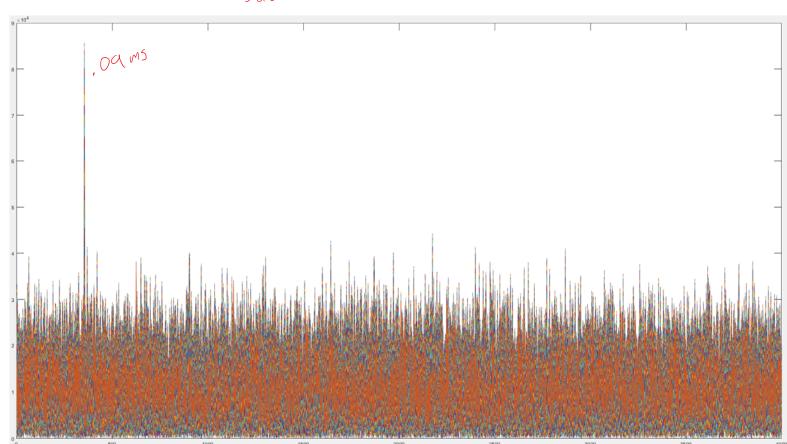
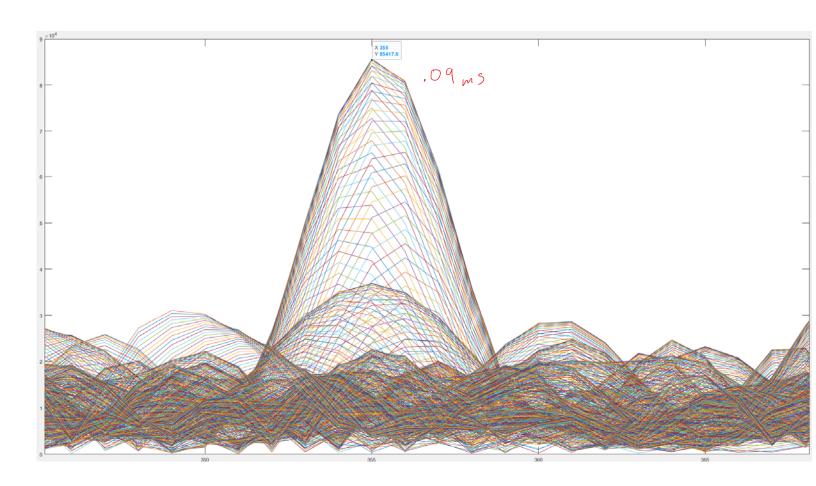
Visible Satellites:	Time delay (milliseconds)	Doppler Frequency (Hertz)
1	.997	
11	.089	
20	.313	
32	.923	-6500

Satellite #11



Satellite #11



% Set up some important variables

Fs = 4e6; % Sample rate of data [samples/second]

% GPS matched filter impulse responses prn_code_id = [1:37]; %#ok<*NBRAK> % PRN code IDs for GPS satellites (32 + extras = 37) for i=1:length(prn_code_id) mf(:,i) = build_matched_filter(prn_code_id(i),Fs); end [Nh,~] = size(mf); % Get the length of the matched filter impulse response

% Parameters for fast convolution $N = 2^{17}; \% \text{ FFT size [samples]}$ MF = fft(mf,N); % Compute zero-padded DFT of matched filters for frequency-domain processing

% Parameters for doppler frequency search Fmax = 8000; % Maximum doppler frequency [Hz] Fmin = -Fmax; % Minimum doppler frequency [Hz] Fbin = Fs/N; % FFT bin width [Hz] KFmax = ceil(Fmax/Fbin); % Number of frequency bins (positive side) KFmin = floor(Fmin/Fbin); % Number of frequency bins (negative side) ksearch = [KFmin:KFmax]; % Set of bins for doppler frequency sesarch

% Read gps.dat

fid = fopen('gps.dat','rb'); % Open the file for binary read Nx = N - Nh + 1; % Number of data samples so that Nx +

```
Nh - 1 = N
x = fread(fid,2*Nx,'int16=>float32'); % Read samples and
convert from short to float
fclose(fid); % Close the file
x = complex(x(1:2:end), x(2:2:end)); % Convert
interleaved real-imaginary to complex
% Transform and search
X = fft(x,N); % Compute zero-padded DFT of samples in x
% Begin search for i=1:size(MF,2) % For loop over satellites
  figure(i);
 for k=1:length(ksearch) % For loop over cyclic shifts
(doppler frequency search)
    %shift, convolve, inverse FFT
   y = ifft(circshift(X,ksearch(k)).*MF(:,i));
    %trim
   y = y(Nh:2*Nh-1); % trim
    %add to plot
   plot(abs(y)); hold on;
 end
 hold off;
```

end