

	Worst Case Scenario	Average Case Scenario	Best Case Scenario
Accessing an element	O(1)	O(1)	O(1)
Updating an element	O(1)	O(1)	O(1)
Deleting an element	O(n)	O(n)	O(1)
Inserting an element	O(n)	O(n)	O(1)
Searching for an element	O(n)	O(n)	O(1)



		Time Complexity		
	Worst Case	Average Case	Best Case	Complexity
Quicksort	O(n²)	O(n log(n))	O(n log(n))	O(log(n))
Mergesort	O(n log(n))	O(n log(n))	O(n log(n))	O(n)
Heapsort	O(n log(n))	O(n log(n))	O(n log(n))	O(1)
Bubble Sort	O(n²)	O(n²)	O(n)	O(1)
Insertion Sort	O(n²)	O(n ²)	O(n)	O(1)
Selection Sort	O(n²)	O(n ²)	O(n²)	O(1)
Binary Search	O(log(n))	O(log(n))	O(1)	O(1)
Linear Search	O(n)	O(n)	O(1)	O(1)





Time complexity.				
	Worst Case Scenario	Average Case Scenario	Best Case Scenario	
Accessing	O(1)	O(1)	O(1)	
Deleting	O(n)	O(n)	O(1)	
Inserting	O(n)	O(n)	O(1)	
Searching (n = string length m = pattern length)	O(n * m)	O(n)	O(1)	
Slicing (n = string length)	O(n)	O(n)	O(n)	
Concatenating (n, m = string lengths)	O(n + m)	O(n + m)	O(n)	
Comparison (n = shorter string length)	O(n)	O(n)	O(n)	
Inserting (Trie) (m = key length)	O(m)	O(m)	O(1)	
Searching (Trie) (m = key length)	O(m)	O(m)	O(1)	

	Ti	Time Complexity			
	Worst Case	Average Case	Best Case	Complexity	
Radix sort (m = longest string length)	O(n * m)	O(n * m)	O(n * m)	O(n + m)	
Naive string search (m = size of pattern)	O(m*(n-m+1))	O(n * m)	O(n)	O(1)	
Knuth-Morris-Pratt search	O(m + n)	O(n)	O(n)	O(m)	
Boyer-Moore string search	O(n * m)	O(n)	O(n/m)	O(m)	
Rubin-Karp Algorithm	O(m*(n-m+1))	O(n + m)	O(m)	O(m)	



	Worst Case Scenario	Average Case Scenario	Best Case Scenario
Delete (Stack)	O(1)	O(1)	O(1)
Insert (Stack)	O(1)	O(1)	O(1)
Search (Stack)	O(n)	O(n)	O(1)
Peek/Top (Stack)	O(1)	O(1)	O(1)
Delete (Queue)	O(1)	O(1)	O(1)
Insert (Queue)	O(1)	O(1)	O(1)
Search (Queue)	O(n)	O(n)	O(1)

Stacks & Queues

(Space-time complexity)

Algorithm Complexity:

	Time Complexity			Space Complexity
	Worst Case	Average Case	Best Case	
Linear Search	O(n)	O(n)	O(1)	O(1)

Stack: LIFO (Last In First Out)

Queue: FIFO (First In First Out)



	Worst Case Scenario	orst Case Scenario Average Case Scenario	
Accessing	O(n)	O(n)	O(1)
Deleting (after search)	O(1)	O(1)	O(1)
Inserting (after search)	O(1)	O(1)	O(1)
Searching	O(n)	O(n)	O(1)
Traversing	O(n)	O(n)	O(n)
Access (Skip List)	O(n)	O(log n)	O(log n)
Delete (Skip List)	O(n)	O(log n)	O(log n)
Insert (Skip List)	O(n)	O(log n)	O(log n)
Search (Skip List)	O(n)	O(log n)	O(log n)

Algorithm Complexity:

		Space Complexity		
	Worst Case	Average Case	Best Case	
Mergesort	O(n log n)	O(n log n)	O(n log n)	O(n)
Bubble Sort	O(n²)	O(n²)	O(n)	O(1)
Selection Sort	O(n²)	O(n²)	O(n²)	O(1)
Insertion Sort	O(n²)	O(n²)	O(n)	O(1)
Linear Search	O(n)	O(n)	O(1)	O(1)

Linked Lists

(Space-time complexity)



		Worst Case Scenario	Average Case Scenario	Best Case Scenario
Binary Search Tree,	Delete	O(n)	O(log n)	O(log n)
Cartesian Tree, KD Tree	Insert	O(n)	O(log n)	O(log n)
	Search	O(n)	O(log n)	O(log n)
B-Tree, Red-Black Tree,	Delete	O(log n)	O(log n)	O(log n)
Splay Tree, AVL Tree	Insert	O(log n)	O(log n)	O(log n)
	Search	O(log n)	O(log n)	O(log n)
Traversal		O(n)	O(n)	O(n)

Trees

(Space-time complexity)

	-	Time Complexity			
	Worst Case	Average Case	Best Case	Complexity	
Depth-First Search (In-order, pre-order, and post-order traversal)	O(n)	O(n)	O(n)	O(n)	
Breadth-First Search (Level-order traversal)	O(n)	O(n)	O(n)	O(n)	
Tree Sort	O(n ²)	O(n log n)	O(n log n)	O(n)	
Splaysort	O(n log n)	O(n log n)	O(n)	O(n)	
Cartesian Tree Sort	O(n log n)	O(n log n)	O(n)	O(n)	



		Worst Case Scenario	Average Case Scenario	Best Case Scenario
Insert Vertex	Adjacency List	O(1)	O(1)	O(1)
	Adjacency Matrix	O(V ²)	O(V ²)	O(V ²)
	Incidence Matrix	O(V*E)	O(V*E)	O(V*E)
Remove Vertex	Adjacency List	O(E)	O(E)	O(E)
	Adjacency Matrix	O(V ²)	O(V ²)	O(V ²)
	Incidence Matrix	O(V*E)	O(V*E)	O(V*E)
Insert Edge	Adjacency List	O(1)	O(1)	O(1)
	Adjacency Matrix	O(1)	O(1)	O(1)
	Incidence Matrix	O(V*E)	O(V*E)	O(V*E)
Remove Edge	Adjacency List	O(V)	O(V)	O(V)
	Adjacency Matrix	O(1)	O(1)	O(1)
	Incidence Matrix	O(V*E)	O(V*E)	O(V*E)
Check if	Adjacency List	O(V)	O(V)	O(V)
Vertices Adjacent	Adjacency Matrix	O(1)	O(1)	O(1)
	Incidence Matrix	O(E)	O(E)	O(E)

	Т	Time Complexity		
	Worst Case	Average Case	Best Case	
Breadth-First Search	O(V+E)	O(V+E)	O(V+E)	O(V)
Depth-First Search	O(V+E)	O(V+E)	O(V+E)	O(V)
A* Search	O(E)	O(E)	O(E)	O(V)
Dijkstra's algorithm	O(V ²)	O(E * log(V))	O(E * log(V))	O(V)
Floyd–Warshall	O(V ³)	O(V ³)	$O(V^3)$	O(V ²)





	Worst Case Scenario	Average Case Scenario	Best Case Scenario
Updating an element	O(n)	O(1)	O(1)
Inserting an element	O(n)	O(1)	O(1)
Deleting an element	O(n)	O(1)	O(1)
Searching for an element	O(n)	O(1)	O(1)
Insert (TreeMap)	O(log n)	O(log n)	O(1)
Delete (TreeMap)	O(log n)	O(log n)	O(1)
Search (TreeMap)	O(log n)	O(log n)	O(1)

	Time Complexity			Space Complexity
	Worst Case	Average Case	Best Case	Complexity
Bucket Sort (k = buckets)	O(n²)	O(n + k)	O(n + k)	O(n)
Insertion Sort	O(n²)	O(n²)	O(n)	O(1)
Selection Sort	O(n²)	O(n²)	O(n²)	O(1)
Heapsort	O(n log(n))	O(n log(n))	O(n log(n))	O(1)
Hash-based Search	O(n)	O(1)	O(1)	O(1)
Binary Search	O(log(n))	O(log(n))	O(1)	O(1)
Linear Search	O(n)	O(n)	O(1)	O(1)
Rabin-Karp Algorithm	O(m*(n-m+1))	O(n + m)	O(m)	O(m)





	Worst Case Scenario	Average Case Scenario	Best Case Scenario
Insert	O(log n)	O(logn)	O(1)
Delete	O(log n)	O(log n)	O(1)
Find min/max	O(1)	O(1)	O(1)
Search	O(n)	O(n)	O(1)
Insert (Fibonacci/Binomial)	O(log n)	O(1)	O(1)
Increase/Decrease key	O(log n)	O(log n)	O(1)
Extract min/max	O(log n)	O(log n)	O(log n)



(Space-time complexity)

	Time Complexity			Space Complexity
	Worst Case	Average Case	Best Case	
Heapsort	O(n log(n))	O(n log(n))	O(n log(n))	O(1)
Smoothsort	O(n log(n))	O(n log(n))	O(n)	O(n)
Quick select	O(n²)	O(n)	O(n)	O(1)
Linear Search	O(n)	O(n)	O(1)	O(1)
Dijkstra's shortest path	O(V ²)	O(E * log(V))	O(E * log(V))	O(V)