CFD Solver for Two-Dimensional Cavity Flow Problem

This work aims to solve the Navier-Stokes (N-S) equations using Finite Difference Method (FDM) for a Two-Dimensional Cavity Fluid Problem.

The CFD Solver is written in C while the obtained velocity profiles are visualized with Python.

Mathematics

A. The Governing Equation

The equation of motion can be written as:

$$\rho \frac{D\vec{v}}{Dt} = -\nabla p - \nabla \cdot \vec{\tau} + \rho \vec{g}$$

For an incompressible fluid with constant ρ and μ_i the equation becomes:

$$\rho \frac{\partial \vec{v}}{\partial t} + \rho (\vec{v} \cdot \nabla) \vec{v} = -\nabla p - \mu \nabla^2 \vec{v} + \rho \vec{g}$$

The Navier-Stokes equations in two-dimensions are

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial y} + \nu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right)$$

B. Pressure Poisson Equation

The pressure Poisson equation can be written as:

$$\frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 p}{\partial y^2} = -\rho \left(\frac{\partial u}{\partial x} \frac{\partial u}{\partial x} + 2 \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + \frac{\partial v}{\partial y} \frac{\partial v}{\partial y} \right) + \rho \frac{\partial}{\partial t} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)$$

C. Discretization

The 2 momentum equations and a pressure equation are discretized using central difference method.

For velocity component u:

$$u_{i,j}^{n+1} = u_{i,j}^{n} - u_{i,j}^{n} \Delta t \frac{(u_{i+1,j}^{n} - u_{i-1,j}^{n})}{2\Delta x} - v_{i,j}^{n} \Delta t \frac{(u_{i,j+1}^{n} - u_{i,j-1}^{n})}{2\Delta y} - \frac{\Delta t}{\rho} \frac{(p_{i+1,j}^{n} - p_{i-1,j}^{n})}{2\Delta x} + \nu \Delta t \left(\frac{u_{i+1,j}^{n} - 2u_{i,j}^{n} + u_{i-1,j}^{n}}{\Delta x^{2}} + \frac{u_{i,j+1}^{n} - 2u_{i,j}^{n} + u_{i,j-1}^{n}}{\Delta y^{2}} \right)$$

For velocity component v:

$$v_{i,j}^{n+1} = v_{i,j}^{n} - u_{i,j}^{n} \Delta t \frac{(v_{i+1,j}^{n} - v_{i-1,j}^{n})}{2\Delta x} - v_{i,j}^{n} \Delta t \frac{(v_{i,j+1}^{n} - v_{i,j-1}^{n})}{2\Delta y} - \frac{\Delta t}{\rho} \frac{(p_{i,j+1}^{n} - p_{i,j-1}^{n})}{2\Delta y} + \nu \Delta t \left(\frac{v_{i+1,j}^{n} - 2v_{i,j}^{n} + v_{i-1,j}^{n}}{\Delta x^{2}} + \frac{v_{i,j+1}^{n} - 2v_{i,j}^{n} + v_{i,j-1}^{n}}{\Delta y^{2}} \right)$$

For pressure component pa

Let b = [R.H.S.]

$$\frac{p_{i+1,j}^n - 2p_{i,j}^n + p_{i-1,j}^n}{\Delta x^2} + \frac{p_{i,j+1}^n - 2p_{i,j}^n + p_{i,j-1}^n}{\Delta y^2} = b$$

$$p_{i,j}^{n} = \frac{\Delta y^{2}(p_{i+1,j}^{n} + p_{i-1,j}^{n}) + \Delta x^{2}(p_{i,j+1}^{n} + p_{i,j-1}^{n}) - b\Delta y^{2}\Delta x^{2}}{2(\Delta x^{2} + \Delta y^{2})}$$

D. Initial Conditions (I.C.)

At the initial, let u, v, p = 0

E. Boundary Conditions (B.C.)

Within the domain $x_i \in [0, 2]$ and $y_i \in [0, 2]$

$$u = \begin{cases} 1 \text{ for } y_i = 2\\ 0 \text{ for } x_i = 0, 2, \ y_i = 0 \end{cases}$$

```
v = 0 for x_i = 0, 2, y_i = 0, 2

p = 0 at y = 2

\frac{\partial p}{\partial x} = 0 at x = 0, 2
```

Codes

A. Process

The CFD solver (C) does the following steps:

- 1. Set up parameters (mesh, time, and fluid properties)
- 2. Initialize velocity components and pressure arrays
- 3. For each timestep: 3.1 Solve N-S and pressure equations via central difference method 3.2 Apply boundary conditions
- 4. Write output arrays of velocity components and pressure to output files

The CFD visualizer (Python) does the following steps:

- 1. Set up mesh
- 2. Initialize velocity components and pressure arrays
- 3. Fill the arrays with values from input files
- 4. Plot cavity flow

B. Directory Structure

```
vectorutils.c
vectorutils.h
finitedifference.c
finitedifference.h
fluiddynamics.c
fluiddynamics.c
main.c
Makefile
results
u.txt
v.txt
p.txt
p.txt
cavityFlow.png
plotProfiles.py
```

C. Programs

The C program consists of the following sections:

- finitedifference compute FDM approximations
- fluiddynamics solve N-S and Poisson equations
- vectorutils utilities
- main setup, solve, and write outputs

C Program, finitedifference.c

```
#include <stdio.h>
#include <stdib.h>
#include <math.h>
#include "vectorutils.h"

float** central_ddx(float** f, float dx, int m, int n){
   float** diff = init_zero_vector(m,n);

for (int i=1; i<m-1; ++i){
   for (int j=1; j<n-1; ++j){
      diff[i][j] = (f[i][j+1] - f[i][j-1])/(2.0*dx);
   }
}</pre>
```

```
}
 return diff;
}
float** central_ddy(float** f, float dy, int m, int n){
 float** diff = init_zero_vector(m,n);
 for (int i=1; i < m-1; ++i){
   for (int j=1; j< n-1; ++j){
     diff[i][j] = (f[i+1][j] - f[i-1][j])/(2.0*dy);
 }
 return diff;
float** laplace(float** f, float dx, float dy, int m, int n){
 float** diff = init_zero_vector(m,n);
 for (int i=1; i < m-1; ++i){
   for (int j=1; j< n-1; ++j){
     [j])/pow(dy, 2);
 }
 return diff;
}
```

C Program, fluiddynamics.c

```
#include <stdio.h>
#include <stdlib.h>
#include <math.h>
#include "vectorutils.h"
#include "finitedifference.h"
float** compute_b(float dx,float dy,float rho,float dt, float** u, float** v, int m, int n){
 float** b = init zero vector(m,n);
  float** dudx = central_ddx(u, dx, m, n);
  float** dvdy = central_ddy(v, dy, m, n);
  float** dudy = central_ddy(u, dy, m, n);
  float** dvdx = central_ddx(v, dx, m, n);
  for (int i=1; i < m-1; ++i){
      for (int j=1; j< n-1; ++j){
       b[i][j] = -rho*(pow(dudx[i][j],2) + 2*dudy[i][j]*dvdx[i][j] + pow(dvdy[i][j],2)) + rho/dt*
(dudx[i][j] + dvdy[i][j]);
    }
    }
  free(dudx);
  free(dvdy);
  free(dudy);
  free(dvdx);
 return b;
}
float** pressure_poisson(float** p, float dx, float dy, float rho, float dt, float** u, float** v, int
m, int n){
  float** pn = init_zero_vector(m,n);
 int maxIteration = 50;
  float** b = compute_b(dx,dy,rho,dt,u,v,m,n);
  for (int it=0; it<maxIteration; ++it){</pre>
```

```
copy_vector(pn, p, m, n);
    for (int i=1; i < m-1; ++i){
     for (int j=1; j< n-1; ++j){
        p[i][j] = (pow(dy,2)*(pn[i][j+1] + pn[i][j-1]) + pow(dx,2)*(pn[i+1][j] + pn[i-1][j]) - b[i]
[j]*pow(dy,2)*pow(dx,2))/(2*pow(dx,2) + 2*pow(dy,2));
    }
    // B.C.
    for (int i=0; i < m; ++i){
     p[i][n-1] = p[i][n-2]; // dp/dx = 0 at x = 2 (right)
     p[i][0] = p[i][1]; // dp/dx = 0 at x = 0
    for (int j=0; j<n; ++j){
      p[0][j] = p[1][j]; // dp/dy = 0 at y = 0
      p[m-1][j] = 0.0; // p = 0 at y = 2 (top)
  free(pn);
 return p;
}
int cavity_flow(int nt, float** u, float** v, float dt, float dx, float dy, float** p, float rho,
float nu, float ut, int m, int n){
  float** un = init_zero_vector(m,n);
  float** vn = init_zero_vector(m,n);
  for (int it=0; it<nt; ++it){</pre>
    copy_vector(un, u, m, n);
    copy_vector(vn, v, m, n);
    p = pressure_poisson(p, dx, dy, rho, dt, un, vn, m, n);
    float** dudx = central_ddx(un, dx, m, n);
    float** dudy = central_ddy(un, dy, m, n);
    float** dpdx = central_ddx(p, dx, m, n);
    float** laplaceU = laplace(un, dx, dy, m, n);
    float** dvdx = central_ddx(vn, dx, m, n);
    float** dvdy = central_ddy(vn, dy, m, n);
    float** dpdy = central_ddy(p, dy, m, n);
    float** laplaceV = laplace(vn, dx, dy, m, n);
    for (int i=1; i < m-1; ++i){
        for (int j=1; j< n-1; ++j){
           u[i][j] = un[i][j] + dt*(-un[i][j]*dudx[i][j]-vn[i][j]*dudy[i][j]-\frac{1}{r}ho*dpdx[i] 
[j]+nu*laplaceU[i][j]);
         v[i][j] = vn[i][j] + dt*(-un[i][j]*dvdx[i][j]-vn[i][j]*dvdy[i][j]-1/rho*dpdy[i]
[j]+nu*laplaceV[i][j]);
        }
    }
    free(dudx);
    free(dudy);
    free(dpdx);
    free(laplaceU);
    free(dvdx);
    free(dvdy);
    free(dpdy);
    free(laplaceV);
    // B.C.
     for (int j=0; j<n; ++j){
      u[0][j] = 0.0; // bottom
      v[0][j] = 0.0;
      u[m-1][j] = ut; // top
      v[m-1][j] = 0.0;
```

C Program, vectorutils.c

```
#include <stdio.h>
#include <stdlib.h>
float** init_zero_vector(int m, int n){
  float* values = calloc(m*n, sizeof(float));
  float** vec = malloc(m*sizeof(float*));
 for (int i=0; i<m; ++i){
   vec[i] = values + i*n;
 return vec;
}
void copy_vector(float** newV, float** previousV, int m, int n){
 size_t size = sizeof(float)*n;
  for (int i=0; i < m; ++i){
   for (int j=0; j<n; ++j){
     newV[i][j] = previousV[i][j];
 }
}
void print_vector(float** vec, int m, int n){
  for (int i = 0; i < m; i++) {
        for (int j = 0; j < n; j++)
            printf("%f,", vec[i][j]);
       printf("\n");
   }
}
int write_result(char* fileName, float** vec, int m, int n){
  FILE *outFile;
  outFile=fopen(fileName,"w+");
  if (outFile==NULL){
       printf("[Error] Failed to open output file %s", fileName);
        return -1;
   }
  for (int i = 0; i < m; i++) {
        for (int j = 0; j < n; j++)
            fprintf(outFile, "%f,", vec[i][j]);
        fprintf(outFile, "\n");
   }
  fclose(outFile);
  return 0;
}
```

```
#include <stdio.h>
#include <stdlib.h>
#include "vectorutils.h"
#include "fluiddynamics.h"
int main(void) {
    printf("Solving Cavity Fluid Flow using Finite-Difference Approach\n");
    // Mesh and parameter set-up
    const int N_{GRID_X} = 41;
    const int N_{GRID_Y} = 41;
    const float LENGTH_X = 2.0;
    const float LENGTH_Y = 2.0;
    const float dx = LENGTH_X / (N_GRID_X - 1);
    const float dy = LENGTH_Y / (N_GRID_Y - 1);
    const int N_TIMESTEP = 100;
    const float dt = 0.001;
    const float DENSITY = 1.0;
    const float KINEMATIC_VISCOSITY = 0.1;
    const float U_TOP = 1.0;
    // I.C.
    float** u = init_zero_vector(N_GRID_X, N_GRID_Y);
    float** v = init_zero_vector(N_GRID_X, N_GRID_Y);
    float** p = init_zero_vector(N_GRID_X, N_GRID_Y);
    // Loop through timesteps
    cavity_flow(
        N_TIMESTEP, u, v, dt, dx, dy, p, DENSITY,
        KINEMATIC_VISCOSITY, U_TOP, N_GRID_X, N_GRID_Y);
    int u_txt = write_result("./results/u.txt", u, N_GRID_X, N_GRID_Y);
    int v_txt = write_result("./results/v.txt", v, N_GRID_X, N_GRID_Y);
    int p_txt = write_result("./results/p.txt", p, N_GRID_X, N_GRID_Y);
    if (u_txt!=0 || u_txt!=0 || u_txt!=0) {
        printf("[ERROR] Failed to write output files\n");
    } else {
        printf("[SUCCESS] Wrote output files\n");
        return 0;
    }
}
```

The Python program consists of the following section:

• plotProfiles - plot velocity profiles

Python Program, plotProfiles.py

```
import numpy as np
import matplotlib.pyplot as plt

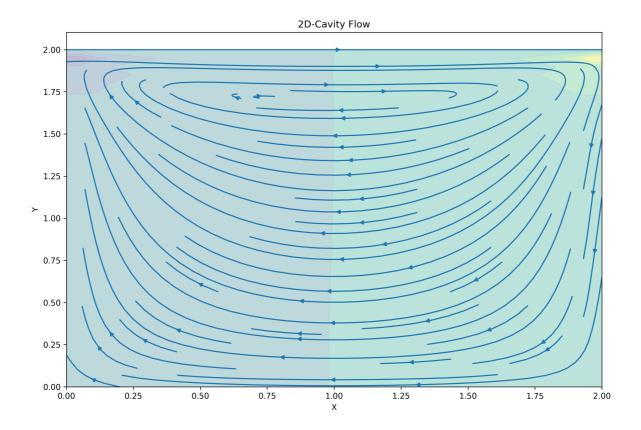
def fill_profile(filename, vec):
    with open(filename) as f:
        for i, line in enumerate(f):
            data = line.split(",")[:-1]
            for j, value in enumerate(data):
                vec[i][j] = float(value)

def plot_flow(lx,ly,nx,ny,u,v,p):
    x = np.linspace(0, lx, nx)
    y = np.linspace(0, ly, ny)
```

```
X, Y = np.meshgrid(x, y)
    fig = plt.figure(figsize=(12,8), dpi=100)
    plt.contourf(X, Y, p, alpha=0.3)
    plt.streamplot(X, Y, u, v)
    plt.xlabel('X')
    plt.ylabel('Y')
    plt.title('2D-Cavity Flow')
    return fig
def main():
    N_{GRID_X} = 41
    N_{GRID_Y} = 41
    LENGTH_X = 2.0
    LENGTH_Y = 2.0
    u = np.zeros((N_GRID_X, N_GRID_Y))
    v = np.zeros((N_GRID_X, N_GRID_Y))
    p = np.zeros((N_GRID_X, N_GRID_Y))
    fill_profile("./results/u.txt", u)
    fill_profile("./results/v.txt", v)
    fill_profile("./results/p.txt", p)
    cavity_flow_plot = plot_flow(
        lx=LENGTH_X,
        ly=LENGTH_Y,
        nx=N_GRID_X,
        ny=N_GRID_Y,
        u=u,
        v=v,
        p=p)
    cavity_flow_plot.savefig("./results/cavityFlow.png", dpi=300)
main()
```

D. Output

After compile and execute the C program to obtain velocities and pressure profiles, run the python program to obtain the cavity flow plot as shown:



Appendix

Additional Code Sections of CFD Solver

C header files and Makefile

C Program, finitedifference.h

```
float** central_ddx(float** f, float dx, int m, int n);
float** central_ddy(float** f, float dy, int m, int n);
float** laplace(float** f, float dx, float dy, int m, int n);
```

C Program, fluiddynamics.h

```
float** compute_b(float dx,float dy,float rho,float dt, float** u, float** v, int m, int n);
float** pressure_poisson(float** p, float dx, float dy, float rho, float dt, float** u, float** v, int
m, int n);
int cavity_flow(int nt, float** u, float** v, float dt, float dx, float dy, float** p, float rho,
float nu, float ut, int m, int n);
```

C Program, vectorutils.h

```
float** init_zero_vector(int m, int n);
void copy_vector(float** newV, float** previousV, int m, int n);
void print_vector(float** vec, int m, int n);
int write_result(char* fileName, float** vec, int m, int n);
```

C Program, Makefile

```
all: vectorutils.o finitedifference.o fluiddynamics.o main.o
    $(CC) vectorutils.o finitedifference.o fluiddynamics.o main.o -o cavityflow

vectorutils.o: vectorutils.c
    $(CC) -c vectorutils.c -o vectorutils.o

finitedifference.o: finitedifference.c
    $(CC) -c finitedifference.c -o finitedifference.o

fluiddynamics.o: fluiddynamics.c
    $(CC) -c fluiddynamics.c -o fluiddynamics.o

main.o: main.c
    $(CC) -c main.c -o main.o

clean:
    rm *.o cavityflow
```