



POD,DMD, SINDY

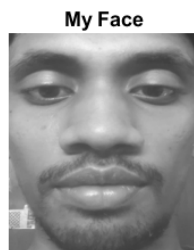
19.04.2025

B Shabarish

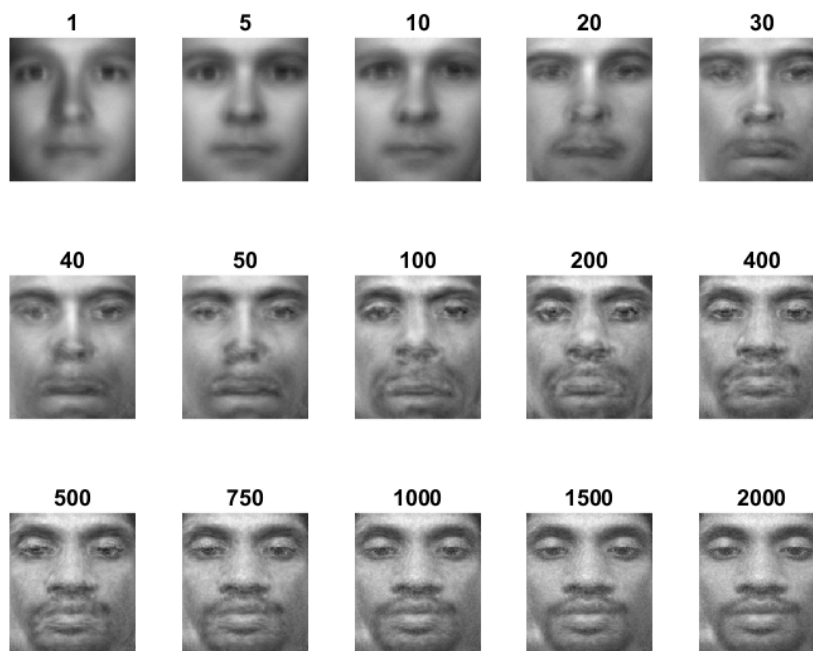
ME22B051

2. POD:

Input image:



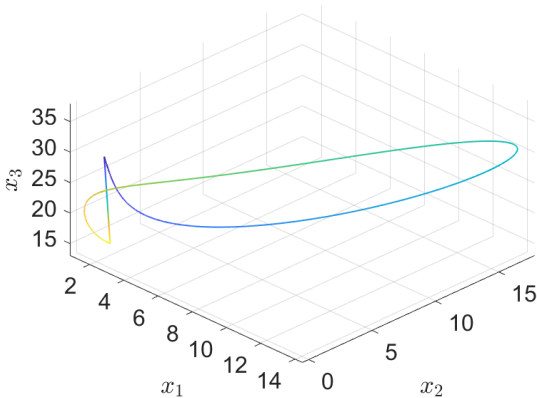
Reconstruction based on number of eigenvectors:



We can see that at around 400 basis faces, we can see the input image. On further addition of information from the other vectors we get lesser noise and a clearer output of the input image.

SINDy:

The data plotted:



When we set the sparsity parameter to zero, we get the following function approximation:

Discovered model using SINDy(sparsity set to zero):

```
dx/dt = - -1.1405e-05 - -10x + 10y
dy/dt = + 28x - -0.999976y - -0.999999xz
dz/dt = - -0.000106264 - -4.64983e-05x + 4.0588e-05y - -2.66666z + 1xy
>>
```

When we set sparsity parameter to 0.1, we get the following function:

Discovered model using SINDy:

```
dx/dt = - -10x + 10y
dy/dt = + 28x - -0.999997y - -1xz
dz/dt = - -2.66667z + 1xy
..
```



This function best approximates the given data and carries the significant terms.



DMD:

