



Machine Learning 2

Final Exam

Date: May 29, 2019 Time: 13:00-16:00

Number of pages: 6 (including front page)

Number of questions: 4

Maximum number of points to earn: 89

At each question is indicated how many points it is worth.

BEFORE YOU START

- Please wait until you are instructed to open the booklet.
- Check if your version of the exam is complete.
- Write down your name, student ID number, and if applicable the version number on each sheet that you hand in. Also number the pages.
- Your **mobile phone** has to be switched off and in the coat or bag. Your **coat and bag** must be under your table.
- Tools allowed: 1 handwritten double-sided A4-size cheat sheet, pen.

PRACTICAL MATTERS

- The first 30 minutes and the last 15 minutes you are not allowed to leave the room, not even to visit the toilet.
- You are obliged to identify yourself at the request of the examiner (or his representative) with a proof of your enrollment or a valid ID.
- During the examination it is not permitted to visit the toilet, unless the proctor gives permission to do so.
- 15 minutes before the end, you will be warned that the time to hand in is approaching.
- If applicable, please fill out the evaluation form at the end of the exam.

Good luck!

1 Information Theory

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We define the higher interaction information between three random variables X, Y, Z as follows:

$$I(X;Y;Z) := I(X;Y) - I(X;Y|Z).$$

Show that we have the symmetry:

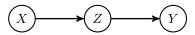
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$$I(X;Y;Z) = I(X;Z;Y).$$

Sketch an "information diagram" for three random variables X, Y, Z (three circles intersecting each other) and indicate which part of the diagram corresponds to which information theoretic quantity. Indicate at least the (marginal) entropies, the joint entropy, a conditional entropy, a conditional mutual information and an (unconditional) mutual information with the correct variables. Where would you put I(X;Y;Z) in this diagram?

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c/Consider the following Markov chain:



Prove the following information processing inequality:

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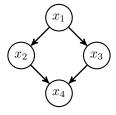
$$I(X;Z) \ge I(X;Y).$$

Hint: You may use the symmetry of the higher interaction information and properties of the graphical model. In addition, you may use that $I(X;Y|Z) \geq 0$ and $I(X;Y|Z) = 0 \iff X \perp \!\!\!\perp Y|Z$.

2 A simple Bayesian network

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Consider the following Bayesian network:



Write down the factorization of the joint probability density $p(x_1, x_2, x_3, x_4)$ implied by the Bayesian network.

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b) Which of the following (conditional) independences necessarily hold in the Bayesian network?

- (i) $x_1 \perp \!\!\! \perp x_2 | \varnothing$
- (ii) $x_1 \perp x_2 | x_3$
- (iii) $x_1 \perp \!\!\! \perp x_2 | x_4$
- (iv) $x_1 \perp x_2 | \{x_3, x_4\}$
- (v) $x_1 \perp x_4 | \varnothing$



(vii)
$$x_1 \perp x_4 | x_2$$

(viii)
$$x_1 \perp x_4 | \{x_2, x_3\}$$

(ix)
$$x_2 \perp x_3 | \varnothing$$

(x)
$$x_2 \perp \!\!\! \perp x_3 | x_1$$

(xi)
$$x_2 \perp x_3 | x_4$$

(xii)
$$x_2 \perp x_3 | \{x_1, x_4\}$$

c) Draw the Markov Random Field representation of the Bayesian network. List all maximal

cliques and express the corresponding potential functions in terms of conditional probability densities.

d) Which of the following (conditional) independences necessarily hold according to the graph of the Markov Random Field?

(i)
$$x_1 \perp \!\!\! \perp x_2 | \varnothing$$

(ii)
$$x_1 \perp x_2 | x_3$$

(iii)
$$x_1 \perp \!\!\! \perp x_2 | x_4$$

(iv)
$$x_1 \perp x_2 | \{x_3, x_4\}$$

(v)
$$x_1 \perp x_4 | \varnothing$$

(vi)
$$x_1 \perp x_4 | x_3$$

(vii)
$$x_1 \perp x_4 | x_2$$

(viii)
$$x_1 \perp x_4 | \{x_2, x_3\}$$

(ix)
$$x_2 \perp x_3 | \varnothing$$

(x)
$$x_2 \perp \!\!\! \perp x_3 | x_1$$

(xi)
$$x_2 \perp x_3 | x_4$$

(xii)
$$x_2 \perp x_3 | \{x_1, x_4\}$$

Draw the factor graph representation of the Bayesian network. Express each factor in

terms of conditional probability densities.

Write down explicitly the steps that the variable elimination algorithm makes to calculate the marginal distribution $p(x_1)$ when eliminating first x_2 , then x_3 and finally x_4 . Clearly indicate the new factors introduced by the variable elimination algorithm and on which variables they depend.

g) The Loopy Belief Propagation algorithm (also known as Sum-Product Algorithm) works by passing messages along the edges of the factor graph representation. Write down the sum-product message update equations for all messages that depend on variable x_1 . You

may assume the variables to be discrete.

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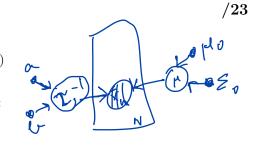
3 Sampling

Consider a model with a Gaussian likelihood:

$$p(\boldsymbol{x}_1,\ldots,\boldsymbol{x}_N\,|\,\boldsymbol{\mu},\tau) = \prod_{n=1}^N \mathcal{N}(\boldsymbol{x}_n\,|\,\boldsymbol{\mu},\tau^{-1}\boldsymbol{C})$$

where all $\boldsymbol{x}_n \in \mathbb{R}^D$, and the following prior distribution for $\boldsymbol{\mu}$ and τ :

$$p(\boldsymbol{\mu} \mid \boldsymbol{\mu}_0, \boldsymbol{\Sigma}_0) = \mathcal{N}(\boldsymbol{\mu} \mid \boldsymbol{\mu}_0, \boldsymbol{\Sigma}_0)$$
$$p(\tau \mid a, b) = \operatorname{Gam}(\tau \mid a, b)$$



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The model has parameters C, μ_0 , Σ_0 , a, b. Suppose we have a dataset $X = (x_1, \dots, x_N)$ of i.i.d. samples. We will construct a Gibbs sampler to sample the posterior $p(\mu, \tau \mid X)$ from this model.

Hint: some properties of the probability distributions used in this exercise:

$$\begin{aligned} &\operatorname{Gam}(\tau \mid a, b) = \frac{1}{\Gamma(a)} b^a \tau^{a-1} \exp(-b\tau), \\ &\operatorname{E}(\tau \mid a, b) = \frac{a}{b}, \quad \operatorname{Var}(\tau \mid a, b) = \frac{a}{b^2}. \\ &\mathcal{N}(\boldsymbol{x} \mid \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{D/2}} |\boldsymbol{\Sigma}|^{-1/2} \exp\left(-\frac{1}{2} (\boldsymbol{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\boldsymbol{x} - \boldsymbol{\mu})\right), \\ &\operatorname{E}(\boldsymbol{x} \mid \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \boldsymbol{\mu}, \quad \operatorname{Cov}(\boldsymbol{x} \mid \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \boldsymbol{\Sigma}. \end{aligned}$$

- (a) Draw the model in plate notation. Clearly distinguish observed variables, latent variables, parameters, and make clear which variable subscripts are "looped over" if you use plates.
- b) Write down an explicit expression for the joint probability $p(\mu, \tau, X)$.
- C) Write down the pseudocode for a Gibbs sampler that samples from $p(\boldsymbol{\mu}, \tau \mid \boldsymbol{X})$.
 - d) Are the samples that the Gibbs sampler generates independent of each other? $\hspace{1cm}/1$
- e) Show that the conditional distribution $p(\mu | \tau, X)$ is a Gaussian distribution and give an explicit expression of its parameters. /4
- Show that the conditional distribution $p(\tau | \mu, X)$ is a Gamma distribution and give an explicit expression of its parameters. /4
 - g) In order to implement the Gibbs sampler, you need to be able to sample from a Gamma distribution. Which sampling method to sample from $Gam(\tau \mid a, b)$ would be suitable in the context of the Gibbs sampler? What will be the main challenge in implementing it?

Suppose you do not have a subroutine that samples from a Gamma distribution, but you do have a subroutine $\mathtt{randnorm}(\mu,\sigma)$ that samples from a Gaussian distribution $\mathcal{N}(\mu,\sigma^2)$ with given mean μ and standard deviation σ . One way to sample from $\mathtt{Gam}(a,b)$ is to use importance sampling.

h) Give an expression for the importance weights in terms of the occurring parameters.

i) Explain how the samples output by the importance sampler can be used in order to approximate the expectation value

$$E(f(\tau)) = \int f(\tau) Gam(\tau|a, b) d\tau$$

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where $f(\tau)$ is some function of τ .

- j) Give a detailed explanation of how you would implement that importance sampler using randnorm. How would you choose μ and σ in order to make the sampler efficient?
- k) Why is the importance sampler not suitable to use within the context of the Gibbs sampler?

Variational EM for mixture of Bernoulli distributions

Consider a multivariate Bernoulli distribution

$$p(x|\mu) = \prod_{i=1}^{D} \mu_i^{x_i} (1 - \mu_i)^{1 - x_i}$$

where $\mathbf{x} = (x_1, \dots, x_D)$ and $\boldsymbol{\mu} = (\mu_1, \dots, \mu_D)$, with $\mu_i \in [0, 1], x_i \in \{0, 1\}$ for $i = 1, \dots, D$.

- a) What is the mean of \boldsymbol{x} under this distribution?
- b) What is the covariance matrix of x under this distribution?

Now consider a mixture of K of these multivariate Bernoulli distributions

$$p(oldsymbol{x}|oldsymbol{\mu},oldsymbol{\pi}) = \sum_{k=1}^K \pi_k p(oldsymbol{x}|oldsymbol{\mu}_k)$$

where $\boldsymbol{\pi} = (\pi_1, \dots, \pi_K)$ and $\boldsymbol{\mu} = (\boldsymbol{\mu}_1, \dots, \boldsymbol{\mu}_K)$, and

$$p(\mathbf{x} \mid \boldsymbol{\mu}_k) = \prod_{i=1}^{D} \mu_{ki}^{x_i} (1 - \mu_{ki})^{1 - x_i}$$

c) What is the mean of x under this mixture distribution?

Suppose we are given a data set $X = (x_1, ..., x_N)$.

- d) Write down the log-likelihood function for this model. Make the expression as explicit as possible, and use brackets to remove any ambiguity regarding what is summed over in the expression.
- e) Why doesn't standard maximum-likelihood work here?

We will use the Variational EM algorithm to learn the parameters of the model. For each datapoint x_n , introduce a latent variable $z_n = (z_{n1}, \ldots, z_{nK})$ which is a one-of-K coded binary vector that indicates the latent class of that datapoint. In other words: the latent variable z_n has K components, all of which are 0 except for the k'th one that is 1, where k is the latent class for data point x_n . Using these conventions, for data point x_n and associated latent class z_n , we can write:

$$p(\boldsymbol{x}_n, \boldsymbol{z}_n | \boldsymbol{\mu}, \boldsymbol{\pi}) = p(\boldsymbol{z}_n | \boldsymbol{\pi}) p(\boldsymbol{x}_n | \boldsymbol{z}_n, \boldsymbol{\mu}) = \prod_{k=1}^K \pi_k^{z_{nk}} p(\boldsymbol{x}_n | \boldsymbol{\mu}_k)^{z_{nk}}$$

- f) Write down the complete-data log-likelihood function for this model. Make the expression as explicit as possible, and use brackets to remove any ambiguity regarding what is summed over in the expression.
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- g) Draw the corresponding graphical model using plate notation. Clearly distinguish observed variables, latent variables, parameters, and make clear which variable subscripts are "looped over" if you use plates.
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- h) Write down the general form of the VEM objective function (ELBO) $\mathcal{B}(q, \theta)$ and show that in this model we have the equality:
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$$\mathcal{B}(\{q_n\}, \boldsymbol{\pi}, \boldsymbol{\mu}) = \sum_{n=1}^{N} \sum_{\boldsymbol{z}_n} q_n(\boldsymbol{z}_n) \sum_{k=1}^{K} z_{nk} \left(\log \pi_k + \sum_{i=1}^{D} \left(x_{ni} \log \mu_{ki} + (1 - x_{ni}) \log (1 - \mu_{ki}) \right) \right) - \sum_{n=1}^{N} \sum_{\boldsymbol{z}_n} q_n(\boldsymbol{z}_n) \log q_n(\boldsymbol{z}_n)$$

- i) Include Lagrange multipliers for all constraints in the model and construct the Lagrangian $\tilde{\mathcal{B}}$ from \mathcal{B} . Make the Lagrangian as explicit as possible.
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- j) Work out the details of the E-step, i.e., optimize $\tilde{\mathcal{B}}$ with respect to q_n for all n = 1, ..., N. Solve the equation. What is the interpretation of $q_n(\mathbf{z}_n)$?
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- k) Work out the details of the M-step for π , i.e., optimize $\tilde{\mathcal{B}}$ with respect to π_k for all k. Solve the equation.
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- 1) Work out the details of the M-step for μ , i.e., optimize $\tilde{\mathcal{B}}$ with respect to μ_{ki} for all k, i. Solve the equation.
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