Week 4

10/18:

Vibrational Motion and the Harmonic Oscillator

4.1 Rotational Motion

• Consider the diatomic molecule AB at a distance r_0 apart rotating about its center of mass.

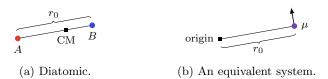


Figure 4.1: Diatomic rotation.

- To simplify the problem, replace the two particles rotating about the center of mass with one particle of reduced mass μ rotating about the center of mass with lever arm r_0 .
- Classically, the kinetic energy of the translational motion is

$$T = \frac{L^2}{2I}$$

where $I = \mu r_0^2$ and $L = p \times r_0 = pr_0$ (for this kind of rotation; see Figure 4.1b).

- To further talk about this problem, we should introduce spherical coordinates.
- Spherical coordinates: The coordinate system (r, θ, ϕ) related to the Cartesian coordinates (x, y, z) by

$$x = r \sin \theta \cos \phi$$
 $y = r \sin \theta \sin \phi$ $z = r \cos \theta$

• Classically, we will have

$$H = \frac{1}{2\mu}(p_x^2 + p_y^2 + p_z^2) + V(x, y, z)$$

in Cartesian coordinates.

• In spherical coordinates, this becomes

$$H = \frac{1}{2\mu} \left(p_r^2 + \frac{L^2}{r^2} \right) + V(r)$$

• Thus, in quantum mechanics, we get

$$\hat{H} = \frac{1}{2\mu} (\hat{p}_x^2 + \hat{p}_y^2 + \hat{p}_z^2) + V(x, y, z)$$
$$= \frac{1}{2\mu} \left(\hat{p}_r^2 + \frac{\hat{L}^2}{r^2} \right) + V(r)$$

• Thus, we have in spherical coordinates that

$$\hat{T}\psi = -\frac{\hbar^2}{2\mu} \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \psi \right) + \frac{1}{r^2 \sin \theta} \left(\frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \psi \right) \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \psi \right]$$

- 2D rigid rotor:
 - Let the system from Figure 4.1b be confined to rotating in two dimensions.
 - This simplifies the problem since both the $\partial/\partial r$ and $\partial/\partial \theta$ terms in the kinetic energy operator disappear (since, respectively, the particle is at a fixed distance from the center of mass and it cannot move out of the 2D plane).
 - Thus, our Schrödinger equation for this system is

$$-\frac{\hbar^2}{2\mu r_0^2}\frac{\partial^2}{\partial \phi^2}\psi(\phi) = E\psi(\phi)$$

- Solution: Let $\psi(\phi) = e^{im\phi}$; then

$$E_m = \frac{\hbar^2 m^2}{2\mu r_0^2}$$

- \blacksquare m = 0, 1, 2, ... is a new quantum number.
- \blacksquare m doesn't go to infinity because |m| is bounded by ℓ (the total angular momentum).
- Remembering our original restriction, we have that this math describes the system from Figure 4.1a but confined to rotate in the xy plane with angular momentum in the z direction.
 - Thus, for example, the energies of the system from Figure 4.1a are dependent on m and $I = \mu r_0^2$.
- Such a system occurs in physical reality when we put the diatomic in an external field, or attach to it a big functional group.
- Zero point energy: m=0 does not violate the UR since we still have $\Delta L \Delta \theta \geq \hbar/2$ (as everything is still rotating in the sense that we have equal probability of the particle being everywhere [as opposed to more localized/normal rotation with higher values of m]).
- 3D rigid rotor:
 - Assume that the potential energy is zero on the surface of the sphere (so we basically have a particle on a sphere).
 - Then

$$\hat{H} = \frac{\hat{L}^2}{2\mu r_0^2} = \frac{\hat{L}^2}{2I}$$

- Solving $\hat{H}\psi = E\psi$ asserts that the eigenfunctions of the Hamiltonian are the spherical harmonics $Y_{\ell m}(\theta,\phi)$.
- Energy:

$$E_{\ell} = \frac{\hbar^2}{2I}\ell(\ell+1)$$

where $\ell = 0, 1, 2, ...$

- Recall that m corresponds to the projection of angular momentum onto the z-axis, so that

$$m = -\ell, \ldots, +\ell$$