```
!pip install -U pm4py
!pip install visualization
import pandas as pd
from pm4py.objects.conversion.log import converter as log_converter
from pm4py.objects.log.importer.xes import importer as xes importer
from pm4py.objects.log.util import dataframe_utils
from pm4py.algo.discovery.inductive import algorithm as inductive_miner
from pm4py.algo.discovery.alpha import algorithm as alpha_miner
from pm4py.algo.discovery.heuristics import algorithm as heuristics_miner
from pm4py.algo.discovery.dfg import algorithm as dfg_discovery
from pm4py.visualization.dfg import visualizer as dfg_visualization
from sklearn.metrics import pairwise_distances_argmin
from pm4py.objects.conversion.log import converter as log converter
from pm4py.algo.discovery.alpha import algorithm as alpha_miner
from pm4py.visualization.petri_net import visualizer as pn_visualizer
from pm4py.visualization.petri_net.util import performance_map
from pm4py.visualization.process_tree import visualizer as pt_visualizer
from pm4py.visualization.heuristics_net import visualizer as hn_visualizer
from pm4py.visualization.process_tree import visualizer as pt_visualizer
from pm4py.objects.conversion.process_tree import converter as pt_converter
from pm4py.objects.conversion.log import converter as log_converter
from pm4py.objects.log.importer.xes import importer as xes_importer
from pm4py.algo.discovery.alpha import algorithm as alpha_miner
from pm4py.algo.discovery.inductive import algorithm as inductive_miner
from pm4py.algo.discovery.heuristics import algorithm as heuristics miner
from pm4py.algo.discovery.dfg import algorithm as dfg_discovery
from pm4py.visualization.process_tree import visualizer as pt_visualizer
from pm4py.visualization.heuristics_net import visualizer as hn_visualizer
from pm4py.visualization.dfg import visualizer as dfg_visualization
     Requirement already satisfied: six>=1.5 in /usr/local/lib/python3.9/dist-packages (from python-dateutil>=2.7->matplotlib->pm4py) (1.1 -
     Looking in indexes: https://pypi.org/simple, https://us-python.pkg.dev/colab-wheels/public/simple/
     Requirement already satisfied: visualization in /usr/local/lib/python3.9/dist-packages (1.0.0)
    Requirement already satisfied: numpy in /usr/local/lib/python3.9/dist-packages (from visualization) (1.22.4)
     Requirement already satisfied: matplotlib in /usr/local/lib/python3.9/dist-packages (from visualization) (3.7.1)
     Requirement already satisfied: autolab-core in /usr/local/lib/python3.9/dist-packages (from visualization) (1.1.1)
     Requirement already satisfied: trimesh[easy] in /usr/local/lib/python3.9/dist-packages (from visualization) (3.21.5)
    Requirement already satisfied: pyrender in /usr/local/lib/python3.9/dist-packages (from visualization) (0.1.35)
    Requirement already satisfied: imageio in /usr/local/lib/python3.9/dist-packages (from visualization) (2.25.1)
     Requirement already satisfied: scikit-learn in /usr/local/lib/python3.9/dist-packages (from autolab-core->visualization) (1.2.2)
     Requirement already satisfied: scikit-image in /usr/local/lib/python3.9/dist-packages (from autolab-core->visualization) (0.19.3)
    Requirement already satisfied: joblib in /usr/local/lib/python3.9/dist-packages (from autolab-core->visualization) (1.2.0)
     Requirement already satisfied: opencv-python in /usr/local/lib/python3.9/dist-packages (from autolab-core->visualization) (4.7.0.72)
     Requirement already satisfied: ruamel.yaml in /usr/local/lib/python3.9/dist-packages (from autolab-core->visualization) (0.17.21)
     Requirement already satisfied: Pillow in /usr/local/lib/python3.9/dist-packages (from autolab-core->visualization) (8.4.0)
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     Requirement already satisfied: requests in /usr/local/lib/python3.9/dist-packages (from trimesh[easy]->visualization) (2.27.1)
     Requirement already satisfied: zipp>=3.1.0 in /usr/local/lib/python3.9/dist-packages (from importlib-resources>=3.2.0->matplotlib->vi
     Requirement already satisfied: pyrsistent!=0.17.0,!=0.17.1,!=0.17.2,>=0.14.0 in /usr/local/lib/python3.9/dist-packages (from jsonsche
     Requirement already satisfied: attrs>=17.4.0 in /usr/local/lib/python3.9/dist-packages (from jsonschema->trimesh[easy]->visualization
     Requirement already satisfied: dill>=0.3.6 in /usr/local/lib/python3.9/dist-packages (from multiprocess->autolab-core->visualization)
     Requirement already satisfied: urllib3<1.27,>=1.21.1 in /usr/local/lib/python3.9/dist-packages (from requests->trimesh[easy]->visuali
     Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.9/dist-packages (from requests->trimesh[easy]-visualizat
     Requirement already satisfied: charset-normalizer~=2.0.0 in /usr/local/lib/python3.9/dist-packages (from requests->trimesh[easy]->vis
     Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.9/dist-packages (from requests->trimesh[easy]->visualization) (
     Requirement already satisfied: ruamel.yaml.clib>=0.2.6 in /usr/local/lib/python3.9/dist-packages (from ruamel.yaml->autolab-core->vis
     Requirement already satisfied: tifffile>=2019.7.26 in /usr/local/lib/python3.9/dist-packages (from scikit-image->autolab-core->visual
     Requirement already satisfied: PyWavelets>=1.1.1 in /usr/local/lib/python3.9/dist-packages (from scikit-image->autolab-core->visualiz
     Requirement already satisfied: threadpoolctl>=2.0.0 in /usr/local/lib/python3.9/dist-packages (from scikit-learn->autolab-core->visua
log = xes_importer.apply('running-example.xes')
     parsing log, completed traces ::
                                                                   6/6 [00:00<00:00,
                                                                   404 70:4/-1
                                                                                                                                           df = pd.read_csv('running-example.csv')
df = dataframe_utils.convert_timestamp_columns_in_df(df)
df = df.sort_values('time:timestamp')
log = log converter.apply(df)
                                                                                                                                           df.sort_values(['case:concept:name', 'time:timestamp']).reset_index(drop=True)
```

4							
	examine casually	Fluxicon Nitro	2	Sean	400	examine casually	7
	decide	Fluxicon Nitro	2	Sara	200	decide	8
	pay compensation	Fluxicon Nitro	2	Ellen	200	pay compensation	9
	registe reques	Fluxicon Nitro	3	Pete	50	register request	10
-	examine casually	Fluxicon Nitro	3	Mike	400	examine casually	11
t	check ticke	Fluxicon Nitro	3	Ellen	100	check ticket	12
	decide	Fluxicon Nitro	3	Sara	200	decide	13
- 10	reinitiate reques	Fluxicon Nitro	3	Sara	200	reinitiate request	14
-	examine thoroughly	Fluxicon Nitro	3	Sean	400	examine thoroughly	15
t	check ticke	Fluxicon Nitro	3	Pete	100	check ticket	16
	decide	Fluxicon Nitro	3	Sara	200	decide	17
-	pay compensation	Fluxicon Nitro	3	Ellen	200	pay compensation	18
	registe reques	Fluxicon Nitro	4	Pete	50	register request	19
t	check ticke	Fluxicon Nitro	4	Mike	100	check ticket	20
	examine thoroughly	Fluxicon Nitro	4	Sean	400	examine thoroughly	21
2	decide	Fluxicon Nitro	4	Sara	200	decide	22
t	reject reques	Fluxicon Nitro	4	Ellen	200	reject request	23
	registe reques	Fluxicon Nitro	5	Ellen	50	register request	24
	examine casually	Fluxicon Nitro	5	Mike	400	examine casually	25
t ,	check ticke	Fluxicon Nitro	5	Pete	100	check ticket	26

```
net, initial_marking, final_marking = alpha_miner.apply(log)
gviz = pn_visualizer.apply(net, initial_marking, final_marking)
pn_visualizer.view(gviz)
```

```
reject request

pay compensation

examine thoroughly

reinitiate request

register request

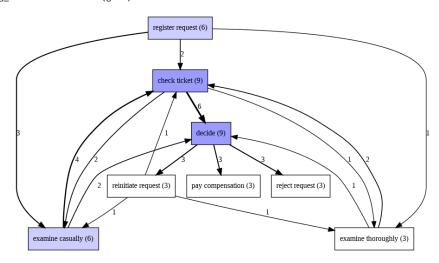
check ticket
```

replaying log with TBR, completed 6/6 [00:00<00:00,

pn_visualizer.save(gviz, "alpha_miner_petri_net.png")

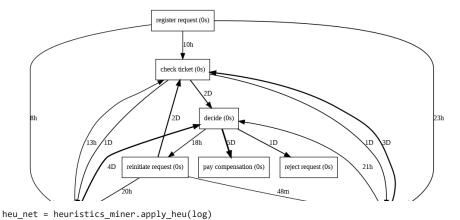
dfg = dfg_discovery.apply(log)

 $\label{eq:gvisualization.apply} $$ gviz = dfg_visualization.Variants.FREQUENCY) $$ dfg_visualization.view(gviz) $$$

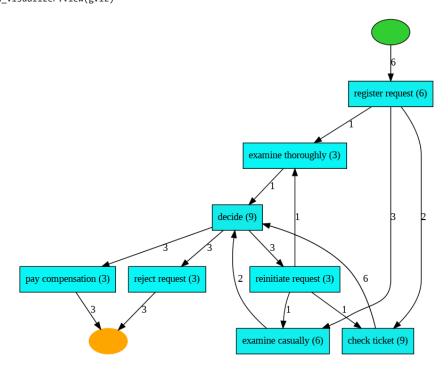


 $\tt dfg = dfg_discovery.apply(log, variant=dfg_discovery.Variants.PERFORMANCE)$

gviz = dfg_visualization.apply(dfg, log=log, variant=dfg_visualization.Variants.PERFORMANCE)
dfg_visualization.view(gviz)

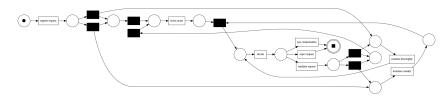


gviz = hn_visualizer.apply(heu_net)
hn_visualizer.view(gviz)



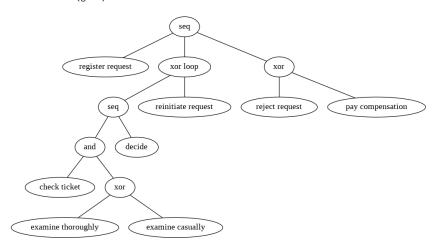
net, im, fm = heuristics_miner.apply(log)

gviz = pn_visualizer.apply(net, im, fm)
pn_visualizer.view(gviz)



tree = inductive_miner.apply(log)

gviz = pt_visualizer.apply(tree)
pt_visualizer.view(gviz)



Double-click (or enter) to edit