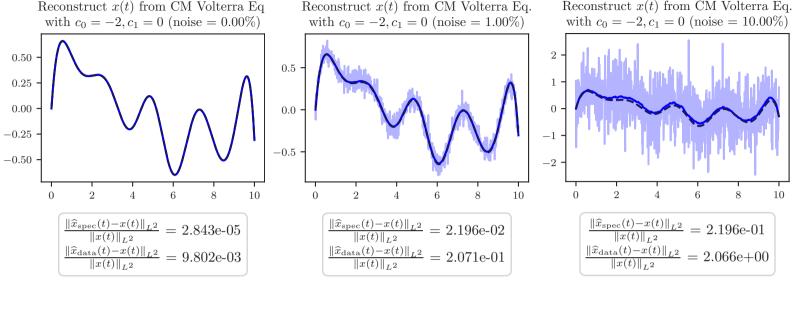
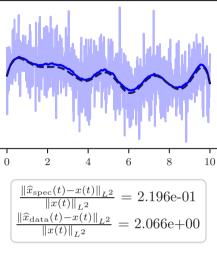
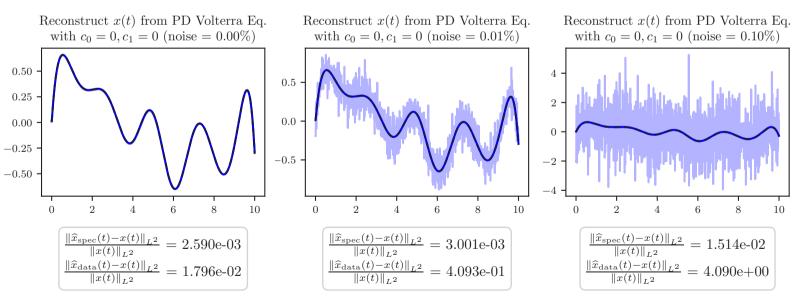
## CM Trajectory Inversion $\tilde{y}(t) \mapsto x(t)$





## PD Trajectory Inversion $\tilde{y}(t) \mapsto x(t)$



$$--- x(t) \qquad \widehat{x}_{\text{spec}}(t) \qquad \widehat{x}_{\text{data}}(t)$$