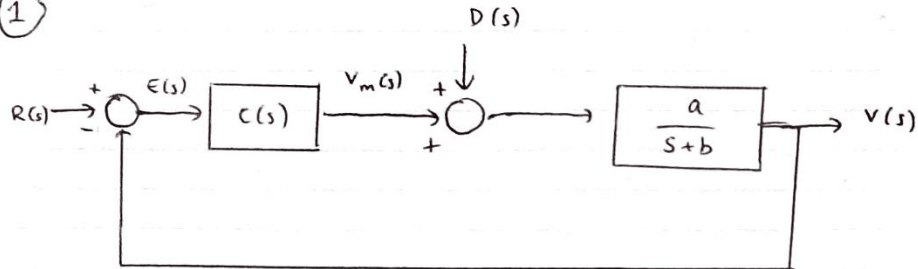


Lab 3 Prep
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①



$$C(s) = \frac{v_m(s)}{E(s)} = K \left(1 + \frac{1}{T_1 s} \right) ; K, T > 0$$

$$E_R(s) = R(s) \cdot \frac{1}{1 + C(s) \cdot \frac{a}{s+b}}$$

$$= R(s) \cdot \frac{1}{1 + \left(K + \frac{K}{T_1 s} \right) \cdot \frac{a}{s+b}}$$

$$= R(s) \cdot \frac{1}{1 + \frac{K T_1 s + K}{T_1 s} \cdot \frac{a}{s+b}}$$

$$= R(s) \cdot \frac{1}{\frac{(T_1 s)(s+b) + a(K T_1 s + K)}{(T_1 s)(s+b)}}$$

$$E_R(s) = \frac{R(s) (s+b)(T_1 s)}{(s+b)(T_1 s) + K a (T_1 s + 1)}$$

$$-E_D(s) = D(s) \cdot \frac{\frac{a}{s+b}}{1 + C(s) \cdot \frac{a}{s+b}}$$

$$= D(s) \cdot \frac{a}{\frac{(T_1 s)(s+b) + a(K T_1 s + K)}{(T_1 s)(s+b)}}$$

$$= D(s) \cdot \frac{a}{s+b} \times \frac{(T_1 s)(s+b)}{(T_1 s)(s+b) + a(K T_1 s + K)}$$

$$= D(s) \cdot \frac{(T_1 s) a}{(T_1 s)(s+b) + K a (T_1 s + 1)}$$

$$E_D(s) = - \frac{D(s) (T_1 s) a}{(T_1 s)(s+b) + K a (T_1 s + 1)}$$

Since transfer function is asked for in the question, we can rewrite $E_R(s)$ and $E_D(s)$.

$$\frac{E_R(s)}{R(s)} = \frac{(s+b)(T_1 s)}{(s+b)(T_1 s) + K a (T_1 s + 1)}$$

$$-\frac{E_D(s)}{D(s)} = \frac{a(T_1 s)}{(s+b)(T_1 s) + K a (T_1 s + 1)}$$

$$(2) D(s) = \frac{\bar{d}}{s}, \quad R(s) = \frac{\bar{v}}{s}$$

$$E(s) = E_R(s) + E_D(s)$$

$$E(s) = R(s) \cdot \frac{(T_1 s)(s+b)}{(T_1 s)(s+b) + K a (T_1 s+1)} - D(s) \cdot \frac{a (T_1 s)}{(T_1 s)(s+b) + K a (T_1 s+1)}$$

$$E(s) = \frac{\bar{v}}{s} \cdot \frac{(T_1 s)(s+b)}{(T_1 s)(s+b) + K a (T_1 s+1)} - \frac{\bar{d}}{s} \cdot \frac{a (T_1 s)}{(T_1 s)(s+b) + K a (T_1 s+1)}$$

(3) Apply FVT!

$$e(\infty) = \lim_{t \rightarrow \infty} e(t) = \lim_{s \rightarrow 0} s E(s)$$

$$= s \left[\frac{\bar{v}}{s} \cdot \frac{T_1(s)(s+b)}{(T_1 s)(s+b) + K a (T_1 s+1)} - \frac{\bar{d}}{s} \cdot \frac{a T_1(s)}{(T_1 s)(s+b) + K a (T_1 s+1)} \right]$$

$$= s \left[\bar{v} \cdot \frac{T_1(s+b)}{(T_1 s)(s+b) + K a (T_1 s+1)} - \bar{d} \cdot \frac{a T_1}{(T_1 s)(s+b) + K a (T_1 s+1)} \right]$$

$$= (0)(E(0))$$

$$= 0$$

\therefore It is proved that a PI controller can meet SPEC1.