

BACHELOR OF COMPUTER SCIENCE & ENGG. EXAMINATION, 2022

(3rd YEAR , 1st SEMESTER)

COMPUTER GRAPHICS

Time: Three Hours

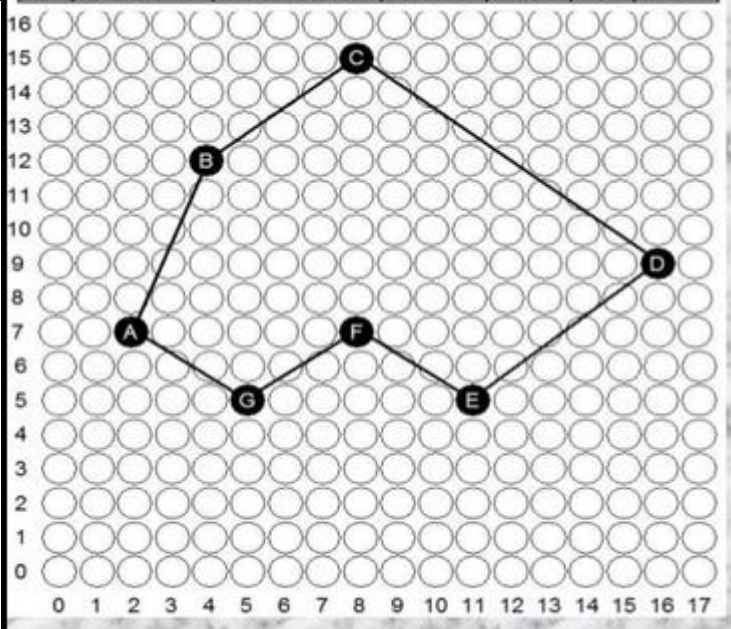
Full Marks: 70

Read the Following Instructions Carefully:

- Put your Name, Class Roll No, Primary Mobile phone no, Email at the first page
- Put Class Roll No at the top-right corner of every page
- Put your signature at the bottom of every page
- Let R be the last two digits of your Class Roll No. and let R_1 and R_2 be the two digits in your Roll No. For example, If your Roll No. is 23, then, $R = 23$, $R_1 = 2$ and $R_2 = 3$; $R_1 + R_2 = 5$. If your Roll No. is 05, then, $R = 5$, $R_1 = 0$ and $R_2 = 5$; $R_1 + R_2 = 5$.

Answer ALL questions

<u>Group-1 (20 Marks)</u>			
1.	a)	Use Bresenham's Midpoint method to derive decision parameters for generating points along an ellipse centered at (R_1, R_2) , $rx = 7 + R_1$ and $ry = 5 + R_2$. Show all the calculations for Quadrant 1 (for both Region 1 and 2) and generate the symmetric points in the other three quadrants. N.B: if rx is equal to ry , consider, $rx = rx + 2$.	20

<u>Group-2 (20 Marks)</u>			
2	a)	Let ABCD be the rectangular window with A(0,0), B(10,0), C(10,10), D(0,10). Use Cohen Sutherland Algorithm to clip the line XY, such that X(-5, R_1) and Y(15, R_2).	10
	b)	 <p>Consider the above polygon and use Scanline fill algorithm to generate the edge intersections and inside points for $y=5$, $y=6$ and $y=7$.</p>	10

<u>Group-3 (20 Marks)</u>			
3.	a)	<p>Q A unit square is transformed by a 2×2 transformation matrix. The resulting position vectors are</p> $\begin{pmatrix} 0 & 2 & 8 & 6 \\ 0 & 3 & 4 & 1 \end{pmatrix}$ <p>What is the transformation matrix?</p> <p>Hint:</p> <p>Let the unit square have coordinates (x, y), $(x + 1, y)$, $(x + 1, y + 1)$, $(x, y + 1)$ and let the transformation matrix be</p> $\begin{pmatrix} a & c \\ b & d \end{pmatrix}$	6
	b)	Prove that if rotation angle is θ the transformation matrix formed when multiplied by the transformation matrix formed when angle is $-\theta$ is equal to identity matrix.	4
	c)	What are interpolation and approximation splines? what is a convex hull? what is a control graph? Derive the equation of a cubic Bezier curve.	10

<u>Group-4 (10 Marks)</u>			
4.	a)	Briefly discuss Phong surface rendering model. Discuss its advantages and disadvantages with respect to the Gouraud model.	5
	b)	Briefly discuss the Painter's algorithm for hidden surface removal	5