

# Chapter 17

## Vector Analysis

### 17.1 Introduction: Vector Fields

- 12/29:
- In this chapter, we will consider vector functions of several variables, such as the function giving the velocity  $\mathbf{v} = \mathbf{F}(x, y, z, t)$  of a particle in a fluid located at position  $(x, y, z)$  at time  $t$ .
  - **Steady-state flow:** A flow for which the velocity function does not depend on the time  $t$ .
  - **Vector field:** The collection of all vectors  $\mathbf{F}(P)$  assigned to each point  $P$  in a region  $G$ .
  - **Gradient field:** The vector field defined for points in the domain  $G$  of a scalar function  $T$  such that  $\mathbf{F}(P) = \nabla T(P)$ .

### 17.2 Surface Integrals

- 12/30:
- Just like we have  $ds = \sqrt{1 + f_x^2} dx$ , we have

$$d\sigma = g(x, y) dA$$

where  $d\sigma$  is “an element of surface area in the tangent plane that approximates the corresponding portion  $\Delta\sigma$  of the surface itself” (Thomas, 1972, p. 581) and  $g(x, y) = \sqrt{1 + f_x^2 + f_y^2}$ .

- Thus, we can think of surface area as either the lefthand or righthand side of the below equation.

$$\iint_{\Sigma} d\sigma = \iint_R g(x, y) dA$$

- The lefthand interpretation sums infinitely many, infinitely small pieces  $d\sigma$  of the surface  $\Sigma$ .
- The righthand interpretation sums infinitely many, infinitely small pieces  $dA$  of the shadow  $R$  of the surface  $\Sigma$  on the  $xy$ -plane, adjusted by the factor  $g(x, y)$ .
- These formulations are important because sometimes we want to conceive and evaluate an integral of the form  $\iint_{\Sigma} h(x, y, z) d\sigma$ .
- **Surface integral** (of  $h(x, y, z)$  over the surface  $\Sigma$ ): The limit as  $\Delta\sigma \rightarrow 0$  of the sum of every  $\Delta\sigma_k$  (composing  $\Sigma$ ) times  $h(x, y, z)$  for some  $(x, y, z) \in \Delta\sigma_k$ . Mathematically,

$$\iint_{\Sigma} h(x, y, z) d\sigma = \lim_{\Delta\sigma \rightarrow 0} \sum_{k=1}^n h(x_k, y_k, z_k) \Delta\sigma_k$$

- Consider a surface  $\Sigma$  consisting of all points  $P(x, y, z)$  satisfying  $z = f(x, y)$  for  $(x, y) \in R$ , where  $R$  is a closed, bounded region of the  $xy$ -plane and  $f, f_x, f_y$  are continuous throughout  $R$  and its boundary.
- Approximate  $R$  by dividing it into  $n$  rectangles using lines parallel to the  $y$ -axis spaced  $\Delta x$  apart and lines parallel to the  $x$ -axis spaced  $\Delta y$  apart.
- Let the part of  $\Sigma$  above each rectangle be denoted by  $\Delta\sigma_k$  for some  $1 \leq k \leq n$ .
- Now if  $P_k(x_k, y_k, z_k)$  is a point in  $\Delta\sigma_k$ , we can consider the above sum and take its limit.