1. a)
$$E \cap Y = \mathbb{R}^d$$

b) $E \cap Y = E \cap \mathbb{R}^d \times \mathbb{I} = \frac{1}{1} (\mathbb{R}^d \times \mathbb{I}) = \frac{1}{1} \mathbb{R}^d \times \mathbb{I} = \frac{1}{1} \cdot \mathbb{I} \times \mathbb{I} = \frac{1}{1} \cdot \mathbb{I} \times \mathbb{I} = \frac{1}{1} \cdot \mathbb{I} \times \mathbb{I$

2. a) No, since **b)** X = U Σ V^T Xw = 4 Σ not invertible so Σ pseudoi averse. $U \Sigma V^T \omega = y$ w = VEtuTy $\omega = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{12}} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{\sqrt{12}/2}{2} & 0 & \frac{\sqrt{12}/2}{2} \\ 0 & 1 & 0 \\ 0 & 0 & \frac{\sqrt{12}/2}{2} & 0 & \frac{\sqrt{12}/2}{2} \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ $= \begin{bmatrix} 1/\sqrt{2} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \sqrt{2} & 1 \\ 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$ C) With $w_0 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$, we get $w_2 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ W_{i+1} $w_0 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, we get $w_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ The better solution is when $w_0 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ as then $Xw = \begin{bmatrix} 1 \\ 1 \end{bmatrix} = y$. This is a different solution than SVD, but still gives us a minimum ℓ_2^2 d) As we increase wo, further we get from an accurate w in 2 iterations. e) ||xw-y||2 + 2||ω||2 = (xw-y)(xw-y) + 2ωτω = wTxTxw-wTxTy +yTxw+yTy + 2wTw $2x^{T}x\omega + 2\lambda\omega = 2x^{T}y$ $(x^Tx + \lambda I)\omega = x^Ty$ $M = (X_{\perp}^{\perp} X + Y \pm)_{\perp} X_{\perp}^{\perp} A$ At $\lambda = 10^{-16} : \omega = [6]$ We see that as $\lambda \rightarrow 0$, we get closer to $\lambda = 10_{0} : M = \begin{bmatrix} 0.842057488 \\ 0.442057488 \end{bmatrix}$ the same was our l2 norm