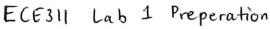
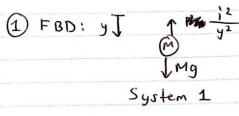
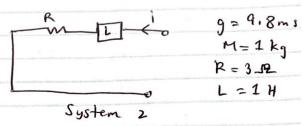
Question 1:







System 1:

$$\xi F = Ma = M\ddot{y}$$

$$-\frac{i^{2}}{y^{2}} + Mg = M\ddot{y}$$

System 2
System 2:

$$-u + V_{1} + V_{R} = 0$$

 $-u + L \frac{di}{dt} + iR = 0$
 $L \frac{di}{dt} + Ri = u$
 $3 \Omega \cdot L = 1 H$

Subs. M=1kg, g=9.8 m/s2, R=31 , L=1H

System 1:

$$-\frac{1^2}{y^2} + 9.8 = \dot{y}$$

System 2:
$$\frac{di}{dt} + 3i = u$$

State Vector
$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} y \\ y \\ i \end{bmatrix}$$

State
$$\begin{array}{ll}
\dot{x}_1 = x_2 \\
\dot{x}_2 = \dot{y} = 9.8 - \frac{1^2}{y^2} = 9.8 - \frac{x_3^2}{x_1^4} \\
Model$$

$$\dot{x}_3 = \dot{1} = u - 3x_3 \\
\dot{y} = \chi_1$$

Question 2:

(2)
$$\begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = 9.8 - \frac{x_3^2}{x_1^2} \\ \dot{x}_1 = u - 3x_3 \end{cases}$$

For equilibrium, x, = x2 = x3 = 0

 $u^{-3}x_{3}^{*} = 0$ $u^{-3}x_{3}^{*} = 0$ $u^{-3}(3.13)x_{1}^{*}$ $u^{-3}(3.13)x_{1}^{*}$

$$(x^{*}, u^{*}) = \begin{pmatrix} \begin{pmatrix} x_{1}^{*} \\ 0 \\ 3.13 x_{1}^{*} \end{pmatrix}, 9.39 \times x_{1}^{*} \end{pmatrix}$$

$$\frac{\partial xf}{\partial x_1} = \begin{bmatrix}
\frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \frac{\partial f_1}{\partial x_3} \\
\frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_1} & \frac{\partial f_3}{\partial x_2} \\
\frac{\partial f_3}{\partial x_1} & \frac{\partial f_3}{\partial x_1} & \frac{\partial f_3}{\partial x_2}
\end{bmatrix} = \begin{bmatrix}
0 & 1 & 0 \\
\frac{2 x_3^2}{x_1^3} & 0 & -\frac{2x_3}{x_1^2} \\
0 & 0 & -3
\end{bmatrix}$$

$$= \begin{bmatrix} O & | & O \\ \frac{2(3,|3\chi_{i}^{+})^{2}}{\chi_{i}^{+}3} & O & -\frac{2(3,|3\chi_{i}^{+})}{\chi_{i}^{+}2} \\ O & O & -3 \end{bmatrix}$$

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 19.6x_1^{**} & 0 & -6.26x_1^{**} \\ 0 & 0 & -3 \end{bmatrix}$$

$$= C$$

$$\partial_u h = 0$$

Question 2 Continued:

$$\begin{aligned}
\partial x &= x - x^{2} & \partial u &= u - u^{2} \\
&= \begin{bmatrix} x_{1} - x_{1}^{2} & & & \\ x_{2} & & & \\ x_{3} - 3 & 1 & 3 & x_{1}^{2} \end{bmatrix} &= u - 9 & 3 & 9 & x_{1}^{4} \\
\end{aligned}$$

Linearization is:
$$\frac{d}{d+}(du) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 0 \\ 19.6 \pi^{-1} & 0 & -6.26 \pi^{-1} \\ 0 & 0 & -3 \end{bmatrix} \times + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u$$

where
$$dx = \begin{bmatrix} x_1 - x_1^* \\ x_2 - x_3 - x_4 \end{bmatrix}$$
 and $du = u - q \cdot 3q x_1^*$

Question 3:

(3) Setting
$$x_1^* = y^* = 1$$
,

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 19.6 & 0 & -6.26 \\ 0 & 0 & -3 \end{bmatrix}$$

$$G(s) = C(sI - A)^{-1}B + D$$

$$= \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} s & -1 & 0 \\ -19.6 & s & +6.26 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$G(s) = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{s}{s^2 - 1.96} & \frac{1}{s^2 - 19.6} & \frac{-(.26)}{(s+3)(s^2 - 19.6)} \end{bmatrix} \begin{bmatrix} 0 \\ \frac{19.6}{s^2 - 19.6} & \frac{s}{s^2 - 19.6} & \frac{-6.26s}{(s+3)^{-1}} \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ \end{bmatrix}$$

$$= \left[\frac{s}{s^2 - 1.96} \frac{1}{s^2 - 19.6} \frac{-6.26}{(s+3)(s^2 - 19.6)} \right] \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$-6.26$$

$$= \frac{-6.26}{(s+3)(s^2-19.6)}$$

$$= \frac{-6.26}{(5+3)(5+\sqrt{19.6})(5-\sqrt{19.6})}$$

Question 4:

$$\frac{4}{9} G_{1}(s) = \frac{-6.26}{(s+3)(s+\sqrt{19.6})(s-\sqrt{19.6})}$$

$$= \frac{-6.26}{(s+3)(s+4.43)(s-4.43)}$$

$$g(+) = \int_{-6.26}^{-1} \frac{5}{(s+3)(s+4.43)(s-4.43)} \int_{s=-3}^{6.26} \frac{1}{(s+3)(s+4.43)} \int_{s=-4.43}^{6.26} \frac{1}{(s+3)(s-4.43)} \int_{s=-4.43}^{6.26} \frac{1}{($$

Plot of g(t):

