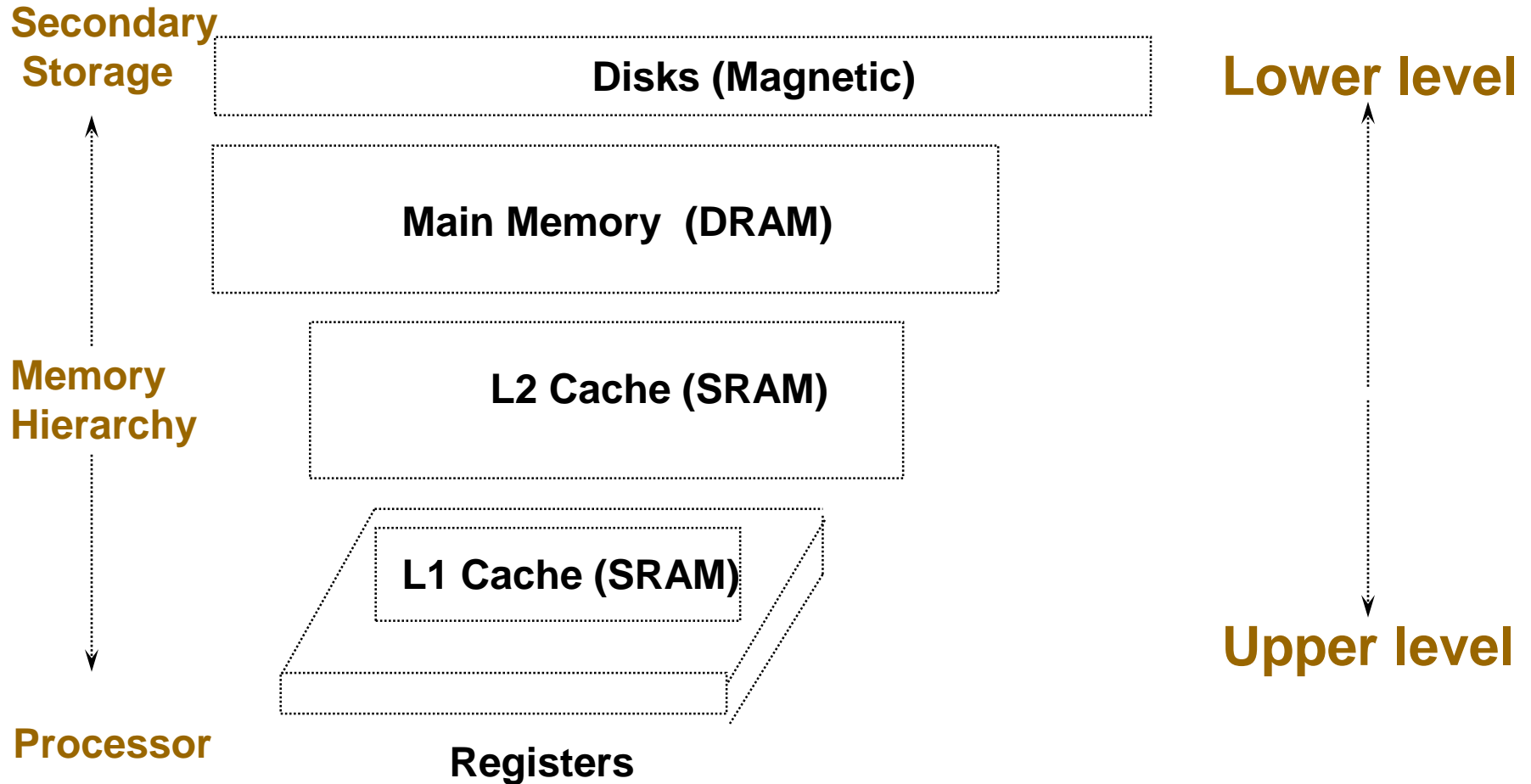
■ Definitions

- *Upper* : memory closer to processor
- *Block* : minimum unit that is present or not present
- *Block address* : location of block in memory
- *Hit* : Data is found in the desired location
- *Hit time* : time to access upper level
- *Miss rate* : percentage of time item not found in upper level

■ Locality + smaller HW is faster = memory hierarchy

- *Levels* : each smaller, faster, more expensive/byte than level below
- *Inclusive* : data found in upper level also found in the lower level

Memory Hierarchy



Differences in Memory Levels (2005)

Level	Memory Technology	Typical Size	Typical Access Time	Cost per Mbyte
Registers	D Flip-Flops	64 32-bit	2 -3 ns	N/A
L1 Cache (on chip)	SRAM	16 Kbytes	5 - 25 ns	\$100 - \$250
L2Cache (off chip)	SRAM	256 Kbytes	5 - 25 ns	\$100 - \$250
Main Memory	DRAM	256 Mbytes	60 - 120 ns	\$5 - \$10
Secondary Storage	Magnetic Disk	8 Gbytes	10 - 20 ms	\$0.10-\$0.20

Memory Technology

- Static RAM (SRAM)
 - 0.5ns – 2.5ns, \$2000 – \$5000 per GB
- Dynamic RAM (DRAM)
 - 50ns – 70ns, \$20 – \$75 per GB
- Magnetic disk
 - 5ms – 20ms, \$0.20 – \$2 per GB
- Ideal memory
 - Access time of SRAM
 - Capacity and cost/GB of disk

Four Questions for Memory Hierarchy Designers

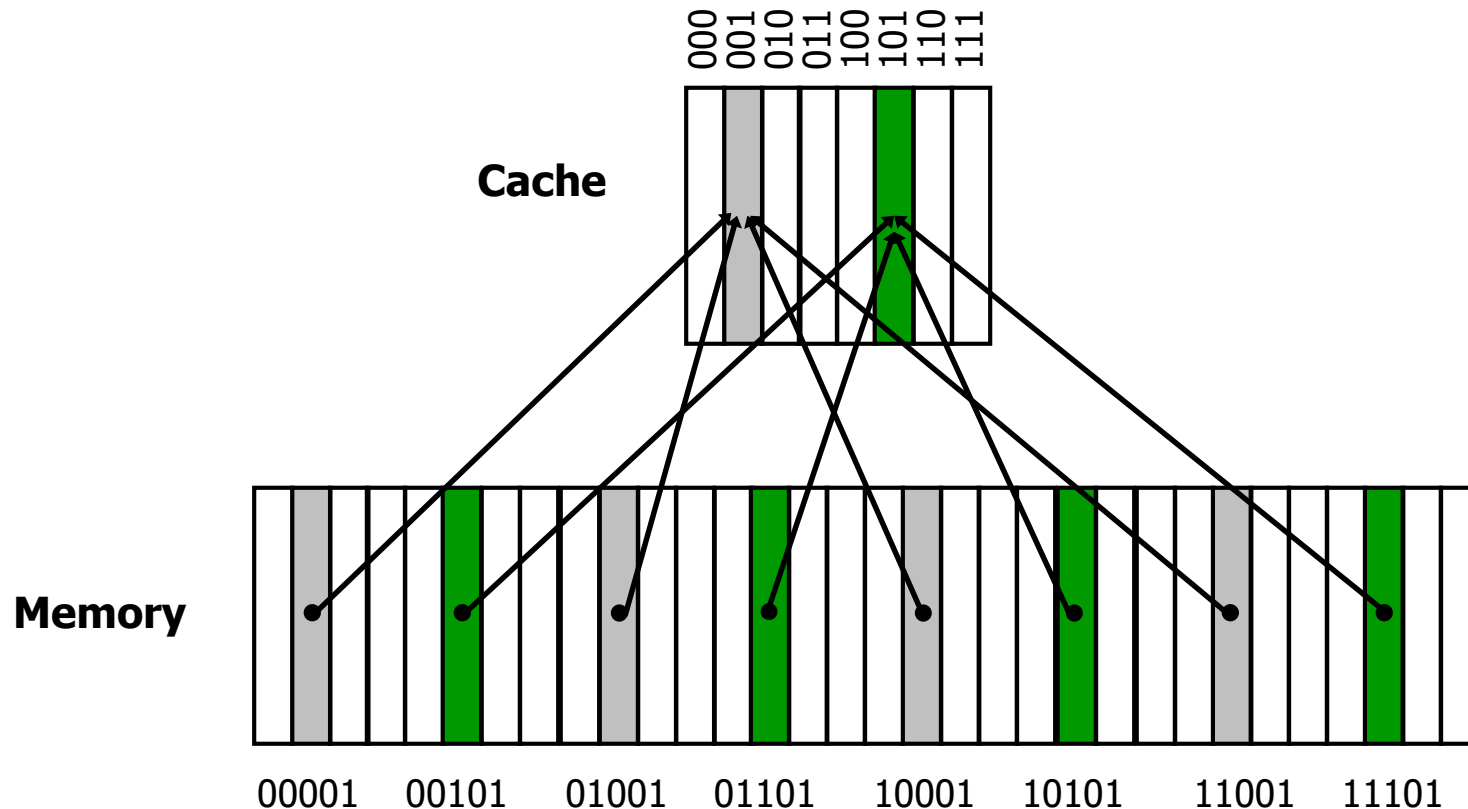
- Q1: Where can a block be placed in the upper level?
(Block placement)
- Q2: How is a block found if it is in the upper level?
(Block identification)
- Q3: Which block should be replaced on a miss?
(Block replacement)
- Q4: What happens on a write?
(Write strategy)

Q1: Where can a block be placed?

- **Direct Mapped:** Each block has only one place that it can appear in the cache.
- **Fully associative:** Each block can be placed anywhere in the cache.
- **Set associative:** Each block can be placed in a restricted set of places in the cache.
 - If there are n blocks in a set, the cache is called n -way set associative
- What is the associativity of a direct mapped cache?

Direct Mapped Caches

- Mapping for direct mapped cache:
(Block address) MOD (Number of blocks in the cache)



Cache Example

- 8-blocks, 1 word/block, direct mapped
- Initial state

Index	V	Tag	Data
000	N		
001	N		
010	N		
011	N		
100	N		
101	N		
110	N		
111	N		

Cache Example

Word addr	Binary addr	Hit/miss	Cache block
22	10 110	Miss	110

Index	V	Tag	Data
000	N		
001	N		
010	N		
011	N		
100	N		
101	N		
110	Y	10	Mem[10110]
111	N		

Cache Example

Word addr	Binary addr	Hit/miss	Cache block
26	11 010	Miss	010

Index	V	Tag	Data
000	N		
001	N		
010	Y	11	Mem[11010]
011	N		
100	N		
101	N		
110	Y	10	Mem[10110]
111	N		

Cache Example

Word addr	Binary addr	Hit/miss	Cache block
22	10 110	Hit	110
26	11 010	Hit	010

Index	V	Tag	Data
000	N		
001	N		
010	Y	11	Mem[11010]
011	N		
100	N		
101	N		
110	Y	10	Mem[10110]
111	N		

Cache Example

Word addr	Binary addr	Hit/miss	Cache block
16	10 000	Miss	000
3	00 011	Miss	011
16	10 000	Hit	000

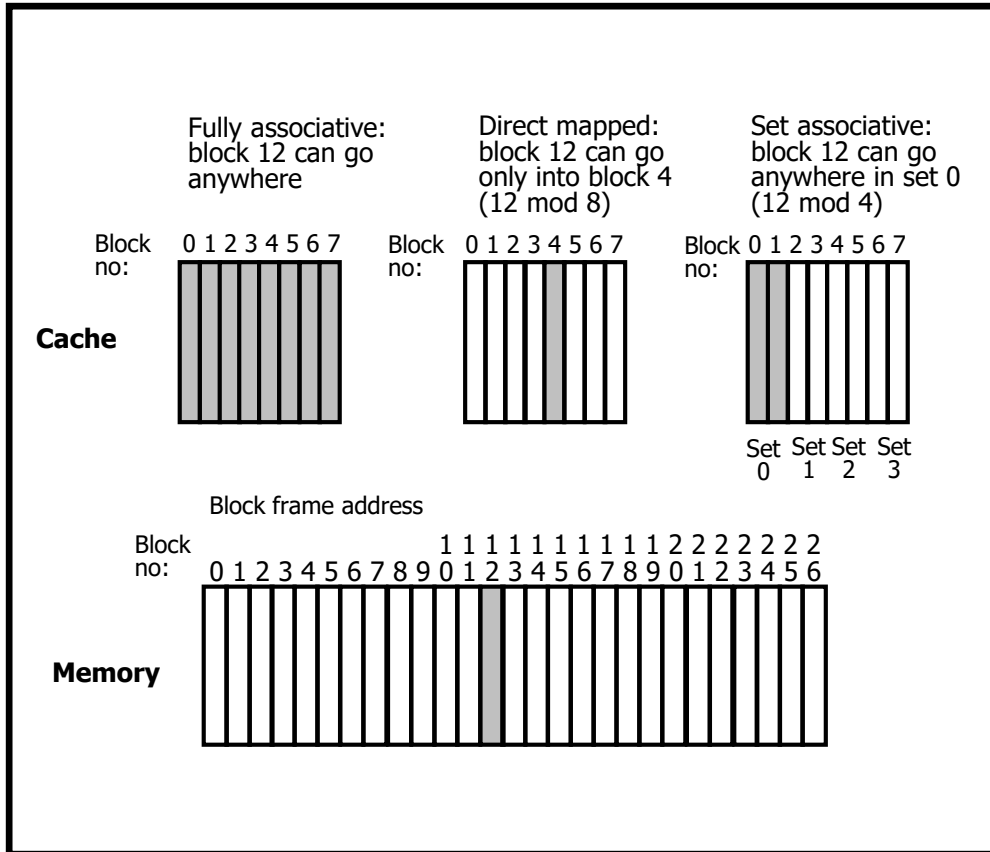
Index	V	Tag	Data
000	Y	10	Mem[10000]
001	N		
010	Y	11	Mem[11010]
011	Y	00	Mem[00011]
100	N		
101	N		
110	Y	10	Mem[10110]
111	N		

Cache Example

Word addr	Binary addr	Hit/miss	Cache block
18	10 010	Miss	010

Index	V	Tag	Data
000	Y	10	Mem[10000]
001	N		
010	Y	10	Mem[10010]
011	Y	00	Mem[00011]
100	N		
101	N		
110	Y	10	Mem[10110]
111	N		

Associativity Examples



Cache size is 8 blocks

Where does word 12 from memory go?

Fully associative:

Block 12 can go anywhere

Direct mapped:

Block no. = (Block address) mod
(No. of blocks in cache)

Block 12 can go only into block 4
($12 \bmod 8 = 4$)

=> Access block using lower 3 bits

2-way set associative:

Set no. = (Block address) mod
(No. of sets in cache)

Block 12 can go anywhere in set 0
($12 \bmod 4 = 0$)

=> Access set using lower 2 bits

Associativity Example

- Compare 4-block caches
 - ❑ Direct mapped, 2-way set associative, fully associative
 - ❑ Block access sequence: 0, 8, 0, 6, 8
- Direct mapped

Block address	Cache index	Hit/miss	Cache content after access			
			0	1	2	3
0	0	miss	Mem[0]			
8	0	miss	Mem[8]			
0	0	miss	Mem[0]			
6	2	miss	Mem[0]		Mem[6]	
8	0	miss	Mem[8]		Mem[6]	

Associativity Example

■ 2-way set associative

Block address	Cache index	Hit/miss	Cache content after access			
			Set 0		Set 1	
0	0	miss	Mem[0]			
8	0	miss	Mem[0]	Mem[8]		
0	0	hit	Mem[0]	Mem[8]		
6	0	miss	Mem[0]	Mem[6]		
8	0	miss	Mem[8]	Mem[6]		

■ Fully associative

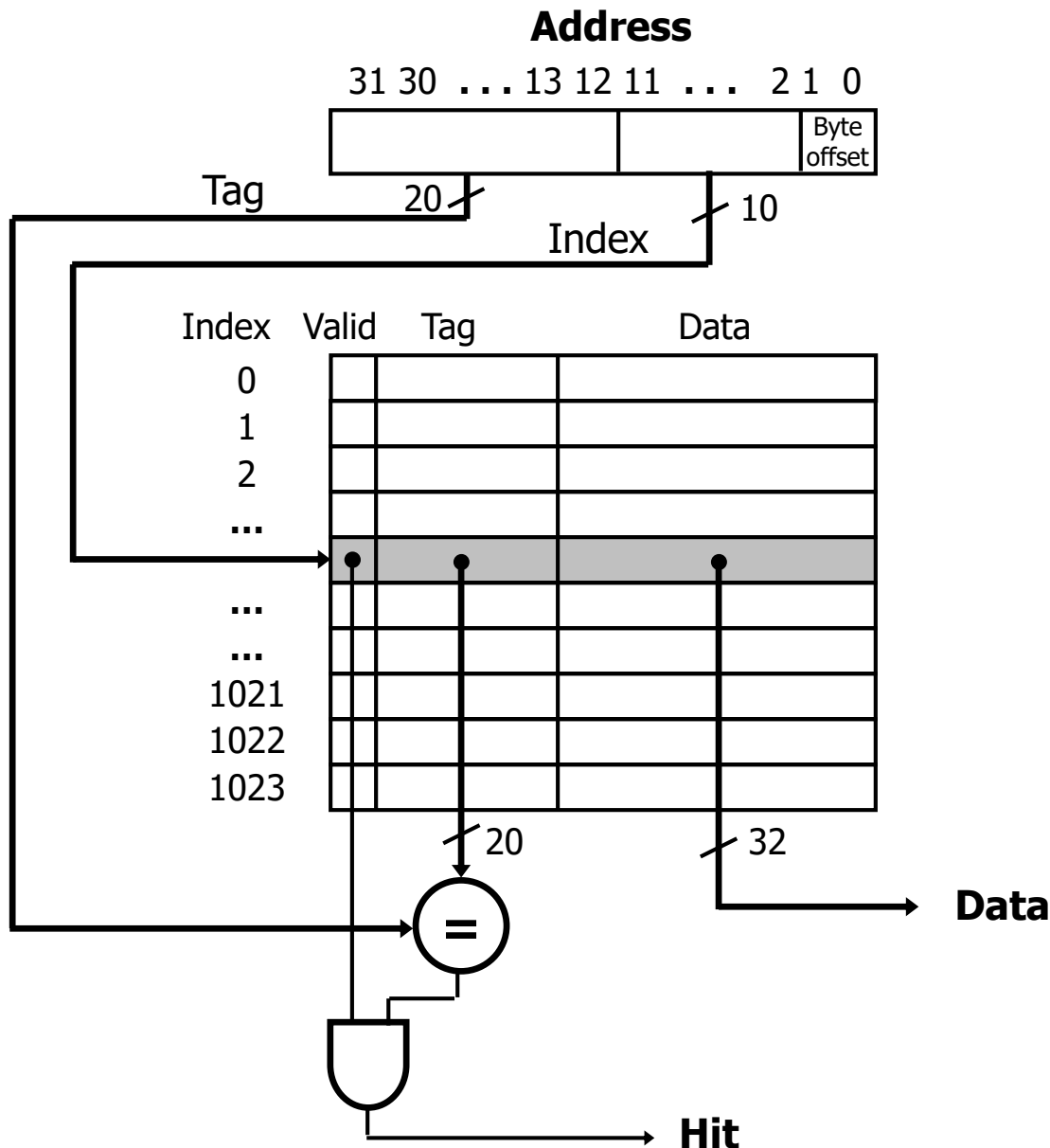
Block address		Hit/miss	Cache content after access			
0		miss	Mem[0]			
8		miss	Mem[0]	Mem[8]		
0		hit	Mem[0]	Mem[8]		
6		miss	Mem[0]	Mem[8]	Mem[6]	
8		hit	Mem[0]	Mem[8]	Mem[6]	

Q2: How Is a Block Found?



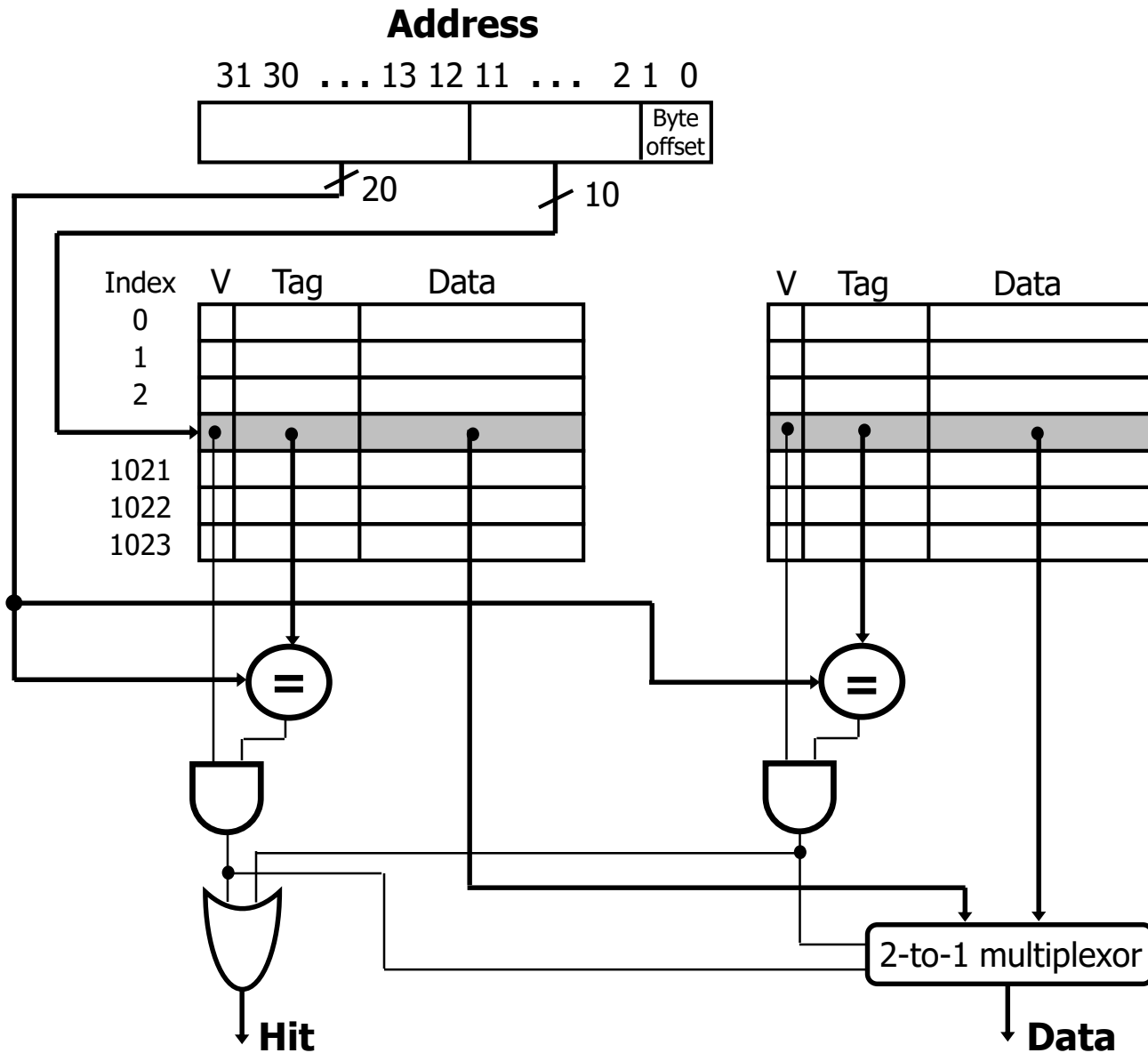
- The address can be divided into two main parts
 - **Block offset:** selects the data from the block
 $\text{offset size} = \log_2(\text{block size})$
 - **Block address:** tag + index
 - index: selects set in cache
 $\text{index size} = \log_2(\text{\#blocks/associativity})$
 - tag: compared to tag in cache to determine hit
 $\text{tag size} = \text{address size} - \text{index size} - \text{offset size}$
- Each block has a valid bit that tells if the block is valid - the block is in the cache if the tags match and the valid bit is set.

A 4-KB Cache Using 1-word (4-byte) Blocks



- **Cache index** is used to select the block
- **Tag field** is used to compare with the value of the tag filed of the cache
- **Valid** bit indicates if a cache block have valid information

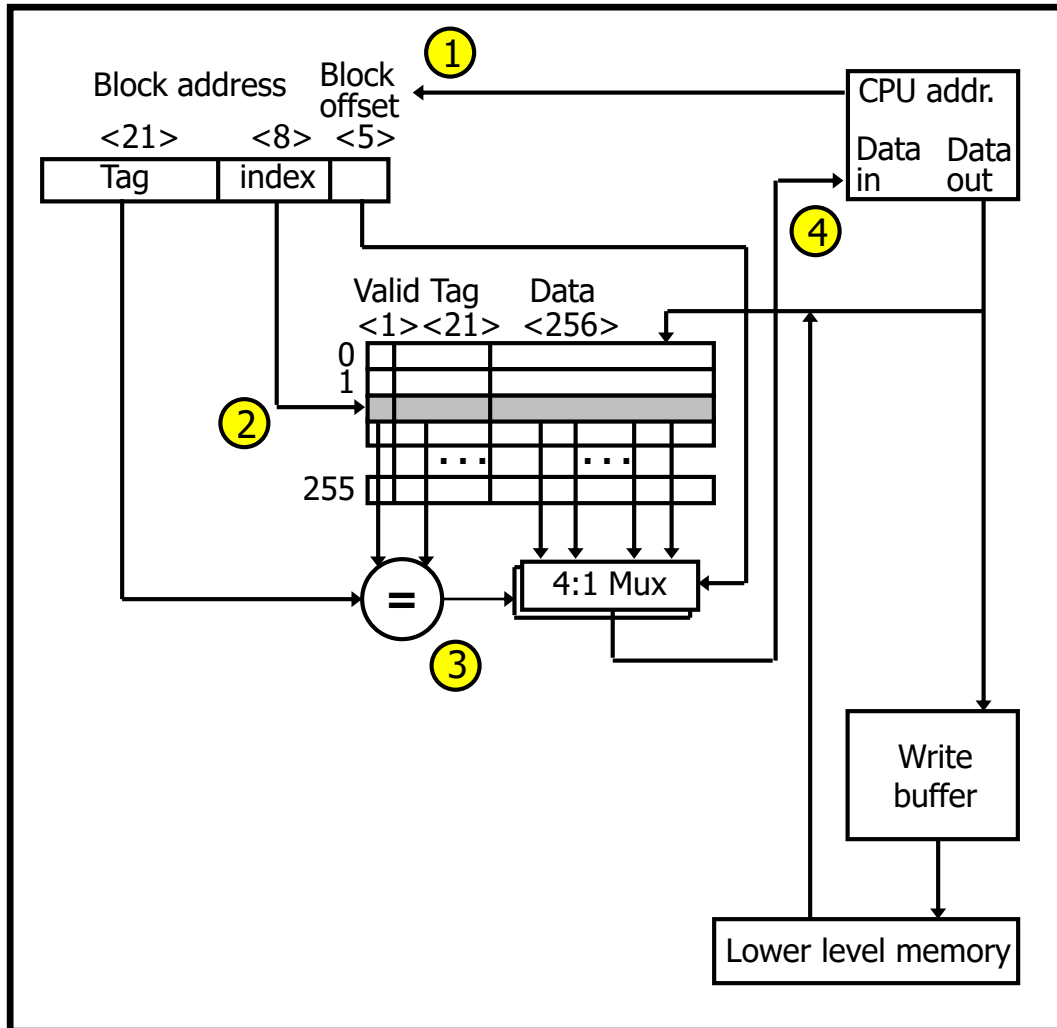
Two-way Set-associative Cache



Example: Alpha 21064 Data Cache

- The data cache of the Alpha 21064 has the following features
 - 8 KB of data
 - 32 byte blocks
 - Direct mapped placement
 - Write through (no-write allocate, 4-block write buffer)
 - 34 bit physical address composed of
 - 5 bit block offset
 - 8 bit index
 - 21 bit tag

Example: Alpha 21064 Data Cache



A cache read has 4 steps

- (1) The address from the cache is divided into the tag, index, and block offset
- (2) The index selects block
- (3) The address tag is compared with the tag in the cache, the valid bit is checked, and data to be loaded is selected
- (4) If the valid bit is set, the data is loaded into the processor

If there is a write, the data is also sent to the write buffer

Q3: Which Block Should be Replaced on a Miss?

- Easy for Direct Mapped - only on choice
- Set Associative or Fully Associative:
 - Random - easier to implement
 - Least Recently Used (the block has been unused for the longest time) - harder to implement
- Miss rates for caches with different size, associativity and replacement algorithm.

Associativity:	2-way		4-way		8-way	
Size	LRU	Random	LRU	Random	LRU	Random
16 KB	5.18%	5.69%	4.67%	5.29%	4.39%	4.96%
64 KB	1.88%	2.01%	1.54%	1.66%	1.39%	1.53%
256 KB	1.15%	1.17%	1.13%	1.13%	1.12%	1.12%

For caches with low miss rates, random is almost as good as LRU.

Cache Misses

- On cache hit, CPU proceeds normally
- On cache miss
 - Stall the CPU pipeline
 - Fetch block from next level of hierarchy
 - Instruction cache miss
 - Restart instruction fetch
 - Data cache miss
 - Complete data access

Q4: What Happens on a Write?

- **Write through:** The information is written to both the block in the cache and to the block in the lower-level memory.
- **Write back:** The information is written only to the block in the cache. The modified cache block is written to main memory only when it is replaced.
 - is block clean or dirty? (add a dirty bit to each block)

Write-Through

- On data-write hit, could just update the block in cache
 - But then cache and memory would be inconsistent
- Write through: also update memory
- But makes writes take longer
 - e.g., if base CPI = 1, 10% of instructions are stores, write to memory takes 100 cycles
 - Effective CPI = $1 + 0.1 \times 100 = 11$
- Solution: write buffer
 - Holds data waiting to be written to memory
 - CPU continues immediately
 - Only stalls on write if write buffer is already full

Write-Back

- Alternative: On data-write hit, just update the block in cache
 - Keep track of whether each block is dirty
- When a dirty block is replaced
 - Write it back to memory
 - Can use a write buffer to allow replacing block to be read first

Pros and Cons of each:

- Write through
 - Read misses cannot result in writes to memory,
 - Easier to implement
 - Always combine with write buffers to avoid memory latency
- Write back
 - Less memory traffic
 - Perform writes at the speed of the cache

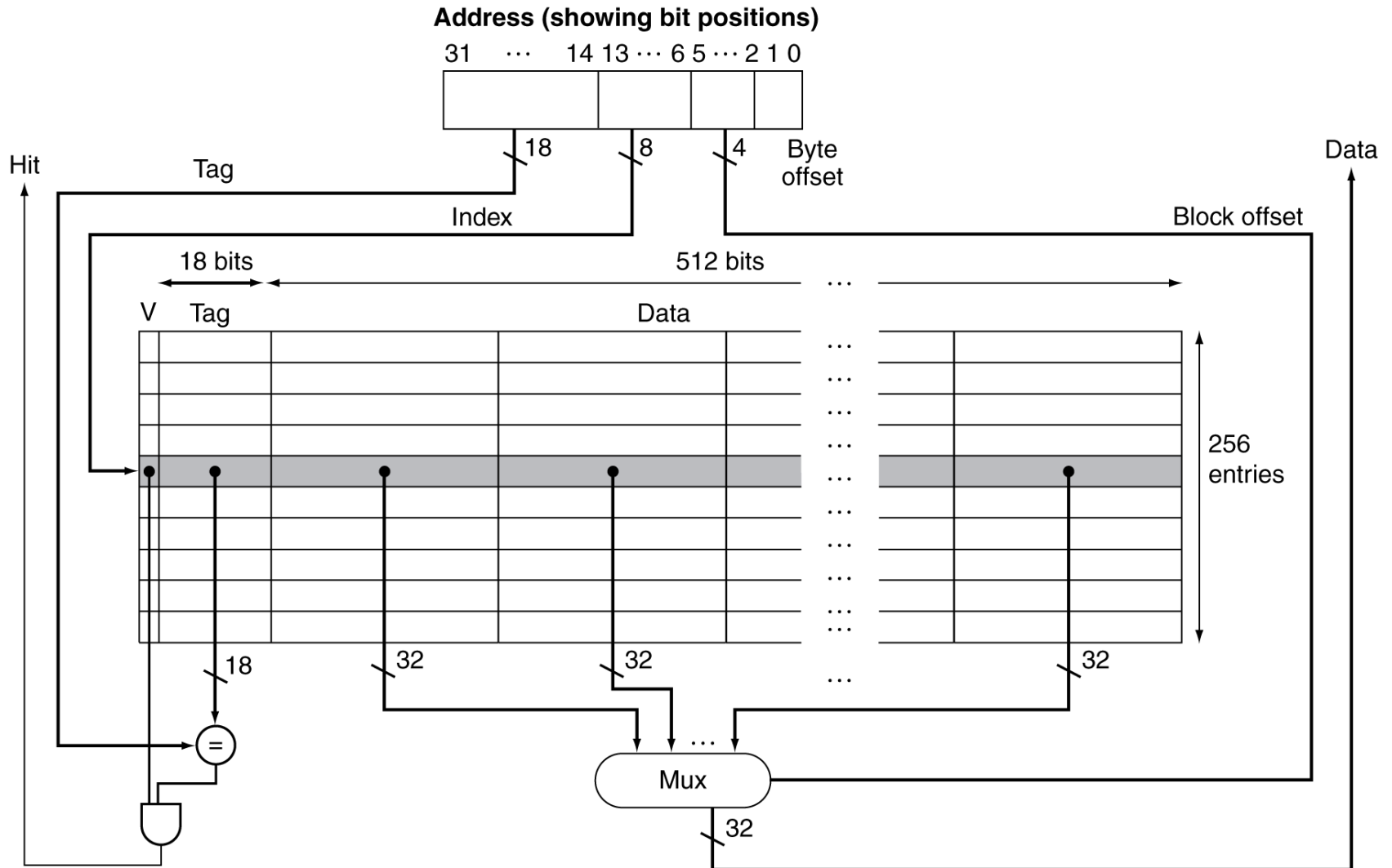
Q4: What Happens on a Write? CONT'D

- Since data does not have to be brought into the cache on a write miss, there are two options:
 - Write allocate
 - The block is brought into the cache on a write miss
 - Used with write-back caches
 - Hope subsequent writes to the block hit in cache
 - No-write allocate
 - The block is modified in memory, but not brought into the cache
 - Used with write-through caches
 - Writes have to go to memory anyway, so why bring the block into the cache

Example: Intrinsity FastMATH

- Embedded MIPS processor
 - 12-stage pipeline
 - Instruction and data access on each cycle
- Split cache: separate I-cache and D-cache
 - Each 16KB: $256 \text{ blocks} \times 16 \text{ words/block}$
 - D-cache: write-through or write-back
- SPEC2000 miss rates
 - I-cache: 0.4%
 - D-cache: 11.4%
 - Weighted average: 3.2%

Example: Intrinsity FastMATH



Calculating Bits in Cache

- How many total bits are needed for a direct- mapped cache with 64 KBytes of data and one word blocks, assuming a 32-bit address?
 - $64 \text{ Kbytes} = 16 \text{ K words} = 2^{14} \text{ words} = 2^{14} \text{ blocks}$
 - $\text{block size} = 4 \text{ bytes} \Rightarrow \text{offset size} = 2 \text{ bits},$
 - $\text{\#sets} = \text{\#blocks} = 2^{14} \Rightarrow \text{index size} = 14 \text{ bits}$
 - $\text{tag size} = \text{address size} - \text{index size} - \text{offset size} = 32 - 14 - 2 = 16 \text{ bits}$
 - $\text{bits/block} = \text{data bits} + \text{tag bits} + \text{valid bit} = 32 + 16 + 1 = 49$
 - $\text{bits in cache} = \text{\#blocks} \times (\text{bits/block}) = 2^{14} \times 49 = \mathbf{98 \text{ Kbytes}}$
- How many total bits would be needed for a 4-way set associative cache to store the same amount of data
 - block size and \#blocks does not change
 - $\text{\#sets} = \text{\#blocks}/4 = (2^{14})/4 = 2^{12} \Rightarrow \text{index size} = 12 \text{ bits}$
 - $\text{tag size} = \text{address size} - \text{index size} - \text{offset} = 32 - 12 - 2 = 18 \text{ bits}$
 - $\text{bits/block} = \text{data bits} + \text{tag bits} + \text{valid bit} = 32 + 18 + 1 = 51$
 - $\text{bits in cache} = \text{\#blocks} \times (\text{bits/block}) = 2^{14} \times 51 = \mathbf{102 \text{ Kbytes}}$
- Increase associativity \Rightarrow increase bits in cache

Calculating Bits in Cache

- How many total bits are needed for a direct-mapped cache with 64 KBytes of data and 8 word blocks, assuming a 32-bit address?
 - $64 \text{ Kbytes} = 2^{14} \text{ words} = (2^{14})/8 = 2^{11} \text{ blocks}$
 - $\text{block size} = 32 \text{ bytes} \Rightarrow \text{offset size} = 5 \text{ bits},$
 - $\# \text{sets} = \# \text{blocks} = 2^{11} \Rightarrow \text{index size} = 11 \text{ bits}$
 - $\text{tag size} = \text{address size} - \text{index size} - \text{offset size} = 32 - 11 - 5 = 16 \text{ bits}$
 - $\text{bits/block} = \text{data bits} + \text{tag bits} + \text{valid bit} = 8 \times 32 + 16 + 1 = 273 \text{ bits}$
 - $\text{bits in cache} = \# \text{blocks} \times (\text{bits/block}) = 2^{11} \times 273 = 68.25 \text{ Kbytes}$
- Increase block size \Rightarrow decrease bits in cache

Summary

- CPU-Memory gap is major performance obstacle for achieving high performance
- Memory hierarchies
 - Take advantage of program locality
 - Closer to processor => smaller, faster, more expensive
 - Further from processor => bigger, slower, less expensive
- 4 questions for memory hierarchy
 - Block placement, block identification, block replacement, and write strategy
- Cache parameters
 - Cache size, block size, associativity