FDS-Theory Assignment 5

Arus 1-

(Validation Set Method)

Holdout Method > Simplest type of cross-validation where

the dataset is separated into 2 sets; ie training and

testing set. Model is prepared using the training set and

predicts the output values for the data in testing set.

Advantage:-

i) It takes very less time to compute.

Disadvartage:-

i) This method can have a high variance.

and depend heavily on which data points end up in the towing set and which end in the test set.

Box one gut & Action

K-fold cross Validation Method -> Dataset is divided into K subsets and the holdout method is prepeated k times. Each iteration uses K-1 subsets as the toraining subset and the remaining one set as the test dataset. The average error across all k iterations is computed.

Advantage :-

points get to be in the training set as well as in the testing set mas well as

Disadvartage: The method is computation intensive since it takes k iterations (compared to Holdout Method) to compute the result. Thus, it takes long time to sun and prepare the model

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heave-one-out Cross Validation -> It is K-folds method's extreme case where k equals N. where No in the number of data points in the set.

i) Advantage: Et gives very good estimates since it has maximum coverage of data points and thus has minimum variance.

Disadvantage:

This method is highly compute intensive since it is repeated N times. i) This method is highly compute intensive since it is repeated N times.

Reference: https://www.cs.cmu.edu/~shenkide/tut5/node42.

html

Bb) The brediction error for an outbut refere to the

86) The prediction error for an output refer to the is basically a result of ever due to bias and govot due to variance. Variance errore is the eror due to variability of the model prediction for a given data point. The Bias everes is the everes obtained as the difference between the average prediction of the model and the correct value is if the model building process is repeated, then this event is due to randomness in the underlying dataset. resulting in a range of predictions.

19

-9

-9

-3

-3

1

1

1

The tradeoff is that if we try reducing one type of error (bias or variance), it nesuth in the increase in the other type of error. For example: Ordinary Least Square method has high variance. Therefore, they are proposed with the help of methods such as Ridge regression and LASSO to reduce variance, but in this process introduce variance.

Ewich Bias Model Complexity

Reference: https://classeval. wordpress.com/introduction/ basic-evaluation-measures/

True positive: When actual and predicted value five been convertly identified as give the same positive class tatet.

Take regative: When the predicted value is falsely

(wrongly) identified as negative. When the actual value is fositive

False positive: When the predicted value is incorrectly identified as positive when the actual value is negative.

Tour negative: When the predicted value is correctly identified as negative value ic. predicted and actual value both are negative

Overall Accuracy: This is defined as the number of Correct predictions divided by total number in the dataset.

Accuracy = TP+TN+FP+FN

Precision: This is defined as the total number of corruct positive predictions divided by the total number of positive predictions.

Precision: TP

TP+FP

Recall: This is defined as the number of correct positive predictions divided by the total number of positives.

Recall: TP TP+FN

F-measure: This is defined as the harmonic mean of frecision and recall.

Formeasure = 2 x tricall x precision frecall + precision

Ans 2-a) Problems in the approach:

Dwing the evaluation phase, there is no check fore
the class values if there is a conflict (due to complete
match of 2 or more now values) where all the attributes
match whereas the class labels are different.

There is no mention of check of mutticollinearity
between the features that we selected.

The correct approach would be to find out the correlation mathers and the p-values to a understand all those features that are significant and the atto the atto the features that can cause multicolinearity issue and only keeping one of them. Also, removing all the insignificant features. After a subset of features is selected, checking for any sase where there might be a conflict due to binite same attribute values and then removing the conflict.

2 0 | Treain Set
3 0 | Treain Set
5 | E Test Set

Mean = $\frac{10}{4} = 2.5$ Hence, Test set predicted = 1 (since 5 > 2.5) Hence, MSE 5 = 1

Mean = $\frac{1+2+3+5}{4}$ = 2.75 Hence, Test Set predicted = 1 (Since, 4>2.75) Hence, MS E=1

$$Mean = \frac{1+2+4+5}{4} = 3$$

$$Mcar = \frac{1+3+4+5}{4} = \frac{13}{4} = \frac{3.25}{4}$$

$$C \cdot V = \sum_{n} MSE_{100} (1+1+1+1+1) \times 100 \% = 100\%$$

Ground

Truth

Prediction

TP (1 TN ← 2 TP <- 1 TP - 1 TP <- 1

FN < 2 FN < 2 TNE 2 FN - 2 TN -2 FN <- 2

TN ← 2 FN -2 TP <- 1

FP -1

	Predicted	
Observed	TP =5	FN= 5
	FP= 1	TN=4

$$\sqrt{\frac{1}{8}} f$$
-measure = $\frac{2\pi p}{n+p} = \frac{2\pi p}{5+1} = \frac{5}{5+3} = \frac{5}{5}$

Ans 3-

Bayesian Interval for a normal prior distribution and normal population is given by,

11 - Zd 5 * < 11 < 11 + Zd 5 *

Where, $\mu = \frac{n\pi \sigma_0 + \mu_0 \sigma^2}{n\sigma_0^2 + \sigma^2}$, $\sigma^* = \sqrt{\frac{\sigma_0^2 + \sigma^2}{n\sigma_0^2 + \sigma^2}}$

Here, n= sample size = 10 x = sample average = 9 x = sample average = 9

100 µ, σ_0^2 = normal prior near & variance = 8,0.2 σ^2 = sample variance = 0.64

Computing u* = (10×9×0·2) + (8×0-8²) = (90×0·2) + (8×0·64) (10×0·2) + 0·8² = (10×0·2) + 0·64

= 23.12 = 8.75

5

Computing $6^{-1/2} = \frac{0.2 \times 0.8^2}{(0 \times 0.2) + 0.8^2} = \frac{0.128}{2.64} = 0.220$

Hence, $\mu^* - \frac{7}{4} \frac{1}{2} = 8.75 - (1.96 \times 0.220) = 8.3188$

1 + 7x/0 + = 8.75 + (1.96 × 0.220) = 9.1812

Hence, the 95% Bayesian Interval is: [8.3188, 9-1812]

a)
$$P(A=0, B=1, C=0, D=1, E=0, F=1)$$

= $P(A=0) \cdot P(B=1) \cdot P(c=0|A=0) \cdot P(b=1|A=0, B=1) \cdot P(E=0|C=0, D=1) \cdot P(F=1|E=0)$

- = 0.4 × 0.4 × 0.8 × 0.7 × 0.4 × 0.9
- = 0.16 × 0.56 × 0.36
- = 0.032256

ii) To prove
$$P(B,D|A,C) = P(B|A,C) * P(D|A,C)$$

Solving
$$P(B|D,A,C)$$

= $\frac{P(B,D,A,C)}{P(b,A,C)}$

$$= \frac{\sum_{EF} P(A,B,C,D,E,F)}{\sum_{BEF} P(A,B,C,D,E,F)}$$

$$=\frac{P(A)\cdot P(B)\cdot P(C|B)\cdot P(D|A,C)}{P(A)\cdot P(D|A,C)\cdot \sum_{B}P(B)\cdot P(C|B)} \sum_{F}P(F|A)\cdot \sum_{F}P(E|B,D,F)$$

$$= \frac{P(B) \cdot P(C|B)}{P(C)}$$

=
$$\frac{P(B,C)}{P(C)} = P(B|C) = P(B)$$
 [from Bayesian Net]

Therefore

Now, taking RH.S ie P(B|A,C) + P(D|A,C)

$$P(B|A,c) = P(B,A,c)$$
 $P(A,c)$

$$= \frac{P(A) \cdot P(B) \cdot P(C|B)}{P(A) \cdot P(C|B)}$$

$$= P(B)$$

Hence, RHS becomes = P(B) * P(D|A,C)

Hence, LHS = RHS. Hence, proved.