## 교과목: 딥러닝 수학 [Mathematics for Machine Learning]



## 목표

- 딥러닝에 국한된 것이 아니라 머신러닝에 대한 전반적인 이해를 위해 필요한 수학 지식 습득
  - **선형대수, 미분, 확률 통계**와 머신러닝과(딥러닝 포함)의 관계
  - 가능한 예제들을 바탕으로 설명
- 수학 문제를 잘 풀기 위한 것이 아니라 이해하고 익숙해지자

John von Neumann



"Young man, in mathematics you don't understand things, you just get used to them."

in reply to Felix Smith who had said "I'm afraid I don't understand the method of characteristics."



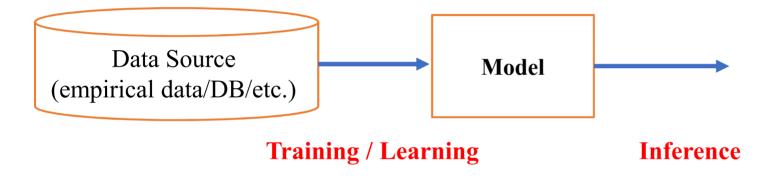
## AI(Artificial Intelligence) 6개 분야

- Knowledge representation to store what it knows or hears
- Automated reasoning to use the stored information to answer questions and to draw new conclusions
- Natural language processing to enable it to communicate successfully
- Computer vision to perceive objects
- Robotics to manipulate objects and move about
- Machine learning to adapt to new circumstances and to detect and extrapolate patterns

Stuart Russell and Peter Norvig, "Artificial Intelligence: A Modern Approach," Pearson.



#### Machine Learning



- Machine Learning: A scientific discipline that is concerned with the design and development of algorithms that allow computers to learn(train) from empirical data (sensor data or database) and to make predictions.
- [컴퓨터가 경험적인 데이터(정제된 데이터, 활용 가능한 데이터[센서 데이터, DB])로 부터 **학습하고 예측**할 수 있 도록 <알고리즘을 설계하고 개발하는 과학 분야>]



## Machine Learning

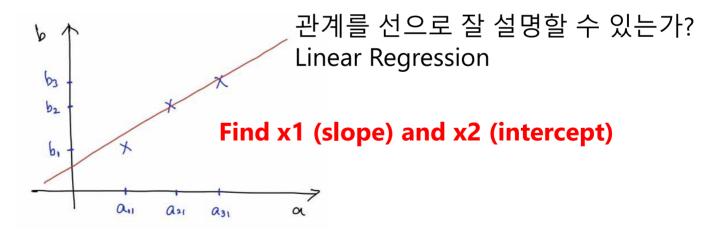
## • 3가지 중요한 요소

ML		Relevant Maths.
Data - Images, text, languages, time series, etc.	데이터를 효과적으로 표현	Data - Vectors, matrix and tensors
<ul> <li>Models</li> <li>Linear models</li> <li>Deep neural networks</li> <li>Kernel machine</li> <li>Probabilistic models</li> </ul>	모델을 체계적으로 공부	Models - Linear algebra - Probability
Training & Inference - Optimization - Regularization - Batch or online - Generalization		Training & Inference - Optimization (Gradient Descent algorithm, backpropagation: 口是) - Estimation - Information theory - Matrix factorization



- Motivation Example
  - 집의 크기와 가격과의 관계 도출

 $\mathbf{a}_{i1}$  represents the size of house i and  $\mathbf{b}_{i}$  corresponds to the price of house i.



- Motivation Example
  - 집의 크기 + α (주변 상점 수)와 가격과의 관계 도출

$$\begin{bmatrix} a_{11} & a_{12} & 1 \\ a_{21} & a_{22} & 1 \\ a_{31} & a_{32} & 1 \\ a_{41} & a_{42} & 1 \\ a_{51} & a_{52} & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \\ b_5 \end{bmatrix}$$
 Modeling: Linear Equation 만드는 것

ML: Model Parameter

모델링(Linear equation from data[matrix a, vector b]) -> solve/find vector x

• Linear regression involves solving the linear equation Ax = b.



• Two Important Equations in Linear Algebra

$$\mathbf{A}\mathbf{x} = \mathbf{b}$$
 (linear equation)

$$\mathbf{A}\mathbf{x}=\lambda\mathbf{x}$$
 (eigenvalue equation)

- Why Linear Algebra for ML?
  - Data are presented in the form of vectors and matrices
  - Model relates input with output, which is often represented by linear equations, which are presented in the form of vectors and matrices.
    - 관심 가지는 것: Linear model: Linear transformation
      - 선형함수



Objects in Linear Algebra

Scalar (
$$\mathbb{R}$$
):  $x$ 

Vector 
$$(\mathbb{R}^n)$$
:  $\mathbf{x}(x_i)$ 

Matrix 
$$(\mathbb{R}^{m \times n})$$
: X  $(X_{i,j})$ 

Tensor (
$$\mathbb{R}^{m \times n \times k \times \cdots}$$
):  $\mathbf{X}$  ( $X_{i,j,k}$ )

#### Outline

Vectors, vector spaces, and matrices

Inverse and transpose

Linear independence and rank

Linear equations (range space and null space)

Norm and inner product

Orthogonality and rotation

Projection

진행 예정



## Vectors



## Linear Algebra - Vector

#### Physicist

 Arrow (with direction and length)

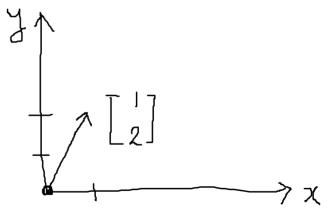
#### Computer scientist

List of numbers

사람을 표현하는 3-dimensional vector

#### Mathematician

Arrow rooted at the origin



Physicist + Computer scientist



## Linear Algebra - Vector

#### **Basis Vector**

$$\left[\begin{array}{c}1\\2\end{array}\right]=1\left[\begin{array}{c}1\\0\end{array}\right]+2\left[\begin{array}{c}0\\1\end{array}\right]$$

Basis vector

#### **Column / Row Vector and Transpose**

The **transpose** of a vector  $\mathbf{x}$  is denoted by  $\mathbf{x}^{\top}$ .

Consider the column vector x:

$$\mathbf{x} = \left[ \begin{array}{c} 1 \\ 3 \\ -2 \end{array} \right].$$

Then,  $\mathbf{x}^{\top}$  is row vecotor, given by

$$\mathbf{x}^{\top} = [1, 3, -2].$$
  $(\mathbf{X}^{\mathsf{T}})^{\mathsf{T}} = \mathbf{X}$ 

$$(x^T)^T = x$$

Basis vector: 그 벡터 공간을 선형생성(span)하는 선형독립(linear independence)인 벡터



#### Definition

A vector space, denoted by V, is a collection of objects, called vectors, which is vector addition (+) and scalar multiplication (·), such that the following axioms hold for any  $x, y, z \in V$  and  $\alpha, \beta \in \mathbb{R}$ :

 $\mathbf{x} + \mathbf{y} \in \mathcal{V}$  and  $\alpha \mathbf{x} \in \mathcal{V}$  (closed under vector addition and scalar multiplication)

$$x + (y + z) = (x + y) + z$$
 (associativity) 결합

$$\alpha(\mathbf{x} + \mathbf{y}) = \alpha \mathbf{x} + \alpha \mathbf{y}$$
 and  $(\alpha + \beta)\mathbf{x} = \alpha \mathbf{x} + \beta \mathbf{x}$  (distributivity) 분배

$$\exists 0 \in \mathcal{V} \text{ such that } 0 + x = x \text{ and } 1x = x \text{ (identity element)}$$

for any 
$$\mathbf{x} \in \mathcal{V}$$
,  $\exists (-\mathbf{x}) \in \mathcal{V}$  such that  $\mathbf{x} + (-\mathbf{x}) = 0$  (inverse element)

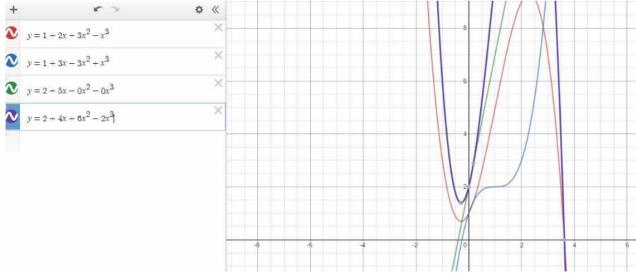
$$\alpha(\beta \mathbf{x}) = (\alpha \beta) \mathbf{x}$$

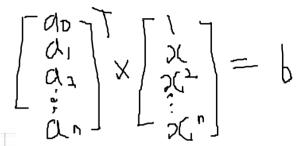
vector space: 어떤 vector들을 모아 놓은 set인데, "+"연산과 "scalar multiplication"에 닫혀 있다.



- Polynomials are vectors?
  - A polynomial of degree n is described as:

$$f(x) = a_0 + a_1x + a_2x^2 + \cdots + a_nx^n$$
.





#### • Polynomials are vectors?

For 
$$f, g \in \mathcal{V}$$
,  $\underline{f + g \in \mathcal{V}}$ ?
$$f(x) + g(x)$$

$$= (a_0 + a_1x + a_2x^2 + \dots + a_nx^n) + (b_0 + b_1x + b_2x^2 + \dots + b_nx^n)$$

$$= (a_0 + b_0) + (a_1 + b_1)x + (a_2 + b_2)x^2 + \dots + (a_n + b_n)x^n \in \mathcal{V}.$$

For 
$$f \in \mathcal{V}$$
 and  $\alpha \in \mathbb{R}$ ,  $\underline{\alpha f \in \mathcal{V}}$ ?

$$\alpha f(x) = \alpha (a_0 + a_1 x + a_2 x^2 + \dots + a_n x^n)$$
  
=  $\alpha a_0 + \alpha a_1 x + \alpha a_2 x^2 + \dots + \alpha a_n x^n \in \mathcal{V}.$ 



• R<sup>3</sup> is a vector space?

Consider two (column) vectors x and y:

$$\mathbf{x} = \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix} \in \mathbb{R}^3, \quad \mathbf{y} = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \in \mathbb{R}^3.$$

Add two vectors with each scaled:

$$2\mathbf{x} + \mathbf{y} = \begin{bmatrix} 2 \\ 6 \\ -4 \end{bmatrix} + \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 7 \\ -4 \end{bmatrix} \in \mathbb{R}^3.$$

## Matrices



#### Rows and Columns

$$\mathbf{A} \in \mathbb{R}^{m \times n} = \left[ egin{array}{cccc} a_{11} & a_{12} & \cdots & a_{1n} \ a_{21} & a_{22} & \cdots & a_{2n} \ \vdots & \vdots & & \vdots \ a_{m1} & a_{m2} & \cdots & a_{mn} \end{array} 
ight] = \left[ \mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n \right],$$

where  $\mathbf{a}_i \in \mathbb{R}^m$  for  $i = 1, \dots, n$ .

The transpose of the matrix **A**, denoted by  $\mathbf{A}^{\top} \in \mathbb{R}^{n \times m}$ , is given by

$$\mathbf{A}^{ op} = \left[ egin{array}{cccc} a_{11} & a_{21} & \cdots & a_{m1} \ a_{12} & a_{22} & \cdots & a_{m2} \ \vdots & \vdots & & \vdots \ a_{1n} & a_{2n} & \cdots & a_{mn} \end{array} 
ight] = \left[ egin{array}{c} \mathbf{a}_1^{ op} \ \mathbf{a}_2^{ op} \ \vdots \ \mathbf{a}_n^{ op} \end{array} 
ight].$$



• Scalar-Matrix Operation:

$$2\begin{bmatrix} 1 & -1 \\ 3 & 5 \end{bmatrix} =$$

• Matrix-Vector Multiplication:

$$\left[\begin{array}{cc} 1 & -1 \\ -1 & 2 \\ 3 & 5 \end{array}\right] \left[\begin{array}{c} x \\ y \end{array}\right] =$$

$$\left[\begin{array}{ccc} 1 & -1 & 0 \\ 2 & 3 & 4 \end{array}\right] \left[\begin{array}{c} x \\ y \\ z \end{array}\right] =$$

Matrix-Matrix Addition:

$$\left[\begin{array}{cc} a & b \\ c & d \end{array}\right] + \left[\begin{array}{cc} w & x \\ y & z \end{array}\right] =$$

• Matrix-Matrix Multiplication:

$$\left[\begin{array}{ccc} 1 & -1 & 0 \\ 2 & 3 & 4 \end{array}\right] \left[\begin{array}{ccc} 1 & -1 \\ -1 & 2 \\ 3 & 5 \end{array}\right] =$$

• Inverse(A-1) and Transpose (AT)

#### Definition

Consider a square matrix  $\mathbf{A} \in \mathbb{R}^{n \times n}$ . The matrix  $\mathbf{B} \in \mathbb{R}^{n \times n}$ , which satisfies  $\mathbf{AB} = \mathbf{BA} = \mathbf{I}$ , is called the **inverse** and denoted by  $\mathbf{A}^{-1}$ .

#### Definition

For  $\mathbf{A} \in \mathbb{R}^{m \times n}$ , the matrix  $\mathbf{B} \in \mathbb{R}^{n \times m}$  with  $b_{ij} = a_{ji}$  is called the **transpose** of  $\mathbf{A}$  and denoted by  $\mathbf{A}^{\top}$ .



• Properties of Inverse(A-1) and Transpose (A<sup>T</sup>)

$$\mathbf{A}\mathbf{A}^{-1} = \mathbf{A}^{-1}\mathbf{A} = \mathbf{I},$$

$$(\mathbf{A}\mathbf{B})^{-1} = \mathbf{B}^{-1}\mathbf{A}^{-1},$$

$$(\mathbf{A} + \mathbf{B})^{-1} \neq \mathbf{A}^{-1} + \mathbf{B}^{-1},$$

$$(\mathbf{A}^{\top})^{\top} = \mathbf{A},$$

$$(\mathbf{A} + \mathbf{B})^{\top} = \mathbf{A}^{\top} + \mathbf{B}^{\top},$$

$$(\mathbf{A}\mathbf{B})^{\top} = \mathbf{B}^{\top}\mathbf{A}^{\top}.$$

• Symmetric Matrix

#### Definition

A square matrix  $\mathbf{A} \in \mathbb{R}^{n \times n}$  is symmetric if  $\mathbf{A} = \mathbf{A}^{\top}$ 

## Example:

$$\mathbf{A} = \left[ \begin{array}{cc} 1 & -1 \\ -1 & 5 \end{array} \right]$$

$$A = XX^{T}$$

$$(\mathbf{A}\mathbf{B})^{\top} = \mathbf{B}^{\top}\mathbf{A}^{\top}.$$



#### Positive Definite Matrix

- 특정한 성질을 가지는 행렬에 대해 양수/음수와 같이 부호를 정의하는 것

#### Definition

A symmetric matrix  $\mathbf{A} \in \mathbb{R}^{n \times n}$  is said to be **positive definite** if

$$\mathbf{x}^{\top} \mathbf{A} \mathbf{x} > 0, \quad \forall \mathbf{x} \in \mathcal{V} \setminus \{\mathbf{0}\}.$$

#### Definition

A symmetric matrix  $\mathbf{A} \in \mathbb{R}^{n \times n}$  is said to be **positive semidefinite** if

$$\boldsymbol{x}^{\top}\boldsymbol{A}\boldsymbol{x} \geq 0, \quad \ \forall \boldsymbol{x} \in \mathcal{V} \backslash \{\boldsymbol{0}\}.$$

#### Example:

$$\mathbf{A} = \begin{bmatrix} 9 & 6 \\ 6 & 5 \end{bmatrix}, \quad \mathbf{x}^{\top} \mathbf{A} \mathbf{x} = 9x_1^2 + 12x_1x_2 + 5x_2^2 = (3x_1 + 2x_2)^2 + x_2^2 > 0.$$



# Linear Independence



## Linear Algebra – Linear Independence (선형독립)

#### Definition

Let us consider a vector space  $\mathcal V$  with  $k \in \mathbb N$  and  $\mathbf x_1, \dots, \mathbf x_k \in \mathcal V$ . If only trivial solution to  $\lambda_1 \mathbf x_1 + \dots \lambda_k \mathbf x_k = \mathbf 0$  exists, i.e.,  $\lambda_1 = \dots = \lambda_k = \mathbf 0$ , then the vectors  $\mathbf x_1, \dots, \mathbf x_k$  are **linearly independent**.

#### **Examples:**

- 1. Two vectors  $[1,0]^{\top}$  and  $[0,1]^{\top}$  are independent?
- 2. Two vectors  $[1,0]^{\top}$  and  $[-1,0]^{\top}$  are independent?

$$\lambda_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \lambda_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$

This equation holds only when  $\lambda_1 = \lambda_2 = 0$ , implying that those two vectors are **linearly** independent.



## Span and Basis

The span of  $A = \{a_1, \dots, a_n\}$  is the set of all linear combinations of vectors in A:

$$span(A) = \{\alpha_1 \mathbf{a}_1 + \cdots + \alpha_n \mathbf{a}_n \mid \alpha_1, \dots, \alpha_n \in \mathbb{R}\}.$$

If A spans the vector space V, then we write

$$\mathcal{V} = \operatorname{span}(\mathcal{A}),$$

and A is called a generating set of V.

Every linear independent generating set of V is minimal and is called a basis of V.



## Span and Basis

The canonical basis in  $\mathbb{R}^3$  is

$$\left\{ \begin{bmatrix} 1\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\1 \end{bmatrix} \right\}.$$

Or alternative basis in  $\mathbb{R}^3$  is

$$\left\{ \left[\begin{array}{c} 1\\0\\0 \end{array}\right], \left[\begin{array}{c} 1\\1\\0 \end{array}\right], \left[\begin{array}{c} 1\\1\\1 \end{array}\right] \right\}.$$

Thank you

Q&A

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