

$$2. (a) \text{softmax}(\text{sim}(z_{it}, z_{jt'})/\tau)$$

$$= \text{softmax}\left(\frac{z_{it} \cdot z_{jt'}}{\|z_{it}\|_2 \|z_{jt'}\|_2 \cdot \tau}\right) = \frac{\exp\left(\frac{z_{it} \cdot z_{jt'}}{\|z_{it}\|_2 \|z_{jt'}\|_2 \cdot \tau}\right)}{\sum_i \sum_j \exp\left(\frac{z_{it} \cdot z_{jt'}}{\|z_{it}\|_2 \|z_{jt'}\|_2 \cdot \tau}\right)}$$

$$(b) \text{InfoNCE} = -\sum_{i,j} y_{it} y_{jt'} \log(\text{softmax}(\text{sim}(z_{it}, z_{jt'})/\tau))$$

$$\begin{aligned} (c) &= -\sum_{i,j} \delta_{ij} \left[\frac{z_{it} \cdot z_{jt'}}{\|z_{it}\|_2 \|z_{jt'}\|_2 \cdot \tau} - \log \left\{ \sum_{i,j'} \exp \left(\frac{z_{it} \cdot z_{jt'}}{\|z_{it}\|_2 \|z_{jt'}\|_2 \cdot \tau} \right) \right\} \right] \\ &= -\sum_{i=1}^n \left(\frac{z_{it} \cdot z_{it'}}{\|z_{it}\|_2 \|z_{it'}\|_2 \cdot \tau} \right) + n \log \left\{ \sum_{i,j} \exp \left(\frac{z_{it} \cdot z_{jt'}}{\|z_{it}\|_2 \|z_{jt'}\|_2 \cdot \tau} \right) \right\} \\ &= -\sum_{i=1}^n \frac{\text{sim}(z_{it}, z_{it'})}{\tau} + n \log \left\{ \sum_{i,j} \exp \left(\frac{\text{sim}(z_{it}, z_{jt'})}{\tau} \right) \right\} \end{aligned}$$

(d) First term implies that, for an original observation, z_i , loss is smaller if two different transformation t and t' give similar mapping.

Second term shows that, for different original observations (z_i, z_j) , loss is higher if two different transformation t and t' give similar mapping. ~~the penalized~~

This second ~~term~~ term prevents mode collapses.

h is used as representation because z ^{the result} is after projection, or dimension reduction.

$$3. (a) K = Q = X + E: \quad X = (x_1, x_2, \dots, x_n)$$

$$(K^T Q)_{i,j} = (X^T + E^T)(X + E)_{i,j} = (X^T X + E^T X + X^T E + E^T E)_{i,j}$$

$$= \sum_{i=1}^n x_i \cdot x_i + \sum_{k=1}^p (x_{ki} \cdot x_{kj} + E_{ki} \cdot x_{kj} + x_{ki} \cdot E_{kj} + E_{ki} \cdot E_{kj})$$

$$= \sum_{k=0}^{p-1} (x_{ki} \cdot x_{kj} + E_{ki} \cdot E_{kj} + x_{ki} \cdot E_{kj} + E_{ki} \cdot x_{kj})$$

$$= \sum_{k=0}^{p-1} \left(\sin(i \cdot \exp(-\frac{2k}{p} \log(10000))) \right)$$

3. (a) (i) Addition: $K = X + E$.

$$K^T Q = (X^T + E^T)(X + E) \\ = X^T X + E^T X + E^T E + X^T E.$$

(ii) concatenation: $K = \begin{pmatrix} X \\ E \end{pmatrix}$.

$$K^T Q = (X^T, E^T) \begin{pmatrix} X \\ E \end{pmatrix} \\ = X^T X + E^T E \quad \text{No cross terms. } E^T X + X^T E.$$

(d) $f(X_i) = y_i = \begin{pmatrix} y_{i0} \\ y_{i1} \\ \vdots \\ y_{id} \\ 0 \\ \vdots \end{pmatrix}$

$Ax_i = y_i$

~~$Ax = \begin{pmatrix} Y \\ 0 \end{pmatrix}$~~

~~$G E = \begin{pmatrix} F \\ 0 \end{pmatrix}$~~ $G E = \begin{pmatrix} I_{f \times f} & 0 \\ 0 & 0 \end{pmatrix}$

~~$E^T X$~~ $A =$ ~~Ax~~ $Ax = \begin{pmatrix} I_{d \times d} & 0 \\ 0 & 0 \end{pmatrix} = Y$

$$E^T X = (G^T G E)^T (A^T A X) = F G^T A^T Y$$

$$H = G^T A^T = \begin{pmatrix} H_{00} & H_{01} \\ H_{10} & H_{11} \end{pmatrix}$$

$$H Y = \begin{pmatrix} I_{f \times d} & H_{01} \\ H_{10} & H_{11} \end{pmatrix} \begin{pmatrix} I_{d \times d} & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} H_{00} & 0 \\ H_{10} & 0 \end{pmatrix}$$

$$F H Y = \begin{pmatrix} I_{f \times f} & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} H_{00} \\ H_{10} \end{pmatrix} = \begin{pmatrix} H_{00} (f \times d) & 0 \\ 0 & 0 \end{pmatrix}$$

$$Y^T H^T F^T = \begin{pmatrix} H_{00}^T (d \times f) & 0 \\ 0 & 0 \end{pmatrix}$$

$$E^T X + X^T E = \begin{pmatrix} H_{00}^T (d \times f) & 0 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} H_{00} (f \times d) & 0 \\ 0 & 0 \end{pmatrix}$$

$\text{rank}(X) = d$
 $\text{rank}(E) = f$