

Math Problem Set # 4 *

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Exercises from **Chapter 6** and **Chapter 7** at “Humpherys, Jeffrey and Tyler J. Jarvis, Foundations of Applied Mathematics, Volume II: Algorithm Design and Optimization, forthcoming. SIAM, Philadelphia, PA.”

Chapter 6

Problem 6. Solving for the critical points:

$$\begin{aligned}f(x, y) &= 2x^2y + 4xy^2 + xy \\f_x &= 4xy + 4y^2 + y \\f_y &= 2x^2 + 8xy + x \\f_{xx} &= 4y \\f_{yy} &= 8x \\f_{xy} = f_{yx} &= 4x + 8y + 1\end{aligned}$$

Set $f_y = 0$, then

$$2x^2 + 8xy + x = 0 \Rightarrow x(2x + 8y + 1) = 0 \Rightarrow x = 0, y = \frac{-2x - 1}{8}$$

Set $f_x = 0$, then

$$\begin{aligned}4xy + 4y^2 + y &= 0 \\x = 0 \Rightarrow y(4y + 1) &= 0 \Rightarrow y = 0, -\frac{1}{4} \\y = \frac{-2x - 1}{8} \Rightarrow x = -\frac{1}{6}, -\frac{1}{2} \Rightarrow y &= -\frac{1}{12}, 0\end{aligned}$$

Therefore the critical points are $\{(0, 0), (0, -\frac{1}{4}), (-\frac{1}{6}, -\frac{1}{12}), (-\frac{1}{2}, 0)\}$. To determine whether the critical points are local min, max, or saddle points, refer to the determinant of the second derivative matrix. We have that:

$$\begin{aligned}D(0, 0) &= -1 \\D(0, -\frac{1}{4}) &= -1 \\D(-\frac{1}{6}, -\frac{1}{12}) &= \frac{1}{3} \\D(-\frac{1}{2}, 0) &= -1\end{aligned}$$

Therefore $(-\frac{1}{6}, -\frac{1}{12})$ is a local maximum and the rest are saddle points.

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Problem 7.

(i) Notice that $Q^T = (A^T + A)^T = A^T + A = A + A^T = Q$. Also, $x^T Ax = \sum_{i=1}^n a_{ij} x_i x_j = \sum_{i=1}^n a_{ji} x_i x_j = x^T A^T x$. Therefore $x^T Qx = 2x^T Ax$ and (6.17) is equivalent to

$$f(x) = x^T Qx/2 - b^T x + c.$$

(ii) The first order necessary conditions for a minimizer imply $Q^T x^* = b$, since $f'(x) = Q^T x - b$.

(iii) If Q is positive definite, then $f''(x) > 0$ for any x . Also, Q is invertible and by (6.19) we have that $x^* = Q^{-1}b$ is such that $f'(x^*) = 0$. Then by the second order sufficient condition, x^* is the unique minimizer of f . Now assume x^* is the unique minimizer of f . Then by the second order necessary condition, Q is positive semi-definite. Also, x^* is a solution to $Q^T x^* = b$. If Q has at least one zero eigenvalue, then x^* is not unique. Therefore Q must be positive definite.

Problem 11. Let $f(x) = ax^2 + bx + c$ where $a > 0$ and $b, c \in \mathbb{R}$. Then

$$x_1 = x_0 - \frac{f'(x_0)}{f''(x_0)} = x_0 - \frac{2ax_0 + b}{2a} = -\frac{b}{2a}$$

The first derivative of f is $2ax + b = 0$. Then the critical point is $-\frac{b}{2a}$. Checking the second derivative $2a > 0$ so the point is a local minimizer and Newton's method converges within one iteration.

Chapter 7

Problem 1. Set arbitrary elements, $x, y \in \text{conv}(S)$. Then, by the definition of convex hull, $x = \sum_{i=1}^k \lambda_i s_i$, and $y = \sum_{i=1}^k \mu_i s_i$. Then, set an arbitrary scalar, $\lambda \in [0, 1]$. Then,

$$\lambda x + (1 - \lambda)y = \sum_{i=1}^k (\lambda \lambda_i + (1 - \lambda)\mu_i) s_i$$

Note that $\sum_{i=1}^k (\lambda \lambda_i + (1 - \lambda)\mu_i) = 1$. Thus, $\lambda x + (1 - \lambda)y \in \text{conv}(S)$

Problem 2.

(i) Let $P = \{x \in V \mid \langle a, x \rangle = b\}$, a hyperplane in V . Then, pick arbitrary $x, y \in P$,

satisfying $\langle a, x \rangle = b$ and $\langle a, y \rangle = b$. Then, for arbitrary scalar $\lambda \in [0, 1]$, the following is satisfied;

$$\langle a, \lambda x + (1 - \lambda)y \rangle = \lambda \langle a, x \rangle + (1 - \lambda) \langle a, y \rangle = b$$

Thus, $\lambda x + (1 - \lambda)y \in P$. (ii)

Proof. The argument is the same as above.

Problem 4.

(i)

$$\begin{aligned} \|x - y\|^2 &= \|x - p + p - y\|^2 \\ &= \langle x - p + p - y, x - p + p - y \rangle \\ &= \|x - p\|^2 + \|p - y\|^2 + 2 \langle x - p, p - y \rangle \end{aligned}$$

(ii) By the assumption that $p \neq y$, $\|p - y\|^2 > 0$. If we have the assumption that $\langle x - p, p - y \rangle \geq 0$, using (i), the statement trivially holds. (iii) Using (i),

$$\begin{aligned} \|x - z\|^2 &= \|x - p\|^2 + \|\lambda y - \lambda p\|^2 + \langle x - p, \lambda p - \lambda y \rangle \\ &= \|x - p\|^2 + 2\lambda \langle x - p, p - y \rangle + \lambda^2 \|y - p\|^2 \end{aligned}$$

(iv)

Using (7.15), and setting $\lambda = 1$, thus $z = y$. Then, using (7.15),

$$0 \leq \|x - y\|^2 - \|x - p\|^2 = 2\lambda \langle x - p, p - y \rangle + \lambda^2 \|y - p\|^2$$

If you divide by λ , then $0 \leq 2 \langle x - p, p - y \rangle + \lambda \|y - p\|^2$

This holds for every $y \in C$, so $\langle x - p, p - y \rangle \geq 0$

Problem 8.

$$\begin{aligned} g(\lambda x + (1 - \lambda)y) &= f(\lambda(Ax + b) + (1 - \lambda)(Ay + b)) \\ &\leq \lambda f(Ax + b) + (1 - \lambda)f(Ay + b) \\ &= \lambda g(x) + (1 - \lambda)g(y) \end{aligned}$$

Problem 12.

(i)

Take $X, Y \in PD_n(\mathbb{R})$ and $\lambda \in [0, 1]$. Then for every $v \in \mathbb{R}^n$ we have that

$$v^T(\lambda X + (1 - \lambda)Y)v = \lambda(v^T X v) + (1 - \lambda)(v^T Y v) > 0,$$

because X and Y are positive definite.

(ii)

(a) Take $t_1, t_2 \in \mathbb{R}$ and $\lambda \in [0, 1]$. On the one hand,

$$\lambda g(t_1) + (1 - \lambda)g(t_2) = \lambda f(t_1 A + (1 - t_1)B) + (1 - \lambda)f(t_2 A + (1 - t_2)B).$$

On the other,

$$\begin{aligned} g(\lambda t_1 + (1 - \lambda)t_2) &= f((\lambda t_1 + (1 - \lambda)t_2)A + (1 - \lambda t_1 + (1 - \lambda)t_2)B) \\ &= f(\lambda(t_1 A + (1 - t_1)B) + (1 - \lambda)(t_2 A + (1 - t_2)B)). \end{aligned}$$

Since g is convex we get

$$f(\lambda X + (1 - \lambda)Y) \leq \lambda f(X) + (1 - \lambda)f(Y),$$

with $X = t_1 A + (1 - t_1)B$ and $Y = t_2 A + (1 - t_2)B$. Since the choice of t was arbitrary and this holds for any $A, B \in PD_n(\mathbb{R})$, we conclude that f is convex.

(b) By Proposition (4.5.7), we know that if A is positive definite, then there exists a non-singular matrix S such that $A = S^H S$. Then, $tA + (1 - t)B = S^H(tI + (1 - t)(S^H)^{-1}BS^{-1})S$, and so

$$g(t) = -\log(\det(tA + (1 - t)B)) = -\log(\det(S^H(tI + (1 - t)(S^H)^{-1}BS^{-1})S)).$$

By the fact that $\det(AB) = \det(A)\det(B)$ and the properties of logarithms, we obtain

$$\begin{aligned} -\log(\det(S^H(tI + (1 - t)(S^H)^{-1}BS^{-1})S)) &= -\log(\det(S^H)) - \log(\det(tI + (1 - t)(S^H)^{-1}BS^{-1})) \\ &\quad - \log(\det(S)) \\ &= -\log(\det(S^H)\det(S)) - \log(\det(tI + (1 - t)(S^H)^{-1}BS^{-1})) \\ &= -\log(\det(A)) - \log(\det(tI + (1 - t)(S^H)^{-1}BS^{-1})). \end{aligned}$$

(c)

Since $A, B \in PD_n(\mathbb{R})$, then $B^{-1} \in PD_n(\mathbb{R})$ and $((S^H)^{-1}BS^{-1})^{-1} = SB^{-1}S^H$ is positive definite since

$$x^H SB^{-1}S^H x = (S^H x)^H B^{-1}(xS) > 0.$$

Therefore $(S^H)^{-1}BS^{-1}$ is positive definite. Now let $\{\lambda_i\}_i$ be the collection of eigenvalues of $((S^H)^{-1}BS^{-1})$ and $\{x_i\}_i$ the corresponding collection of eigenvectors. Then for every i :

$$(tI + (1 - t)(S^H)^{-1}BS^{-1})x_i = tx_i + (1 - t)\lambda_i x_i = (t + (1 - t)\lambda_i)x_i.$$

Thus, $\{t + (1 - t)\lambda_i\}_i$ are the eigenvalues of $(tI + (1 - t)(S^H)^{-1}BS^{-1})$ corresponding to the $\{x_i\}_i$, and we can conclude that

$$\begin{aligned} -\log(\det(A)) - \log(\det(tI + (1 - t)(S^H)^{-1}BS^{-1})) &= -\log(\det(A)) - \log(\prod_{i=1}^n (t + (1 - t)\lambda_i)) \\ &= -\log(\det(A)) - \sum_{i=1}^n \log((t + (1 - t)\lambda_i)). \end{aligned}$$

(d)

By using the expression of $g(t)$ in part (c) we can see that $g'(t) \sum_{i=1}^n (1 - \lambda_i)/(t + (1 - t)\lambda_i)$ and $g''(t) = \sum_{i=1}^n (1 - \lambda_i)^2/(t + (1 - t)\lambda_i)^2$, which is clearly nonnegative for all $t \in [0, 1]$.

Problem 13.

Suppose $f(x) < M$ for all x for some real M and f is convex and not constant. Then, there exist $x, y \in \mathbb{R}^n$ such that $f(x) \neq f(y)$. But then the line between $(x, f(x))$ and $(y, f(y))$ intersects $f(\cdot) = M$. Since f must lie on or above this line, at some point it must cross $f(\cdot) = M$ as well, which is a contradiction.

Problem 20.

Take $x, y \in \mathbb{R}^n$, with $x \neq y$, and $\lambda \in [0, 1]$. Since f is convex we have $f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y)$. Since $-f$ is convex, the opposite hold. Therefore we must have $f(\lambda x + (1 - \lambda)y) = \lambda f(x) + (1 - \lambda)f(y)$. Therefore f is affine.

Problem 21.

Let $x^* \in \mathbb{R}^n$ be a local minimizer of f . Then $f(x^*) \leq f(x)$ for all $x \in \mathcal{N}_r(x^*)$, where $\mathcal{N}_r(x^*)$ is an open ball around x^* of radius $r > 0$. Since ϕ is monotonically increasing, $\phi(f(x^*)) \leq \phi(f(x))$ for all $x \in \mathcal{N}_r(x^*)$. Thus, x^* is a local minimizer of $\phi \circ f$. Now let x^* be a local minimizer of $\phi \circ f$. Then $\phi(f(x^*)) \leq \phi(f(x))$ for all $x \in \mathcal{N}_r(x^*)$, and since ϕ is monotonically increasing, this implies that $f(x^*) \leq f(x)$ for all $x \in \mathcal{N}_r(x^*)$. Thus, x^* is a local minimizer of f .