

Week 1

1.1 Gaussian Curvature (Neves)

6/28:

- Plan:
 1. What is a surface?
 2. What is the tangent space?
 3. What are the principal curvatures?
 4. What is the Gaussian curvature?
- In analysis:
 1. What is a function?
 2. What is the derivative?
 3. What is the Hessian of function?
 4. 2nd derivative test (determinant of Hessian).
- **Surface:** A subset $\sigma \subseteq \mathbb{R}^3$ such that for all $p \in \Sigma$, there's a neighborhood B of p in \mathbb{R}^3 so that $\Sigma \cap B$ "looks like a disk." More precisely, there exists an open neighborhood $U \subseteq \mathbb{R}^2$ and a map $\varphi : U \rightarrow \Sigma \cap B \subseteq \mathbb{R}^3$ such that
 - i) φ is continuous and smooth.
 - ii) φ is a bijection (with φ^{-1} continuous).
 - iii) $d\varphi|_x : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ is injective for all $x \in U$.
- **Chart:** The quantity (φ, U) near $p \in U$.
- Examples:
 - A) Plane. $\Sigma = \mathbb{R}^2 \times \{0\} \subseteq \mathbb{R}^3$ is a surface with chart $\varphi : \mathbb{R}^2 \rightarrow \Sigma$ where $(x, y) \mapsto (x, y, 0)$.
 - B) Sphere. $\Sigma = \{\vec{u} \in \mathbb{R}^3 \mid |\vec{u}| = 1\}$.
 - Charts: Consider the sets $U = \{(x_1, x_2) \mid x_1^2 + x_2^2 < 1\} \subseteq \mathbb{R}^2$. Let $\varphi_1^+ : U \rightarrow \Sigma \cap \{(x, y, z) \mid x > 0\}$ be defined by $\varphi_1^+(u_1, u_2) = (\sqrt{1 - x_1^2 - x_2^2}, u_1, u_2)$, $\varphi_1^- : U \rightarrow \Sigma \cap \{(x, y, z) \mid x < 0\}$ be defined by $\varphi_1^-(u_1, u_2) = (-\sqrt{1 - x_1^2 - x_2^2}, u_1, u_2)$.
 - Same thing for $\varphi_2^\pm, \varphi_3^\pm$.
 - C) A cone $\Sigma = \{(x, y, z) \mid z = \sqrt{x^2 + y^2}\}$ is *not* a surface because it fails property (iii).
 - D) The closed unit disk $\Sigma = \{(x, y, 0) \mid x^2 + y^2 \leq 1\}$ is also not a surface.
- **Tangent space:** Let $\Sigma \subseteq \mathbb{R}^3$ be a surface and let $p \in \Sigma$. Then $T_p \Sigma \subseteq \mathbb{R}^3$ is the z -plane so that $p + T_p \Sigma$ is the affine plane that best approximates Σ near p .
 - Best linear approximation near the surface.

- Very similar/analogous to the derivative.
- If (φ, U) is a chart near p , then $T_p\Sigma = \text{span} \left\{ \frac{\partial \varphi}{\partial x_1}(\bar{x}_1, \bar{x}_2), \frac{\partial \varphi}{\partial x_2}(\bar{x}_1, \bar{x}_2) \right\}$.
- Proves linear independence of above vectors.
- Principal curvatures.
- Let $\Sigma \subseteq \mathbb{R}^3$ be a surface, $p \in \Sigma$, and \vec{N} be a unit normal vector defined around p (i.e., $\vec{N}(q) \cdot \vec{v} = 0$ for all q near p and $\vec{v} \in T_q\Sigma$).
- Choose $\vec{v} \in T_p\Sigma$ such that $|\vec{v}| = 1$. Set $P_v = \text{span} \{ \vec{v}, \vec{N}(p) \}$. Claim: $(\Sigma - p) \cap P_v$ is a curve near the origin.
- **Principal curvature:** The reciprocal of the radius of the circle in P_v that best approximates $(\Sigma - p) \cap P_v$ near the origin. *Also known as $\mathbf{K}(\vec{v})$.*
 - The sign is positive if the center of the circle is in the direction of $\vec{N}(p)$ and negative otherwise.
 - If the sign of $\vec{N}(p)$ changes, then $K(\vec{v})$ will change in sign.
- If we change \vec{N} by $-\vec{N}$, then the new $K(\vec{v})$ is the opposite of the old one.
- Given $p \in \Sigma$ and $\vec{N}(p)$ a normal vector at p , we define $K_1(p)$ to have the maximum $K(\vec{v})$ over all unit vectors $\vec{v} \in T_p\Sigma$ and $K_2(p) = \min\{K(\vec{v}) \mid \vec{v} \in T_p\Sigma, |\vec{v}| = 1\}$.
- K_1, K_2 are computable quantities.