

GADTs Meet Their Match:

Pattern-Matching Warnings That Account for GADTs, Guards, and Laziness

SEBASTIAN GRAF, Karlsruhe Institute of Technology, Germany

SIMON PEYTON JONES, Microsoft Research, UK

RYAN G. SCOTT, Indiana University, USA

1 INTRODUCTION

Pattern matching is a tremendously useful feature in Haskell and many other programming languages, but it must be wielded with care. Consider the following example of pattern matching gone wrong:

```
f :: Int → Bool
f 0 = True
f 0 = False
```

The f function exhibits two serious flaws. One obvious issue is that there are two clauses that match on 0, and due to the top-to-bottom semantics of pattern matching, this makes the $f\ 0 = False$ clause completely unreachable. Even worse is that f never matches on any patterns besides 0, making it not fully defined. Attempting to invoke $f\ 1$, for instance, will fail.

To avoid these mishaps, compilers for languages with pattern matching often emit warnings whenever a programmer misuses patterns. Such warnings indicate if a function is missing clauses (i.e., if it is *non-exhaustive*) or if a function has overlapping clauses (i.e., if it is *redundant*). We refer to the combination of checking for exhaustivity and redundancy as *pattern-match coverage checking*. Coverage checking is the first line of defence in catching programmer mistakes when defining code that uses pattern matching.

If coverage checking catches mistakes in pattern matches, then who checks for mistakes in the coverage checker itself? It is a surprisingly frequent occurrence for coverage checkers to contain bugs that impact correctness. This is especially true in Haskell, which has an especially rich pattern language, and the Glasgow Haskell Compiler (GHC) complicates the story further by adding pattern-related language extensions. Designing a coverage checker that can cope with all of these features is no small task.

The current state of the art for coverage checking GHC is Karachalias et al. [2015], which presents an algorithm that handles the intricacies of checking GADTs, lazy patterns, and pattern guards. We argue that this algorithm is insufficient in a number of key ways. It does not account for a number of important language features and even gives incorrect results in certain cases. Moreover, the implementation of this algorithm in GHC is inefficient and has proved to be difficult to maintain due to its complexity.

In this paper we propose a new algorithm, called **SYSNAME**, that addresses the deficiencies of Karachalias et al. [2015]. The key insight of **SYSNAME** is to condense all of the complexities of pattern matching into just three constructs: **let** bindings, pattern guards, and bang guards. We make the following contributions: **Ryan: Cite section numbers in the list below.**

- We characterise the nuances of coverage checking that not even the algorithm in [Karachalias et al. 2015] handles. We also identify issues in GHC's implementation of this algorithm.

Authors' addresses: Sebastian Graf, Karlsruhe Institute of Technology, Karlsruhe, Germany, sebastian.graf@kit.edu; Simon Peyton Jones, Microsoft Research, Cambridge, UK, simonpj@microsoft.com; Ryan G. Scott, Indiana University, Bloomington, Indiana, USA, rgscott@indiana.edu.

Fig. 1. Definitions used in the text

- **Ryan:** Describe the "Overview Over Our Solution" section and "Formalism" sections.
- We have implemented **SYSNAME** in GHC. **Ryan:** More details.

We discuss the wealth of related work in **TODO:** .

2 THE PROBLEM WE WANT TO SOLVE

What makes coverage checking so difficult in a language like Haskell? At first glance, implementing a coverage checker algorithm might appear simple: just check that every function matches on every possible combination of data constructors exactly once. A function must match on every possible combination of constructors in order to be exhaustive, and it must match on them exactly once to avoid redundant matches.

This algorithm, while concise, leaves out many nuances. What constitutes a “match”? Haskell has multiple matching constructs, including function definitions, **case** expressions, and guards. How does one count the number of possible combinations of data constructors? This is not a simple exercise since term and type constraints can make some combinations of constructors unreachable if matched on. Moreover, what constitutes a “data constructor”? In addition to traditional data constructors, GHC features *pattern synonyms* [Pickering et al. 2016], which provide an abstract way to embed arbitrary computation into patterns. Matching on a pattern synonym is syntactically identical to matching on a data constructor, which makes coverage checking in the presence of pattern synonyms challenging.

Prior work on coverage checking (which we will expound upon further in **Ryan: Cite related work section**) accounts for some of these nuances, but not all of them. In this section we identify all of the language features that complicate coverage checking. While these features may seem disparate at first, we will later show in **Ryan: Cite the relevant section** that these ideas can all fit into a unified framework.

2.1 Guards

TODO:

2.2 Strictness

The evaluation order of pattern matching can impact whether a pattern is reachable or not. While Haskell is a lazy language, programmers can opt into extra strict evaluation by giving the fields of a data type strict fields, such as in this example: **Ryan: Consider moving some of this code to the figure Ryan: There is an erroneous space between the ! and the a**

```
data Void -- No data constructors
data SMaybe a = SJust ! a | SNothing
v :: SMaybe Void → Int
v SNothing = 0
```

The *SJust* constructor is strict in its field, and as a consequence, evaluating *SJust* \perp to weak-head normal form will diverge. This has consequences when coverage checking functions that match on *SMaybe* values, such as *v*. The definition of *v* is curious, since it appears to omit a case for *SJust*. We could imagine adding one:

```
v (SJust _) = 1
```

Meta variables		Pattern Syntax	
x, y, z, f, g, h	Term variables	$defn ::= \overline{clause}$	
a, b, c	Type variables	$clause ::= f \overline{pat} \overline{match}$	
K	Data constructors	$pat ::= x \mid _ \mid K \overline{pat} \mid x@pat \mid !pat \mid \sim pat \mid x + l$	
P	Pattern synonyms	$match ::= = \overline{expr} \mid \overline{grhs}$	
T	Type constructors	$grhs ::= \mid \overline{guard} = \overline{expr}$	
l	Literal	$guard ::= pat \leftarrow expr \mid expr \mid \text{let } x = expr$	
$expr$	Expressions		

Fig. 2. Source syntax

It turns out, however, that the RHS of this case can never be reached. The only way to use $SJust$ to construct a value of type $SMaybe Void$ is $SJust \perp$, since $Void$ has no data constructors. Because $SJust$ is strict in its field, matching on $SJust$ will cause $SJust \perp$ to diverge, since matching on a data constructor evaluates it to WHNF. As a result, there is no argument one could pass to v to make it return 1, which makes the $SJust$ case unreachable.

Although [Karachalias et al. \[2015\]](#) incorporates strictness constraints into their algorithm, it does not consider constraints that arise from strict fields. **Ryan: Say more here?**

2.2.1 Bang patterns. Strict fields are the primary mechanism for adding extra strictness in Haskell, but GHC adds another mechanism in the form of *bang patterns*. A bang pattern such as $!pat$ indicates that matching against pat *always* evaluates it to WHNF. While data constructor matches are normally the only patterns that match strictly, bang patterns extend this treatment to other patterns. For example, one can rewrite the earlier v example to use the ordinary, lazy *Maybe* data type: **Ryan: I actually wanted to write $Just !_$, but LaTeX won't parse that :(**

$v' :: Maybe Void \rightarrow Int$

$v' \text{ Nothing} = 0$

$v' (Just ! x) = 1$

Ryan: Finish me

2.2.2 Newtypes. TODO:

2.3 Programmable patterns

TODO:

2.3.1 Overload literals. TODO:

2.3.2 Pattern synonyms. TODO:

2.4 Term and type constraints

TODO:

2.4.1 Long-distance information. TODO:

3 OVERVIEW OF OUR SOLUTION

In this section, we aim to provide an intuitive understanding of our pattern match checking algorithm, by way of deriving the intermediate representations of the pipeline step by step from motivating examples.

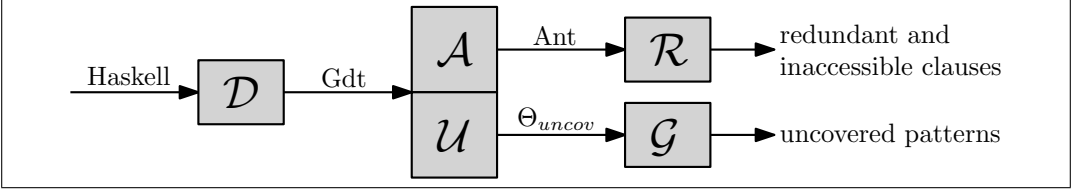


Fig. 3. Bird's eye view of pattern match checking

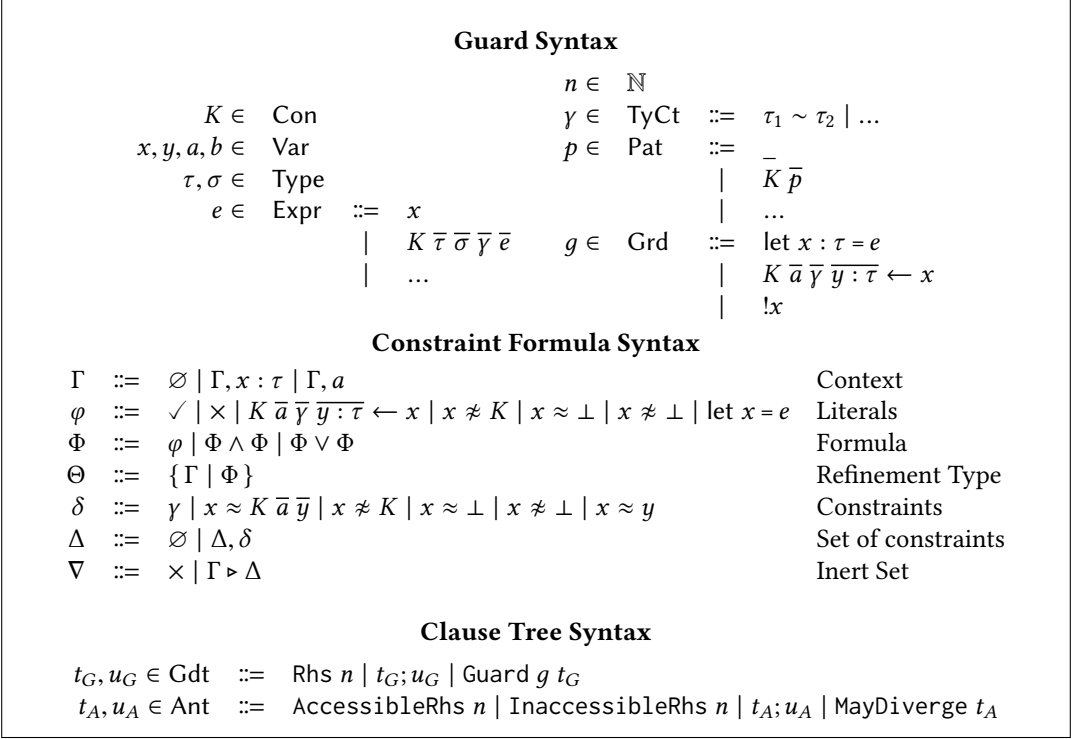


Fig. 4. IR Syntax

Figure 3 depicts a high-level overview over this pipeline. Desugaring the complex source Haskell syntax to the very elementary language of guard trees Gdt via \mathcal{D} is an incredible simplification for the checking process. At the same time, \mathcal{D} is the only transformation that is specific to Haskell, implying easy applicability to other languages. The resulting guard tree is then processed by two different functions, \mathcal{A} and \mathcal{U} , which compute redundancy information and uncovered patterns, respectively. \mathcal{A} boils down this information into an annotated tree Ant, for which the set of redundant and inaccessible right-hand sides can be computed in a final pass of \mathcal{R} **SG: TODO: Write \mathcal{R}** . \mathcal{U} on the other hand returns a *refinement type* representing the set of *uncovered values*, for which \mathcal{G} can generate the inhabiting patterns to show to the user.

3.1 Desugaring to Guard Trees

To understand what language we should desugar to, consider the following 3am attempt at lifting equality over *Maybe*:

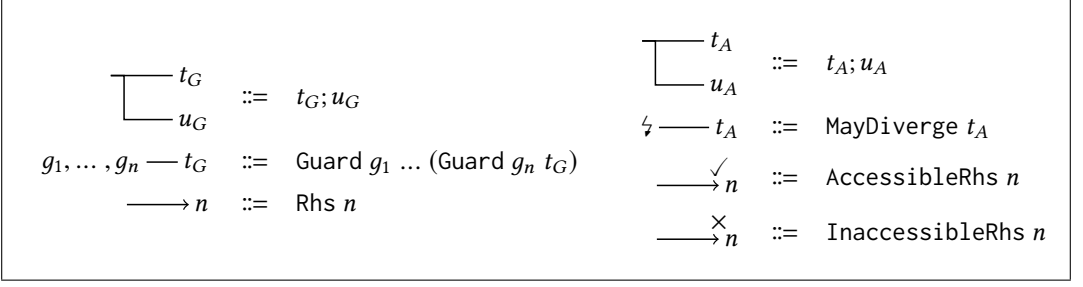


Fig. 5. Graphical notation

liftEq *Nothing Nothing* = *True*

liftEq (*Just x*) (*Just y*)

| *x* == *y* = *True*

| *otherwise* = *False*

Function definitions in Haskell allow one or more *guarded right-hand sides* (GRHS) per syntactic *clause* (see fig. 2). For example, *liftEq* has two clauses, the second of which defines two GRHSs. Semantically, neither of them will match the call site *liftEq (Just 1) Nothing*, leading to a crash.

To see that, we can follow Haskell’s top-to-bottom, left-to-right pattern match semantics. The first clause fails to match *Just 1* against *Nothing*, while the second clause successfully matches 1 with *x* but then fails trying to match *Nothing* against *Just y*. There is no third clause, and the *uncovered* tuple of values (*Just 1*) *Nothing* that falls out at the bottom of this process will lead to a crash.

Compare that to matching on (*Just 1*) (*Just 2*): While matching against the first clause fails, the second matches *x* to 1 and *y* to 2. Since there are multiple GRHSs, each of them in turn has to be tried in a top-to-bottom fashion. The first GRHS consists of a single boolean guard (in general we have to consider each of them in a left-to-right fashion!) that will fail because $1 \neq 2$. The second GRHS is tried next, and because *otherwise* is a boolean guard that never fails, this successfully matches.

Note how both the pattern matching per clause and the guard checking within a syntactic *match* share top-to-bottom and left-to-right semantics. Having to make sense of both pattern and guard semantics seems like a waste of energy. Perhaps we can express all pattern matching by (nested) pattern guards, thus:

liftEq mx my

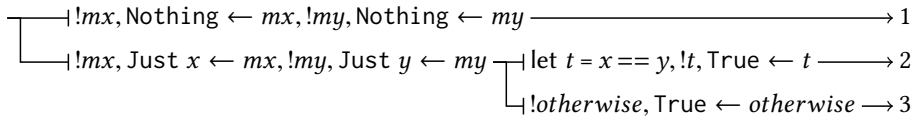
| *Nothing* ← *mx*, *Nothing* ← *my* = *True*

| *Just x* ← *mx*, *Just y* ← *my* | *x* == *y* = *True*

| *otherwise* = *False*

Transforming the first clause with its single GRHS is easy. But the second clause already has two GRHSs, so we need to use *nested* pattern guards. This is not a feature that Haskell offers (yet), but it allows a very convenient uniformity for our purposes: after the successful match on the first two guards left-to-right, we try to match each of the GRHSs in turn, top-to-bottom (and their individual guards left-to-right).

Hence our algorithm desugars the source syntax to the following *guard tree* (see fig. 4 for the full syntax and fig. 5 the corresponding graphical notation):



This representation is quite a bit more explicit than the original program. For one thing, every source-level pattern guard is strict in its scrutinee, whereas the pattern guards in our tree language are not, so we had to insert *bang guards*. By analogy with bang patterns, `!x` evaluates x to WHNF, which will either succeed or diverge. Moreover, the pattern guards in Grd only scrutinise variables (and only one level deep), so the comparison in the boolean guard’s scrutinee had to be bound to an auxiliary variable in a let binding. Note that *otherwise* is an external identifier which we can assume to be bound to *True*, which is in fact how it defined.

Pattern guards in Grd are the only guards that can possibly fail to match, in which case the value of the scrutinee was not of the shape of the constructor application it was matched against. The Gdt tree language determines how to cope with a failed guard. Left-to-right matching semantics is captured by Guard, whereas top-to-bottom backtracking is expressed by sequence (;). The leaves in a guard tree each correspond to a GRHS.

3.2 Checking Guard Trees

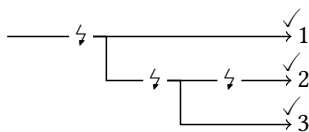
Pattern match checking works by gradually refining the set of reaching values **Ryan:** Did you mean to write “reachable values” here? “Reaching values” reads strangely to me. **SG:** I was thinking “reaching values” as in “reaching definitions”: The set of values that reach that particular piece of the guard tree, as they flow through the guard tree until it produces two outputs. One output is the set of uncovered values that wasn’t covered by any clause, and the other output is an annotated guard tree skeleton Ant with the same shape as the guard tree to check, capturing redundancy and divergence information.

For the example of *liftEq*'s guard tree t_{liftEq} , we represent the set of values reaching the first clause by the *refinement type* $\{(mx : \text{Maybe } a, my : \text{Maybe } a) \mid \checkmark\}$ (which is a Θ from fig. 4). This set is gradually refined until finally we have $\Theta_{\text{liftEq}} := \{(mx : \text{Maybe } a, my : \text{Maybe } a) \mid \Phi\}$ as the uncovered set, where the predicate Φ is semantically equivalent to:

$$(mx \neq \perp \wedge (mx \neq \text{Nothing} \vee (\text{Nothing} \leftarrow mx \wedge my \neq \perp \wedge my \neq \text{Nothing}))) \wedge (mx \neq \perp \wedge (mx \neq \text{Just} \vee (\text{Just } x \leftarrow mx \wedge my \neq \perp \wedge (my \neq \text{Just}))))$$

Every \vee disjunct corresponds to one way in which a pattern guard in the tree could fail. It is not obvious at all for humans to read off satisfying values **Ryan: Did you mean to write “satisfiable values” instead of “satisfying values” here?** Again, the latter reads strangely to me. **SG: I think I agree. I was thinking of the values that satisfy Φ and thus inhabit Θ . Maybe “inhabiting values” then?** from this representation, but we will give an intuitive treatment of how to do so in the next subsection.

The annotated guard tree skeleton corresponding to t_{liftEq} looks like this:



A GRHS is deemed accessible (\checkmark) whenever there is a non-empty set of values reaching it. For the first GRHS, the set that reaches it looks like $\{(mx, my) \mid mx \not\approx \perp, \text{Nothing} \leftarrow mx, my \not\approx \perp, \text{Nothing} \leftarrow my\}$, which is inhabited by $(\text{Nothing}, \text{Nothing})$. Similarly, we can find inhabitants for the other two clauses.

A ζ denotes possible divergence in one of the bang guards and involves testing the set of reaching values for compatibility with i.e. $mx \approx \perp$. We cannot know in advance whether mx , my or t are \perp (hence the three uses of ζ), but we can certainly rule out *otherwise* $\approx \perp$ simply by knowing that it is defined as *True*. But since all GRHSs are accessible, there is nothing to report in terms of redundancy and the ζ decorators are irrelevant.

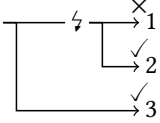
Perhaps surprisingly and most importantly, Grd with its three primitive guards, combined with left-to-right or top-to-bottom semantics in Gdt, is expressive enough to express all pattern matching in Haskell (cf. the desugaring function \mathcal{D} in fig. 6)! We have yet to find a language extension that does not fit into this framework.

3.2.1 Why do we not report redundant GRHSs directly? Why not compute the redundant GRHSs directly instead of building up a whole new tree? Because determining inaccessibility vs. redundancy is a non-local problem. Consider this example: **SG: I think this kind of detail should be motivated in a prior section and then referenced here for its solution.**

```
g :: () → Int
g () | False = 1
      | True  = 2
g _      = 3
```

Is the first GRHS just inaccessible or even redundant? Although the match on $()$ forces the argument, we can delete the first GRHS without changing program semantics, so clearly it is redundant. **Ryan:** Wait, wouldn't deleting the first clause (with its two GRHSs) change its semantics? With the first clause present, $g \perp = \perp$. Without the first clause, $g \perp = 3$. Or am I missing something? **SG:** I meant the first GRHS, not the whole syntactic clause. But that wouldn't be true if the second GRHS wasn't there to "keep alive" the $()$ pattern!

Here is the corresponding annotated tree after checking:



In general, at least one GRHS under a ζ may not be flagged as redundant (\times). Thus the checking algorithm can't decide which GRHSs are redundant (vs. just inaccessible) when it reaches a particular GRHS.

3.3 Generating Inhabitants of a Refinement Type

The predicate literals φ of refinement types look quite similar to the original Grd language, so how is checking them for emptiness an improvement over reasoning about guard trees directly? To appreciate the transition, it is important to realise that semantics of Grds are *highly non-local*! Left-to-right and top-to-bottom match semantics means that it is hard to view Grds in isolation; we always have to reason about whole Gdts. By contrast, refinement types are self-contained, which means the process of generating inhabitants can be treated separately from the process of pattern match checking **Ryan:** We inconsistently switch between calling it "pattern match checking" and "coverage checking" in the prose. We should adopt one term and stick with it. **SG:** I think I like "coverage checking" (after introducing it as "pattern match coverage checking" better, provided the term subsumes both exhaustivity and overlap checking.

Apart from generating inhabitants of the final uncovered set for non-exhaustive match warnings, there are two points at which we have to check whether a refinement type has become empty: To

determine whether a right-hand side is inaccessible and whether a particular bang guard may lead to divergence and requires us to wrap a ζ .

Take the final uncovered set Θ_{liftEq} after checking *liftEq* above as an example. **SG: Do we need to give its predicate here again?** A bit of eyeballing *liftEq*'s definition reveals that *Nothing* (*Just* $_$) is an uncovered pattern, but eyeballing the constraint formula of Θ_{liftEq} seems impossible in comparison. A more systematic approach is to adopt a generate-and-test scheme: Enumerate possible values of the data types for each variable involved (the pattern variables *mx* and *my*, but also possibly the guard-bound *x*, *y* and *t*) and test them for compatibility with the recorded constraints.

Starting from *mx my*, we enumerate all possibilities for the shape of *mx*, and similarly for *my*. The obvious first candidate in a lazy language is \perp ! But that is a contradicting assignment for both *mx* and *my* independently. Refining to *Nothing Nothing* contradicts with the left part of the top-level \wedge . Trying *Just y* (*y* fresh) instead as the shape for *my* yields our first inhabitant! Note that *y* is unconstrained, so \perp is a trivial inhabitant. Similarly for (*Just* $_$) *Nothing* and (*Just* $_$) (*Just* $_$).

Why do we have to test guard-bound variables in addition to the pattern variables? It is because of empty data types and strict fields: **SG: This example will probably move to an earlier section**

```
data Void    -- No data constructors
data SMaybe a = SJust ! a | SNothing
v :: SMaybe Void → Int
v x@SNothing = 0
```

v does not have any uncovered patterns. And our approach should see that by looking at its uncovered set $\{x : \text{Maybe Void} \mid x \neq \perp \wedge x \neq \text{Nothing}\}$. Specifically, the candidate *SJust y* (for fresh *y*) for *x* should be rejected, because there is no inhabitant for *y*! \perp is ruled out by the strict field and *Void* has no data constructors with which to instantiate *y*. Hence it is important to test guard-bound variables for inhabitants, too.

SG: GMTM goes into detail about type constraints, term constraints and worst-case complexity here. That feels a bit out of place.

4 FORMALISM

The previous section gave insights into how we represent pattern match checking problems as clause trees and provided an intuition for how to check them for exhaustiveness and redundancy. This section formalises these intuitions in terms of the syntax (cf. fig. 4) we introduced earlier.

As in the previous section, this comes in two main parts: Pattern match checking and finding inhabitants of the arising refinement types.

4.1 Desugaring to Guard Trees

SG: I find this section quite boring. There's nothing to see in fig. 6 that wasn't already clear after reading 3.1.

Figure 6 outlines the desugaring step from source Haskell to our guard tree language Gdt. It is assumed that the top-level match variables x_1 through x_n in the *clause* cases have special, fixed names. **SG: If we had a different font for meta variables than for object variables, we could make that visible in syntax. But we don't...** All other variables that aren't bound in arguments to \mathcal{D} have fresh names.

Consider this example function **SG: Maybe use the same function as in 3.1? But we already desugar it there...**

```
f (Just (!xs, _)) ys@Nothing = 1
f Nothing           zs         = 2
```


$\mathcal{D}(defn) = \text{Gdt}, \mathcal{D}(clause) = \text{Gdt}, \mathcal{D}(grhs) = \text{Gdt}$	
$\mathcal{D}(guard) = \overline{\text{Grd}}, \mathcal{D}(x, pat) = \overline{\text{Grd}}$	
$\mathcal{D}(clause_1 \dots clause_n)$	$= \begin{array}{l} \text{---} \mathcal{D}(clause_1) \\ \\ \text{---} \dots \\ \\ \text{---} \mathcal{D}(clause_n) \end{array}$
$\mathcal{D}(f \text{ } pat_1 \dots pat_n = expr)$	$= \begin{array}{l} \text{---} \vdash \mathcal{D}(x_1, pat_1) \dots \mathcal{D}(x_n, pat_n) \rightarrow k \\ \text{---} \vdash \mathcal{D}(x_1, pat_1) \dots \mathcal{D}(x_n, pat_n) \end{array}$
$\mathcal{D}(f \text{ } pat_1 \dots pat_n \text{ } grhs_1 \dots grhs_m)$	$= \begin{array}{l} \text{---} \vdash \mathcal{D}(x_1, pat_1) \dots \mathcal{D}(x_n, pat_n) \end{array} \begin{array}{l} \text{---} \mathcal{D}(grhs_1) \\ \\ \text{---} \dots \\ \\ \text{---} \mathcal{D}(grhs_m) \end{array}$
$\mathcal{D}(\mid guard_1 \dots guard_n = expr)$	$= \text{---} \vdash \mathcal{D}(guard_1) \dots \mathcal{D}(guard_n) \rightarrow k$
$\mathcal{D}(pat \leftarrow expr)$	$= \text{let } x = expr, \mathcal{D}(x, pat)$
$\mathcal{D}(expr)$	$= \text{let } b = expr, \mathcal{D}(b, \text{True})$
$\mathcal{D}(\text{let } x = expr)$	$= \text{let } x = expr$
$\mathcal{D}(x, y)$	$= \text{let } y = x$
$\mathcal{D}(x, _)$	$= \epsilon$
$\mathcal{D}(x, K \text{ } pat_1 \dots pat_n)$	$= !x, K \text{ } y_1 \dots y_n \leftarrow x, \mathcal{D}(y_1, pat_1), \dots, \mathcal{D}(y_n, pat_n)$
$\mathcal{D}(x, y @ pat)$	$= \text{let } y = x, \mathcal{D}(y, pat)$
$\mathcal{D}(x, !pat)$	$= !x, \mathcal{D}(x, pat)$
$\mathcal{D}(x, \sim pat)$	$= \epsilon$
$\mathcal{D}(x, y + l)$	$= \mathcal{D}(x \geq l), \text{let } y = x - l$

Fig. 6. Desugaring Haskell to Gdt

Under \mathcal{D} , this desugars to

$$\begin{array}{l} \text{---} \vdash !x_1, \text{Just } t_1 \leftarrow x_1, !t_1, (t_2, t_3) \leftarrow t_1, !t_2, \text{let } xs = t_2, \text{let } ys = x_2, !ys, \text{Nothing} \leftarrow ys \rightarrow 1 \\ | \\ \text{---} \vdash !x_1, \text{Nothing} \leftarrow x_1, \text{let } zs = x_2 \text{---} \rightarrow 2 \end{array}$$

The definition of \mathcal{D} is mostly straight-forward, but a little expansive because of the realistic source language. Its most intricate job is keeping track of all the renaming going on to resolve name mismatches. Other than that, the desugaring follows from the restrictions on the Grd language.

Note how our naive desugaring function generates an abundance of fresh temporary variables. In practice, the implementation of \mathcal{D} can be smarter about it, by looking at the pattern when choosing a name for the variable.

4.2 Checking Guard Trees

Figure 7 shows the two main functions for checking guard trees. \mathcal{U} carries out exhaustiveness checking by computing the set of uncovered values for a particular guard tree, whereas \mathcal{A} computes the corresponding annotated tree, capturing redundancy information.

Operations on Θ

$$\begin{aligned}\{\Gamma \mid \Phi\} \wedge \varphi &= \{\Gamma \mid \Phi \wedge \varphi\} \\ \{\Gamma \mid \Phi_1\} \cup \{\Gamma \mid \Phi_2\} &= \{\Gamma \mid \Phi_1 \vee \Phi_2\}\end{aligned}$$

Checking Guard Trees

$$\boxed{\mathcal{U}(\Theta, t_G) = \Theta}$$

$$\begin{aligned}\mathcal{U}(\{\Gamma \mid \Phi\}, \text{Rhs } n) &= \{\Gamma \mid \times\} \\ \mathcal{U}(\Theta, t; u) &= \mathcal{U}(\mathcal{U}(\Theta, t), u) \\ \mathcal{U}(\Theta, \text{Guard } (!x) \ t) &= \mathcal{U}(\Theta \dot{\wedge} (x \not\approx \perp), t) \\ \mathcal{U}(\Theta, \text{Guard } (\text{let } x = e) \ t) &= \mathcal{U}(\Theta \dot{\wedge} (\text{let } x = e), t) \\ \mathcal{U}(\Theta, \text{Guard } (K \ \bar{a} \ \bar{y} \ \bar{y} : \bar{\tau} \leftarrow x) \ t) &= (\Theta \dot{\wedge} (x \not\approx K)) \cup \mathcal{U}(\Theta \dot{\wedge} (K \ \bar{a} \ \bar{y} \ \bar{y} : \bar{\tau} \leftarrow x), t)\end{aligned}$$

$$\boxed{\mathcal{A}(\Delta, t_G) = t_A}$$

$$\begin{aligned}\mathcal{A}(\Theta, \text{Rhs } n) &= \begin{cases} \text{InaccessibleRhs } n, & \mathcal{G}(\Theta) = \emptyset \\ \text{AccessibleRhs } n, & \text{otherwise} \end{cases} \\ \mathcal{A}(\Theta, (t; u)) &= \mathcal{A}(\Theta, t); \mathcal{A}(\mathcal{U}(\Theta, t), u) \\ \mathcal{A}(\Theta, \text{Guard } (!x) \ t) &= \begin{cases} \mathcal{A}(\Theta \dot{\wedge} (x \not\approx \perp), t), & \mathcal{G}(\Theta \dot{\wedge} (x \approx \perp)) = \emptyset \\ \text{MayDiverge } \mathcal{A}(\Theta \dot{\wedge} (x \not\approx \perp), t) & \text{otherwise} \end{cases} \\ \mathcal{A}(\Theta, \text{Guard } (\text{let } x = e) \ t) &= \mathcal{A}(\Theta \dot{\wedge} (x \approx e), t) \\ \mathcal{A}(\Theta, \text{Guard } (K \ \bar{a} \ \bar{y} \ \bar{y} : \bar{\tau} \leftarrow x) \ t) &= \mathcal{A}(\Theta \dot{\wedge} (K \ \bar{a} \ \bar{y} \ \bar{y} : \bar{\tau} \leftarrow x), t)\end{aligned}$$

Putting it all together

- (0) Input: Context with match vars Γ and desugared Gdt t
 - (1) Report n pattern vectors of $\mathcal{G}(\mathcal{U}(\{\Gamma \mid \checkmark\}, t))$ as uncovered
 - (2) Report the collected redundant and not-redundant-but-inaccessible clauses in $\mathcal{A}(\{\Gamma \mid \checkmark\}, t)$
- (TODO: Write a function that collects the RHSs).

Fig. 7. Pattern match checking

Both functions take as input the set of values *reaching* the particular guard tree node passed in as second parameter. The definition of \mathcal{U} follows the intuition we built up earlier: It refines the set of reaching values as a subset of it falls through from one clause to the next. This is most visible in the $;$ case (top-to-bottom composition), where the set of values reaching the right (or bottom) child is exactly the set of values that were uncovered by the left (or top) child on the set of values reaching the whole node. A GRHS covers every reaching value. The left-to-right semantics of `Guard` are respected by refining the set of values reaching the wrapped subtree, depending on the particular guard. Bang guards and let bindings don't do anything beyond that refinement, whereas pattern guards additionally account for the possibility of a failed pattern match. Note that ultimately, a failing pattern guard is the only way in which the uncovered set can become non-empty!

When \mathcal{A} hits a GRHS, it asks \mathcal{G} for inhabitants of Θ to decide whether the GRHS is accessible or not. Since \mathcal{A} needs to compute and maintain the set of reaching values just the same as \mathcal{U} , it has to call out to \mathcal{U} for the $;$ case. Out of the three guard cases, the one handling bang guards is the only one doing more than just refining the set of reaching values for the subtree (thus respecting left-to-right semantics). A bang guard `!x` is handled by testing whether the set of reaching values Θ is compatible with the assignment $x \approx \perp$, which again is done by asking \mathcal{G} for concrete inhabitants

Generate inhabitants of Θ

$$\boxed{\mathcal{G}(\Theta) = \mathcal{P}(\bar{p})}$$

$$\mathcal{G}(\{\Gamma \mid \Phi\}) = \bigcup \{\mathcal{E}(\nabla, \text{dom}(\Gamma)) \mid \nabla \in C(\Gamma \triangleright \emptyset, \Phi)\}$$

Construct inhabited ∇ s from Φ

$$\boxed{C(\nabla, \Phi) = \mathcal{P}(\nabla)}$$

$$\begin{aligned} C(\nabla, \varphi) &= \begin{cases} \{\Gamma' \triangleright \Phi'\} & \text{where } \Gamma' \triangleright \Phi' = \nabla \oplus_{\varphi} \varphi \\ \emptyset & \text{otherwise} \end{cases} \\ C(\nabla, \Phi_1 \wedge \Phi_2) &= \bigcup \{C(\nabla', \Phi_2) \mid \nabla' \in C(\nabla, \Phi_1)\} \\ C(\nabla, \Phi_1 \vee \Phi_2) &= C(\nabla, \Phi_1) \cup C(\nabla, \Phi_2) \end{aligned}$$

Expand variables to Pat with ∇

$$\boxed{\mathcal{E}(\nabla, \bar{x}) = \mathcal{P}(\bar{p})}$$

$$\begin{aligned} \mathcal{E}(\nabla, \epsilon) &= \{\epsilon\} \\ \mathcal{E}(\Gamma \triangleright \Delta, x_1 \dots x_n) &= \begin{cases} \{(K \ q_1 \dots q_m) p_2 \dots p_n \mid (q_1 \dots q_m p_2 \dots p_n) \in \mathcal{E}(\Gamma \triangleright \Delta, y_1 \dots y_m x_2 \dots x_n)\} & \text{if } \Delta(x) \approx K \ \bar{a} \ \bar{y} \\ \{_ p_2 \dots p_n \mid (p_2 \dots p_n) \in \mathcal{E}(\Gamma \triangleright \Delta, x_2 \dots x_n)\} & \text{otherwise} \end{cases} \end{aligned}$$

Finding the representative of a variable in Δ

$$\boxed{\Delta(x) = y}$$

$$\Delta(x) = \begin{cases} \Delta(y) & x \approx y \in \Delta \\ x & \text{otherwise} \end{cases}$$

Fig. 8. Generating inhabitants of Θ via ∇

of the resulting refinement type. If it is inhabited, then the bang guard might diverge and we need to wrap the annotated subtree in a ζ .

Pattern guard semantics are important for \mathcal{U} and bang guard semantics are important for \mathcal{A} . But what about let bindings? They are in fact completely uninteresting to the checking process, but making sense of them is important for the precision of the emptiness check involving \mathcal{G} , as we'll see in section 4.3.

4.3 Generating Inhabitants of a Refinement Type

The key function for the emptiness test is \mathcal{G} in fig. 8, which generates a set of patterns which inhabit a given refinement type Θ . There might be multiple inhabitants, and C will construct multiple ∇ s, each representing at least one inhabiting assignment of the refinement predicate Φ . Each such assignment corresponds to a pattern vector, so \mathcal{E} expands the assignments in a ∇ into multiple pattern vectors. **SG: Currently, \mathcal{E} will only expand positive constraints and not produce multiple pattern vectors for a ∇ with negative info (see the TODO comment attached to \mathcal{E} 's definition)**

But what is ∇ ? To a first approximation, it is a set of mutually compatible constraints δ (or a proven incompatibility \times between them). It is also a unifier to the particular Φ it is constructed for, in that the recorded constraints are valid assignments for the variables occurring in the original

predicate **SG: This is not true of \times** . Each ∇ is the trace of commitments to a left or right disjunct in a Φ **SG: Not sure how to say this more accurately**, which are checked in isolation. So in contrast to Φ , there is no disjunction in Δ . Which makes it easy to check if a new constraint is compatible with the existing ones without any backtracking. Another fundamental difference is that δ has no binding constructs (so every variable has to be bound in the Γ part of ∇), whereas pattern bindings in φ bind constructor arguments.

C is the function that breaks down a Φ into multiple ∇ s. At the heart of C is adding a φ literal to the ∇ under construction via \oplus_φ and filtering out any unsuccessful attempts (via intercepting the \times failure mode) to do so. Conjunction is handled by the equivalent of a *concatMap*, whereas a disjunction corresponds to a plain union.

Expanding a ∇ to a pattern vector in \mathcal{E} is syntactically heavy, but straightforward: When there is a positive constraint like $x \approx \text{Just } y$ in Δ for the head x of the variable vector of interest, expand y in addition to the other variables and wrap it in a *Just*. Only that it's not plain $x \approx \text{Just } y$, but $\Delta(x) \approx \text{Just } y$. That's because Δ is in *triangular form* (alluding to *triangular substitutions*, as opposed to an idempotent substitution): We have to follow $x \approx y$ constraints in Δ until we find the representative of its equality class, to which all constraints apply. Note that a $x \approx y$ constraint implies absence of any other constraints mentioning x in its left-hand side ($x \approx y \in \Delta \Rightarrow (\Delta \cap x = x \approx y)$, foreshadowing notation from fig. 9). For \mathcal{E} to be well-defined, there needs to be at most one positive constraint in Δ .

Thus, constraints within ∇ s constructed by \oplus_φ satisfy a number of well-formedness constraints, like mutual compatibility, triangular form and the fact that there is at most one positive constraint $x \approx _$ per variable x . We refer to such ∇ s as an *inert set*, in the sense that constraints inside it satisfy it are of canonical form and already checked for mutual compatibility, in analogy to a typechecker's implementation **SG: Feel free to flesh out or correct this analogy**.

4.4 Extending the inert set

After tearing down abstraction after abstraction in the previous sections we nearly hit rock bottom: Figure 9 depicts how to add a φ constraint to an inert set ∇ .

It does so by expressing a φ in terms of once again simpler constraints δ and calling out to \oplus_δ . Specifically, for a lack of binding constructs in δ , pattern bindings extend the context and disperse into separate type constraints and a positive constructor constraint arising from the binding. The fourth case of \oplus_δ makes sense of let bindings: In case the right-hand side was a constructor application (which is not to be confused with a pattern binding, if only for the difference in binding semantics!), we add appropriate positive constructor and type constraints, as well as recurse into the field expressions, which might in turn contain nested constructor applications. The last case of \oplus_φ turns the syntactically and semantically identical subset of φ into δ and adds that constraint via \oplus_δ .

Which brings us to the prime unification procedure, \oplus_δ . Consider adding a positive constructor constraint like $x \approx \text{Just } y$: The unification procedure will first look for any positive constructor constraint involving the representative of x with *that same constructor*. Let's say there is $\Delta(x) = z$ and $z \approx \text{Just } u \in \Delta$. Then \oplus_δ decomposes the new constraint just like a classic unification algorithm, by equating type and term variables with new constraints, i.e. $y \approx u$. If there was no positive constructor constraint with the same constructor, it will look for such a constraint involving a different constructor, like $x \approx \text{Nothing}$. In this case the new constraint is incompatible by *generativity* of data constructors [Eisenberg 2016]. There are two other ways in which the constraint can be incompatible: If there was a negative constructor constraint $x \not\approx \text{Just}$ or if any of the fields were not inhabited, which is checked by the $\nabla \vdash x$ judgment in fig. 10. Otherwise, the constraint is compatible and is added to Δ .

Add a formula literal to the inert set

$$\boxed{\nabla \oplus_{\varphi} \varphi = \nabla}$$

$$\begin{aligned}
 \nabla \oplus_{\varphi} \times &= \times \\
 \nabla \oplus_{\varphi} \checkmark &= \nabla \\
 \Gamma \triangleright \Delta \oplus_{\varphi} K \bar{a} \bar{y} \bar{y} : \tau \leftarrow x &= \Gamma, \bar{a}, \bar{y} : \tau \triangleright \Delta \oplus_{\delta} \bar{y} \oplus_{\delta} x \approx K \bar{a} \bar{y} \\
 \Gamma \triangleright \Delta \oplus_{\varphi} \text{let } x : \tau = K \bar{\sigma}' \bar{\sigma} \bar{y} \bar{e} &= \Gamma, x : \tau, \bar{a}, \bar{y} : \tau' \triangleright \Delta \oplus_{\delta} \bar{a} \sim \tau' \oplus_{\delta} x \approx K \bar{a} \bar{y} \oplus_{\varphi} \overline{\text{let } y = e} \text{ where } \bar{a} \# \Gamma, \bar{y} \\
 \Gamma \triangleright \Delta \oplus_{\varphi} \text{let } x : \tau = y &= \Gamma, x : \tau \triangleright \Delta \oplus_{\delta} x \approx y \\
 \Gamma \triangleright \Delta \oplus_{\varphi} \text{let } x : \tau = e &= \Gamma, x : \tau \triangleright \Delta \\
 \Gamma \triangleright \Delta \oplus_{\varphi} \varphi &= \Gamma \triangleright \Delta \oplus_{\delta} \varphi
 \end{aligned}$$

Add a constraint to the inert set

$$\boxed{\nabla \oplus_{\delta} \delta = \nabla}$$

$$\begin{aligned}
 \times \oplus_{\delta} \delta &= \times \\
 \Gamma \triangleright \Delta \oplus_{\delta} \gamma &= \begin{cases} \Gamma \triangleright (\Delta, \gamma) & \text{if type checker deems } \gamma \text{ compatible with } \Delta \\ & \text{and } \forall x \in \text{dom}(\Gamma) : \Gamma \triangleright (\Delta, \gamma) \vdash \Delta(x) \\ \times & \text{otherwise} \end{cases} \\
 \Gamma \triangleright \Delta \oplus_{\delta} x \approx K \bar{a} \bar{y} &= \begin{cases} \Gamma \triangleright \Delta \oplus_{\delta} \bar{a} \sim \bar{b} \oplus_{\delta} \bar{y} \approx \bar{z} & \text{if } \Delta(x) \approx K \bar{b} \bar{z} \in \Delta \\ \times & \text{if } \Delta(x) \approx K' \bar{b} \bar{z} \in \Delta \\ \Gamma \triangleright (\Delta, \Delta(x) \approx K \bar{a} \bar{y}) & \text{if } \Delta(x) \neq K \notin \Delta \text{ and } \overline{\Gamma \triangleright \Delta \vdash \Delta(y)} \\ \times & \text{otherwise} \end{cases} \\
 \Gamma \triangleright \Delta \oplus_{\delta} x \neq K &= \begin{cases} \times & \text{if } \Delta(x) \approx K \bar{a} \bar{y} \in \Delta \\ \times & \text{if not } \Gamma \triangleright (\Delta, \Delta(x) \neq K) \vdash \Delta(x) \\ \Gamma \triangleright (\Delta, \Delta(x) \neq K) & \text{otherwise} \end{cases} \\
 \Gamma \triangleright \Delta \oplus_{\delta} x \approx \perp &= \begin{cases} \times & \text{if } \Delta(x) \neq \perp \in \Delta \\ \Gamma \triangleright (\Delta, \Delta(x) \approx \perp) & \text{otherwise} \end{cases} \\
 \Gamma \triangleright \Delta \oplus_{\delta} x \neq \perp &= \begin{cases} \times & \text{if } \Delta(x) \approx \perp \in \Delta \\ \times & \text{if not } \Gamma \triangleright (\Delta, \Delta(x) \neq \perp) \vdash \Delta(x) \\ \Gamma \triangleright (\Delta, \Delta(x) \neq \perp) & \text{otherwise} \end{cases} \\
 \Gamma \triangleright \Delta \oplus_{\delta} x \approx y &= \begin{cases} \Gamma \triangleright \Delta & \text{if } \Delta(x) = \Delta(y) \\ \Gamma \triangleright ((\Delta \setminus \Delta(x)), \Delta(x) \approx \Delta(y)) \oplus_{\delta} ((\Delta \cap \Delta(x))[\Delta(y)/\Delta(x)]) & \text{otherwise} \end{cases}
 \end{aligned}$$

$$\boxed{\Delta \setminus x = \Delta}$$

$$\begin{aligned}
 \emptyset \setminus x &= \emptyset \\
 (\Delta, x \approx K \bar{a} \bar{y}) \setminus x &= \Delta \setminus x \\
 (\Delta, x \neq K) \setminus x &= \Delta \setminus x \\
 (\Delta, x \approx \perp) \setminus x &= \Delta \setminus x \\
 (\Delta, x \neq \perp) \setminus x &= \Delta \setminus x \\
 (\Delta, \delta) \setminus x &= (\Delta \setminus x), \delta
 \end{aligned}$$

$$\boxed{\Delta \cap x = \Delta}$$

$$\begin{aligned}
 \emptyset \cap x &= \emptyset \\
 (\Delta, x \approx K \bar{a} \bar{y}) \cap x &= (\Delta \cap x), x \approx K \bar{a} \bar{y} \\
 (\Delta, x \neq K) \cap x &= (\Delta \cap x), x \neq K \\
 (\Delta, x \approx \perp) \cap x &= (\Delta \cap x), x \approx \perp \\
 (\Delta, x \neq \perp) \cap x &= (\Delta \cap x), x \neq \perp \\
 (\Delta, \delta) \cap x &= \Delta \cap x
 \end{aligned}$$

Fig. 9. Adding a constraint to the inert set ∇

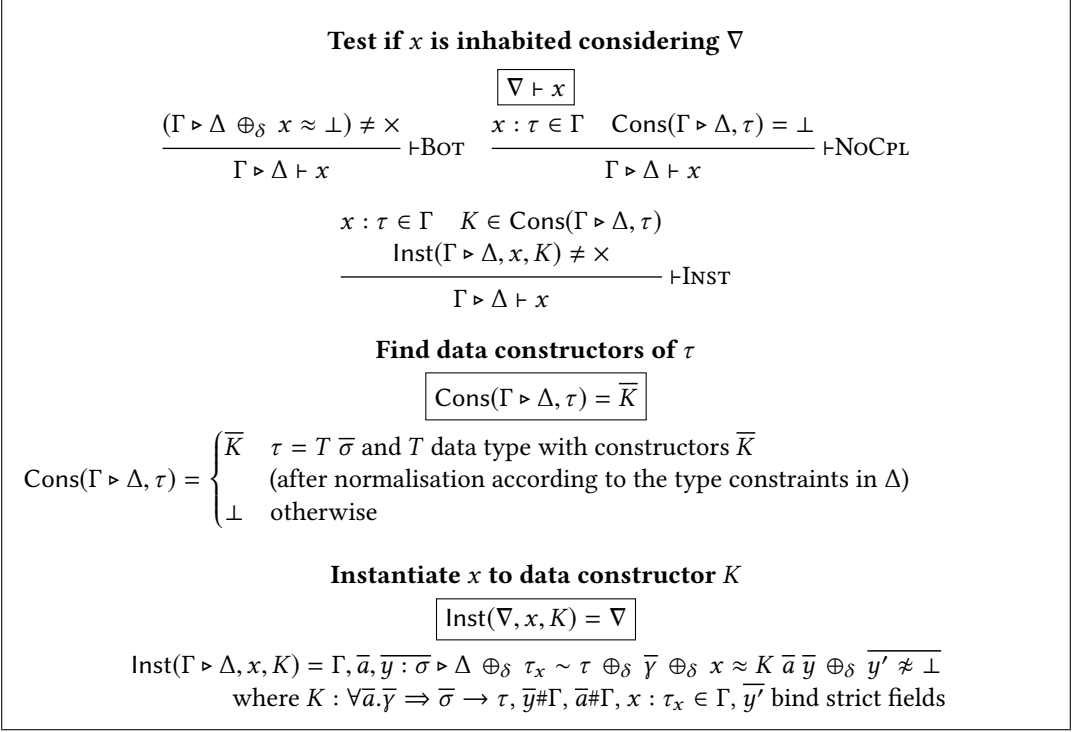


Fig. 10. Inhabitation test

Adding a negative constructor constraint $x \neq \text{Just}$ is quite similar, so is handling of positive and negative constraints involving \perp . The scheme is that whenever we add a negative constraint that doesn't contradict with positive constraints, we still have to test if there are any inhabitants left.

SG: Maybe move down the type constraint case in the definition? Adding a type constraint drives this paranoia to a maximum: After calling out to the type-checker (the logic of which we do not and would not replicate in this paper or our implementation) to assert that the constraint is consistent with the inert set, we have to test *all* variables in the domain of Γ for inhabitants, because the new type constraint could have rendered a type empty. To demonstrate why this is necessary, imagine we have $x : a \triangleright x \neq \perp$ and try to add a *Void*. Although the type constraint is consistent, x in $x : a \triangleright x \neq \perp$, a *Void* is no longer inhabited. There is room for being smart about which variables we have to re-check: For example, we can exclude variables whose type is a non-GADT data type.

SG: That trick probably belongs in the implementation section.

The last case of \oplus_{δ} equates two variables ($x \approx y$) by merging their equivalence classes. Consider the case where x and y don't already belong to the same equivalence class, so have different representatives $\Delta(x)$ and $\Delta(y)$. $\Delta(y)$ is arbitrarily chosen to be the new representative of the merged equivalence class. Now to uphold one of the well-formedness conditions **SG: Which one? Better have a list of them and reference them here.**, all constraints mentioning $\Delta(x)$ have to be removed and renamed in terms of $\Delta(y)$ and then re-added to Δ . That might fail, because $\Delta(x)$ might have a constraint that conflicts with constraints on $\Delta(y)$, so better use \oplus_{δ} rather than add it blindly to Δ .

4.5 Inhabitation Test

$$\begin{array}{l}
\boxed{\bar{\nabla} \dot{\oplus}_\varphi \varphi = \bar{\nabla}} \\
\epsilon \dot{\oplus}_\varphi \varphi = \epsilon \\
(\nabla_1 \dots \nabla_n) \dot{\oplus}_\varphi \varphi = \begin{cases} (\Gamma \triangleright \Delta) (\nabla_2 \dots \nabla_n \dot{\oplus}_\varphi \varphi) & \text{if } \Gamma \triangleright \Delta = \nabla \dot{\oplus}_\varphi \varphi \\ (\nabla_2 \dots \nabla_n) \dot{\oplus}_\varphi \varphi & \text{otherwise} \end{cases} \\
\boxed{\mathcal{UA}(\bar{\nabla}, t_G) = (\bar{\nabla}, \text{Ant})} \\
\begin{array}{ll}
\mathcal{UA}(\epsilon, \text{Rhs } n) & = (\epsilon, \text{InaccessibleRhs } n) \\
\mathcal{UA}(\bar{\nabla}, \text{Rhs } n) & = (\epsilon, \text{AccessibleRhs } n) \\
\mathcal{UA}(\bar{\nabla}, t_G; u_G) & = (\bar{\nabla}_2, t_A; u_A) \text{ where } \begin{array}{l} \bar{\nabla}_1, t_A = \mathcal{UA}(\bar{\nabla}, t_G) \\ \bar{\nabla}_2, u_A = \mathcal{UA}(\bar{\nabla}_1, u_G) \end{array} \\
\mathcal{UA}(\bar{\nabla}, \text{Guard } (!x) t_G) & = \begin{cases} (\bar{\nabla}', t_A), & \bar{\nabla} \dot{\oplus}_\varphi (x \approx \perp) = \epsilon \\ (\bar{\nabla}', \text{MayDiverge } t_A) & \text{otherwise} \end{cases} \\
& \quad \text{where } (\bar{\nabla}', t_A) = \mathcal{UA}(\bar{\nabla} \dot{\oplus}_\varphi (x \not\approx \perp), t_G) \\
\mathcal{UA}(\bar{\nabla}, \text{Guard } (\text{let } x = e) t) & = \mathcal{UA}(\bar{\nabla} \dot{\oplus}_\varphi (\text{let } x = e), t) \\
\mathcal{UA}(\bar{\nabla}, \text{Guard } (K \bar{a} \bar{y} \bar{y} : \bar{\tau} \leftarrow x) t_G) & = ((\bar{\nabla} \dot{\oplus}_\varphi (x \not\approx K)) \bar{\nabla}', t_A) \\
& \quad \text{where } (\bar{\nabla}', t_A) = \mathcal{UA}(\bar{\nabla} \dot{\oplus}_\varphi (K \bar{a} \bar{y} \bar{y} : \bar{\tau} \leftarrow x), t_G)
\end{array}
\end{array}$$

Fig. 11. Fast pattern match checking

SG: We need to find better subsection titles that clearly distinguish "Testing (Θ) for Emptiness" from "Inhabitation Test(ing a particular variable in ∇)". The process for adding a constraint to an inert set above (which turned out to be a unification procedure in disguise) frequently made use of an *inhabitation test* $\nabla \vdash x$, depicted in fig. 10. In contrast to the emptiness test in fig. 8, this one focuses on a particular variable and works on a ∇ rather than a much higher-level Θ .

The \vdash_{BOT} judgment of $\nabla \vdash x$ tries to instantiate x to \perp to conclude that x is inhabited. \vdash_{INST} instantiates x to one of its data constructors. That will only work if its type ultimately reduces to a data type under the type constraints in ∇ . Rule $\vdash_{\text{NO CPL}}$ will accept unconditionally when its type is not a data type, i.e. for $x : \text{Int} \rightarrow \text{Int}$.

5 IMPLEMENTATION

The implementation of our algorithm in GHC accumulates quite a few tricks that go beyond the pure formalism. This section is dedicated to describing these.

Warning messages need to reference source syntax in order to be comprehensible by the user. At the same time, completeness checks involving GADTs need a type-checked program, so the only reasonable phase to run the Pattern match checker is between type-checking and desugaring to GHC Core, a typed intermediate representation lacking the connection to source syntax. We perform pattern match checking in the same tree traversal as desugaring.

SG: New implementation has 3850 lines, out of which 1753 is code. Previous impl as of GHC 8.6.5 had 3118 lines, out of which 1438 were code. Not sure how to sell that.

5.1 Interleaving \mathcal{U} and \mathcal{A}

The set of reaching values is an argument to both \mathcal{U} and \mathcal{A} . given a particular set of reaching values and a guard tree, one can see by a simple inductive argument that both \mathcal{U} and \mathcal{A} are always

called at the same arguments! Hence for an implementation it makes sense to compute both results together, if only for not having to recompute the results of \mathcal{U} again in \mathcal{A} .

But there's more: Looking at the last clause of \mathcal{U} in fig. 7, we can see that we syntactically duplicate Θ every time we have a pattern guard. That can amount to exponential growth of the refinement predicate in the worst case and for the time to prove it empty!

Clearly, the space usage won't actually grow exponentially due to sharing in the implementation, but the problems for runtime performance remain. What we really want is to summarise a Θ into a more compact canonical form before doing these kinds of *splits*. But that's exactly what ∇ is! Therefore, in our implementation we don't really build up a refinement type but pass around the result of calling C on what would have been the set of reaching values.

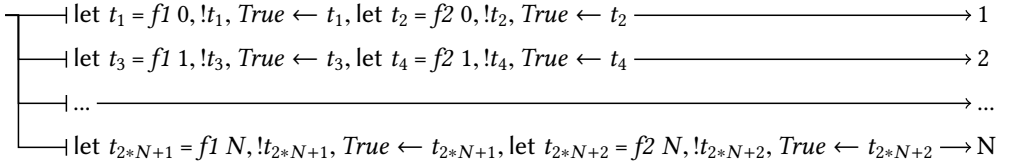
You can see the resulting definition in fig. 11. The readability of the interleaving of both functions is clouded by unwrapping of pairs. Other than that, all references to Θ were replaced by a vector of ∇ s. \mathcal{UA} requires that these ∇ s are non-empty, i.e. not \times . This invariant is maintained by adding φ constraints through \oplus_φ , which filters out any ∇ that would become empty. All mentions of \mathcal{G} are gone, because we never were interested in inhabitants in the first place, only whether there were any inhabitants at all! In this new representation, whether a vector of ∇ is inhabited is easily seen by syntactically comparing it to the empty vector, ϵ .

5.2 Throttling for Graceful Degradation

Even with the tweaks from section 5.1, checking certain pattern matches remains NP-hard **SG: Cite something here or earlier, bring an example**. Naturally, there will be cases where we have to conservatively approximate in order not to slow down compilation too much. After all, pattern match checking is just a static analysis pass without any effect on the produced binary! Consider the following example:

```
f1, f2 :: Int → Bool
g =
  | True ← f1 0, True ← f2 0 = ()
  | True ← f1 1, True ← f2 1 = ()
  ...
  | True ← f1 N, True ← f2 N = ()
```

Here's the corresponding guard tree:



Each of the N GRHS can fall through in two distinct ways: By failure of either pattern guard involving $f1$ or $f2$. Each way corresponds to a way in which the vector of reaching ∇ s is split. For example, the single, unconstrained ∇ reaching the first equation will be split in one ∇ that records that either $t_1 \neq \text{True}$ or that $t_2 \neq \text{True}$. Now two ∇ s fall through and reach the second branch, where they are split into four ∇ s. This exponential pattern repeats N times, and leads to horrible performance!

There are a couple of ways to go about this. First off, that it is always OK to overapproximate the set of reaching values! Instead of *refining* ∇ with the pattern guard, leading to a split, we could just continue with the original ∇ , thus forgetting about the $t_1 \neq \text{True}$ or $t_2 \neq \text{True}$ constraints. In terms of the modeled refinement type, ∇ is still a superset of both refinements.

Another realisation is that each of the temporary variables binding the pattern guard expressions are only scrutinised once, within the particular branch they are bound. That makes one wonder why we record a fact like $t_1 \neq \text{True}$ in the first place. Some smart "garbage collection" process might get rid of this additional information when falling through to the next equation, where the variable is out of scope and can't be accessed. The same procedure could even find out that in the particular case of the split that the ∇ falling through from the $f1$ match models a superset of the ∇ falling through from the $f2$ match (which could additionally diverge when calling $f2$). This approach seemed far too complicated for us to pursue.

Instead, we implement *throttling*: We limit the number of reaching ∇ s to a constant. Whenever a split would exceed this limit, we continue with the original reaching ∇ (which as we established is a superset, thus a conservative estimate) instead. Intuitively, throttling corresponds to *forgetting* what we matched on in that particular sub-tree.

Throttling is refreshingly easy to implement! Only the last clause of \mathcal{UA} , where splitting is performed, needs to change:

$$\mathcal{UA}(\bar{\nabla}, \text{Guard } (K \ \bar{a} \ \bar{y} \ \bar{y} : \bar{\tau} \leftarrow x) \ t_G) = \left(\left[\bar{\nabla} \dot{\oplus}_{\phi} (x \neq K) \right]_{\bar{\nabla}}, t_A \right)$$

where $(\bar{\nabla}', t_A) = \mathcal{UA}(\bar{\nabla} \dot{\oplus}_{\phi} (K \ \bar{a} \ \bar{y} \ \bar{y} : \bar{\tau} \leftarrow x), t_G)$

where the new throttling operator $[_]_{\bar{\nabla}}$ is defined simply as

$$\left[\bar{\nabla} \right]_{\bar{\nabla}'} = \begin{cases} \bar{\nabla} & \text{if } |\{\bar{\nabla}\}| \leq K \\ \bar{\nabla}' & \text{otherwise} \end{cases}$$

with K being an arbitrary constant. We use 30 as an arbitrary limit in our implementation (dynamically configurable via a command-line flag) without noticing any false positives in terms of exhaustiveness warnings outside of the test suite.

For the sake of our above example we'll use 4 as the limit. The initial ∇ will be split by the first equation in two, which in turn results in 4 ∇ s reaching the third equation. Here, splitting would result in 8 ∇ s, so we throttle, so that the same four ∇ s reaching the third equation also reach the fourth equation, and so on. Basically, every equation is checked for overlaps *as if* it was the third equation, because we keep on forgetting what was matched beyond that.

SG: I'm not sure what other hacks we should mention beyond this. I don't think we want to write about ad-hoc details like 6.2 in GMTM, because they are specific to how Δ is represented (solved, canonical type constraints in particular). That's of limited value for other implementations and not a conceptual improvement.

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