

2. (4 points) Transform formulas

What is the formula for the Laplace transform of a signal $f(t)$?

$$\int_0^{\infty} f(t) e^{-st} dt$$

3. (15 pts) A system is described by the differential equation

$$(D^2 - D - 12)y(t) = (D + 2)f(t)$$

and has initial conditions $y_0(0) = 1, \dot{y}_0(0) = 3$. Using **time-domain** methods:

(a) (4 pts) Determine the zero-input response of the system.

$$D^2 - D - 12 = 0$$

$$(D-4)(D+3) = 0 \quad \text{roots: } -3, 4$$

$$y(t) = A e^{-3t} + B e^{4t}$$

$$y(0) = A e^{-3 \cdot 0} + B e^{4 \cdot 0} = 1 \quad A + B = 1$$

$$-3A + 4B = 3$$

$$y'(0) = -3A e^{-3 \cdot 0} + 4B e^{4 \cdot 0} = 3 \quad A = 7, B = 6/7$$

$$y(t) = \left[\frac{1}{7} e^{-3t} + \frac{6}{7} e^{4t} \right] u(t)$$

(b) (4 pts) Given that the impulse response of the system is

$$h(t) = \left[\frac{1}{7} e^{-3t} + \frac{6}{7} e^{4t} \right] u(t),$$

Determine the zero-state response of the system if the input is $f(t) = 3e^{-5t}u(t)$.

$$H(s) = \frac{s+2}{(s-4)(s+3)} \quad \bar{F}(s) = \frac{3}{s+5}$$

$$H(s) \cdot \bar{F}(s) = \frac{3(s+2)}{(s-4)(s+3)(s+5)} \Rightarrow \frac{A}{s-4} + \frac{B}{s+3} + \frac{C}{s+5} \Rightarrow \begin{aligned} A &= \frac{2}{7} \\ B &= 3/19 \\ C &= -1/2 \end{aligned}$$

$$\frac{2/7}{s-4} + \frac{3/14}{s+3} - \frac{1/2}{s+5} \Rightarrow \left[\frac{2}{7} e^{4t} + \frac{3}{14} e^{-3t} - \frac{1}{2} e^{-5t} \right] u(t)$$

(c) (2 pts) Determine the total response of the system.

$$R_{tot} = Zsr + ZiR = \left[\frac{1}{7} e^{-3t} + \frac{6}{7} e^{4t} \right] u(t) + \left[\frac{2}{7} e^{4t} + \frac{3}{14} e^{-3t} - \frac{1}{2} e^{-5t} \right] u(t)$$

$$= \left[\frac{8}{7} e^{4t} + \frac{5}{14} e^{-3t} - \frac{1}{2} e^{-5t} \right] u(t)$$

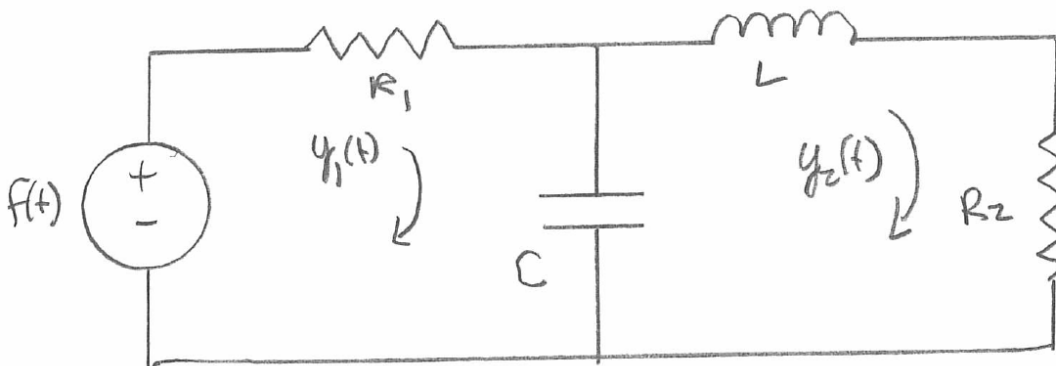
(d) (1 pt) Is the system linear? ☒ yes ☐ no. (circle the correct answer)

(f) (1 pt) Is the system dynamic? ☒ yes ☐ no.

(g) (1 pt) Is the system time-invariant? ☒ yes ☐ no.

(h) (1 pt) Is the system continuous-time? ☒ yes ☐ no.

4. (8 pts) For the circuit below:



(a) (3 pts) Write the **integro-differential** equations (equations with differentials and integrals) for two loops (one equation for each loop), where the elements $f(t)$, R_1 , and C are in the first loop, and L , R_2 , and C are in the second loop. Use loop currents $y_1(t)$ and $y_2(t)$ as shown.

$$f(t) = y_1(t) \cdot R_1 + \frac{1}{C} \int_{t_0}^t y_1(\tau) d\tau - \frac{1}{C} \int_{t_0}^t y_2(\tau) d\tau$$

$$0 = y_2(t) \cdot R_2 + \frac{1}{C} \int_{t_0}^t y_2(\tau) d\tau - \frac{1}{C} \int_{t_0}^t y_1(\tau) d\tau + L \frac{dy_2(t)}{dt}$$

- (b) (3 pts) Express these two equations as a pair of **differential** equations. (Use the D operator in your equations.)

$$\left(R_1 D + \frac{1}{C}\right) y_1(t) = \frac{1}{C} y_2(t) + f(t)$$

$$\frac{1}{C} y_1(t) = \left(L D^2 + R_2 D + \frac{1}{C}\right) y_2(t)$$

- (c) (2 pts) What initial conditions would you **measure** in the circuit to find the zero-input solution? (Do **not** compute initial conditions for the solution.)

$$V_C(0^-) \text{ \& \& } I_L(0^-)$$

5. (6 pts) Convolution

- (a) (3 pts) The unit impulse response of an LTI system is $h(t) = (1 - 5t)e^{-4t}u(t)$. Find this system's (zero-state) response $y(t)$ if the input is $f(t) = u(t)$.

$$H(s) = \frac{Y(s)}{X(s)} \quad \mathcal{L}[h(t)] = H(s) = \frac{s-1}{(s+4)^2}$$

$$\mathcal{L}[f(t)] = X(s) = \frac{1}{s}$$

$$ZSR = \mathcal{L}^{-1}[Y(s)] = \mathcal{L}^{-1}\left[\frac{s-1}{s(s+4)^2}\right] = \boxed{\frac{1}{16}e^{-4t} + \frac{5}{4}te^{-4t} - \frac{1}{16}}$$

$$\frac{A}{s+4} + \frac{B}{s+4}^2 + \frac{C}{s} \quad \begin{aligned} A &= 1/16 \\ B &= 5/4 \\ C &= -1/16 \end{aligned}$$

- (b) (3 pts) The unit impulse response of an LTI system is $h(t) = e^{-3t}u(t)$. Find this system's (zero-state) response $y(t)$ if the input is $f(t) = \cos(2t)u(t)$.

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$$\left[\frac{1}{s+3} \right] \left[\frac{5}{s^2+4} \right] = \frac{5}{(s+3)(s^2+4)}$$

$$= \frac{A}{s+3} + \frac{B}{s^2+4} \quad A = -\frac{3}{13}$$

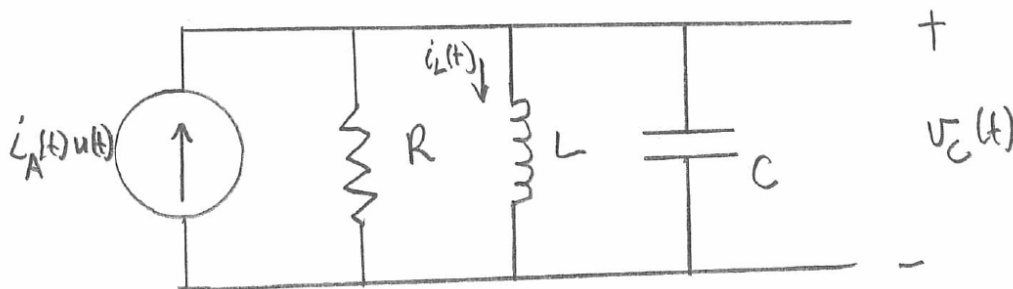
$$B = \frac{3}{13}s + \frac{4}{13}$$

$$\mathcal{L}^{-1} \left[\frac{\frac{3}{13}s + \frac{4}{13}}{s^2+4} - \frac{\frac{3}{13}}{s+3} \right] =$$

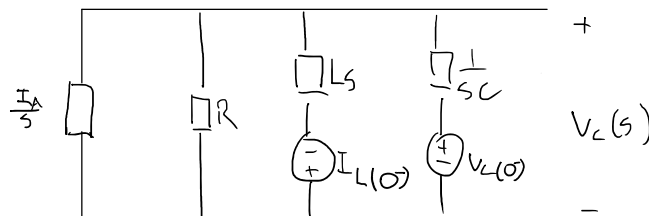
$$\left[\frac{3}{13} \cos(2t) + \frac{2}{13} \sin(2t) - \frac{3}{13} e^{-3t} \right] u(t)$$

6. Laplace domain circuit analysis (5 pts.)

For the following circuit, $v_C(0^-) = 20$ and $i_L(0^-) = 5$.



- (a) (2 pts) Transform the circuit into the s (Laplace) domain (including initial conditions).



- (b) (3 pts) Solve the system for $V_C(s)$. Leave the solution as a function of L , R , and C . (Hint: use admittances.)

$$0 = \frac{V_C}{I_A/s} + \frac{V_C}{R} + \frac{V_C + I_L(0)}{Ls} + \frac{V_C - V_C(0)}{1/sC}$$

$$0 = \frac{V_L s}{I_A} + \frac{V_C}{R} + \frac{V_C + I_L(0)}{Ls} + (V_C - V_C(0))sC$$

$$0 = \frac{I_A}{V_C s} + \frac{R}{V_C} + \frac{Ls}{V_C} + \frac{Ls}{I_L(0)} + \frac{1}{V_C sC} - \frac{1}{V_C(0)sC}$$

$$0 = \frac{V_C s}{I_A} + \frac{V_C}{R} + \frac{V_C}{Ls} + \frac{I_L(0)}{Ls} + V_C sC - V_C(0)sC$$

$$0 = \left[\frac{1}{I_A} + \frac{1}{R} + \frac{1}{Ls} + sC \right] V_C + \frac{I_L(0)}{Ls} - V_C(0)sC$$

$$- \frac{I_L(0)}{Ls} + V_C(0)sC = \left[\frac{1}{I_A} + \frac{1}{R} + \frac{1}{Ls} + sC \right] V_C$$

$$\frac{- \frac{I_L(0)}{Ls} + V_C(0)sC}{\left[\frac{1}{I_A} + \frac{1}{R} + \frac{1}{Ls} + sC \right]} = V_C$$

$$V_C = \left(- \frac{I_L(0)}{Ls} + V_C(0)sC \right) \left[I_A + R + Ls + \frac{1}{sC} \right]$$

7. Finding the output of a circuit with Laplace transforms (10 pts.)

Given the following equation from circuit analysis,

$$s^2 Y(s) + 8sY(s) + 116Y(s) - sy(0^-) - \dot{y}(0^-) - 10y(0^-) = -20(s + 29)F(s),$$

with $y(0^-) = 2$, $\dot{y}(0^-) = 10.3607$, and $f(t) = u(t)$:

(a) (2 pts) Find the transfer function of the circuit.

$$\frac{-20s - 580}{s^2 + 8s + 116}$$

(b) (3 pts) Find the zero-input solution part of $y(t)$ using Laplace transforms. Express your answer in terms of real functions.

$$s^2 Y + 8sY + 116Y - 2s - 10.3607 - 20 = 0$$

$$s^2 Y + 8sY + 116Y = 2s + 30.3607$$

$$Y + 8Y + 116Y = 20 + 30.3607$$

$$Y(s) = \frac{25 + 30.3607}{s^2 + 8s + 116} \Rightarrow e^{-4t} \left[2 \cos(10t) + 2.2 \sin(10t) \right] u(t)$$

(c) (3 pts) Find the zero-state solution part of $y(t)$ using Laplace transforms. Express your answer in terms of real functions. (Hint: math helps.)

$$\frac{-20s - 580}{s^2 + 8s + 116} \cdot \frac{1}{s} = \frac{-20s - 580}{s^3 + 8s^2 + 116s}$$

(d) (2 pts) Find $y(t)$.

$$\left[e^{-4t} \left[2 \cos(10t) + 2.2 \sin(10t) \right] + \right] u(t)$$