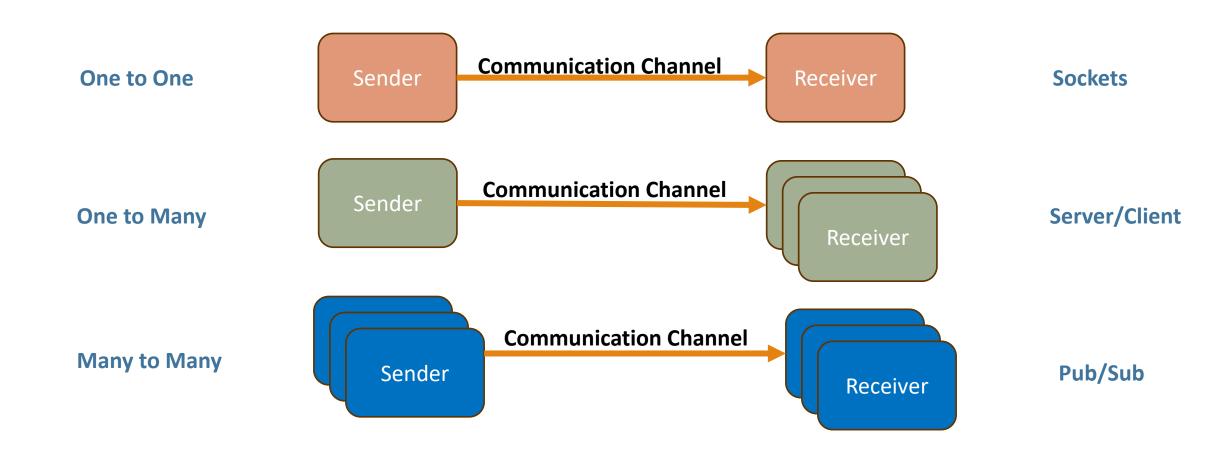
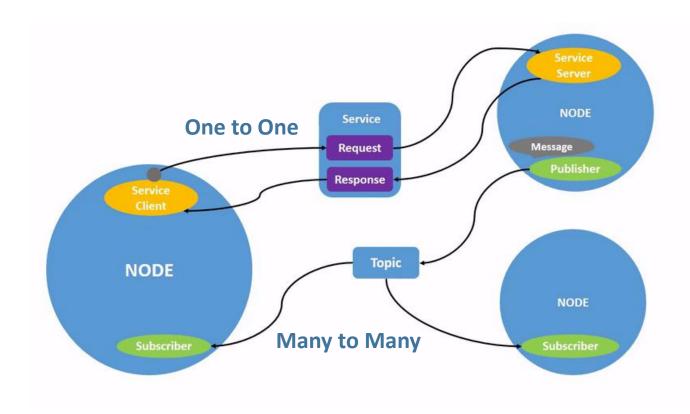
Data Distribution Service

MOHAMAD SHAABAN

Communication Models

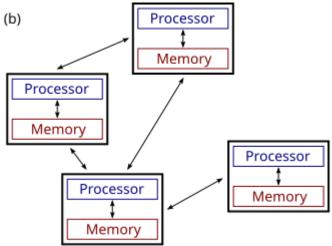


Robotics Communication Model (ROS)



What is DDS?

- •A data-centric communication protocol for distributed software systems.
- Protocol is designed by Object Management Group (OMG)
- •Based on the **Data-Centric Publish Subscribe (DCPS)** model.
 - Publication Entities: Define information-generating objects.
 - Subscription Entities: Define information-consuming objects.
 - Configuration Entities
- •Defines APIs and Communication Semantics for data providers and consumers.



Example Project



DDS Middleware Implementations

Open-Source Implementations

- Fast DDS (eProsima)
 - High performance and low latency
 - Extensive QoS support and ROS2 compatibility
 - Apache-2.0 license
- Cyclone DDS (Eclipse Foundation)
 - Lightweight and optimized for embedded systems.
 - Popular in ROS2 environments.
 - Eclipse-2.0





DDS Middleware Implementations

•Commercial Implementations:

- RTI Connext DDS:
 - Industry-leading performance and reliability.
 - · Comprehensive tools for monitoring and debugging.
- OpenSplice DDS:
 - Focused on scalability and fault tolerance.
 - Offers both open-source and commercial versions.







Fast DDS

Key DCPS Elements

•Publisher:

- Creates and configures DataWriters.
- **DataWriter**: Handles the actual publication of data.
- Publishes messages under assigned **Topics**.

•Subscriber:

- •Receives data published under subscribed **Topics**.
- •Manages DataReaders that notify the application of new data.

Key DCPS Elements

•Topic:

- Binds publications and subscriptions.
- Ensures uniform data types between publishers and subscribers.
- Unique within a DDS domain.

•Domain:

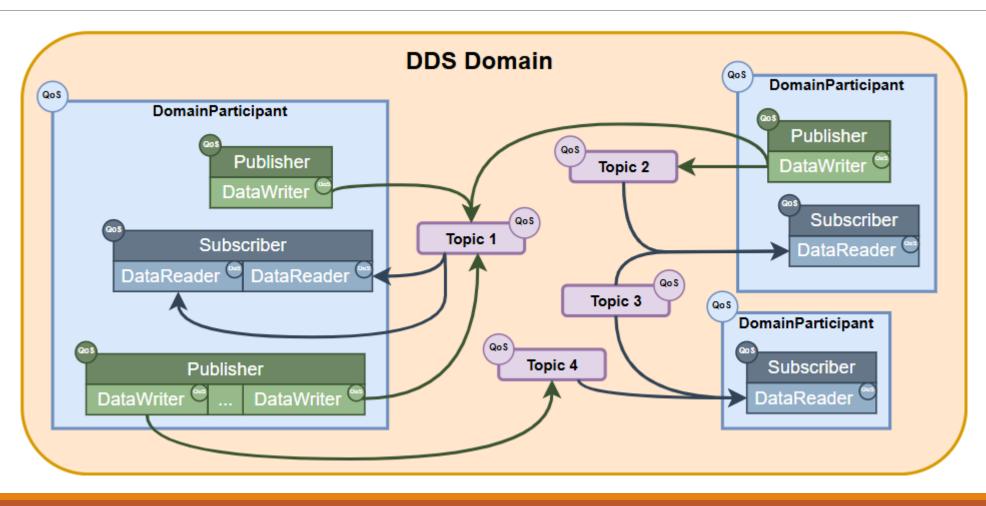
- •Links all **Publishers** and **Subscribers** in a DDS domain.
- •Identified by a unique domain ID:
 - Different IDs create independent communication channels.
 - •Prevents interference between multiple applications.

Key DCPS Elements

•DomainParticipant:

- Defines the **domain ID** to specify the DDS domain it belongs to.
- Acts as a container for DCPS Entities (Publisher, Subscriber, and Topic).
- Serves as a **factory** for creating these entities.

DDS Model (DCPS)





Installing FastDDS (3.1.0)

Download FastDDS Binaries

curl -o fastdds.tgz 'https://www.eprosima.com/component/ars/item/eProsima_Fast-DDS-v3.1.0-Linux.tgz?format=tgz&category_id=7&release_id=169&Itemid=0'

Unzip fastdds.tgz

mkdir fastdds tar -xvzf ./fastdds.tgz -C ./fastdds cd fastdds sudo ./install.sh

Linking DDS

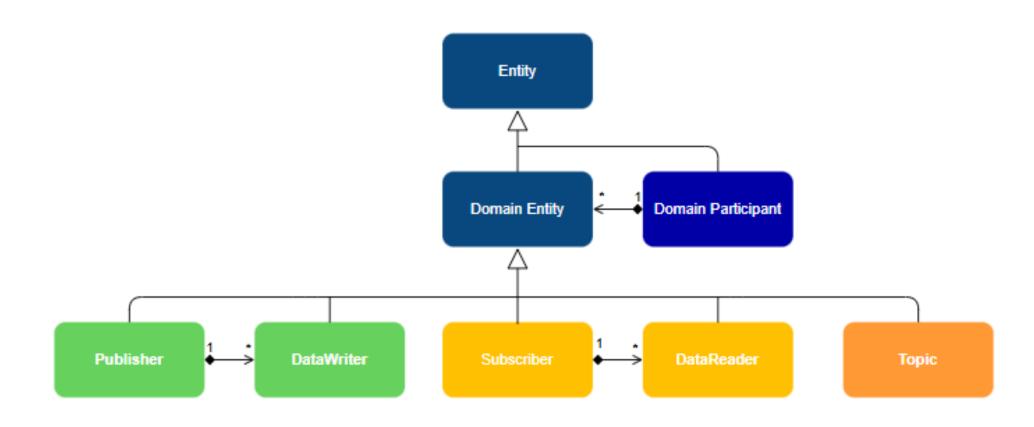
Tasks.json → Adding gcc args

```
"-I/usr/include/fastdds" → FastDDS include directory
"-I/usr/include/fastcdr" → FastCDR include directory
"-std=c++11" → We want to use C++11
"-lstdc++" → link standard C++ library
"-lfastcdr" → link libfastcdr (for serialization and deserialization)
"-lfastdds" → link libfastdds
```

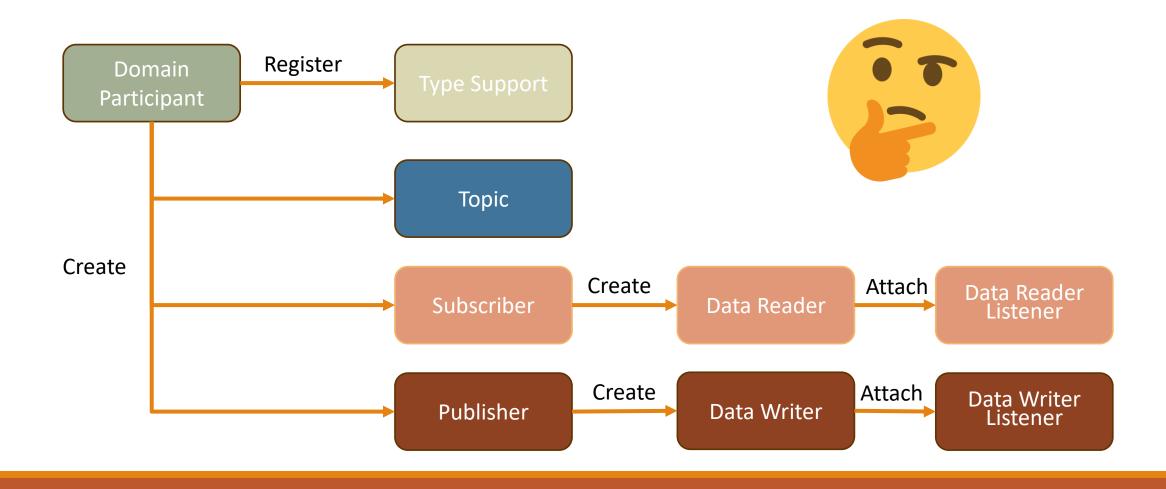


HelloWorld Example

Entities Relations



Entities Relations



Data Listeners

- •Data Reader Listener: abstract class defining the callbacks that will be triggered in response to state changes on the **DataReader**.
 - on_subscription_matched: There is new data available for the application on the DataReader.
 - on_data_available: The DataReader has found a DataWriter that matches the Topic.
- •Data Write Listener: abstract class defining the callbacks that will be triggered in response to state changes on the **DataWriter**.
 - on_publication_matched: DataWriter has found a DataReader that matches the Topic



Listeners Example

Type Support & IDL

- •IDL: Interface Definition Language
- •For Publisher and subscriber to be able to communicate they should agree on a message structure
- Message structure is defined using IDL
- •To convert from IDL to Cpp we use **Fast DDS-Gen**.
- •Fast DDS-Gen is not case sensitive (string message = string Message)

```
struct HelloWorld
{
   unsigned long index;
   string message;
};
```

IDL	C++11
char	char
octet	uint8_t
short	int16_t
unsigned short	uint16_t
long	int32_t
unsigned long	uint32_t
long long	int64_t
unsigned long long	uint64_t
float	float
double	double
long double	long double
boolean	bool
string	std::string

Primitive Types

Arrays(std::array)

IDL	C++11
char a[5]	std::array <char,5> a</char,5>
octet a[5]	std::array <uint8_t,5> a</uint8_t,5>
short a[5]	std::array <int16_t,5> a</int16_t,5>
unsigned short a[5]	std::array <uint16_t,5> a</uint16_t,5>
long a[5]	std::array <int32_t,5> a</int32_t,5>
unsigned long a[5]	std::array <uint32_t,5> a</uint32_t,5>
long long a[5]	std::array <int64_t,5> a</int64_t,5>
unsigned long long a[5]	std::array <uint64_t,5> a</uint64_t,5>
float a[5]	std::array <float,5> a</float,5>
double a[5]	std::array <double,5> a</double,5>

IDL	C++11
sequence <char></char>	std::vector <char></char>
sequence <octet></octet>	std::vector <uint8_t></uint8_t>
sequence <short></short>	std::vector <int16_t></int16_t>
sequence <unsigned short=""></unsigned>	std::vector <uint16_t></uint16_t>
sequence <long></long>	std::vector <int32_t></int32_t>
sequence <unsigned long=""></unsigned>	std::vector <uint32_t></uint32_t>
sequence <long long=""></long>	std::vector <int64_t></int64_t>
sequence <unsigned long=""></unsigned>	std::vector <uint64_t></uint64_t>
sequence <float></float>	std::vector <float></float>
sequence <double></double>	std::vector <double></double>

Sequences (std::vector)

IDL to CPP Classes

fastddsgen ~/CustomIDL/src/MyMessage.idl -d ~/CustomIDL/src/Generated

```
struct MyMessage

unsigned long index;
double first_number;
double second_number;

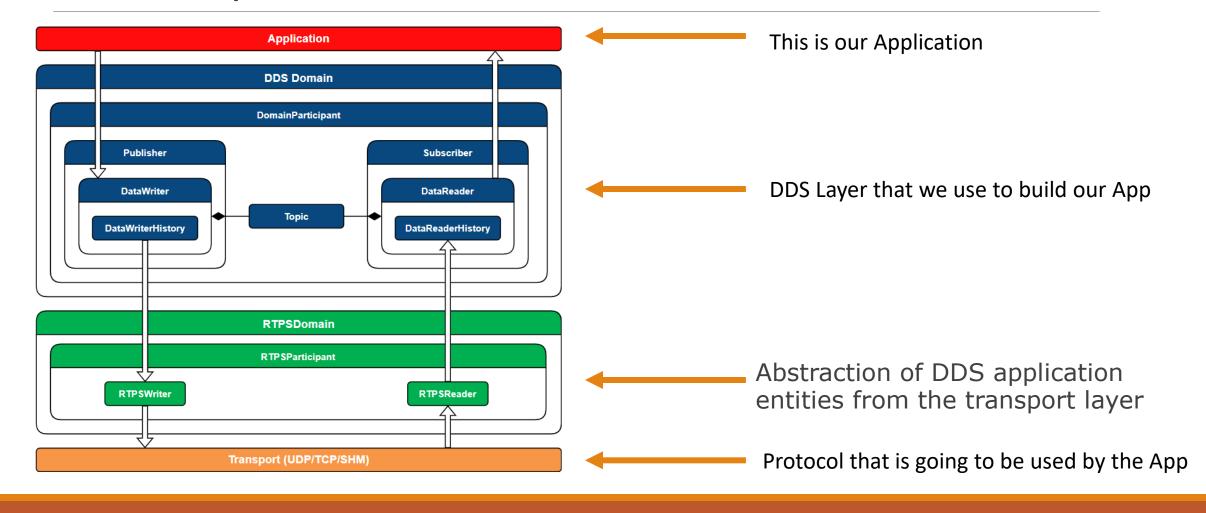
double second_number;

f MyMessagePubSubTypes.cxx
MyMessagePubSubTypes.hpp
MyMessageTypeObjectSupport.cxx
MyMessageTypeObjectSupport.cxx
MyMessageTypeObjectSupport.hpp
Header File to Include
```



CustomIDL Example

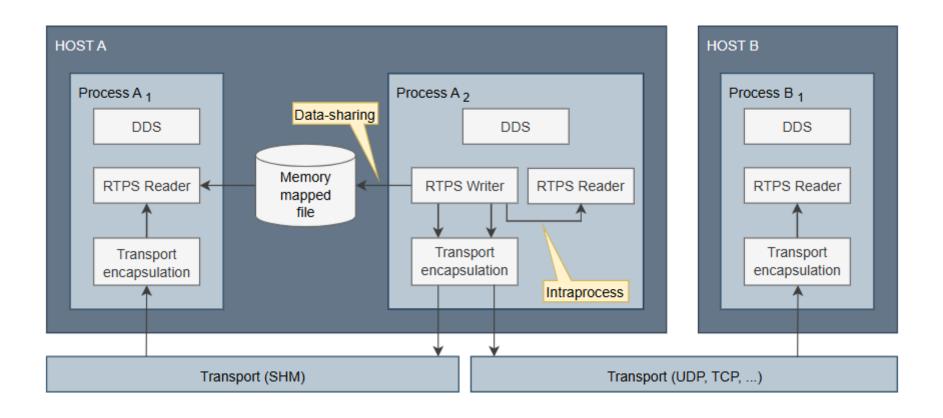
DDS Layer Model



Transport Layer

- •UDPv4: UDP Datagram communication over IPv4. (Default Protocol)
- •UDPv6: UDP Datagram communication over IPv6.
- •TCPv4: TCP communication over IPv4.
- •**TCPv6**: TCP communication over IPv6.
- •SHM: Shared memory communication among entities running on the same host.

Transport Layer





Transports Example

Selecting a Transport

```
•By default, UDPv4 is used.

Starting publisher.

Publisher matched.

Using UDPv4
```

```
// Explicit configuration of shm transport
participantQos.transport().use_builtin_transports = false;
auto shm_transport = std::make_shared<SharedMemTransportDescriptor>();
shm_transport->segment_size(10 * 1024 * 1024);
participantQos.transport().user_transports.push_back(shm_transport);
```

Starting subscriber.
Subscriber matched.
Using Shared Memory