

# A Semi-incremental Scheme for Fatigue Damage Computations

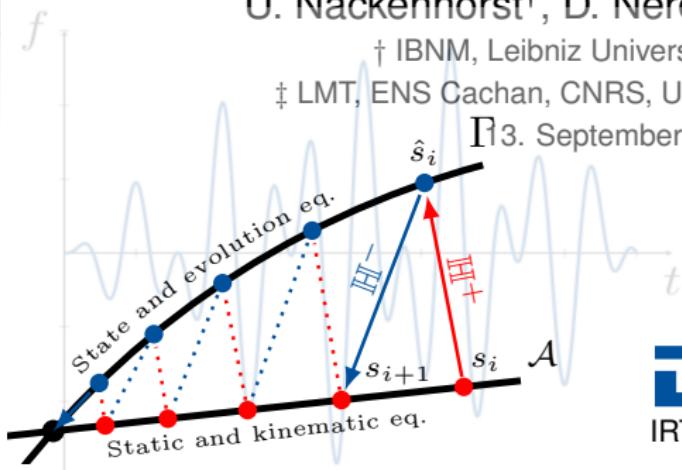
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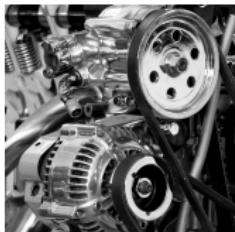


**DFG**  
IRTG-1627

Deutsche  
Forschungsgemeinschaft

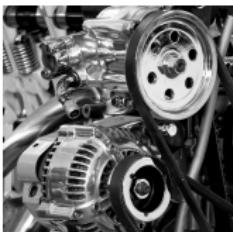
# Fatigue damage

## ■ Fluctuating loads



# Fatigue damage

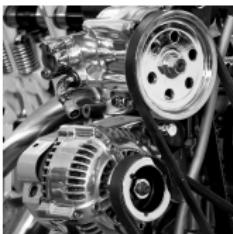
- Fluctuating loads



- Material degradation  
lower load carrying capacity
- Large number of load cycles  
thousands or millions
- Continuum damage model  
 $\dot{D} = dD/dt$
- Computational expense  
memory and time

# Fatigue damage

- Fluctuating loads



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## Model order reduction (MOR) techniques

# Proper Generalised Decomposition

- Low-rank approximation

$$\boldsymbol{u}(\boldsymbol{x}, t) = \sum_{j=1}^N \boldsymbol{v}_j(\boldsymbol{x}) \circ \boldsymbol{\lambda}_j(t)$$

- Enrichment to  $(\mu)$  previously generated modes

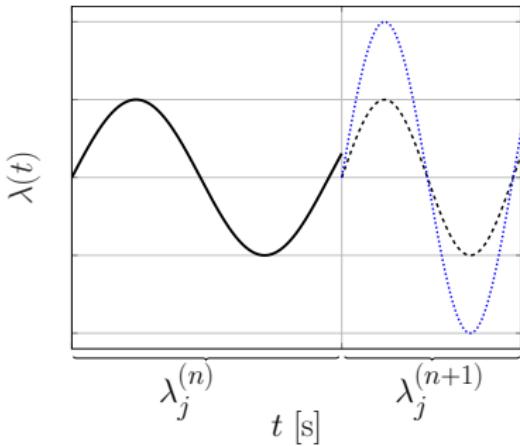
$$\Delta \boldsymbol{u}_{i+1}(\boldsymbol{x}, t) = \boldsymbol{v}_{\mu+1}(\boldsymbol{x}) \circ \boldsymbol{\lambda}_{\mu+1}(t)$$

- POD-like update of  $(\mu)$  previously generated modes

$$\Delta \boldsymbol{u}_{i+1}(\boldsymbol{x}, t) = \sum_{j=1}^{\mu} \underbrace{\boldsymbol{v}_j(\boldsymbol{x})}_{\text{known}} \circ \Delta \boldsymbol{\lambda}_j(t)$$

# Semi-incremental extension

- The temporal domain is divided into cycles
- Cycles are simulated consecutively

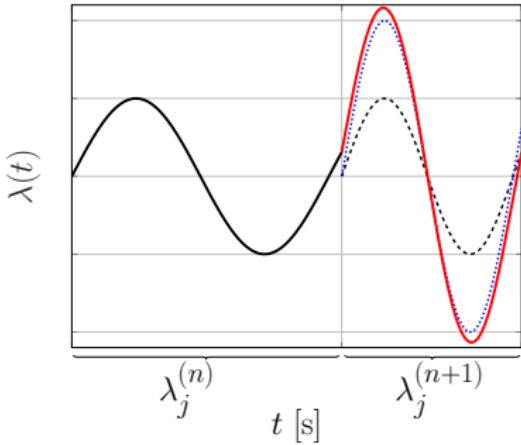


- Already generated  $\{\lambda_j(t)\}_{j=1}^{\mu}$  are scaled to  $\tilde{t} \in [0, 1]$
- Scaled back to the temporal coordinate of the current cycle

# Semi-incremental extension

- Continuity of the temporal modes is an issue
- Temporal modes are vertically scaled and shifted via

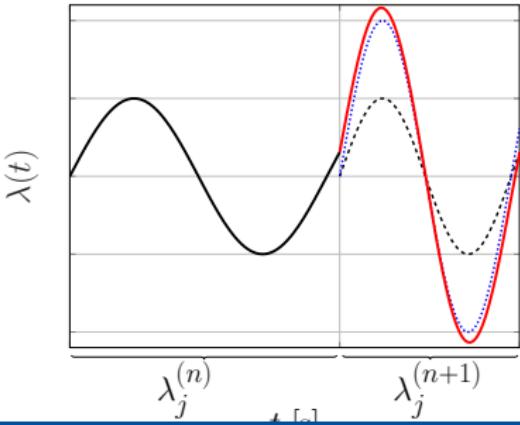
$$\tilde{\lambda}_j^{(n+1)}(\tilde{t}) = m \tilde{\lambda}_j^{(n)}(\tilde{t}) + g \tilde{t} + h \quad \text{with I.C. and B.C.}$$



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Variable loading / integration over confined domains 😊

# SVD Compression of PGD

- Large number of modes
- Slow temporal update step

$$\underline{\tilde{A}} \underline{\tilde{\Lambda}}^T = \underline{\tilde{B}}$$
$$\underline{\tilde{A}} \in \mathbb{R}^{\mu \times \mu} \quad \underline{\tilde{B}} \in \mathbb{R}^{\mu \times n_t} \quad \underline{\tilde{\Lambda}} = [\Delta \lambda_1, \dots, \Delta \lambda_\mu]$$

- Enrichment with a Gram-Schmidt scheme is not optimal
- SVD is optimal but expensive to compute

# SVD Compression of PGD

- Given a solution  $\underline{\underline{U}} = \underline{\underline{V}} \underline{\underline{\Lambda}}^T \in \mathbb{R}^{n \times n_t}$  with

$$\underline{\underline{V}} = [\underline{v}_1, \dots, \underline{v}_\mu] \in \mathbb{R}^{n \times \mu} \quad \underline{\underline{\Lambda}} = [\underline{\lambda}_1, \dots, \underline{\lambda}_\mu] \in \mathbb{R}^{n_t \times \mu}$$

- Exploit the outer product format of PGD

$$\underline{\underline{V}} = \underline{\underline{Q}}_v \underline{\underline{R}}_v \quad \underline{\underline{\Lambda}} = \underline{\underline{Q}}_\lambda \underline{\underline{R}}_\lambda$$

- Compute SVD of a small matrix

$$\underline{\underline{T}} = \underline{\underline{R}}_v \underline{\underline{R}}_\lambda^T \in \mathbb{R}^{\mu \times \mu} \quad \underline{\underline{T}} \approx \hat{\underline{\underline{V}}} \hat{\underline{\underline{S}}} \hat{\underline{\underline{\Lambda}}}^T$$

- Solution with a compressed basis

$$\underline{\underline{U}} \approx \underline{\underline{Q}}_v \hat{\underline{\underline{V}}} \quad \hat{\underline{\underline{S}}} \quad \hat{\underline{\underline{\Lambda}}}^T \underline{\underline{Q}}_\lambda^T$$

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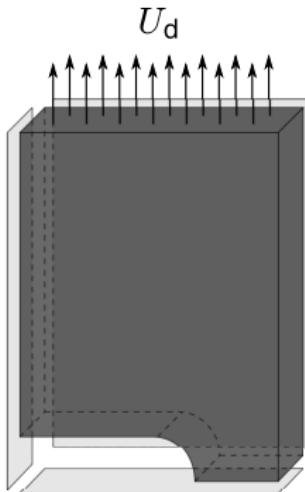
$$U \approx \underline{\underline{Q}} \hat{\underline{\underline{V}}} \hat{\underline{\underline{S}}} \hat{\underline{\underline{\Lambda}}}^T \underline{\underline{Q}}^T$$

Non-demanding optimal decomposition 😊

# Numerical results

## Viscoplastic viscodamage material

- A plate subjected to cyclic loading (Cr-Mo steel at 580°C)

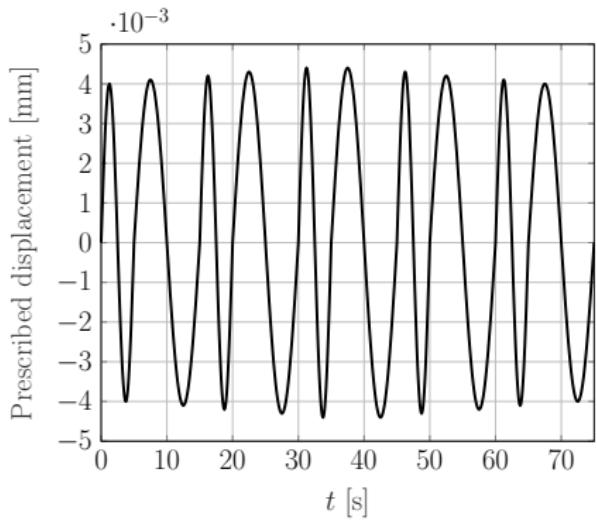


- Plasticity, kinematic and isotropic hardening, damage

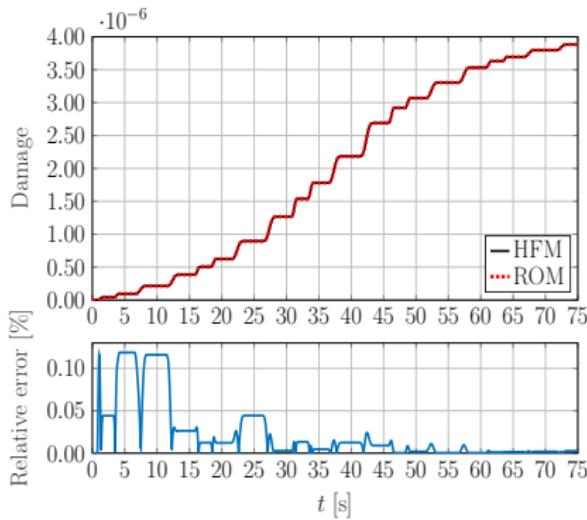
# Model verification

$1884 \cdot 41 \cdot 10$  DOF

With respect to a modified Newton-Raphson scheme



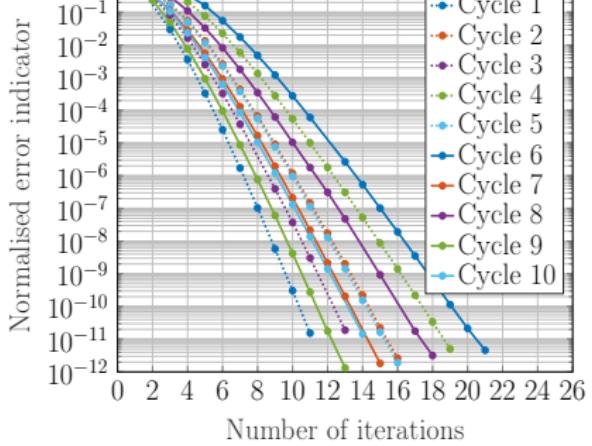
Prescribed displacement



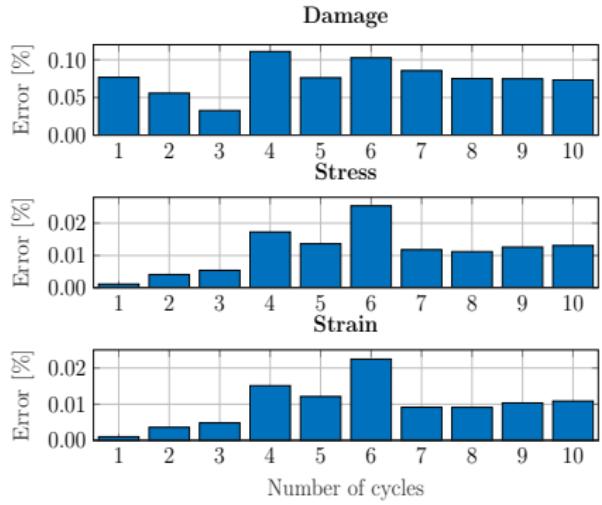
Damage evolution

# Model verification

$$\|e\|_{\Omega \times \mathcal{I}}^2 = \frac{1}{T |\Omega|} \int_{\mathcal{I}} \int_{\Omega} e : e \, d\Omega \, dt$$



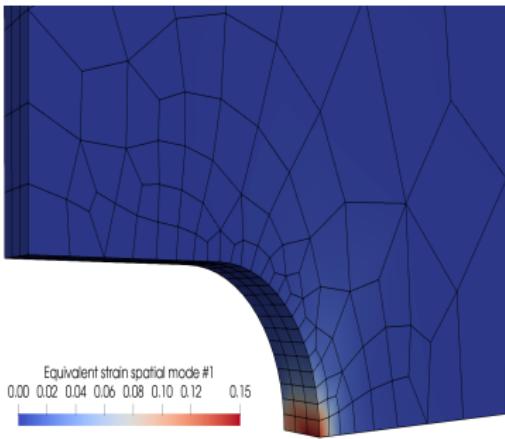
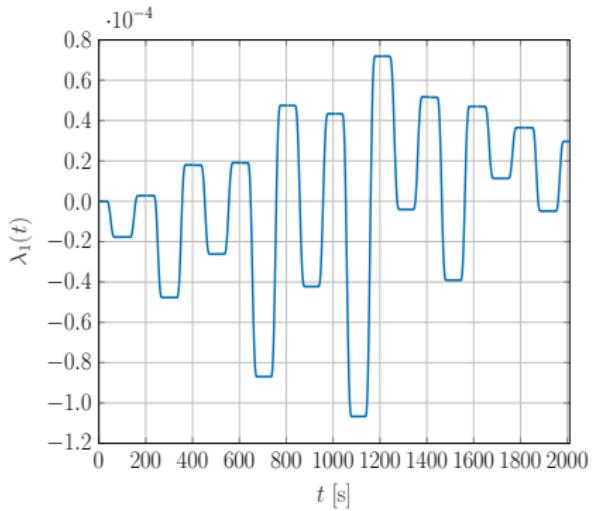
Error indicator



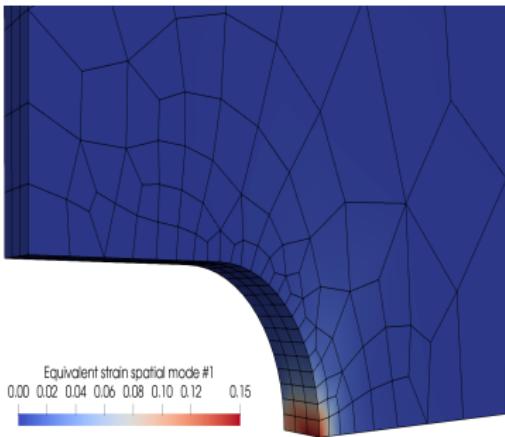
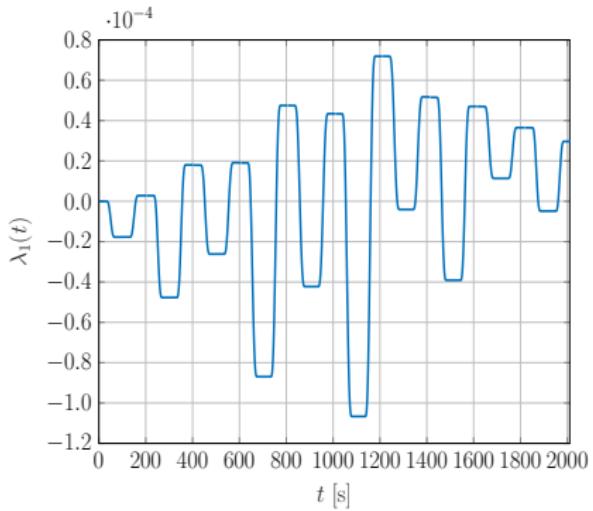
Space-time average relative error

# Model verification

## The first temporal and spatial modes



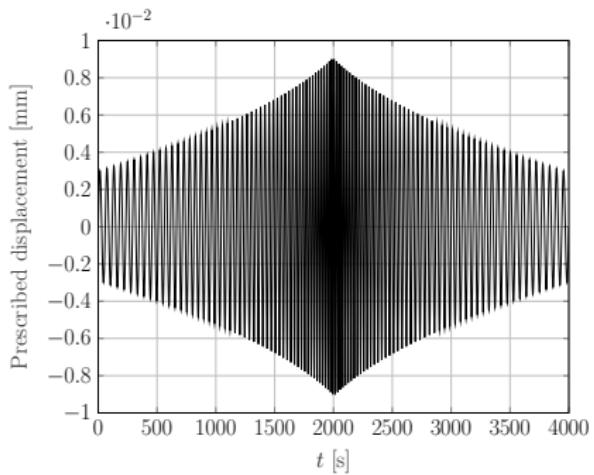
## The first temporal and spatial modes



12 modes / Speedup factor  $\sim 25$

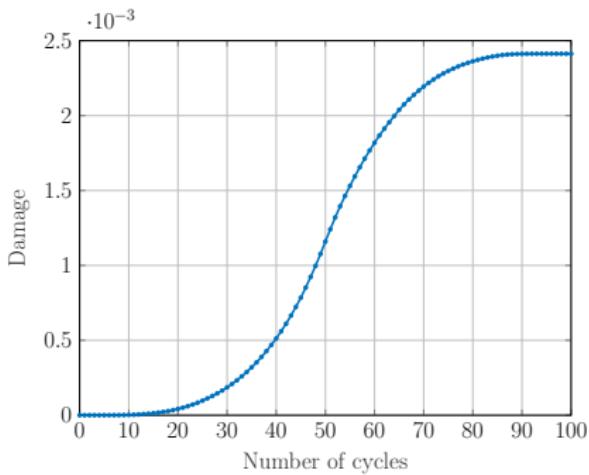
# Variable amplitudes & frequencies

Amplitudes:  $[30, 90] \cdot 10^{-4}$  mm



Prescribed displacement

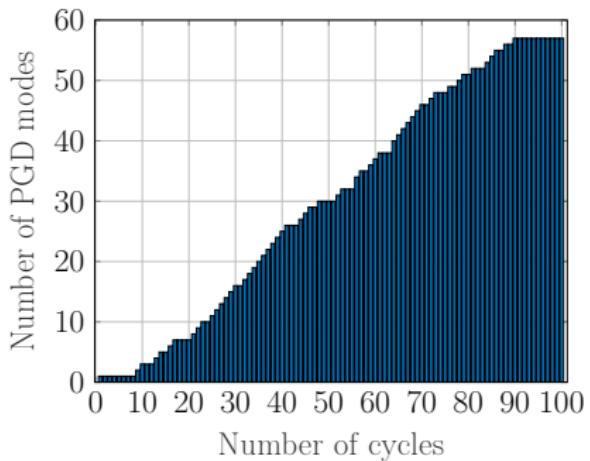
Time periods: [20, 60] sec



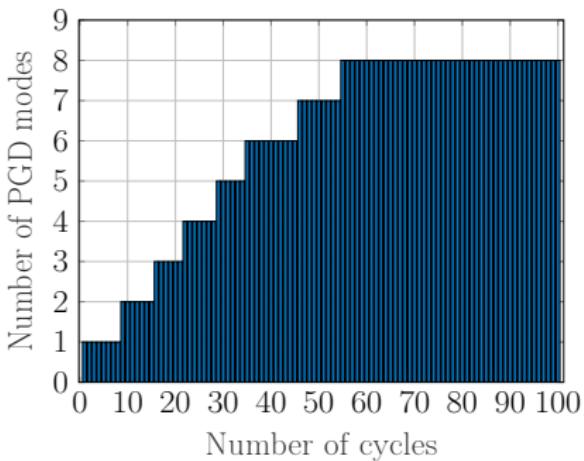
Damage evolution

# Variable amplitudes & frequencies

The growth of the ROB using an SVD scheme



Gram-Schmidt

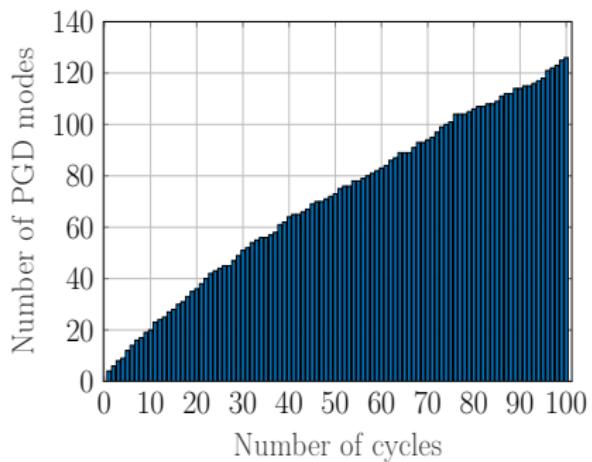


SVD scheme

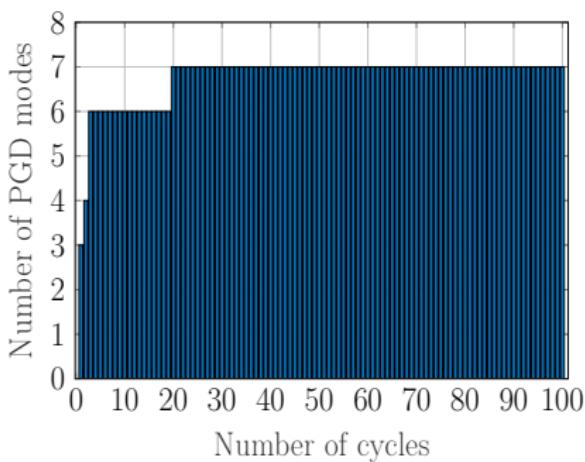
# Different ortho. schemes

$50,547 \cdot 33 \cdot 100$  DOF

In case of random loading and fine discretisation



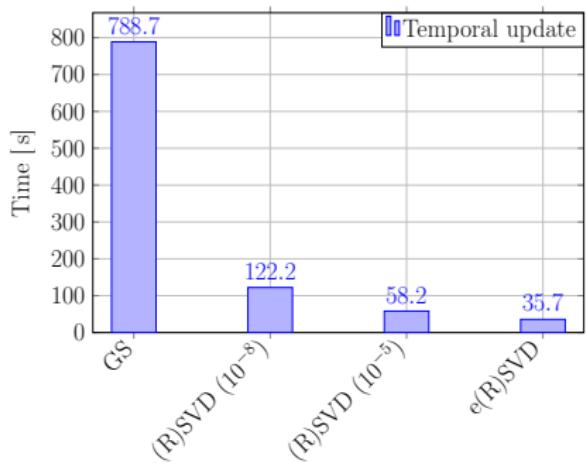
Gram-Schmidt



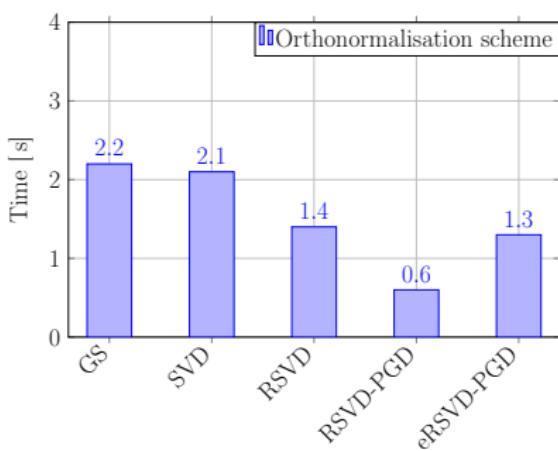
SVD scheme

# Different ortho. schemes

The required time to update and orthonormalise the modes



Temporal update

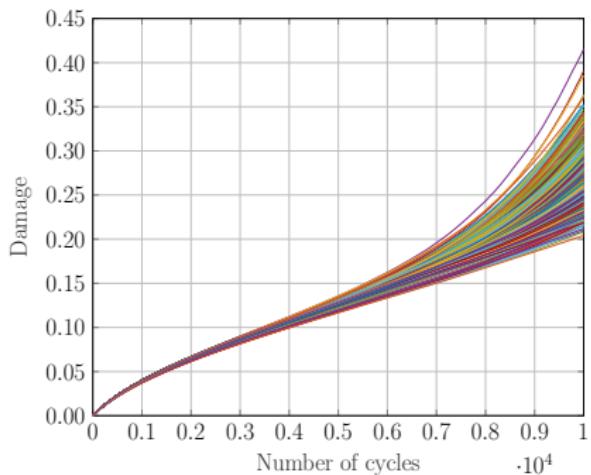


Orthonormalisation step

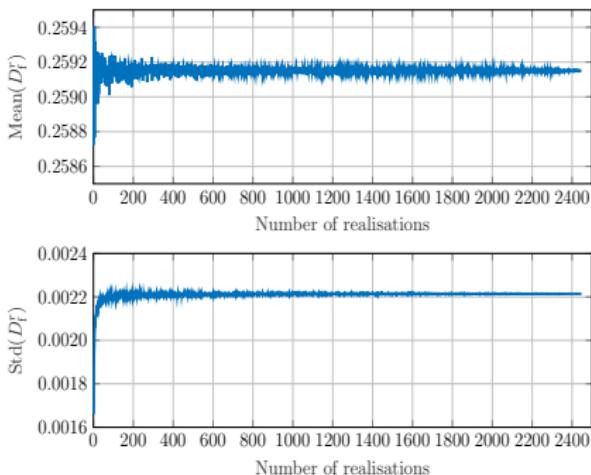
# Random amplitude loading

$1884 \cdot 41 \cdot 10^4$  DOF

■  $10^4$  cycles, uniform distribution in  $[53, 56] \cdot 10^{-2}$  mm



Different damage realisations

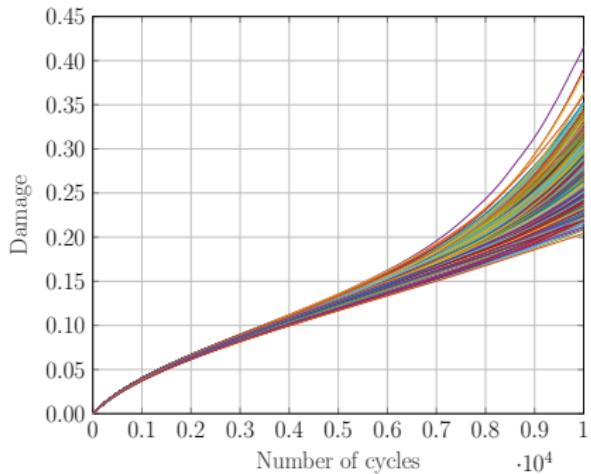


The mean and STD of  $D_f$

# Random amplitude loading

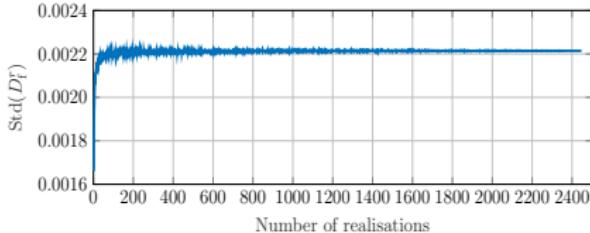
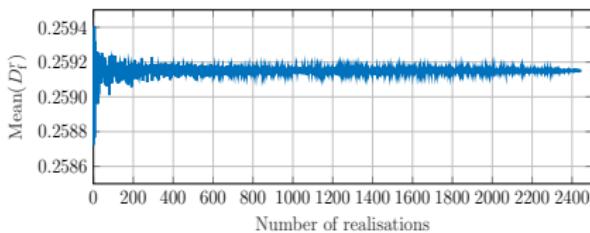
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Critical damage value  $D_c = 0.3$

Probability of failure  $P_f = 5.4\%$



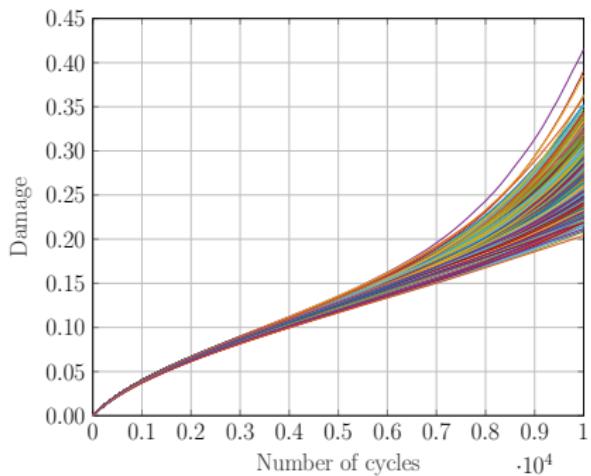
Requirements:

[15 – 35] min and [1 – 1.5] GB

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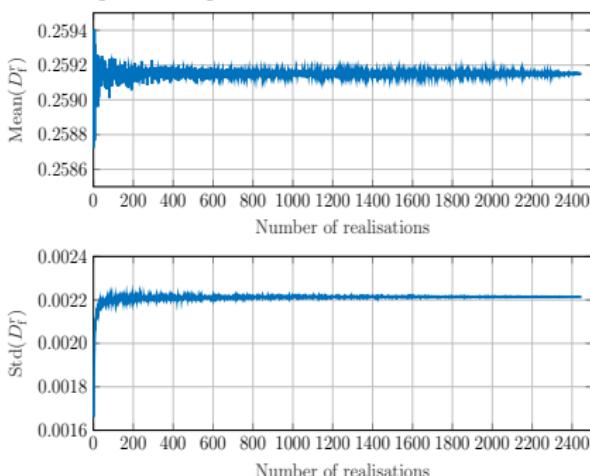
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Approx. 10 modes / Time-saving factors  $50 \sim 100$

# Conclusions

- Efficient semi-incremental scheme for damage problems
- Can handle variable amplitude and frequency loadings
- Provides a minimal expansion of PGD
- Most operations are done over decomposed QoI
- Open-source code: [gitlab.com/shadialameddin/romfem](https://gitlab.com/shadialameddin/romfem)

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Thank you for your attention