Lab 1. PyTorch and ANNs

This lab is a warm up to get you used to the PyTorch programming environment used in the course, and also to help you review and renew your knowledge of Python and relevant Python libraries. The lab must be done individually. Please recall that the University of Toronto plagarism rules apply.

By the end of this lab, you should be able to:

- 1. Be able to perform basic PyTorch tensor operations.
- 2. Be able to load data into PyTorch
- 3. Be able to configure an Artificial Neural Network (ANN) using PyTorch
- 4. Be able to train ANNs using PyTorch
- 5. Be able to evaluate different ANN configuations

You will need to use numpy and PyTorch documentations for this assignment:

- https://docs.scipy.org/doc/numpy/reference/
- https://pytorch.org/docs/stable/torch.html

You can also reference Python API documentations freely.

What to submit

Submit a PDF file containing all your code, outputs, and write-up from parts 1-5. You can produce a PDF of your Google Colab file by going to File -> Print and then save as PDF. The Colab instructions has more information.

Do not submit any other files produced by your code.

Include a link to your colab file in your submission.

Please use Google Colab to complete this assignment. If you want to use Jupyter Notebook, please complete the assignment and upload your Jupyter Notebook file to Google Colab for submission.

Adjust the scaling to ensure that the text is not cutoff at the margins.

Colab Link

Submit make sure to include a link to your colab file here

Colab Link:

▼ Part 1. Python Basics [3 pt]

The purpose of this section is to get you used to the basics of Python, including working with functions, numbers, lists, and strings.

Note that we will be checking your code for clarity and efficiency.

If you have trouble with this part of the assignment, please review http://cs231n.github.io/python-numpy-tutorial/

▼ Part (a) -- 1pt

Write a function <code>sum_of_cubes</code> that computes the sum of cubes up to <code>n</code>. If the input to <code>sum_of_cubes</code> invalid (e.g. negative or non-integer <code>n</code>), the function should print out "Invalid input" and return <code>-1</code>.

```
def sum of cubes(n):
    """Return the sum (1^3 + 2^3 + 3^3 + ... + n^3)
    Precondition: n > 0, type(n) == int
    >>> sum_of_cubes(3)
    >>> sum_of_cubes(1)
    1
    # Check if n is negative or n isn't an integer
    if n < 0 or type(n) is not int:
      # Print invalid input and output -1
      print("Invalid input")
      return -1
    # Initialize sum variable
    sum = 0
    # Iterate through all values of n
    while n:
      # Find n^3 and add it to the sum
      sum += n ** 3
      # Decrease n by 1 each time
      n -= 1
    print(sum)
    return sum
```

▼ Part (b) -- 1pt

Write a function word_lengths that takes a sentence (string), computes the length of each word in that sentence, and returns the length of each word in a list. You can assume that words are always separated by a space character " ".

Hint: recall the str.split function in Python. If you arenot sure how this function works, try typing help(str.split) into a Python shell, or check out

https://docs.python.org/3.6/library/stdtypes.html#str.split

```
help(str.split)
     Help on method descriptor:
     split(self, /, sep=None, maxsplit=-1)
         Return a list of the words in the string, using sep as the delimiter string.
         sep
           The delimiter according which to split the string.
           None (the default value) means split according to any whitespace,
           and discard empty strings from the result.
         maxsplit
           Maximum number of splits to do.
           -1 (the default value) means no limit.
def word lengths(sentence):
    """Return a list containing the length of each word in
   sentence.
   >>> word lengths("welcome to APS360!")
    [7, 2, 7]
   >>> word_lengths("machine learning is so cool")
    [7, 8, 2, 2, 4]
   # Initialize a list that will store the lengths of the words
   lengths = []
   # Split the sentence
    sentence = sentence.split()
   # Go through the split sentence
   for x in sentence:
      # Add the length of each word to the list
      lengths.append(len(x))
   return lengths
```

▼ Part (c) -- 1pt

Write a function all_same_length that takes a sentence (string), and checks whether every word in the string is the same length. You should call the function word_lengths in the body of this new function.

```
def all_same_length(sentence):
    """Return True if every word in sentence has the same
    length, and False otherwise.
    >>> all same length("all same length")
    False
    >>> word lengths("hello world")
    True
    .....
    # Call the word_lengths function
    lengths = word lengths(sentence)
    # Go through the lengths list
    for x in lengths:
      # Check if the current length is loop is not equal to the first length
      if x != lengths[0]:
        # Return false in this case because they aren't equal
        return False
    # Return true if it successfully finishes the loop
    return True
```

→ Part 2. NumPy Exercises [5 pt]

In this part of the assignment, you'll be manipulating arrays usign NumPy. Normally, we use the shorter name np to represent the package numpy.

```
import numpy as np
```

▼ Part (a) -- 1pt

The below variables matrix and vector are numpy arrays. Explain what you think <NumpyArray>.size and <NumpyArray>.shape represent.

```
matrix.size
# <NumpyArray>.size represents the multiplication of the number of columns by the number of r
# it can also be interpreted as the total number of entries in the numpy array

12

matrix.shape
# <NumpyArray>.shape represents the dimensions in the array (num of rows, num of columns)

(3, 4)

vector.size
# <NumpyArray>.size represents the multiplication of the number of columns by the number of r
# it can also be interpreted as the total number of entries in the numpy array

4

vector.shape
# <NumpyArray>.shape represents the dimensions in the array (num of rows, num of columns)

(4,)
```

▼ Part (b) -- 1pt

Perform matrix multiplication output = matrix x vector by using for loops to iterate through the columns and rows. Do not use any builtin NumPy functions. Cast your output into a NumPy array, if it isn't one already.

Hint: be mindful of the dimension of output

```
utput = None

# Initialize output as a list to store the result
output = []

# Use nested for loop to get values in matrix
for x in range(matrix.shape[0]):
    sum = 0
    for y in range(matrix.shape[1]):
        # Perform dot product
        sum += matrix[x, y] * vector[y]
    output.append(sum)

# Cast output to a numpy array
output = np.array(output)
output
    array([ 4.,  8., -3.])
```

▼ Part (c) -- 1pt

Perform matrix multiplication output2 = matrix x vector by using the function numpy.dot.

We will never actually write code as in part(c), not only because <code>numpy.dot</code> is more concise and easier to read/write, but also performance-wise <code>numpy.dot</code> is much faster (it is written in C and highly optimized). In general, we will avoid for loops in our code.

```
output2 = None

# Use np.dot
output2 = np.dot(matrix, vector)
output2

array([ 4., 8., -3.])
```

▼ Part (d) -- 1pt

As a way to test for consistency, show that the two outputs match.

▼ Part (e) -- 1pt

Show that using np.dot is faster than using your code from part (c).

You may find the below code snippit helpful:

```
# ---- Time for np.dot implementation ----
import time

# record the time before running code
start_time = time.time()

output2 = np.dot(matrix, vector)

# record the time after the code is run
```

```
end time = time.time()
# compute the difference
time npdot = end time - start time
time_npdot
     8.749961853027344e-05
# ---- Time for manual implementation -----
import time
# record the time before running code
start time = time.time()
# Initialize output as a list to store the result
output = []
# Use nested for loop to get values in matrix
for x in range(matrix.shape[0]):
 sum = 0
 for y in range(matrix.shape[1]):
   # Perform dot product
   sum += matrix[x, y] * vector[y]
 output.append(sum)
# Cast output to a numpy array
output = np.array(output)
# record the time after the code is run
end_time = time.time()
# compute the difference
time_manual = end_time - start_time
time_manual
     0.0002567768096923828
# ---- Comparison ----
difference = time_npdot - time_manual
print(difference)
# As we see, since the difference is negative, that means that time_manual > time_npdot
# which proves that numpy.dot() is faster
     -0.00016927719116210938
```

→ Part 3. Images [6 pt]

A picture or image can be represented as a NumPy array of "pixels", with dimensions $H \times W \times C$, where H is the height of the image, W is the width of the image, and C is the number of colour

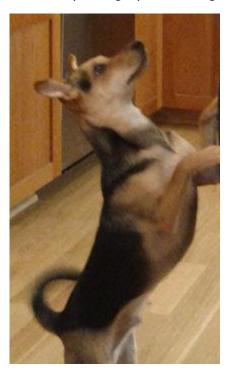
channels. Typically we will use an image with channels that give the Red, Green, and Blue "level" of each pixel, which is referred to with the short form RGB.

You will write Python code to load an image, and perform several array manipulations to the image and visualize their effects.

import matplotlib.pyplot as plt

▼ Part (a) -- 1 pt

This is a photograph of a dog whose name is Mochi.



Load the image from its url (https://drive.google.com/uc?
export=view&id=1oaLVR2hr1_qzpKQ47i9rVUlklwbDcews) into the variable img using the plt.imread function.

Hint: You can enter the URL directly into the plt.imread function as a Python string.

```
[0.37254903, 0.22352941, 0.17254902, 1.
 [0.30980393, 0.20392157, 0.16078432, 1.
                                                  ]],
[[0.5411765 , 0.32156864, 0.09019608, 1.
                                                  ],
 [0.5647059 , 0.34509805 , 0.11372549 , 1.
                                                  ],
 [0.59607846, 0.3764706, 0.14509805, 1.
 [0.4117647 , 0.22352941, 0.16862746, 1.
                                                  ],
 [0.3882353 , 0.23921569 , 0.19607843 , 1.
                                                  1,
 [0.31764707, 0.21176471, 0.1764706, 1.
                                                  11,
[[0.6156863 , 0.3764706 , 0.15294118, 1.
                                                  1,
 [0.61960787, 0.38431373, 0.14901961, 1.
 [0.61960787, 0.38431373, 0.14117648, 1.
                                                  1,
 [0.4117647 , 0.22352941, 0.1764706 , 1.
                                                  ],
 [0.39607844, 0.24705882, 0.21176471, 1.
                                                  1,
 [0.32156864, 0.21568628, 0.1882353 , 1.
                                                  ]],
. . . ,
[[0.70980394, 0.5764706 , 0.3882353 , 1.
 [0.7058824 , 0.57254905, 0.38431373, 1.
 [0.69803923, 0.5686275 , 0.36862746, 1.
 [0.7411765 , 0.64705884 , 0.4745098 , 1.
 [0.74509805, 0.64705884, 0.4862745, 1.
                                                  1,
 [0.77254903, 0.6745098 , 0.5137255 , 1.
                                                  11,
[[0.72156864, 0.5882353 , 0.4
                                                  ],
 [0.7176471 , 0.58431375 , 0.39607844 , 1.
 [0.7176471 , 0.58431375 , 0.39607844 , 1.
 [0.7411765 , 0.6392157 , 0.4392157 , 1.
                                                  ],
 [0.75686276, 0.654902 , 0.4627451 , 1.
                                                  1,
 [0.7764706 , 0.6745098 , 0.48235294, 1.
                                                  ]],
[[0.7137255 , 0.5803922 , 0.39215687, 1.
                                                  1,
 [0.7137255 , 0.5803922 , 0.39215687, 1.
 [0.7176471 , 0.58431375 , 0.39607844 , 1.
 [0.75686276, 0.654902 , 0.45490196, 1.
                                                  1,
 [0.76862746, 0.6666667, 0.4745098, 1.
 [0.77254903, 0.67058825, 0.47843137, 1.
                                                  ]]], dtype=float32)
```

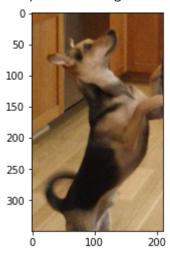
▼ Part (b) -- 1pt

Use the function plt.imshow to visualize img.

This function will also show the coordinate system used to identify pixels. The origin is at the top left corner, and the first dimension indicates the Y (row) direction, and the second dimension indicates the X (column) dimension.

```
img_show = plt.imshow(img)
img_show
```

<matplotlib.image.AxesImage at 0x7fb3492587d0>

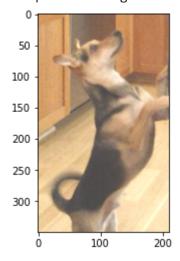


▼ Part (c) -- 2pt

Modify the image by adding a constant value of 0.25 to each pixel in the <code>img</code> and store the result in the variable <code>img_add</code>. Note that, since the range for the pixels needs to be between [0, 1], you will also need to clip img_add to be in the range [0, 1] using <code>numpy.clip</code>. Clipping sets any value that is outside of the desired range to the closest endpoint. Display the image using <code>plt.imshow</code>.

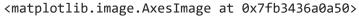
```
img_add = np.clip(img + 0.25, 0, 1)
plt.imshow(img_add)
```

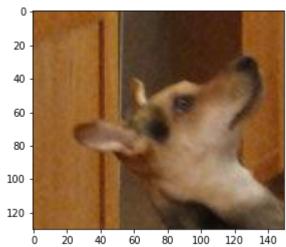
<matplotlib.image.AxesImage at 0x7fb343f34b10>



▼ Part (d) -- 2pt

Crop the **original** image (img variable) to a 130 x 150 image including Mochi's face. Discard the alpha colour channel (i.e. resulting img cropped should **only have RGB channels**)





Part 4. Basics of PyTorch [6 pt]

PyTorch is a Python-based neural networks package. Along with tensorflow, PyTorch is currently one of the most popular machine learning libraries.

PyTorch, at its core, is similar to Numpy in a sense that they both try to make it easier to write codes for scientific computing achieve improved performance over vanilla Python by leveraging highly optimized C back-end. However, compare to Numpy, PyTorch offers much better GPU support and provides many high-level features for machine learning. Technically, Numpy can be used to perform almost every thing PyTorch does. However, Numpy would be a lot slower than PyTorch, especially with CUDA GPU, and it would take more effort to write machine learning related code compared to using PyTorch.

import torch

▼ Part (a) -- 1 pt

Use the function torch.from_numpy to convert the numpy array img_cropped into a PyTorch tensor. Save the result in a variable called img torch.

```
img_torch = torch.from_numpy(img_cropped)
img_torch
```

```
tensor([[[0.5882, 0.3725, 0.1490],
         [0.5765, 0.3608, 0.1373],
         [0.5569, 0.3412, 0.1176],
         [0.5804, 0.3412, 0.1294],
         [0.6039, 0.3647, 0.1529],
         [0.6157, 0.3765, 0.1647]],
        [[0.5412, 0.3216, 0.0902],
         [0.5647, 0.3451, 0.1137],
         [0.5961, 0.3765, 0.1451],
         [0.5882, 0.3490, 0.1373],
         [0.6078, 0.3686, 0.1569],
         [0.6196, 0.3804, 0.1686]],
        [[0.6157, 0.3765, 0.1529],
         [0.6196, 0.3843, 0.1490],
         [0.6196, 0.3843, 0.1412],
         [0.5922, 0.3529, 0.1373],
         [0.6157, 0.3765, 0.1608],
         [0.6275, 0.3882, 0.1725]],
        . . . ,
        [[0.6039, 0.3882, 0.1686],
         [0.6078, 0.3922, 0.1686],
         [0.6118, 0.3961, 0.1725],
         [0.3804, 0.3098, 0.2157],
         [0.3765, 0.3059, 0.2118],
         [0.3765, 0.3098, 0.2078]],
        [[0.5882, 0.3725, 0.1529],
         [0.6078, 0.3922, 0.1725],
         [0.6196, 0.4039, 0.1804],
         [0.3882, 0.3176, 0.2314],
         [0.3804, 0.3098, 0.2157],
         [0.3804, 0.3098, 0.2157]],
        [[0.5804, 0.3647, 0.1451],
         [0.6039, 0.3882, 0.1686],
         [0.6235, 0.4078, 0.1882],
         [0.4196, 0.3373, 0.2549],
         [0.4039, 0.3216, 0.2392],
         [0.3961, 0.3137, 0.2314]]
```

▼ Part (b) -- 1pt

Use the method <Tensor>.shape to find the shape (dimension and size) of img torch.

```
img_torch.shape
torch.Size([130, 150, 3])
```

▼ Part (c) -- 1pt

How many floating-point numbers are stored in the tensor img_torch?

```
# Find the number of floating-point numbers stored in the tensor by multiplying the dimension
floating_point_nums = 1
for i in list(img_torch.shape):
    floating_point_nums = floating_point_nums * i

floating_point_nums
    58500
```

▼ Part (d) -- 1 pt

What does the code img_torch.transpose(0,2) do? What does the expression return? Is the original variable img_torch_updated? Explain.

```
# Print the before for img torch, the transpose implementation and the after img torch to see
print(img_torch)
print(img_torch.transpose(0,2))
print(img torch.transpose(0,2).shape)
print(img_torch)
print(img_torch.shape)
     tensor([[[0.5882, 0.3725, 0.1490],
              [0.5765, 0.3608, 0.1373],
              [0.5569, 0.3412, 0.1176],
              [0.5804, 0.3412, 0.1294],
              [0.6039, 0.3647, 0.1529],
              [0.6157, 0.3765, 0.1647]],
             [[0.5412, 0.3216, 0.0902],
              [0.5647, 0.3451, 0.1137],
              [0.5961, 0.3765, 0.1451],
              [0.5882, 0.3490, 0.1373],
              [0.6078, 0.3686, 0.1569],
              [0.6196, 0.3804, 0.1686]],
             [[0.6157, 0.3765, 0.1529],
              [0.6196, 0.3843, 0.1490],
```

```
[0.6196, 0.3843, 0.1412],
         . . . ,
         [0.5922, 0.3529, 0.1373],
         [0.6157, 0.3765, 0.1608],
         [0.6275, 0.3882, 0.1725]],
        . . . ,
        [[0.6039, 0.3882, 0.1686],
         [0.6078, 0.3922, 0.1686],
         [0.6118, 0.3961, 0.1725],
         [0.3804, 0.3098, 0.2157],
         [0.3765, 0.3059, 0.2118],
         [0.3765, 0.3098, 0.2078]],
        [[0.5882, 0.3725, 0.1529],
         [0.6078, 0.3922, 0.1725],
         [0.6196, 0.4039, 0.1804],
         [0.3882, 0.3176, 0.2314],
         [0.3804, 0.3098, 0.2157],
         [0.3804, 0.3098, 0.2157]],
        [[0.5804, 0.3647, 0.1451],
         [0.6039, 0.3882, 0.1686],
         [0.6235, 0.4078, 0.1882],
         [0.4196, 0.3373, 0.2549],
         [0.4039, 0.3216, 0.2392],
         [0.3961, 0.3137, 0.2314]]
tensor([[[0.5882, 0.5412, 0.6157, ..., 0.6039, 0.5882, 0.5804],
         [0.5765, 0.5647, 0.6196, \ldots, 0.6078, 0.6078, 0.6039],
         [0.5569, 0.5961, 0.6196, \ldots, 0.6118, 0.6196, 0.6235],
         [0.5804, 0.5882, 0.5922,
                                    ..., 0.3804, 0.3882, 0.4196],
         [0.6039, 0.6078, 0.6157, \ldots, 0.3765, 0.3804, 0.4039],
         [0.6157, 0.6196, 0.6275, \ldots, 0.3765, 0.3804, 0.3961]],
```

Explanation: The original tensor stays the same even after the transpose is applied. Its value is not updated. The code img_torch.transpose(0,2) transposes the original tensor based on the dimensions passed in. Thus, in this context, the values of the first dimension of the tensor are swapped with the values of the third dimension of the tensor.

▼ Part (e) -- 1 pt

What does the code img_torch.unsqueeze(0) do? What does the expression return? Is the original variable img_torch updated? Explain.

```
# Print the before for img torch, the unsqueeze implementation and the after img torch to see
print(img torch)
print(img torch.unsqueeze(0))
print(img torch.unsqueeze(0).shape)
print(img_torch)
print(img torch.shape)
              [[ע.סס.ש , 4שסכ.ש],
               [0.6039, 0.3882, 0.1686],
               [0.6235, 0.4078, 0.1882],
               [0.4196, 0.3373, 0.2549],
               [0.4039, 0.3216, 0.2392],
               [0.3961, 0.3137, 0.2314]]])
     torch.Size([1, 130, 150, 3])
     tensor([[[0.5882, 0.3725, 0.1490],
              [0.5765, 0.3608, 0.1373],
              [0.5569, 0.3412, 0.1176],
              [0.5804, 0.3412, 0.1294],
              [0.6039, 0.3647, 0.1529],
              [0.6157, 0.3765, 0.1647]
             [[0.5412, 0.3216, 0.0902],
              [0.5647, 0.3451, 0.1137],
              [0.5961, 0.3765, 0.1451],
              [0.5882, 0.3490, 0.1373],
              [0.6078, 0.3686, 0.1569],
              [0.6196, 0.3804, 0.1686]],
             [[0.6157, 0.3765, 0.1529],
              [0.6196, 0.3843, 0.1490],
              [0.6196, 0.3843, 0.1412],
              [0.5922, 0.3529, 0.1373],
              [0.6157, 0.3765, 0.1608],
              [0.6275, 0.3882, 0.1725]],
             . . . ,
             [[0.6039, 0.3882, 0.1686],
              [0.6078, 0.3922, 0.1686],
              [0.6118, 0.3961, 0.1725],
              [0.3804, 0.3098, 0.2157],
              [0.3765, 0.3059, 0.2118],
              [0.3765, 0.3098, 0.2078]],
             [[0.5882, 0.3725, 0.1529],
              [0.6078, 0.3922, 0.1725],
              [0.6196, 0.4039, 0.1804],
              [0.3882, 0.3176, 0.2314],
              [0.3804, 0.3098, 0.2157],
```

[0.3804, 0.3098, 0.2157]],

```
[[0.5804, 0.3647, 0.1451],
        [0.6039, 0.3882, 0.1686],
        [0.6235, 0.4078, 0.1882],
        ...,
        [0.4196, 0.3373, 0.2549],
        [0.4039, 0.3216, 0.2392],
        [0.3961, 0.3137, 0.2314]]])
torch.Size([130, 150, 3])
```

Explanation: The code img_torch.unsqueeze(0) adds a new dimension to the tensor and places it before the other dimensions. The original tensor is not updated after doing unsqueeze(0).

▼ Part (f) -- 1 pt

Find the maximum value of img_torch along each colour channel? Your output should be a one-dimensional PyTorch tensor with exactly three values.

Hint: lookup the function torch.max.

```
max_value = torch.max(torch.max(img_torch, 1)[0], 0)[0]
max_value
tensor([0.8941, 0.7882, 0.6745])
```

▼ Part 5. Training an ANN [10 pt]

The sample code provided below is a 2-layer ANN trained on the MNIST dataset to identify digits less than 3 or greater than and equal to 3. Modify the code by changing any of the following and observe how the accuracy and error are affected:

- number of training iterations
- · number of hidden units
- numbers of layers
- types of activation functions
- learning rate

Please select at least three different options from the list above. For each option, please select two to three different parameters and provide a table.

```
import torch
import torch.nn as nn
import torch.nn.functional as F
from torchvision import datasets, transforms
import matplotlib.pyplot as plt # for plotting
```

```
import torch.optim as optim
torch.manual seed(1) # set the random seed
# define a 2-layer artificial neural network
class Pigeon(nn.Module):
   def __init__(self):
        super(Pigeon, self).__init__()
        \#self.laver1 = nn.Linear(28 * 28, 30)
        #self.layer2 = nn.Linear(30, 1)
        self.layer1 = nn.Linear(28 * 28, 128)
        self.layer2 = nn.Linear(128, 16)
        self.layer3 = nn.Linear(16, 1)
   def forward(self, img):
        flattened = img.view(-1, 28 * 28)
        activation1 = self.layer1(flattened)
        activation1 = F.relu(activation1)
        activation2 = self.layer2(activation1)
        activation2 = F.relu(activation2)
        activation3 = self.layer3(activation2)
        return activation3
pigeon = Pigeon()
# load the data
mnist data = datasets.MNIST('data', train=True, download=True)
mnist data = list(mnist data)
mnist train = mnist data[:1000]
mnist val = mnist data[1000:2000]
img_to_tensor = transforms.ToTensor()
# simplified training code to train `pigeon` on the "small digit recognition" task
criterion = nn.BCEWithLogitsLoss()
optimizer = optim.SGD(pigeon.parameters(), lr=0.003, momentum=0.9)
# Adding more training iterations
for epoch in range(5):
 for (image, label) in mnist train:
      # actual ground truth: is the digit less than 3?
      actual = torch.tensor(label < 3).reshape([1,1]).type(torch.FloatTensor)</pre>
      # pigeon prediction
      out = pigeon(img to tensor(image)) # step 1-2
      # update the parameters based on the loss
      loss = criterion(out, actual)
                                       # step 3
                                         # step 4 (compute the updates for each parameter)
      loss.backward()
      optimizer.step()
                                       # step 4 (make the updates for each parameter)
      optimizer.zero grad()
                                         # a clean up step for PyTorch
# computing the error and accuracy on the training set
error = 0
```

```
for (image, label) in mnist train:
     prob = torch.sigmoid(pigeon(img to tensor(image)))
     if (prob < 0.5 \text{ and } label < 3) \text{ or } (prob >= 0.5 \text{ and } label >= 3):
print("Training Error Rate:", error/len(mnist_train))
print("Training Accuracy:", 1 - error/len(mnist train))
# computing the error and accuracy on a test set
error = 0
for (image, label) in mnist val:
     prob = torch.sigmoid(pigeon(img_to_tensor(image)))
     if (prob < 0.5 \text{ and } label < 3) \text{ or } (prob >= 0.5 \text{ and } label >= 3):
          error += 1
print("Test Error Rate:", error/len(mnist_val))
print("Test Accuracy:", 1 - error/len(mnist val))
      Downloading http://yann.lecun.com/exdb/mnist/train-images-idx3-ubyte.gz
      Downloading <a href="http://yann.lecun.com/exdb/mnist/train-images-idx3-ubyte.gz">http://yann.lecun.com/exdb/mnist/train-images-idx3-ubyte.gz</a> to data/MNIST/rain-images-idx3-ubyte.gz
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       Extracting data/MNIST/raw/train-images-idx3-ubyte.gz to data/MNIST/raw
      Downloading <a href="http://yann.lecun.com/exdb/mnist/train-labels-idx1-ubyte.gz">http://yann.lecun.com/exdb/mnist/train-labels-idx1-ubyte.gz</a>
      Downloading <a href="http://yann.lecun.com/exdb/mnist/train-labels-idx1-ubyte.gz">http://yann.lecun.com/exdb/mnist/train-labels-idx1-ubyte.gz</a> to data/MNIST/rain-labels-idx1-ubyte.gz
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      Downloading <a href="http://yann.lecun.com/exdb/mnist/t10k-images-idx3-ubyte.gz">http://yann.lecun.com/exdb/mnist/t10k-images-idx3-ubyte.gz</a>
      Downloading <a href="http://yann.lecun.com/exdb/mnist/t10k-images-idx3-ubyte.gz">http://yann.lecun.com/exdb/mnist/t10k-images-idx3-ubyte.gz</a> to data/MNIST/rai
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      Extracting data/MNIST/raw/t10k-images-idx3-ubyte.gz to data/MNIST/raw
      Downloading <a href="http://yann.lecun.com/exdb/mnist/t10k-labels-idx1-ubyte.gz">http://yann.lecun.com/exdb/mnist/t10k-labels-idx1-ubyte.gz</a>
      Downloading <a href="http://yann.lecun.com/exdb/mnist/t10k-labels-idx1-ubyte.gz">http://yann.lecun.com/exdb/mnist/t10k-labels-idx1-ubyte.gz</a> to data/MNIST/raw
       100%
                                                                    4542/4542 [00:00<00:00, 171082.31it/s]
       Extracting data/MNIST/raw/t10k-labels-idx1-ubyte.gz to data/MNIST/raw
      Training Error Rate: 0.005
      Training Accuracy: 0.995
      Test Error Rate: 0.055
      Test Accuracy: 0.945
```

▼ Part (a) -- 3 pt

Comment on which of the above changes resulted in the best accuracy on training data? What accuracy were you able to achieve?

Increasing the number of training iterations, also known as epochs, resulted in the best accuracy on training data. The accuracy I was able to achieve with 6 epochs was 99.9% on the training data. The accuracy on the training data stayed consistent with 99.9% even after I increased the number of epochs gradually from 6 to 15. One more change I made was changing the learning rate to 0.003 from the initial rate of 0.005. I was then able to achieve a training data accuracy of 100%.

▼ Part (b) -- 3 pt

Comment on which of the above changes resulted in the best accuracy on testing data? What accuracy were you able to achieve?

I used the same number of epochs as part a. The testing data accuracy then was 93.4%. One way I improved the testing data accuracy was reducing the number of epochs to 5 from the 6 I had in part a; I kept the learning rate the same (0.003) and then got a testing data accuracy of 93.9%. To further improve this, I added another layer to the ANN. This addition of a hidden layer improved my testing data accuracy to 94.5% but the trade-off was that my training data accuracy is now 99.5%.

→ Part (c) -- 4 pt

Which model hyperparameters should you use, the ones from (a) or (b)?

I would use the hyperparameters from part (b). This is because we get more accurate results for test data, which is more applicable as we can better predict new data that currently isn't at our disposal. Furthermore, a higher training data accuracy is sometimes indicative of overfitting the data which doesn't give good insight on predictions for test data. Thus, due to the real-life applicability of predicting new data, I would choose the hyperparamaters from part (b) as it gives us the highest accuracy for test data.

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