## Chapter 3

# Linear Maps

## 3.A The Vector Space of Linear Maps

• Linear map (from V to W): A function  $T:V\to W$  with the following properties. Also known as linear transformation.

#### additivity

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T(u+v) = Tu + Tv for all  $u, v \in V$ .

#### homogeneity

 $T(\lambda v) = \lambda(Tv)$  for all  $\lambda \in \mathbb{F}$  and all  $v \in V$ .

- Note that for linear maps, Tv means the same as the more standard functional notation T(v).
- $\mathcal{L}(V, W)$ : The set of all linear maps from V to W.
- **Zero map**: The function  $0 \in \mathcal{L}(V, W)$  that takes each element of some vector space to the additive identity of another vector space. Defined by

$$0v = 0$$

• Identity map: The function  $I \in \mathcal{L}(V, V)$  on some vector space that takes each element to itself. Defined by

$$Iv = v$$

- We can also formalize more esoteric linear processes as linear maps.
  - For example,  $D \in \mathcal{L}(\mathcal{P}(\mathbb{R}), \mathcal{P}(\mathbb{R}))$  can be thought of as the differentiation map Dp = p'. This formalizes the fact that (f+g)' = f' + g' and  $(\lambda f)' = \lambda f'$ .
  - We can do the same with integration: Let  $T \in \mathcal{L}(\mathcal{P}(\mathbb{R}), \mathbb{R})$  be described by  $Tp = \int_0^1 p(x) dx$ . This formalizes the fact that integrals are additive and homogeneous.
  - Axler (2015) gives a number more examples.
- We now prove that there exists a unique linear map from a vector space of dimension n to any n vectors in another vector space.

**Theorem 3.1.** Suppose  $v_1, \ldots, v_n$  is a basis of V and  $w_1, \ldots, w_n \in W$ . Then there exists a unique linear map  $T: V \to W$  such that  $Tv_j = w_j$  for each  $j = 1, \ldots, n$ .

*Proof.* First, we define a function  $T: V \to W$ . We then show that T satisfies the specified property. After that, we show that it is a linear map. Lastly, we show that it is unique. Let's begin.

Let  $T: V \to W$  be defined by

$$T(c_1v_1 + \dots + c_nv_n) = c_1w_1 + \dots + c_nw_n$$

for all  $c_1v_1 + \cdots + c_nv_n \in V$ . Note that this definition is valid since, by Theorem 2.5, each  $v \in V$  can be written in the form  $c_1v_1 + \cdots + c_nv_n$  where  $c_1, \ldots, c_n \in \mathbb{F}$ .

To prove that  $Tv_j = w_j$  for all j = 1, ..., n, let each  $c_i$  in the above definition equal 0 save  $c_j$ , which we set equal to 1. Then we have

$$T(0v_1 + \dots + 0v_{j-1} + 1v_j + 0v_{j+1} + \dots + 0v_n) = 0w_1 + \dots + 0w_{j-1} + 1w_j + 0w_{j+1} + \dots + 0w_n$$
$$T(v_j) = w_j$$

as desired.

To prove that T is a linear map, it will suffice to verify additivity and homogeneity, which we may do as follows. Let  $u, v \in V$  with  $u = a_1v_1 + \cdots + a_nv_n$  and  $v = c_1v_1 + \cdots + c_nv_n$ , and let  $\lambda \in \mathbb{F}$ . Then

$$T(u+v) = T((a_1 + c_1)v_1 + \dots + (a_n + c_n)v_n)$$
  
=  $(a_1 + c_1)w_1 + \dots + (a_n + c_n)w_n$   
=  $Tu + Tv$ 

and

$$T(\lambda v) = T(\lambda c_1 v_1 + \dots + \lambda c_n v_n)$$
  
=  $\lambda c_1 w_1 + \dots + \lambda c_n w_n$   
=  $\lambda T v$ 

as desired.

Now suppose  $\tilde{T} \in \mathcal{L}(V,W)$  satisfies  $\tilde{T}v_j = w_j$  for all  $j = 1, \ldots, n$ . To prove that  $T = \tilde{T}$ , it will suffice to show that  $\tilde{T}(c_1v_1 + \cdots + c_nv_n) = T(c_1v_1 + \cdots + c_nv_n)$  for all  $c_1v_1 + \cdots + c_nv_n \in V$ . Let  $c_1v_1 + \cdots + c_nv_n \in V$  be arbitrary. We know that  $\tilde{T}(v_j) = w_j$  for all  $j = 1, \ldots, n$ . It follows since  $\tilde{T}$  is a linear map (specifically, since it's homogeneous) that  $c_jw_j = c_j\tilde{T}(v_j) = \tilde{T}(c_jv_j)$  for all  $j = 1, \ldots, n$ . Similarly, the additivity of  $\tilde{T}$  implies that

$$T(c_1v_1 + \dots + c_nv_n) = c_1w_1 + \dots + c_nw_n$$
$$= \tilde{T}(c_1v_1) + \dots + \tilde{T}(c_nv_n)$$
$$= \tilde{T}(c_1v_1 + \dots + c_nv_n)$$

as desired.

- Sum (of  $S, T \in \mathcal{L}(V, W)$ ): The linear map  $(S + T) \in \mathcal{L}(V, W)$  defined by (S + T)(v) = Sv + Tv for all  $v \in V$ .
- **Product** (of  $T \in \mathcal{L}(V, W)$  and  $\lambda \in \mathbb{F}$ ): The linear map  $(\lambda T) \in \mathcal{L}(V, W)$  defined by  $(\lambda T)(v) = \lambda(Tv)$  for all  $v \in V$ .
- It follows that, under these definitions of addition and multiplication,  $\mathcal{L}(V, W)$  is a vector space.
- **Product** (of  $T \in \mathcal{L}(U, V)$  and  $S \in \mathcal{L}(V, W)$ ): The linear map  $ST \in \mathcal{L}(U, W)$  defined by (ST)(u) = S(Tu) for all  $u \in U$ .
  - Note that the product is just function composition, but most mathematicians do write ST instead of  $S \circ T$ .
- Linear maps (with the correct corresponding domains) satisfy the associativity, identity, and distributive properties. However, multiplication of linear maps is not necessarily commutative.

- $(T_1T_2)T_3 = T_1(T_2T_3)$ . -  $TI_V = I_WT = T$  (note that if  $T \in \mathcal{L}(V, W)$ ,  $I_V \in \mathcal{L}(V, V)$  and  $I_W \in \mathcal{L}(W, W)$ ). -  $(S_1 + S_2)T = S_1T + S_2T$  and  $S(T_1 + T_2) = ST_1 + ST_2$ .
- Linear maps send 0 to 0.

**Theorem 3.2.** Suppose  $T \in \mathcal{L}(V, W)$ . Then T(0) = 0.

*Proof.* By additivity, we have

$$T(0) = T(0+0) = T(0) + T(0)$$
$$0 = T(0)$$

as desired.

## 3.B Null Spaces and Ranges

• Null space (of  $T \in \mathcal{L}(V, W)$ ): The subset of V consisting of those vectors that T maps to 0. Also known as kernel. Denoted by null T. Given by

$$\operatorname{null} T = \{ v \in V : Tv = 0 \}$$

 $\bullet\,$  The null space is a subspace.

**Theorem 3.3.** Suppose  $T \in \mathcal{L}(V, W)$ . Then null T is a subspace of V.

*Proof.* To prove that null T is a subspace of V, it will suffice to show that  $0 \in \text{null } T$ ,  $u, v \in \text{null } T$  implies that  $u + v \in \text{null } T$ , and  $u \in \text{null } T$  and  $\lambda \in \mathbb{F}$  imply  $\lambda u \in \text{null } T$ . Let's begin.

By Theorem 3.2, T(0) = 0. Therefore,  $0 \in \text{null } T$ , as desired.

Let  $u, v \in \text{null } T$  be arbitrary. Then by additivity

$$T(u+v) = Tu + Tv = 0 + 0 = 0$$

so  $u + v \in \text{null } T$ , as desired.

Let  $u \in \text{null } T$  and  $\lambda \in \mathbb{F}$  be arbitrary. Then by homogeneity,

$$T(\lambda u) = \lambda T u = \lambda 0 = 0$$

so  $\lambda u \in \text{null } T$ , as desired.

- Injective (function): A function  $T: V \to W$  such that Tu = Tv implies u = v. Also known as one-to-one.
- If 0 is the only vector that gets mapped to 0, then T is injective.

**Theorem 3.4.** Let  $T \in \mathcal{L}(V, W)$ . Then T is injective if and only if null  $T = \{0\}$ .

*Proof.* Suppose first that T is injective. To prove that  $\text{null } T = \{0\}$ , it will suffice to show that  $0 \in \text{null } T$  and for every  $v \in \text{null } T$ , v = 0. By Theorem 3.3,  $0 \in \text{null } T$ . Now let  $v \in \text{null } T$  be arbitrary. By the definition of the null space, we have Tv = 0. By Theorem 3.2, we have T(0) = 0. Thus, by transitivity, we have that Tv = T(0). It follows by injectivity that v = 0, as desired.

Now suppose that  $\operatorname{null} T = \{0\}$ . To prove that T is injective, it will suffice to show that if Tu = Tv, then u = v. Suppose  $u, v \in V$  satisfy Tu = Tv. Then

$$0 = Tu - Tv = T(u - v)$$

so  $(u-v) \in \text{null } T = \{0\}$ . It follows that u-v=0, i.e., that u=v, as desired.

• Range (of  $T \in \mathcal{L}(V, W)$ ): The subset of W consisting of those vectors that are of the form Tv for some  $v \in V$ . Also known as **image**. Denoted by **range** T. Given by

$$\operatorname{range} T = \{Tv : v \in V\}$$

• The range is a subspace.

**Theorem 3.5.** Suppose  $T \in \mathcal{L}(V, W)$ . Then range T is a subspace of W.

*Proof.* To prove that range T is a subspace of W, it will suffice to show that  $0 \in \text{range } T$ ,  $w_1, w_2 \in \text{range } T$  implies that  $(w_1 + w_2) \in \text{range } T$ , and  $w \in \text{range } T$  and  $\lambda \in \mathbb{F}$  imply  $\lambda w \in \text{range } T$ . Let's begin.

By the definition of a vector space,  $0 \in V$ . By Theorem 3.2, T(0) = 0. Therefore,  $0 \in \text{range } T$ , as desired.

Let  $w_1, w_2 \in \text{range } T$  be arbitrary. Then there exist  $v_1, v_2 \in V$  such that  $Tv_1 = w_1$  and  $Tv_2 = w_2$ . It follows by additivity that

$$T(v_1 + v_2) = Tv_1 + Tv_2 = w_1 + w_2$$

Therefore, since  $v_1 + v_2 \in V$ , we have that  $(w_1 + w_2) \in \text{range } T$ , as desired.

Let  $w \in \operatorname{range} T$  and  $\lambda \in \mathbb{F}$  be arbitrary. Then there exists  $v \in V$  such that Tv = w. It follows by homogeneity that

$$T(\lambda v) = \lambda T v = \lambda w$$

Therefore, since  $\lambda v \in V$ , we have that  $\lambda w \in \operatorname{range} T$ , as desired.

- Surjective (function): A function  $T: V \to W$  such that range T = W. Also known as onto.
- We now prove a very important theorem.

**Theorem 3.6** (Fundamental Theorem of Linear Maps). Suppose V is finite-dimensional and  $T \in \mathcal{L}(V,W)$ . Then range T is finite-dimensional and

$$\dim V = \dim \operatorname{null} T + \dim \operatorname{range} T$$

*Proof.* By Theorem 3.3, null T is a subspace of V finite-dimensional. Thus, by Theorem 2.4, null T is finite-dimensional. It follows by Theorem 2.7 that we may let  $u_1, \ldots, u_m$  be a basis of null T. As a basis of a subspace of V,  $u_1, \ldots, u_m$  is a linearly independent list of vectors in V. Consequently, by Theorem 2.8, we may extend it to a basis  $u_1, \ldots, u_m, v_1, \ldots, v_n$  of V.

Having established this terminology, we can now see that to prove that range T is finite-dimensional, it will suffice to show that  $Tv_1, \ldots, Tv_n$  spans it. To show that  $\operatorname{span}(Tv_1, \ldots, Tv_n) = \operatorname{range} T$ , it will suffice to show that every  $b_1Tv_1 + \cdots + b_nTv_n \in \operatorname{span}(Tv_1, \ldots, Tv_n)$  is an element of range T and that every  $Tv \in \operatorname{range} T$  is an element of  $\operatorname{span}(Tv_1, \ldots, Tv_n)$ . Let  $b_1Tv_1 + \cdots + b_nTv_n \in \operatorname{span}(Tv_1, \ldots, Tv_n)$  be arbitrary. Then

$$b_1 T v_1 + \dots + b_n T v_n = T(b_1 v_1 + \dots + b_n v_n)$$
  
=  $T(0u_1 + \dots + 0u_m + b_1 v_1 + \dots + b_n v_n)$ 

Therefore, since  $0u_1 + \cdots + 0u_m + b_1v_1 + \cdots + b_nv_n \in V$  by V's closure under addition and scalar multiplication, we have that  $b_1Tv_1 + \cdots + b_nTv_n \in \text{range } T$ , as desired. Now let  $Tv \in \text{range } T$  be arbitrary. Since  $v \in V$  and  $u_1, \ldots, u_m, v_1, \ldots, v_n$  is a basis of V, Theorem 2.5 implies that  $v = a_1u_1 + \cdots + a_mu_m + b_1v_1 + \cdots + b_nv_n$  for some  $a_1, \ldots, a_m, b_1, \ldots, b_n \in \mathbb{F}$ . Therefore,

$$Tv = T(a_1u_1 + \dots + a_mu_m + b_1v_1 + \dots + b_nv_n)$$

$$= T(a_1u_1 + \dots + a_mu_m) + T(b_1v_1 + \dots + b_nv_n)$$

$$= a_1Tu_1 + \dots + a_mTu_m + b_1Tv_1 + \dots + v_nTv_n$$

$$= a_10 + \dots + a_m0 + b_1Tv_1 + \dots + v_nTv_n$$

$$= b_1Tv_1 + \dots + v_nTv_n$$

where each  $Tu_j = 0$  because each  $u_j \in \text{null } T$ , so  $Tv \in \text{span}(Tv_1, \dots, Tv_n)$ , as desired.

Before we can verify the equation from the theorem, we need to establish one last fact: that  $Tv_1, \ldots, Tv_n$  is linearly independent. Suppose  $c_1, \ldots, c_n \in \mathbb{F}$  make

$$c_1Tv_1 + \dots + c_nTv_n = 0$$
  
$$T(c_1v_1 + \dots + c_nv_n) = 0$$

It follows that  $c_1v_1 + \cdots + c_nv_n \in \text{null } T$ . Thus, since  $u_1, \ldots, u_m$  is a basis of null T by Theorem 2.5, we have that

$$c_1v_1 + \dots + c_nv_n = d_1u_1 + \dots + d_mu_m$$
  

$$0 = d_1u_1 + \dots + d_mu_m - c_1v_1 - \dots - c_nv_n$$

for some  $d_1, \ldots, d_m \in \mathbb{F}$ . But since  $u_1, \ldots, u_m, v_1, \ldots, v_n$  is linearly independent as the basis of V, the above equation implies that  $c_1 = \cdots = c_n = 0$ , as desired.

Having established that  $u_1, \ldots, u_m, v_1, \ldots, v_n$  is a basis of  $V, u_1, \ldots, u_m$  is a basis of null T, and  $Tv_1, \ldots, Tv_n$  spans range T and is linearly independent in range T (i.e., is a basis of range T), we have that

$$\dim V = m + n$$

$$= \dim \operatorname{null} T + \dim \operatorname{range} T$$

as desired.

• We can now prove that a linear map to a "smaller" vector space cannot be injective.

**Theorem 3.7.** Suppose V and W are finite-dimensional vector spaces such that  $\dim V > \dim W$ . Then no linear map from V to W is injective.

*Proof.* Let  $T \in \mathcal{L}(V, W)$ . Then

$$\dim \operatorname{null} T = \dim V - \dim \operatorname{range} T$$
 Fundamental Theorem of Linear Maps 
$$\geq \dim V - \dim \operatorname{range} T$$
 Theorem 2.11 
$$> 0$$

It follows that null T has a basis consisting of a list of one or more vectors. As a linearly independent list, naturally none of these vectors will be equal to the zero vector. Thus, since null T contains vectors other than 0, Theorem 3.4 implies that T is not injective.

• Similarly, we can prove that a linear map to a "bigger" vector space cannot be surjective.

**Theorem 3.8.** Suppose V and W are finite-dimensional vector spaces such that  $\dim V < \dim W$ . Then no linear map from V to W is surjective.

*Proof.* Let  $T \in \mathcal{L}(V, W)$ . Then

$$\dim \operatorname{range} T = \dim V - \dim \operatorname{null} T \qquad \qquad \operatorname{Fundamental \ Theorem \ of \ Linear \ Maps} \\ \leq \dim V \qquad \qquad < \dim W$$

Therefore, range  $T \neq W$ , so T cannot be surjective.

• Theorems 3.7 and 3.8 allow us to express questions about systems of linear equations in terms of linear maps.

- For example, a question about a **homogenous** system of linear equations could be, "does there exist a nonzero solution to the homogenous system  $\sum_{k=1}^{n} A_{1,k} x_k = 0, \dots, \sum_{k=1}^{n} A_{m,k} x_k = 0$ ?"
- If we define  $T: \mathbb{F}^n \to \mathbb{F}^m$  by

$$T(x_1, \dots, x_n) = \left(\sum_{k=1}^n A_{1,k} x_k, \dots, \sum_{k=1}^n A_{m,k} x_k\right)$$

we can express the system of equations as  $T(x_1, \ldots, x_n) = 0$  and ask instead, "is dim null T > 0?"

- **Homogenous** (system of linear equations): A system of m linear equations  $\sum_{k=1}^{n} A_{1,k} x_k = c_1$  through  $\sum_{k=1}^{n} A_{m,k} x_k = c_m$  such that the constant term  $c_j = 0$  for all  $j = 1, \ldots, m$ .
- Continuing with the linear equations example, we can rigorously show the following.

**Theorem 3.9.** A homogenous system of linear equations with more variables than equations has nonzero solutions.

*Proof.* In terms of the above,  $T: \mathbb{F}^n \to \mathbb{F}^m$  where n > m. Thus, by Theorem 3.7, T is not injective. Consequently, by Theorem 3.4, dim null T > 0. Therefore, the system has nonzero solutions.

**Theorem 3.10.** An inhomogenous system of linear equations with more equations than variables has no solution for some choice of constant terms.

Proof. In terms of the above,  $T: \mathbb{F}^n \to \mathbb{F}^m$  where m > n. We want to know if there exists  $(c_1, \ldots, c_m) \in \mathbb{F}^m$  such that  $T(x_1, \ldots, x_n) \neq (c_1, \ldots, c_m)$  for any  $(x_1, \ldots, x_n) \in \mathbb{F}^n$ . In other words, we want to know if there exists  $(c_1, \ldots, c_m) \in \mathbb{F}^m$  such that  $(c_1, \ldots, c_m) \notin \text{range } T$ , i.e., if range  $T \neq \mathbb{F}^m$ . But since n < m, Theorem 3.8 asserts that T is not surjective, meaning that range  $T \neq W$ , as desired.

 Note that while the past two results are typically proven with Gaussian elimination, the abstract approach taken here leads to cleaner proofs.

#### 3.C Matrices

• m-by-n matrix: A rectangular array A of elements of  $\mathbb{F}$  with m rows and n columns

$$A = \begin{pmatrix} A_{1,1} & \cdots & A_{1,n} \\ \vdots & & \vdots \\ A_{m,1} & \cdots & A_{m,n} \end{pmatrix}$$

where m and n are positive integers.

- The notation  $A_{j,k}$  denotes the entry in row j, column k of A. In other words, the first index refers to the row number and the second index refers to the column number.
- Matrix (of  $T \in \mathcal{L}(V, W)$  with respect to the bases  $v_1, \ldots, v_n$  of V and  $w_1, \ldots, w_m$  of W): The m-by-n matrix  $\mathcal{M}(T)$  whose entries  $A_{j,k}$  are defined by

$$Tv_k = A_{1,k}w_1 + \dots + A_{m,k}w_m$$

- If the bases are not clear from context, then the notation  $\mathcal{M}(T,(v_1,\ldots,v_n),(w_1,\ldots,w_m))$  is used.
- Another way of wording the definition states that the  $k^{\text{th}}$  column of  $\mathcal{M}(T)$  consists of the scalars needed to write  $Tv_k$  as a linear combination of  $w_1, \ldots, w_m$ .
- Assuming standard bases, we "can think of the  $k^{\text{th}}$  column of  $\mathcal{M}(T)$  as the T applied to the  $k^{\text{th}}$  standard basis vector" (Axler, 2015, p. 71).

- Sum (of two m-by-n matrices A, C): The m-by-n matrix A + C defined by  $(A + C)_{j,k} = A_{j,k} + C_{j,k}$ .
  - Symbolically,

$$\begin{pmatrix} A_{1,1} & \cdots & A_{1,n} \\ \vdots & & \vdots \\ A_{m,1} & \cdots & A_{m,n} \end{pmatrix} + \begin{pmatrix} C_{1,1} & \cdots & C_{1,n} \\ \vdots & & \vdots \\ C_{m,1} & \cdots & C_{m,n} \end{pmatrix} = \begin{pmatrix} A_{1,1} + C_{1,1} & \cdots & A_{1,n} + C_{1,n} \\ \vdots & & \vdots \\ A_{m,1} + C_{m,1} & \cdots & A_{m,n} + C_{m,n} \end{pmatrix}$$

- Suppose  $S, T \in \mathcal{L}(V, W)$ . Then  $\mathcal{M}(S + T) = \mathcal{M}(S) + \mathcal{M}(T)$ .
- **Product** (of an m-by-n matrix A and  $\lambda \in \mathbb{F}$ ): The m-by-n matrix  $\lambda A$  defined by  $(\lambda A)_{j,k} = \lambda A_{j,k}$ .
  - Symbolically,

$$\lambda \begin{pmatrix} A_{1,1} & \cdots & A_{1,n} \\ \vdots & & \vdots \\ A_{m,1} & \cdots & A_{m,n} \end{pmatrix} = \begin{pmatrix} \lambda A_{1,1} & \cdots & \lambda A_{1,n} \\ \vdots & & \vdots \\ \lambda A_{m,1} & \cdots & \lambda A_{m,n} \end{pmatrix}$$

- Suppose  $\lambda \in \mathbb{F}$  and  $T \in \mathcal{L}(V, W)$ . Then  $\mathcal{M}(\lambda T) = \lambda \mathcal{M}(T)$ .
- $\mathbb{F}^{m,n}$ : The set of all m-by-n matrices with entries in  $\mathbb{F}$ , where m and n are positive integers.
- We have that dim  $\mathbb{F}^{m,n} = mn$ .
  - Note that a basis of  $\mathbb{F}^{m,n}$  is the set of all m-by-n matrices that have 0s everywhere save a 1 in a single place.
- **Product** (of an *m*-by-*n* matrix *A* and an *n*-by-*p* matrix *C*): The *m*-by-*p* matrix *AC* defined by  $(AC)_{j,k} = \sum_{r=1}^{n} A_{j,r} C_{r,k}$ .
  - We may derive this by noting that if  $\mathcal{M}(S) = A$  and  $\mathcal{M}(T) = C$ ,  $T: U \to V$  and  $S: V \to W$ , and  $u_1, \ldots, u_p, v_1, \ldots, v_n$ , and  $w_1, \ldots, w_m$  are bases, then

$$(ST)u_k = S\left(\sum_{r=1}^n C_{r,k}v_r\right)$$

$$= \sum_{r=1}^n C_{r,k}Sv_r$$

$$= \sum_{r=1}^n C_{r,k}\sum_{j=1}^m A_{j,r}w_j$$

$$= \sum_{i=1}^m \left(\sum_{r=1}^n A_{j,r}C_{r,k}\right)w_j$$

- Matrix multiplication is not commutative, but is distributive and associative.
- We now prove a relation between matrix and operator composition.

**Theorem 3.11.** Suppose  $T \in \mathcal{L}(U, V)$  and  $S \in \mathcal{L}(V, W)$ . Then  $\mathcal{M}(ST) = \mathcal{M}(S)\mathcal{M}(T)$ .

- If A is an m-by-n matrix, then...
  - We let  $A_{i}$  denote the 1-by-n matrix consisting of row j of A;
  - We let  $A_{\cdot,k}$  denote the m-by-1 matrix consisting of column k of A.
- Thus, if A is an m-by-n matrix and C is an n-by-p matrix, then  $(AC)_{j,k} = A_{j,.}C_{.,k}$  for all  $1 \le j \le m$  and  $1 \le k \le p$ .

- Similarly,  $(AC)_{\cdot,k} = AC_{\cdot,k}$ .
- Lastly, suppose A is an m-by-n matrix and  $c = (c_1, \ldots, c_n)$  is an n-by-1 matrix. Then  $Ac = c_1 A_{\cdot,1} + \cdots + c_n A_{\cdot,n}$ .
  - In other words, Ac is a linear combination of the columns of A, with the scalars that multiply the columns coming from c.

## 3.D Invertibility and Isomorphic Vector Spaces

- Invertible (linear map): A linear map  $T \in \mathcal{L}(V, W)$  such that there exists a linear map  $S \in \mathcal{L}(V, W)$  such that ST equals the identity map on V and TS equals the identity map on W.
- Inverse (of  $T \in \mathcal{L}(V, W)$ ): The linear map  $S \in \mathcal{L}(W, V)$  satisfying  $ST = I_V$  and  $TS = I_W$ . Denoted by  $T^{-1}$ .
- We now justify the use of the word "the" in the definition of the inverse.

**Theorem 3.12.** An invertible linear map has a unique inverse.

*Proof.* Suppose  $T \in \mathcal{L}(V, W)$  is invertible and  $S_1, S_2$  are inverses of T. Then

$$S_1 = S_1 I = S_1 (TS_2) = (S_1 T) S_2 = IS_2 = S_2$$

as desired.

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• We now give a criterion for invertibility.

**Theorem 3.13.** A linear map is invertible if and only if it is injective and surjective.

*Proof.* Let  $T \in \mathcal{L}(V, W)$ . Suppose first that T is invertible.

To prove that T is injective, it will suffice to show that for all  $u, v \in V$ , Tu = Tv implies that u = v. Let u, v be arbitrary elements of V that satisfy Tu = Tv. Then

$$u = T^{-1}(Tu) = T^{-1}(Tv) = v$$

as desired.

To prove that T is surjective, it will suffice to show that range T = W. Since range  $T \subset W$ , we need only show that  $W \subset \operatorname{range} T$ . Let  $w \in W$  be arbitrary. Since  $w = T(T^{-1}w)$  where  $T^{-1}w \in V$ , we have that  $w \in \operatorname{range} T$ , as desired.

Now suppose that T is injective and surjective. To prove that T is invertible, we will define a function  $S: W \to V$ , prove that it is a linear map, prove that  $TS = I_W$ , and prove that  $ST = I_V$ . Let SW be the unique element of V such that T(SW) = W (the surjectivity of T guarantees that there exists an element of V that T maps to W, and the injectivity of T guarantees the uniqueness of said element).

To prove that S is a linear map, it will suffice to show that S is additive and homogenous. To verify additivity, first note that the additivity of T implies that

$$T(Sw_1 + Sw_2) = T(Sw_1) + T(Sw_2) = w_1 + w_2$$

But since the above equation implies that  $Sw_1 + Sw_2$  is the unique element of V that T maps to  $w_1 + w_2$ , we have by the definition of S that  $S(w_1 + w_2) = Sw_1 + Sw_2$ . The proof is symmetric for homogeneity.

To prove that  $TS = I_W$ , we need only appeal to the definition of S, which states that (TS)w = T(Sw) = w for all  $w \in W$ . It immediately follows that  $TS = I_W$ .

To prove that  $ST = I_V$ , first note that for all  $v \in V$ ,

$$T((ST)v) = (TS)(Tv) = I(Tv) = Tv$$

It follows by the injectivity of T that (ST)v = v, i.e., that  $ST = I_V$ , as desired.

- **Isomorphism**: An invertible linear map.
- **Isomorphic** (vector spaces): Two vector spaces such that there exists an isomorphism from one vector space onto the other one.
- Isomorphic vector spaces have the same dimension.

**Theorem 3.14.** Two finite-dimensional vector spaces over  $\mathbb{F}$  are isomorphic if and only if they have the same dimension.

*Proof.* Suppose V,W are isomorphic finite-dimensional vector spaces over  $\mathbb{F}$ . Then there exists an isomorphism  $T:V\to W$ . By the definition of isomorphism, T is an invertible linear map, meaning by Theorem 3.13 that T is injective and surjective. Thus, since there exists an injective linear map  $T:V\to W$ , the contrapositive of Theorem 3.7 asserts that  $\dim V\leq \dim W$ . Additionally, since there exists a surjective linear map  $T:V\to W$ , the contrapositive of Theorem 3.8 asserts that  $\dim V\geq \dim W$ . Therefore, we have that  $\dim V=\dim W$ , as desired.

Now suppose that  $\dim V = \dim W$ . Let  $v_1, \ldots, v_n$  be a basis of V, and let  $w_1, \ldots, w_n$  be a basis of W. By Theorem 3.1, there exists a unique linear map  $T:V\to W$  such that  $Tv_j=w_j$  for each  $j=1,\ldots,n$ . To prove that T is an isomorphism, Theorem 3.13 tells us that it will suffice to show that it is injective and surjective. To show that T is surjective, it will suffice to show that range  $T=W=\mathrm{span}(w_1,\ldots,w_n)$ . But since  $Tv_j=w_j\in\mathrm{range}\,T$  for all  $j=1,\ldots,n$ , range  $T\subset W$ , and range T is a vector space (see Theorem 3.5), we have that range  $T=\mathrm{span}(w_1,\ldots,w_n)=W$ , as desired. To prove that T is injective, Theorem 3.4 tells us that it will suffice to show that null  $T=\{0\}$ , i.e., that  $\dim \mathrm{null}\,T=0$ . But since  $\dim \mathrm{range}\,T=\dim W=\dim V$ , we have by the Fundamental Theorem of Linear Maps that

$$\dim\operatorname{null} T + \dim\operatorname{range} T = \dim V$$
 
$$= \dim W$$
 
$$= \dim\operatorname{range} T$$
 
$$\dim\operatorname{null} T = 0$$

as desired.

- This result implies that every finite-dimensional vector space of dimension n is isomorphic to  $\mathbb{F}^n$ .
- It also allows us to formalize the link between linear maps from V to W and matrices in  $\mathbb{F}^{m,n}$ .

**Theorem 3.15.** Suppose  $v_1, \ldots, v_n$  is a basis of V and  $w_1, \ldots, w_m$  is a basis of W. Then  $\mathcal{M}$  is an isomorphism between  $\mathcal{L}(V, W)$  and  $\mathbb{F}^{m,n}$ .

*Proof.* We have already established that  $\mathcal{M}(S+T) = \mathcal{M}(S) + \mathcal{M}(T)$  and that  $\mathcal{M}(\lambda T) = \lambda \mathcal{M}(T)$ , so we already know that  $\mathcal{M}$  is a linear map. To prove that it is invertible, Theorem 3.13 tells us that it will suffice to show that  $\mathcal{M}$  is injective and surjective.

To show that  $\mathcal{M}$  is injective, Theorem 3.4 tells us that it will suffice to verify that null  $\mathcal{M} = \{0\}$ . Let  $T \in \mathcal{L}(V, W)$  be arbitrary. If  $\mathcal{M}(T) = 0$  (0 denoting the zero matrix), then

$$Tv_k = 0w_1 + \cdots + 0w_m = 0$$

for all k = 1, ..., n. But since  $v_1, ..., b_n$  is a basis of V, this implies that T = 0 (0 denoting the zero transformation), as desired.

To show that  $\mathcal{M}$  is surjective, it will suffice to verify that range  $\mathcal{M} = \mathbb{F}^{m,n}$ . Clearly range  $\mathcal{M} \subset \mathbb{F}^{m,n}$ , so we focus on the other direction. Let  $A \in \mathbb{F}^{m,n}$  be arbitrary. Define  $T \in \mathcal{L}(V, W)$  by

$$Tv_k = \sum_{j=1}^m A_{j,k} w_j$$

for k = 1, ..., n. It follows by the definition of a matrix of a linear transformation that  $\mathcal{M}(T) = A$ , as desired.

• We can now determine the dimension of the vector space of linear maps from one finite-dimensional vector space to another.

**Theorem 3.16.** Suppose V and W are finite-dimensional. Then  $\mathcal{L}(V,W)$  is finite-dimensional and

$$\dim \mathcal{L}(V, W) = (\dim V)(\dim W)$$

*Proof.* By Theorem 3.15,  $\mathcal{L}(V, W)$  and  $\mathbb{F}^{m,n}$  are isomorphic. Thus, by Theorem 3.14,  $\mathcal{L}(V, W)$  and  $\mathbb{F}^{m,n}$  have the same dimension. Therefore, we have that

$$\dim \mathcal{L}(V, W) = \dim \mathbb{F}^{m,n}$$

$$= mn$$

$$= (\dim V)(\dim W)$$

as desired.

• Matrix (of  $v \in V$  with respect to the basis  $v_1, \ldots, v_n$  of V): The n-by-1 matrix  $\mathcal{M}(v)$  whose entries  $A_{j,1}$  are defined by

$$v = A_{1,1}v_1 + \dots + A_{n,1}v_n$$

 $\bullet$  We now show that the columns of the matrix of T are directly related to the effect T has on basis vectors.

**Theorem 3.17.** Suppose  $T \in \mathcal{L}(V, W)$ ,  $v_1, \ldots, v_n$  is a basis of V, and  $w_1, \ldots, w_m$  is a basis of W. Let  $1 \leq k \leq n$ . Then

$$\mathcal{M}(T)_{\cdot,k} = \mathcal{M}(Tv_k)$$

*Proof.* As an element of W,  $Tv_k = c_1w_1 + \cdots + c_mw_m$  for some  $c_1, \ldots, c_m \in \mathbb{F}$ . By the definition of the matrix of T, the values in column k are  $c_1, \ldots, c_m$ . Similarly, by the definition of the matrix of  $Tv_k$ , the values in its one column are  $c_1, \ldots, c_m$ , as desired.

• Linear maps act like matrix multiplication.

**Theorem 3.18.** Suppose  $T \in \mathcal{L}(V, W)$ ,  $v \in V$ ,  $v_1, \ldots, v_n$  is a basis of V, and  $w_1, \ldots, w_m$  is a basis of W. Then

$$\mathcal{M}(Tv) = \mathcal{M}(T)\mathcal{M}(v)$$

*Proof.* Let  $v = c_1v_1 + \cdots + c_nv_n$ . Then by the linearity of T,  $Tv = c_1Tv_1 + \cdots + c_nTv_n$ . It follows by the linearity of  $\mathcal{M}$ , Theorem 3.17, and the fact that a matrix times a vector is equal to a linear combination of columns that

$$\mathcal{M}(Tv) = c_1 \mathcal{M}(Tv_1) + \dots + c_n \mathcal{M}(Tv_n)$$
  
=  $c_1 \mathcal{M}(T)_{\cdot,1} + \dots + c_n \mathcal{M}(T)_{\cdot,n}$   
=  $\mathcal{M}(T) \mathcal{M}(v)$ 

as desired.

- "Each m-by-n matrix A induces a linear map from  $\mathbb{F}^{n,1}$  to  $\mathbb{F}^{m,1}$ , namely the matrix multiplication function that takes  $x \in \mathbb{F}^{n,1}$  to  $Ax \in \mathbb{F}^{m,1}$ " (Axler, 2015, p. 85).
- Operator: A linear map from a vector space to itself.
- $\mathcal{L}(V)$ : The set of all operators on V.
  - Mathematically,  $\mathcal{L}(V) = \mathcal{L}(V, V)$ .

- On infinite-dimensional vector spaces, neither injectivity nor surjectivity, alone, implies invertibility.
- However, only one does on finite-dimensional vector spaces.

**Theorem 3.19.** Suppose V is finite-dimensional and  $T \in \mathcal{L}(V)$ . Then the following are equivalent.

- (a) T is invertible;
- (b) T is injective;
- (c) T is surjective.

*Proof.* First, suppose that T is invertible. Then by Theorem 3.13, T is injective, as desired.

Second, suppose that T is injective. Then by Theorem 3.4, null  $T = \{0\}$ . It follows by the Fundamental Theorem of Linear Maps that

$$\dim \operatorname{range} T = \dim V - \dim \operatorname{null} T$$
$$= \dim V$$

Thus, since range T has the same dimension as V and is a subspace of V (by Theorem 3.5), range T = V. Therefore, T is surjective, as desired.

Third, suppose that T is surjective. Then range T = V. It follows that dim range  $T = \dim V$ . Thus, by the Fundamental Theorem of Linear Maps, we have that

$$\dim \operatorname{null} T = \dim V - \dim \operatorname{range} T$$
$$= 0$$

Consequently, by Theorem 3.4, T is injective. Therefore, by Theorem 3.13, T is invertible, as desired.

#### **Exercises**

10/11: **9** Suppose V is finite-dimensional and  $S, T \in \mathcal{L}(V)$ . Prove that ST is invertible if and only if both S and T are invertible.

Proof. Suppose first that ST is invertible. Then by Theorem 3.19, ST is injective and surjective. We will prove that S, T are invertible in turn; in particular, we will first prove that S is surjective and then prove that T is injective. Let's begin. To prove that S is surjective, it will suffice to show that range S = V. Let  $v \in V$  be arbitrary. Since ST is surjective, there exists  $v' \in V$  such that STv' = v. Thus, since  $Tv' \in V$ , the fact that S(Tv') = v implies that  $v \in \text{range } S$ . The inclusion in the other direction is obvious. Now to prove that T is injective, it will suffice to show that Tv = Tv' implies v' = v'. Let Tv = Tv'. Then STv = STv'. It follows that v = v' by the injectivity of ST, as desired.

Now suppose that S and T are invertible. Then by Theorem 3.12, there exist  $S^{-1}, T^{-1}$  such that

$$SS^{-1} = I = S^{-1}S$$
  $TT^{-1} = I = T^{-1}T$ 

Let  $(ST)^{-1} = T^{-1}S^{-1}$ . Then

$$ST(ST)^{-1} = STT^{-1}S^{-1} = SIS^{-1} = SS^{-1} = I = T^{-1}T = T^{-1}IT = T^{-1}S^{-1}ST = (ST)^{-1}ST$$

so ST is invertible, as desired.

10 Suppose V is finite-dimensional and  $S, T \in \mathcal{L}(V)$ . Prove that ST = I if and only if TS = I.

*Proof.* Suppose first that ST = I. It is easy to see that defining  $(ST)^{-1} = I^{-1} = I$  yields an inverse of ST. Thus, since ST is invertible, we have by Exercise 3.D.9 that S and T are invertible. It follows since ST = I that  $S = T^{-1}$ , meaning that

$$TS = TT^{-1} = I$$

as desired.

The proof is symmetric in the other direction.

## 3.E Products and Quotients of Vector Spaces

9/6: • **Product** (of  $V_1, \ldots, V_m$ ): The set

$$V_1 \times \cdots \times V_m = \{(v_1, \dots, v_m) : v_1 \in V_1, \dots, v_m \in V_m\}$$

- Addition on  $V_1 \times \cdots \times V_m$  is defined by

$$(u_1,\ldots,u_m)+(v_1,\ldots,v_m)=(u_1+v_1,\ldots,u_m+v_m)$$

- Scalar multiplication on  $V_1 \times \cdots \times V_m$  is defined by

$$\lambda(v_1, \dots, v_m) = (\lambda v_1, \dots, \lambda v_m)$$

- The product of n vector spaces over  $\mathbb{F}$  is a vector space over  $\mathbb{F}$ , with addition and scalar multiplication defined as above.
- We can, for example, identify  $\mathbb{R}^2 \times \mathbb{R}^3$  with  $\mathbb{R}^5$  by constructing an isomorphism from every vector  $((x_1, x_2), (x_3, x_4, x_5)) \in \mathbb{R}^2 \times \mathbb{R}^3$  to the vector  $(x_1, x_2, x_3, x_4, x_5) \in \mathbb{R}^5$ .
- The dimension of the product of vector spaces is equal to the sum of the dimensions of the component vector spaces.

**Theorem 3.20.** Suppose  $V_1, \ldots, V_m$  are finite-dimensional vector spaces. Then  $V_1 \times \cdots \times V_m$  is finite-dimensional and

$$\dim(V_1 \times \cdots \times V_m) = \dim V_1 + \cdots + \dim V_m$$

*Proof.* Choose a basis of each  $V_j$ . For each basis vector of each  $V_j$ , consider the element of  $V_1 \times \cdots \times V_m$  that equals the basis vector in the  $j^{\text{th}}$  slot and 0 in the other slots. The list of all such vectors is linearly independent and spans  $V_1 \times \cdots \times V_m$ . Thus, it is a basis of  $V_1 \times \cdots \times V_m$ . The length of this basis is  $\dim V_1 + \cdots + \dim V_m$ , as desired.

• We now relate products and direct sums.

**Theorem 3.21.** Suppose that  $U_1, \ldots, U_m$  are subspaces of V. Define a linear map  $\Gamma: U_1 \times \cdots \times U_m \to U_1 + \cdots + U_m$  by

$$\Gamma(u_1,\ldots,u_m)=u_1+\cdots+u_m$$

Then  $U_1 + \cdots + U_m$  is a direct sum if and only if  $\Gamma$  is injective.

*Proof.* Suppose first that  $\Gamma$  is injective. Then the only way to write 0 as a sum  $u_1 + \cdots + u_m$ , where each  $u_j \in U_j$ , is by taking each  $u_j = 0$ . It follows by the condition on direct sums that  $U_1 + \cdots + U_m$  is a direct sum. The proof is symmetric in the reverse direction.

- Note that since Γ is surjective by the definition of  $U_1 + \cdots + U_m$ , the condition that Γ is injective could be changed to the condition that Γ is invertible.
- We can now prove that the dimensions add up in a direct sum.

**Theorem 3.22.** Suppose V is finite-dimensional and  $U_1, \ldots, U_m$  are subspaces of V. Then  $U_1 + \cdots + U_m$  is a direct sum if and only if

$$\dim(U_1 + \dots + U_m) = \dim U_1 + \dots + \dim U_m$$

*Proof.* Suppose first that  $U_1 + \cdots + U_m$  is a direct sum. Then by Theorem 3.21, there exists an invertible linear map  $\Gamma$  from  $U_1 \times \cdots \times U_m$  to  $U_1 + \cdots + U_m$ . Thus, by Theorem 3.14,  $U_1 \times \cdots \times U_m$  and  $U_1 + \cdots + U_m$  have the same dimension. Therefore,

$$\dim(U_1 + \dots + U_m) = \dim(U_1 \times \dots \times U_m)$$

$$= \dim U_1 + \dots + \dim U_m$$
 Theorem 3.20

as desired.

The proof is symmetric in the other direction.

Labalme 12

• Sum (of  $v \in V$  and U a subspace of V): The subset of V defined by

$$v + U = \{v + u : u \in U\}$$

- Affine subset (of V): A subset of V of the form v + U for some  $v \in V$  and some subspace U of V.
- Parallel (subset to U): An affine subset v + U of V.
- Quotient space: The set of all affine subsets of V parallel to U.

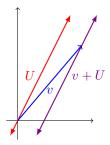


Figure 3.1: Visualizing v + U.

- Symbolically,

$$V/U = \{v + U : v \in V\}$$

 $\bullet$  Two affine subsets parallel to U are equal or disjoint.

**Theorem 3.23.** Suppose U is a subspace of V and  $v, w \in V$ . Then the following are equivalent.

- (a)  $v w \in U$ ;
- (b) v + U = w + U;
- (c)  $(v+U) \cap (w+U) \neq \emptyset$ .

*Proof.* First, suppose that  $v-w\in U$ . Let  $x\in v+U$  be arbitrary. Then x=v+u for some  $u\in U$ . Now since  $v-w\in U$ ,  $u\in U$ , and U is a subspace, we have that  $v-w+u\in U$ . Thus,  $x=w-w+v+u=w+(v-w+u)\in w+U$ . The proof is symmetric in the other direction. Therefore, v+U=w+U, as desired.

Second, suppose that v+U=w+U. Since U is nonempty  $(0 \in U \text{ by definition})$ , we know that  $v+U \neq \emptyset \neq w+U$ . Therefore,  $(v+U) \cap (w+U) \supset \{0\} \neq \emptyset$ , as desired.

Third, suppose that  $(v+U) \cap (w+U) \neq \emptyset$ . Then there exists x such that  $x \in v+U$  and  $x \in w+U$ . It follows that  $x = v + u_1$  and  $x = w + u_2$  for some  $u_1, u_2 \in U$ . Thus, by transitivity,  $v + u_1 = w + u_2$ . Therefore,  $v - w = u_2 - u_1 \in U$ , as desired.

- Sum (of  $v + U, w + U \in V/U$ ): The affine subset (v + w) + U.
- **Product** (of  $v + U \in V/U$  and  $\lambda \in \mathbb{F}$ ): The affine subset  $(\lambda v) + U$ .
- We now verify that the above operations are well-defined and prove that the quotient space is a vector space.

**Theorem 3.24.** Suppose U is a subspace of V. Then V/U, with the operations of addition and scalar multiplication as defined above, is a vector space.

*Proof.* The way affine subsets are defined, we may have  $v + U = \hat{v} + U$  and yet have  $v \neq \hat{v}$ . Thus, we must first guarantee that the operations of addition and scalar multiplication, as defined above, are well-defined, i.e., that if  $v + U = \hat{v} + U$  and  $w + U = \hat{w} + U$ , then  $(v + w) + U = (\hat{v} + \hat{w}) + U$  and  $(\lambda v) + U = (\lambda \hat{v}) + U$ . Let's begin.

To confirm that addition as defined above is a well-defined operation, let  $v, \hat{v}, w, \hat{w} \in V$  be such that  $v + U = \hat{v} + U$  and  $w + U = \hat{w} + U$ . Then by Theorem 3.23,  $v - \hat{v} \in U$  and  $w - \hat{w} \in U$ . It follows since U is a subspace that  $(v - \hat{v}) + (w - \hat{w}) \in U$ . Consequently,  $(v + w) - (\hat{v} + \hat{w}) \in U$ , so by Theorem 3.23 again,  $(v + w) + U = (\hat{v} + \hat{w}) + U$ , as desired.

Similarly,  $v + U = \hat{v} + U$  implies  $v - \hat{v} \in U$ , implies  $\lambda(v - \hat{v}) = \lambda v - \lambda \hat{v} \in U$ , implies  $(\lambda v) + U = (\lambda \hat{v}) + U$ , as desired.

The remaining proof that V/U is a vector space is straightforward; note that 0+U is the identity element and (-v)+U is the additive inverse.

- Quotient map: The linear map  $\pi: V \to V/U$  defined by  $\pi(v) = v + U$  for all  $v \in V$ .
- We now give a formula for the dimension of a quotient space.

**Theorem 3.25.** Suppose V is finite-dimensional and U is a subspace of V. Then

$$\dim V/U = \dim V - \dim U$$

*Proof.* Let  $\pi$  be the quotient map from V to V/U. From Theorem 3.23, we know that in order for w+U=0+U, we must have  $v-0=v\in U$ . Thus,  $\pi(u)=0$  if and only if  $u\in U$ , meaning null  $\pi=U$ . Additionally, we clearly have that range  $\pi=V/U$ . Therefore, by the Fundamental Theorem of Linear Maps, we have that

$$\dim V = \dim \operatorname{null} \pi + \dim \operatorname{range} \pi$$

$$= \dim U + \dim V/U$$

$$\dim V/U = \dim V - \dim U$$

as desired.

- Lastly, consider the fact that we can add any vector in the null space of a linear map T to an argument passed to T without changing its output. In other words, if  $T \in \mathcal{L}(V, W)$ ,  $v \in V$ , and  $u \in \text{null } T$ , then T(v+u) = Tv + Tu = Tv. We formalize this concept with the following definition.
- $\tilde{T}$ : The function from V/(null T) to W defined by  $\tilde{T}(v+\text{null }T)=Tv$ , where  $T\in\mathcal{L}(V,W)$ .
- We now state a few basic results about  $\tilde{T}$ .

**Theorem 3.26.** Suppose  $T \in \mathcal{L}(V, W)$ . Then

- (a)  $\tilde{T}$  is a linear map from V/(null T) to W;
- (b)  $\tilde{T}$  is injective;
- (c) range  $\tilde{T} = \text{range } T$ ;
- (d) V/(null T) is isomorphic to range T.

## 3.F Duality

- 9/7: Linear functional (on v): A linear map from V to  $\mathbb{F}$ .
  - In other words, a linear functional is an element of  $\mathcal{L}(V, \mathbb{F})$ .

• Dual space (of V): The vector space of all linear functionals on V. Denoted by V'. Also known as  $V^*$ . Given by

$$V' = \mathcal{L}(V, \mathbb{F})$$

• We now give a definition of the dimension of the dual space.

**Theorem 3.27.** Suppose V is finite-dimensional. Then V' is also finite-dimensional and

$$\dim V' = \dim V$$

*Proof.* By Theorem 3.16, we have that

$$\dim V' = \dim \mathcal{L}(V, \mathbb{F})$$

$$= (\dim V)(\dim \mathbb{F})$$

$$= (\dim V)(1)$$

$$= \dim V$$

as desired.

• **Dual basis** (of a basis  $v_1, \ldots, v_n$  of V): The list  $\varphi_1, \ldots, \varphi_n$  of elements of V', where each  $\varphi_j$  is the linear functional on V such that

$$\varphi_j(v_k) = \begin{cases} 1 & k = j \\ 0 & k \neq j \end{cases}$$

where  $v_1, \ldots, v_n$  is a basis of V.

• We now verify that the dual basis of a basis of V is actually a basis of the dual space.

**Theorem 3.28.** Suppose V is finite-dimensional. Then the dual basis of a basis of V is a basis of V'.

*Proof.* Let  $v_1, \ldots, v_n$  be a basis of V, and let  $\varphi_1, \ldots, \varphi_n$  be the corresponding dual basis. Since the dual basis has length equal to the dimension of V' (by Theorem 3.27), Theorem 2.12 tells us that it will suffice to show that  $\varphi_1, \ldots, \varphi_n$  is linearly independent to confirm that it is a basis of V'. To do so, suppose

$$a_1\varphi_1 + \dots + a_n\varphi_n = 0$$

where  $a_1, \ldots, a_n \in \mathbb{F}$  and 0 denotes the zero transformation. Since  $(a_1\varphi_1 + \cdots + a_n\varphi_n)(v_j) = a_j$  for  $j = 1, \ldots, n$ , we have that for any vector  $c_1v_1 + \cdots + c_nv_n \in V$ ,

$$(a_1\varphi_1 + \dots + a_n\varphi_n)(c_1v_1 + \dots + c_nv_n) = c_1a_1 + \dots + c_na_n$$

Therefore, the only way to guarantee that  $c_1a_1 + \cdots + c_na_n = 0$  is to let  $a_1 = \cdots = a_n = 0$ , as desired.

• **Dual map** (of  $T \in \mathcal{L}(V, W)$ ): The linear map  $T' \in \mathcal{L}(W', V')$  defined by

$$T'(\varphi)=\varphi\circ T$$

for all  $\varphi \in W'$ . Also known as  $T^*$ .

• We now prove some algebraic properties of dual maps.

#### Theorem 3.29.

(a) 
$$(S+T)' = S' + T'$$
 for all  $S, T \in \mathcal{L}(V, W)$ .

*Proof.* Let  $S,T\in\mathcal{L}(V,W)$  be arbitrary. To prove that (S+T)'=S'+T', it will suffice to show that  $(S+T)'(\varphi)=(S'+T')(\varphi)$  for all  $\varphi\in W'$ . Let  $\varphi\in W'$  be arbitrary. However, before we go into the main equality, it will be useful if we verify that  $\varphi\circ(S+T)=\varphi\circ S+\varphi\circ T$ . To do so, it will suffice to show that  $(\varphi\circ(S+T))(v)=(\varphi\circ S+\varphi\circ T)(v)$  for all  $v\in V$ . Let  $v\in V$  be arbitrary. Then

$$(\varphi \circ (S+T))(v) = \varphi((S+T)(v))$$

$$= \varphi(S(v) + T(v))$$

$$= \varphi(S(v)) + \varphi(T(v))$$

$$= (\varphi \circ S)(v) + (\varphi \circ T)(v)$$

$$= (\varphi \circ S + \varphi \circ T)(v)$$

Now we can show that

$$(S+T)'(\varphi) = \varphi \circ (S+T)$$
$$= \varphi \circ S + \varphi \circ T$$
$$= S'(\varphi) + T'(\varphi)$$
$$= (S'+T')(\varphi)$$

as desired.

(b)  $(\lambda T)' = \lambda T'$  for all  $\lambda \in \mathbb{F}$  and all  $T \in \mathcal{L}(V, W)$ .

*Proof.* The proof is symmetric to the proof of part (a).

(c) (ST)' = T'S' for all  $T \in \mathcal{L}(U, V)$  and  $S \in \mathcal{L}(V, W)$ .

*Proof.* Let  $\varphi \in W'$  be arbitrary. Then

$$(ST)'(\varphi) = \varphi \circ (ST) = (\varphi \circ S) \circ T = T'(\varphi \circ S) = T'(S'(\varphi)) = (T'S')(\varphi)$$

as desired.

• Annihilator (of  $U \subset V$ ): The set

$$U^0 = \{ \varphi \in V' : \varphi(u) = 0 \ \forall \ u \in U \}$$

• The annihilator is a subspace.

**Theorem 3.30.** Suppose  $U \subset V$ . Then  $U^0$  is a subspace of V'

*Proof.* To prove that  $U^0$  is a subspace of V', it will suffice to show that  $0 \in U^0$ ,  $\varphi, \psi \in U^0$  implies  $\varphi + \psi \in U^0$ , and  $\varphi \in U^0$  and  $\lambda \in \mathbb{F}$  imply  $\lambda \varphi \in U^0$ . Let's begin.

Since 0(u) = 0 for all  $u \in U$ ,  $0 \in U^0$ .

Let  $\varphi, \psi \in U^0$  be arbitrary. Let  $u \in U$  be arbitrary. Then  $(\varphi + \psi)(u) = \varphi(u) + \psi(u) = 0 + 0 = 0$ , as desired.

The proof is symmetric for scalar multiplication.

• Dimension of the annihilator.

**Theorem 3.31.** Suppose V is finite-dimensional and U is a subspace of V. Then

$$\dim U + \dim U^0 = \dim V$$

*Proof.* Let  $i \in \mathcal{L}(U, V)$  be the identity map i(u) = u for all  $u \in U$ . Then  $i' : V' \to U'$  is a linear map. It follows by the Fundamental Theorem of Linear Maps that

$$\dim \operatorname{range} i' + \dim \operatorname{null} i' = \dim V'$$

Since  $i'(\varphi) = \varphi \circ i = \varphi$  for all  $\varphi \in V'$ , and  $U^0 = \{\varphi \in V' : \varphi = 0\}$ , we have that  $i'(\varphi) = 0$  for all  $\varphi \in U^0$ . Thus,  $U^0 = \text{null } i'$ . Additionally, we have that  $\dim V = \dim V'$  by Theorem 3.27. Lastly, let  $\psi \in U'$  be arbitrary. Define  $\psi \in V'$  by

$$\psi(v) = \begin{cases} \varphi(v) & v \in U \\ 0 & v \notin U \end{cases}$$

Thus,  $i'(\psi) = \psi \circ i = \varphi$ . It follows that  $\varphi \in \text{range } i'$ . Consequently, range i' = U', so dim  $U = \dim U' = \dim \operatorname{range} i'$  by Theorem 3.27. Therefore, we have from the first equation and the three substitutions that

$$\dim U + \dim U^0 = \dim V$$

as desired.<sup>[1]</sup>

• We now describe the null space of T'.

**Theorem 3.32.** Suppose V and W are finite-dimensional and  $T \in \mathcal{L}(V, W)$ . Then

(a) null  $T' = (\operatorname{range} T)^0$ .

*Proof.* First, let  $\varphi \in \text{null } T'$  be arbitrary. Then  $T'(\varphi) = \varphi \circ T = 0$ . It follows that  $0 = (\varphi \circ T)(v) = \varphi(Tv)$  for all  $v \in V$ . But this means that  $\varphi$  is a linear functional that maps every element of range T to 0, i.e., that  $\varphi \in (\text{range } T)^0$ . The proof is symmetric in the other direction.

(b)  $\dim \operatorname{null} T' = \dim \operatorname{null} T + \dim W - \dim V$ .

Proof. We have that

$$\dim \operatorname{null} T' = \dim(\operatorname{range} T)^0 \qquad \qquad \operatorname{Theorem} \ 3.32a$$

$$= \dim W - \dim \operatorname{range} T \qquad \qquad \operatorname{Theorem} \ 3.31$$

$$= \dim W - (\dim V - \dim \operatorname{null} T) \qquad \qquad \operatorname{Fundamental} \ \operatorname{Theorem} \ \operatorname{of} \ \operatorname{Linear} \ \operatorname{Maps}$$

$$= \dim \operatorname{null} T + \dim W - \dim V$$

as desired.

- Note that the proof of part (a) does not use the hypothesis that V, W are finite-dimensional, so the argument holds for infinite-dimensional vector spaces as well.
- T surjective is equivalent to T' injective.

**Theorem 3.33.** Suppose V and W are finite-dimensional and  $T \in \mathcal{L}(V, W)$ . Then T is surjective if and only if T' is injective.

*Proof.* Suppose first that T is surjective. Then range T = W. It follows by Theorem 3.31 that

$$\dim(\operatorname{range} T)^0 = \dim W - \dim\operatorname{range} T = 0$$

meaning that (range T)<sup>0</sup> = {0}. Thus, by Theorem 3.32a, null  $T' = \{0\}$ . Therefore, by Theorem 3.4, T' is injective, as desired.

The proof is symmetric in the other direction.

<sup>&</sup>lt;sup>1</sup>Note that we may also prove this by constructing a basis of U extending it to a basis of V, and showing that the extended portion of the dual basis is a basis of  $U^0$ .

• We now describe the range space of T'.

**Theorem 3.34.** Suppose V and W are finite-dimensional and  $T \in \mathcal{L}(V, W)$ . Then

(a)  $\dim \operatorname{range} T' = \dim \operatorname{range} T$ .

Proof. We have that

$$\dim \operatorname{range} T' = \dim W' - \dim \operatorname{null} T'$$
 Fundamental Theorem of Linear Maps 
$$= \dim W - \dim \operatorname{null} T'$$
 Theorem 3.27 
$$= \dim W - \dim (\operatorname{range} T)^0$$
 Theorem 3.32a 
$$= \dim \operatorname{range} T$$
 Theorem 3.31

as desired.

(b) range  $T' = (\text{null } T)^0$ .

*Proof.* First, let  $\varphi \in \operatorname{range} T'$  be arbitrary. Then there exists  $\psi \in W'$  such that  $\varphi = T'(\psi)$ . Now let  $v \in \operatorname{null} T$  be arbitrary. It follows that

$$\varphi(v) = (T'(\psi))(v) = (\psi \circ T)(v) = \psi(Tv) = \psi(0) = 0$$

Therefore,  $\varphi \in (\text{null } T)^0$ , as desired.

Second, we have that

$$\dim \operatorname{range} T' = \dim \operatorname{range} T \qquad \qquad \operatorname{Theorem} \ 3.34a$$
 
$$= \dim V - \dim \operatorname{null} T \qquad \qquad \operatorname{Fundamental} \ \operatorname{Theorem} \ \operatorname{of} \ \operatorname{Linear} \ \operatorname{Maps}$$
 
$$= \dim (\operatorname{null} T)^0 \qquad \qquad \operatorname{Theorem} \ 3.31$$

Therefore, since Theorem 3.5 implies that range T' is a subspace of  $(\text{null } T)^0$  and  $\dim \text{range } T' = \dim(\text{null } T)^0$ , Exercise 2.C.1 asserts that range  $T' = (\text{null } T)^0$ , as desired.

• T injective is equivalent to T' surjective.

**Theorem 3.35.** Suppose V and W are finite-dimensional and  $T \in \mathcal{L}(V, W)$ . Then T is injective if and only if T' is surjective.

*Proof.* Suppose first that T is injective. Then by Theorem 3.4, null  $T = \{0\}$ . Thus, since Theorem 3.2 asserts that  $\varphi(0) = 0$  for any linear functional, we have that every linear functional is in the annihilator of null T, i.e., that  $(\text{null } T)^0 = V'$ . It follows by Theorem 3.34b that range T' = V'. Therefore, T' is surjective, as desired.

The proof is symmetric in the other direction.

- 9/8: Transpose (of an m-by-n matrix A): The matrix obtained from A by interchanging the rows and columns. More specifically, the n-by-m matrix  $A^t$  whose entries are given by  $(A^t)_{k,j} = A_{j,k}$ . Denoted by  $A^t$ .
  - Properties of the transpose:

$$(A+C)^t = A^t + C^t (\lambda A)^t = \lambda A^t$$

• Transpose of a product.

**Theorem 3.36.** If A is an m-by-n matrix and C is an n-by-p matrix, then

$$(AC)^t = C^t A^t$$

Proof. We have that

$$((AC)^{t})_{k,j} = (AC)_{j,k}$$

$$= \sum_{r=1}^{n} A_{j,r} C_{r,k}$$

$$= \sum_{r=1}^{n} (C^{t})_{k,r} (A^{t})_{r,j}$$

$$= (C^{t}A^{t})_{k,j}$$

for all  $1 \le k \le p$  and  $1 \le j \le m$ , as desired.

• We now show that the transpose and the dual map are essentially the same object.

**Theorem 3.37.** Suppose  $T \in \mathcal{L}(V, W)$ . Then  $\mathcal{M}(T') = (\mathcal{M}(T))^t$ .

*Proof.* Let  $v_1, \ldots, v_n$  be a basis of V, and let  $\varphi_1, \ldots, \varphi_n$  be the corresponding dual basis of V'. Similarly, let  $w_1, \ldots, w_m$  be a basis of W, and let  $\psi_1, \ldots, \psi_m$  be the corresponding dual basis of W'. Let  $A = \mathcal{M}(T)$  and  $C = \mathcal{M}(T')$ . Let  $1 \leq j \leq m$  and  $1 \leq k \leq n$  be arbitrary. Then we have from the definition of  $\mathcal{M}(T')$  that

$$T'(\psi_j) = \sum_{r=1}^n C_{r,j} \varphi_r$$

from the definition of T' that

$$(\psi \circ T)(v_k) = \sum_{r=1}^{n} C_{r,j} \varphi_r(v_k)$$
$$= C_{k,j}$$

and from the definition of  $\mathcal{M}(T)$  that

$$(\psi \circ T)(v_k) = \psi_j(Tv_k)$$

$$= \psi_j\left(\sum_{r=1}^m A_{r,k}w_r\right)$$

$$= \sum_{r=1}^m A_{r,k}\psi_j(w_r)$$

$$= A_{j,k}$$

Therefore, from the last two results, we have by transitivity that  $A_{j,k} = C_{k,j}$  for all  $1 \le j \le m$  and  $1 \le k \le n$ . It follows that  $C = A^t$ , i.e., that  $\mathcal{M}(T') = (\mathcal{M}(T))^t$ , as desired.

- Row rank (of a matrix A): The dimension of the span of the rows of A in  $\mathbb{F}^{1,n}$ .
- Column rank (of a matrix A): The dimension of the span of the columns of A in  $\mathbb{F}^{m,1}$ .
- The dimension of range T equals the column rank of  $\mathcal{M}(T)$ .

**Theorem 3.38.** Suppose V and W are finite-dimensional and  $T \in \mathcal{L}(V, W)$ . Then dim range T equals the column rank of  $\mathcal{M}(T)$ .

*Proof.* Let  $v_1, \ldots, v_n$  be a basis of V, and let  $w_1, \ldots, w_m$  be a basis of W. Since  $Tv = c_1Tv_1 + \cdots + c_nTv_n$  for all  $Tv \in \text{range } T$  (because  $v = c_1v_1 + \cdots + c_nTv_n$  for some  $c_1, \ldots, c_n \in \mathbb{F}$  for all  $v \in V$ , and T is a linear map), we have that range  $T = \text{span}(Tv_1, \ldots, Tv_n)$ . Additionally, since  $\mathcal{M}$  is

an isomorphism from span $(Tv_1, \ldots, Tv_n)$  to span $(\mathcal{M}(Tv_1), \ldots, \mathcal{M}(Tv_n))$ , Theorem 3.14 asserts that  $\dim \operatorname{span}(Tv_1, \ldots, Tv_n) = \dim \operatorname{span}(\mathcal{M}(Tv_1), \ldots, \mathcal{M}(Tv_n))$ . Therefore,

$$\dim \operatorname{range} T = \dim \operatorname{span}(Tv_1, \dots, Tv_n)$$
$$= \dim \operatorname{span}(\mathcal{M}(Tv_1), \dots, \mathcal{M}(Tv_n))$$

where the latter value is the column rank, as desired.

• Row rank equals column rank.

**Theorem 3.39.** Suppose  $A \in \mathbb{F}^{m,n}$ . Then the row rank of A equals the column rank of A.

*Proof.* Let  $T: \mathbb{F}^{n,1} \to \mathbb{F}^{m,1}$  be defined by Tx = Ax. It follows that  $\mathcal{M}(T) = A$ . Thus,

as desired.

• Rank (of A): The column rank of A.